HP 64797
H8/3048 Emulator
Softkey Interface

User’s Guide
**Notice**

Hewlett-Packard makes no warranty of any kind with regard to this material, including, but not limited to, the implied warranties of merchantability and fitness for a particular purpose. Hewlett-Packard shall not be liable for errors contained herein or for incidental or consequential damages in connection with the furnishing, performance, or use of this material.

Hewlett-Packard assumes no responsibility for the use or reliability of its software on equipment that is not furnished by Hewlett-Packard.

© Copyright 1995, Hewlett-Packard Company.

This document contains proprietary information, which is protected by copyright. All rights are reserved. No part of this document may be photocopied, reproduced or translated to another language without the prior written consent of Hewlett-Packard Company. The information contained in this document is subject to change without notice.

HP is a trademark of Hewlett-Packard Company.

UNIX is a registered trademark in the United States and other countries, licensed exclusively through X/Open Company Limited.

H8/3048™ registered trademark of Hitachi Ltd.

**Hewlett-Packard Company**  
P.O. Box 2197  
1900 Garden of the Gods Road  
Colorado Springs, CO 80901-2197, U.S.A.

**RESTRICTED RIGHTS LEGEND** Use, duplication, or disclosure by the U.S. Government is subject to restrictions set forth in subparagraph (C) (1) (ii) of the Rights in Technical Data and Computer Software Clause at DFARS 252.227-7013. Hewlett-Packard Company, 3000 Hanover Street, Palo Alto, CA 94304 U.S.A. Right for non-DOD U.S. Government Department and Agencies are as set forth in FAR 52.227-19(c)(1,2).
Printing History

New editions are complete revisions of the manual. The date on the title page changes only when a new edition is published.

A software code may be printed before the date; this indicates the version level of the software product at the time the manual was issued. Many product updates and fixes do not require manual changes, and manual corrections may be done without accompanying product changes. Therefore, do not expect a one-to-one correspondence between product updates and manual revisions.

**Edition 1** 64797-97001, January 1995
Using This Manual

This manual will show you how to use the HP 64797 H8/3048 Emulator with the Softkey Interface. This manual will also help define how these emulators differ from other HP 64700 Emulators.

This manual will:

■ Show you how to use emulation commands by executing them on a sample program and describing their results.
■ Show you how to configure the emulator for your development needs. Topics include: restricting the emulator to real-time execution, and selecting a target system clock source.
■ Show you how to use the emulator in-circuit (connected to a target system).

This manual will not:

■ Show you how to use every Softkey Interface command and option; the Softkey Interface is described in the Softkey Interface Reference.
Chapter 1  **Introduction.** This chapter lists the H8/3048 emulator features and describes how they can help you in developing new hardware and software.

Chapter 2  **Getting Started.** This chapter shows you how to use emulation commands by executing them on a sample program. This chapter describes the sample program and how to: load programs into the emulator, map memory, display and modify memory, display registers, step through programs, run programs, set software breakpoints, search memory for data, and use the analyzer.

Chapter 3  **In-Circuit Emulation.** This chapter shows you how to plug the emulator into a target system, and how to use the "in-circuit" emulation features.

Chapter 4  **Configuring the Emulator.** You can configure the emulator to adapt it to your specific development needs. This chapter describes the options available when configuring the emulator and how to save and restore particular configurations.

Chapter 5  **Using the Emulator.** This chapter describes emulation topics which are not covered in the "Getting Started" chapter.

Chapter 6  **Using On-chip Flash Memory.** This chapter describes differences between flash memory functions of the H8/3048 emulator and actual on-chip flash memory.
Conventions

Example commands throughout the manual use the following conventions:

**bold**

Commands, options, and parts of command syntax.

**bold italic**

Commands, options, and parts of command syntax which may be entered by pressing softkeys.

*normal*

User specified parts of a command.

$  

Represents the HP-UX prompt. Commands which follow the "$" are entered at the HP-UX prompt.

<RETURN>

The carriage return key.
<table>
<thead>
<tr>
<th>Section</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Softkey Driven Help</td>
<td>2-9</td>
</tr>
<tr>
<td>Pod Command Help</td>
<td>2-10</td>
</tr>
<tr>
<td>Loading Absolute Files</td>
<td>2-11</td>
</tr>
<tr>
<td>Displaying Symbols</td>
<td>2-11</td>
</tr>
<tr>
<td>Global</td>
<td>2-11</td>
</tr>
<tr>
<td>Local</td>
<td>2-12</td>
</tr>
<tr>
<td>Displaying Memory in Mnemonic Format</td>
<td>2-13</td>
</tr>
<tr>
<td>Displaying Memory with Symbols</td>
<td>2-14</td>
</tr>
<tr>
<td>Running the Program</td>
<td>2-15</td>
</tr>
<tr>
<td>From Transfer Address</td>
<td>2-15</td>
</tr>
<tr>
<td>From Reset</td>
<td>2-15</td>
</tr>
<tr>
<td>Displaying Memory Repetitively</td>
<td>2-15</td>
</tr>
<tr>
<td>Modifying Memory</td>
<td>2-16</td>
</tr>
<tr>
<td>Breaking into the Monitor</td>
<td>2-17</td>
</tr>
<tr>
<td>Using Software Breakpoints</td>
<td>2-17</td>
</tr>
<tr>
<td>Enabling/Disabling Software Breakpoints</td>
<td>2-18</td>
</tr>
<tr>
<td>Setting a Software Breakpoint</td>
<td>2-19</td>
</tr>
<tr>
<td>Clearing a Software Breakpoint</td>
<td>2-20</td>
</tr>
<tr>
<td>Stepping Through the Program</td>
<td>2-20</td>
</tr>
<tr>
<td>Displaying Registers</td>
<td>2-21</td>
</tr>
<tr>
<td>Using the Analyzer</td>
<td>2-22</td>
</tr>
<tr>
<td>Specifying a Simple Trigger</td>
<td>2-22</td>
</tr>
<tr>
<td>Displaying the Trace</td>
<td>2-23</td>
</tr>
<tr>
<td>Displaying Trace with Time Count Absolute</td>
<td>2-24</td>
</tr>
<tr>
<td>H8/3048 Analysis Status Qualifiers</td>
<td>2-25</td>
</tr>
<tr>
<td>Trace Analysis Considerations</td>
<td>2-26</td>
</tr>
<tr>
<td>How to Specify Trigger Condition</td>
<td>2-26</td>
</tr>
<tr>
<td>Store Condition and Trace</td>
<td>2-27</td>
</tr>
<tr>
<td>Triggering the Analyzer by Data</td>
<td>2-29</td>
</tr>
<tr>
<td>For a Complete Description</td>
<td>2-30</td>
</tr>
<tr>
<td>Exiting the Softkey Interface</td>
<td>2-30</td>
</tr>
<tr>
<td>End Release System</td>
<td>2-30</td>
</tr>
<tr>
<td>Ending to Continue Later</td>
<td>2-30</td>
</tr>
<tr>
<td>Ending Locked from All Windows</td>
<td>2-30</td>
</tr>
<tr>
<td>Selecting the Measurement System Display or Another Module</td>
<td>2-31</td>
</tr>
</tbody>
</table>

### 3 In-Circuit Emulation

<table>
<thead>
<tr>
<th>Section</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Installing the Target System Probe</td>
<td>3-2</td>
</tr>
<tr>
<td>PGA adaptor</td>
<td>3-3</td>
</tr>
<tr>
<td>QFP adaptor</td>
<td>3-3</td>
</tr>
<tr>
<td>QFP socket/adaptor</td>
<td>3-3</td>
</tr>
</tbody>
</table>
Installing into a 5 voltage target .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 3-4
Installing 64784E PGA adaptor .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 3-5
Installing QFP adaptor .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 3-6
Installing into a low voltage target .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 3-7
Specification .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 3-7
Installing 64797B PGA adaptor .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 3-8
Installing the H8/3048 microprocessor .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 3-9
In-Circuit Configuration Options .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 3-10
Target System Interface and Timing Specification .  .  .  .  .  .  .  . 3-11
Running the Emulator from Target Reset .  .  .  .  .  .  .  .  .  .  .  .  .  . 3-11
PGA Pin Assignments .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 3-12

4 Configuring the Emulator

Introduction .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 4-1
General Emulator Configuration .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 4-3
Micro-processor clock source? .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 4-3
Enter monitor after configuration? .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 4-5
Restrict to real-time runs? .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 4-5
Processor type? .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 4-6
Source for processor operation mode? .  .  .  .  .  .  .  .  .  .  .  .  .  . 4-7
Memory Configuration .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 4-9
Mapping Memory .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 4-9
Emulator Pod Configuration .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 4-12
Enable bus arbitration? .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 4-12
Enable NMI input from target system? .  .  .  .  .  .  .  .  .  .  .  .  .  . 4-13
Enable reset input from target system? .  .  .  .  .  .  .  .  .  .  .  .  .  . 4-14
Drive background cycles to the target system? .  .  .  .  .  .  .  . 4-15
Reset value for stack pointer? .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 4-16
Target memory access size? .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 4-16
Debug/Trace Configuration .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 4-17
Break processor on write to ROM? .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 4-17
Trace background or foreground operation? .  .  .  .  .  .  .  .  .  .  . 4-18
Trace on-chip DMAC cycles? .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 4-18
Trace refresh cycles? .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 4-19
Simulated I/O Configuration .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 4-19
Interactive Measurement Configuration .  .  .  .  .  .  .  .  .  .  .  .  . 4-20
External Analyzer Configuration .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 4-20
Saving a Configuration .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 4-20
Loading a Configuration .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  .  . 4-21

5 Using the Emulator
<table>
<thead>
<tr>
<th>Section</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Introduction</td>
<td>5-1</td>
</tr>
<tr>
<td>Features Available via Pod Commands</td>
<td>5-2</td>
</tr>
<tr>
<td>Using a Command File</td>
<td>5-3</td>
</tr>
<tr>
<td>Debugging C Programs</td>
<td>5-4</td>
</tr>
<tr>
<td>- Displaying Memory with C Sources</td>
<td>5-4</td>
</tr>
<tr>
<td>- Displaying Trace with C Sources</td>
<td>5-4</td>
</tr>
<tr>
<td>- Stepping C Sources</td>
<td>5-4</td>
</tr>
<tr>
<td>- Storing Memory Contents to an Absolute File</td>
<td>5-5</td>
</tr>
<tr>
<td>Coordinated Measurements</td>
<td>5-5</td>
</tr>
<tr>
<td>Register Classes and Names</td>
<td>5-6</td>
</tr>
<tr>
<td>Summary</td>
<td>5-6</td>
</tr>
</tbody>
</table>

### 6 Using the On-chip Flash Memory

<table>
<thead>
<tr>
<th>Section</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Introduction</td>
<td>6-1</td>
</tr>
<tr>
<td>Memory Mapping</td>
<td>6-1</td>
</tr>
<tr>
<td>Flash Memory Registers</td>
<td>6-2</td>
</tr>
<tr>
<td>Programming/Erasing Flash Memory</td>
<td>6-2</td>
</tr>
<tr>
<td>- Programming Data</td>
<td>6-2</td>
</tr>
<tr>
<td>- Erasing Data</td>
<td>6-3</td>
</tr>
<tr>
<td>- Protection Mode</td>
<td>6-3</td>
</tr>
<tr>
<td>Boot Mode</td>
<td>6-4</td>
</tr>
</tbody>
</table>

### Illustrations

- Figure 1-1. HP 64797 Emulator for the H8/3048                         | 1-2  |
- Figure 2-1. Sample Program Listing                                   | 2-3  |
- Figure 2-2. Linkage Editor Subcommand File                           | 2-6  |
- Figure 2-3. Softkey Interface Display                                | 2-8  |
- Figure 3-1 Installing HP 64784E/HP 64784G                             | 3-5  |
- Figure 3-2 Installing HP 64784D                                      | 3-6  |
- Figure 3-3 Installing HP 64797B/HP 64784G                             | 3-8  |
- Figure 3-4 Installing the H8/3048 processor                          | 3-8  |
- Figure 3-5 PGA Adaptor Pin Assignment                                | 3-16 |
## Tables

<table>
<thead>
<tr>
<th>Table Description</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Table 1-1 Supported Microprocessors</td>
<td>1-3</td>
</tr>
<tr>
<td>Table 1-2 Clock Speeds</td>
<td>1-4</td>
</tr>
<tr>
<td>Table 3-1 DC Characteristics of input high voltage</td>
<td>3-7</td>
</tr>
<tr>
<td>Table 3-2 PGA Pin Assignment</td>
<td>3-12</td>
</tr>
<tr>
<td>Table 4-1 Clock Speeds</td>
<td>4-4</td>
</tr>
</tbody>
</table>
Introduction

The topics in this chapter include:

- Purpose of the H8/3048 Emulator
- Features of the H8/3048 Emulator

Purpose of the H8/3048 Emulator

The H8/3048 Emulator is designed to replace the H8/3048 microprocessor in your target system so you can control operation of the microprocessor in your application hardware (usually referred to as the target system). The H8/3048 emulator performs just like the H8/3048 microprocessor, but is a device that allows you to control the H8/3048 microprocessor directly. These features allow you to easily debug software before any hardware is available, and ease the task of integrating hardware and software.
Figure 1-1. HP 64797 Emulator for the H8/3048

1-2 Introduction to the H8/3048 Emulator
The HP 64797A H8/3048 emulator supports the microprocessors listed in Table 1-1.

### Table 1-1. Supported Microprocessors

<table>
<thead>
<tr>
<th>Supported Microprocessors</th>
<th>Type</th>
<th>Package</th>
<th>On-chip ROM</th>
<th>Supply Voltage</th>
</tr>
</thead>
<tbody>
<tr>
<td>H8/3048</td>
<td>100 pin QFP</td>
<td>PROM</td>
<td></td>
<td>4.75 to 5.25V</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>2.70 to 5.25V</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Masked ROM</td>
<td>4.75 to 5.25V</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>2.70 to 5.25V</td>
</tr>
<tr>
<td>H8/3048F</td>
<td>100 pin QFP</td>
<td>Flash Memory</td>
<td></td>
<td>4.25 to 5.25V</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>2.70 to 5.25V</td>
</tr>
<tr>
<td>H8/3047</td>
<td>100 pin QFP</td>
<td>Masked ROM</td>
<td></td>
<td>4.75 to 5.25V</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>2.70 to 5.25V</td>
</tr>
<tr>
<td>H8/3044</td>
<td>100 pin QFP</td>
<td>Masked ROM</td>
<td></td>
<td>4.75 to 5.25V</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>2.70 to 5.25V</td>
</tr>
</tbody>
</table>

The H8/3048 emulator is provided without any adaptor and probe. To emulate each processor with your target system, you need to purchase appropriate adaptor and probe. To purchase them, contact your local HP sales representative.

The list of supported microprocessors in Table 1-1 is not necessarily complete. To determine if your microprocessor is supported or not, contact Hewlett-Packard.
**Clock Speeds**

You can select whether the emulator will be clocked by the internal clock source or by the external clock source on your target system. You need to select a clock input conforming to the specification of Table 1-2.

Crystal oscillator frequency of internal clock is 8MHz.

Refer to the "Configuration the Emulator" Chapter in this manual for more details.

<table>
<thead>
<tr>
<th>Emulation Memory</th>
<th>Clock Speed</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>With HP64784D</td>
</tr>
<tr>
<td>64726A</td>
<td>From 1 up to 16MHz (System Clock)</td>
</tr>
<tr>
<td>64727A</td>
<td>From 1 up to 16MHz (System Clock)</td>
</tr>
<tr>
<td>64728A</td>
<td>From 1 up to 13MHz (System Clock)</td>
</tr>
<tr>
<td>64729A</td>
<td>From 1 up to 18MHz (System Clock)</td>
</tr>
</tbody>
</table>

**Table 1-2. Clock Speeds**
**Emulation memory**

The H8/3048 emulator is used with one of the following Emulation Memory Cards.

- HP 64726A 128K byte Emulation Memory Card
- HP 64727A 512K byte Emulation Memory Card
- HP 64728A 1M byte Emulation Memory Card
- HP 64729A 2M byte Emulation Memory Card

When you use the HP64797A emulator over 16MHz, you have to use the HP 64729A 2M byte Emulation Memory Card.

You can define up to 16 memory ranges (at 512 byte boundaries and least 512 byte in length.) The emulator occupies 6K byte, which is used for monitor program and internal RAM of microprocessor mapped as emulation RAM, leaving 122K, 506K, 1018K, 2042K byte of emulation memory which you may use.

You can characterize memory range as emulation RAM (eram), emulation ROM (erom), target system RAM (tram), target system ROM (trom), or guarded memory (grd). The emulator generates an error message when accesses are made to guarded memory locations.

You can also configure the emulator so that writes to memory defined as ROM cause emulator execution to break out of target program execution.

**Analysis**

The H8/3048 emulator is used with one of the following analyzers which allows you to trace code execution and processor activity.

- HP 64704A 80-channel Emulation Bus Analyzer
- HP 64703A 64-channel Emulation Bus Analyzer and 16-channel State/Timing Analyzer.
- HP 64794A/C/D Deep Emulation Bus Analyzer

The Emulation Bus Analyzer monitors the emulation processor using an internal analysis bus. The HP 64703A 64-channel Emulation Bus Analyzer and 16-channel State/Timing Analyzer allows you to probe up to 16 different lines in your target system.

** Registers**

You can display or modify the H8/3048 internal register contents. This includes the ability to modify the program counter (PC) value so you can control where the emulator starts a program run.
Breakpoints

You can set the emulator/analyzer interaction so the emulator will break to the monitor program when the analyzer finds a specific state or states, allowing you to perform post-mortem analysis of the program execution. You can also set software breakpoints in your program. This feature is realized by inserting a special instruction into user program. One of undefined opcodes (5770 hex) is used as software breakpoint instruction. Refer to the "Using Software Breakpoints" section of "Getting Started" chapter for more information.

Reset Support

The emulator can be reset from the emulation system under your control; or your target system can reset the emulation processor.

Real Time Operation

Real-time signifies continuous execution of your program at full rated processor speed without interference from the emulator. (Such interference occurs when the emulator needs to break to the monitor to perform an action you requested, such as displaying target system memory.) Emulator features performed in real time include: running and analyzer tracing. Emulator features not performed in real time include: display or modification of target system memory, load/dump of target memory, display or modification of registers.

Easy Product Updates

Because the HP 64700 Series development tools (emulator, analyzer, LAN board) contain programmable parts, it is possible to reprogram the firmware and some of the hardware without disassembling the HP 64700B Card Cage. This means that you’ll be able to update product firmware, if desired, without having to call to HP field representative to your site.

1-6 Introduction to the H8/3048 Emulator
## Limitations, Restrictions

<table>
<thead>
<tr>
<th><strong>Foreground Monitor</strong></th>
<th>Foreground monitor is not supported for the H8/3048 emulator.</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>DMA Support</strong></td>
<td>Direct memory access to the emulation by external DMAC is not allowed.</td>
</tr>
<tr>
<td><strong>Watch Dog Timer in Background</strong></td>
<td>Watch dog timer is suspended count up while the emulator is running in background monitor.</td>
</tr>
<tr>
<td><strong>Monitor Break at Sleep/Standby Mode</strong></td>
<td>When the emulator breaks into the background monitor, sleep or software standby mode is released. Then, PC indicates next address of &quot;SLEEP&quot; instruction.</td>
</tr>
<tr>
<td><strong>Hardware Standby Mode</strong></td>
<td>Hardware standby mode is not supported for the H8/3048 emulator. Hardware standby request from target system will drive the emulator into the reset state.</td>
</tr>
<tr>
<td><strong>Interrupts in Background Cycles</strong></td>
<td>The H8/3048 emulator does not accept any interrupts while in background monitor. Such interrupts are suspended while running the background monitor, and will occur when context is changed to foreground.</td>
</tr>
<tr>
<td><strong>On-chip Flash Memory</strong></td>
<td>The H8/3048 emulator uses emulation memory instead of actual on-chip flash memory. So, operation for on-chip flash memory is different from H8/3048 microprocessor. Refer to &quot;Using the On-chip Flash Memory&quot; chapter in this manual for more details.</td>
</tr>
<tr>
<td><strong>Evaluation chip</strong></td>
<td>Hewlett-Packard makes no warranty of the problem caused by the H8/3048 Evaluation chip in the emulator.</td>
</tr>
</tbody>
</table>

*Introduction to the H8/3048 Emulator 1-7*
1-8 Introduction to the H8/3048 Emulator
Getting Started

Introduction

This chapter will lead you through a basic, step by step tutorial designed to familiarize you with the use of the H8/3048 emulator with the Softkey Interface.

This chapter will:

- Tell you what must be done before you can use the emulator as shown in the tutorial examples.
- Describe the sample program used for this chapter’s example.

This chapter will show you how to:

- Start up the Softkey Interface.
- Load programs into emulation and target system memory.
- Enter emulation commands to view execution of the sample program.
Before You Begin

Prerequisites

Before beginning the tutorial presented in this chapter, you must have completed the following tasks:

1. Connected the emulator to your computer. The *HP 64700 Series Installation/Service* manual show you how to do this.

2. Installed the Softkey Interface software on your computer. Refer to the *HP 64700 Series Installation/Service* manual for instructions on installing software.

3. In addition, you should read and understand the concepts of emulation presented in the *Concepts of Emulation and Analysis* manual. The *Installation/Service* manual also covers HP64700 system architecture. A brief understanding of these concepts may help avoid questions later.

You should read the *Softkey Interface Reference* manual to learn how to use the Softkey Interface in general. For the most part, this manual contains information specific to the H8/3048 emulator.

A Look at the Sample Program

The sample program used in this chapter is listed in figure 2-1. The program emulates a primitive command interpreter. The sample program is shipped with the Softkey Interface and may be copied from the following location.

```
/usr/hp64000/demo/emul/hp64797/cmd_rds.src
```

Data Declarations

The "Table" section defines the messages used by the program to respond to various command inputs. These messages are labeled *Msg_A*, *Msg_B*, and *Msg_I*.

2-2 Getting Started
GLOBAL    Init,Msgs,Cmd_Input
GLOBAL    Msg_Dest

SECTION    Table,DATA
Msgs
Msg_A          .SDATA          "THIS IS MESSAGE A"
Msg_B          .SDATA          "THIS IS MESSAGE B"
Msg_I          .SDATA          "INVALID COMMAND"
End_Msgs

SECTION    Prog,CODE
;*****************************************************************************
;* Set up the Stack Pointer.
;*****************************************************************************
Init            MOV.L           #Stack,ER7
;*****************************************************************************
;* Clear previous command.
;*****************************************************************************
Clear           MOV.B           #H'00,ROL
MOV.B           ROL, @Cmd_Input
;*****************************************************************************
;* Read command input byte. If no command has been
;* entered, continue to scan for it.
;*****************************************************************************
Scan            MOV.B           @Cmd_Input, R2L
CMP.B           #H'00,R2L
BEQ             Scan
;*****************************************************************************
;* A command has been entered. Check if it is
;* command A, command B, or invalid command.
;*****************************************************************************
Exe_Cmd         CMP.B           #H'41,R2L
BEQ             Cmd_A
CMP.B           #H'42,R2L
BEQ             Cmd_B
BRA             Cmd_I
;*****************************************************************************
;* Command A is entered. R3L = the number of bytes
;* in message A. R4 = location of the message.
;* Jump to the routine which writes the message.
;*****************************************************************************
Cmd_A           MOV.B           #Msg_B-Msg_A,R3L
MOV.L           #Msg_A,ER4
BRA             Write_Msg
;*****************************************************************************
;* Command B is entered.
;*****************************************************************************
Cmd_B           MOV.B           #Msg_I-Msg_B,R3L
MOV.L           #Msg_B,ER4
BRA             Write_Msg
;*****************************************************************************
;* An invalid command is entered.
;*****************************************************************************
Cmd_I           MOV.B           #End_Msgs-Msg_I,R3L
MOV.L           #Msg_I,ER4
;*****************************************************************************

Figure 2-1. Sample Program Listing
Initialization

The program instruction at the **Init** label initializes the stack pointer.

Reading Input

The instruction at the **Clear** label clears any random data or previous commands from the **Cmd_Input** byte. The **Scan** loop continually reads the **Cmd_Input** byte to see if a command is entered (a value other than 0 hex).
Processing Commands

When a command is entered, the instructions from **Exe_Cmd** to **Cmd_A** determine whether the command was "A", "B", or an invalid command.

If the command input byte is "A" (ASCII 41 hex), execution is transferred to the instructions at **Cmd_A**.

If the command input byte is "B" (ASCII 42 hex), execution is transferred to the instructions at **Cmd_B**.

If the command input byte is neither "A" nor "B", an invalid command has been entered, and execution is transferred to the instructions at **Cmd_I**.

The instructions at **Cmd_A**, **Cmd_B**, and **Cmd_I** each load register R3L with the length of the message to be displayed and register ER4 with the starting location of the appropriate message. Then, execution transfers to **Write_Msg** which writes the appropriate message to the destination location, **Msg_Dest**.

Prior to writing the message, **Clear_Old** clears the destination area. After the message is written, the program branches back to read the next command.

The Destination Area

The "Data" section declares memory storage for the command input byte, the destination area, and the stack area.
Sample Program Assembly

The sample program is written for and assembled with the Hitachi Cross System. The sample program was assembled with the following command.

```
$ asm38 cmd_rds.src -debug -cpu=300ha
<RETURN>
```

Linking the Sample Program

The sample program can be linked with following command and generates the absolute file. The contents of "cmd_rds.k" linkage editor subcommand file is shown in figure 2-2.

```
$ link -subcommand=cmd_rds.k <RETURN>
```

debug
input cmd_rds
start Prog(1000), Table(2000), Data(0FF800)
output cmd_rds
print cmd_rds
exit

Figure 2-2. Linkage Editor Subcommand File

Generate HP Absolute file

To generate HP Absolute file for the Softkey Interface, you need to use "h83cnvhp" absolute file format converter program. The h83cnvhp converter is provided with HP 64797 Softkey Interface. To generate HP Absolute file, enter following command:

```
$ h83cnvhp cmd_rds <RETURN>
```

You will see that cmd_rds.X, cmd_rds.L, and cmd_rds.A are generated. These are sufficient throughout this chapter.

Note

You need to specify "debug" command line option for compiler, assembler and linker command to generate local symbol information. Otherwise, you will see the warning message when file format converter h83cnvhp is executed. And no local symbol file will be generated. The "debug" option directs to include local symbol information to the object file.

---

2-6 Getting Started
Entering the Softkey Interface

If you have installed your emulator and Softkey Interface software as directed in the *HP 64700 Series Emulators Softkey Interface Installation Notice*, you are ready to enter the interface. The Softkey Interface can be entered from the HP-UX shell.

From the HP-UX Shell

If `/usr/hp64000/bin` is specified in your PATH environment variable, you can also enter the Softkey Interface with the following command.

```bash
$ emul700 <emul_name> <RETURN>
```

The "emul_name" in the command above is the logical emulator name given in the HP 64700 emulator device table (/usr/hp64000/etc/64700tab or /usr/hp64000/etc/64700tab.net).

<table>
<thead>
<tr>
<th>Channel</th>
<th>Logical</th>
<th>Processor</th>
<th>Remainder of Information for the Channel</th>
</tr>
</thead>
<tbody>
<tr>
<td>lan:</td>
<td>h8300</td>
<td>h6470048</td>
<td>21.17.9.143</td>
</tr>
</tbody>
</table>

If this command is successful, you will see a display similar to figure 2-3. The status message shows that the default configuration file has been loaded. If the command is not successful, you will be given an error message and returned to the HP-UX prompt. Error messages are described in the *Softkey Interface Reference* manual.
Using the Default Configuration

The default emulator configuration is used with the sample program. The H8/3048 emulator is configured to emulate H8/3048 chip and the address range 0 hex through ffff hex is mapped as emulation ROM.

Note

When you use internal ROM/on-chip flash memory area, you must map that area as emulation memory. If you don’t map internal ROM properly, you cannot access that area.

Note

Since the H8/3048 emulator automatically maps internal RAM as emulation RAM, you don’t need to map this area.

Refer to "Memory Configuration" section of "Configuring the Emulator" chapter in this manual for more details.
On-Line Help

There are two ways to access on-line help in the Softkey Interface. The first is by using the Softkey Interface help facility. The second method allows you to access the firmware resident Terminal Interface on-line help information.

Softkey Driven Help

To access the Softkey Interface on-line help information, type either "help" or "?" on the command line; you will notice a new set of softkeys. By pressing one of these softkeys and <RETURN>, you can cause information on that topic to be displayed on your screen. For example, you can enter the following command to access "system command" help information.

? system_commands <RETURN>

---SYSTEM COMMANDS & COMMAND FILES---

?                         displays the possible help files
help                      displays the possible help files
!<shell command>          fork a shell (specified by shell variable SH)
Pwd                       print the working directory
Cd <directory>            change the working directory
Pws                       print the default symbol scope
Cws <SYMB>                change the working symbol - the working symbol also gets updated when displaying local symbols and displaying memory mnemonic
Forward <UI> "command"    send the command in the quoted string from this user interface to another one. Replace <UI> with the name the other user interface as shown on the softkeys:

--More--(15%)

The help information is scrolled on to the screen. If there is more than a screenful of information, you will have to press the space bar to see the next screenful, or the <RETURN> key to see the next line, just as you do with the HP-UX more command. After all the information on the particular topic has been displayed (or after you press "q" to quit scrolling through information), you are prompted to press <RETURN> to return to the Softkey Interface.
Pod Command Help

To access the emulator’s firmware resident Terminal Interface help information, you can use the following commands.

```
display pod_command <RETURN>
pod_command 'help m' <RETURN>
```

The command enclosed in string delimiters (", ‘, or ^) is any Terminal Interface command, and the output of that command is seen in the pod_command display. The Terminal Interface help (or ?) command may be used to provide information on any Terminal Interface command or any of the emulator configuration options (as the example command above shows).

### Pod Commands

<table>
<thead>
<tr>
<th>Time</th>
<th>Command</th>
</tr>
</thead>
<tbody>
<tr>
<td>m &lt;addr&gt;</td>
<td>display memory at address</td>
</tr>
<tr>
<td>m -d&lt;dtype&gt; &lt;addr&gt;</td>
<td>display memory at address with display option</td>
</tr>
<tr>
<td>m &lt;addr&gt;..&lt;addr&gt;</td>
<td>display memory in specified address range</td>
</tr>
<tr>
<td>m -dm &lt;addr&gt;..&lt;addr&gt;</td>
<td>display memory mnemonics in specified range</td>
</tr>
<tr>
<td>m &lt;addr&gt;..</td>
<td>display 128 byte block starting at address A</td>
</tr>
<tr>
<td>m &lt;addr&gt;=&lt;value&gt;</td>
<td>modify memory at address to &lt;value&gt;</td>
</tr>
<tr>
<td>m -d&lt;dtype&gt; &lt;addr&gt;=&lt;value&gt;</td>
<td>modify memory with display option</td>
</tr>
<tr>
<td>m &lt;addr&gt;=&lt;value&gt;,&lt;value&gt;</td>
<td>modify memory to data sequence</td>
</tr>
<tr>
<td>m &lt;addr&gt;..&lt;addr&gt;=&lt;value&gt;,&lt;value&gt;</td>
<td>fill range with repeating sequence</td>
</tr>
</tbody>
</table>

--- VALID <dtype> MODE OPTIONS ---
| b | display size is 1 byte(s) |
| w | display size is 2 byte(s) |
| l | display size is 4 byte(s) |
| m | display processor mnemonics |

STATUS:   H8/3042--Running in monitor___________________________________...R....
pod_command 'help m'  
pod_cmd    set    perfinit perfrun          perfend                    ---ETC--
Loading Absolute Files

The "load" command allows you to load absolute files into emulation or target system memory. If you wish to load only that portion of the absolute file that resides in memory mapped as emulation RAM or ROM, use the "load emul_mem" syntax. If you wish to load only the portion of the absolute file that resides in memory mapped as target RAM, use the "load user_mem" syntax. If you want both emulation and target memory to be loaded, do not specify "emul_mem" nor "user_mem". For example:

```
load cmd_rds <RETURN>
```

Normally, you will configure the emulator and map memory before you load the absolute file; however, the default configuration is sufficient for the sample program.

Displaying Symbols

When you load an absolute file into memory (unless you use the "nosymbols" option), symbol information is loaded. Both global symbols and symbols that are local to a source file can be displayed.

**Global**

To display global symbols, enter the following command.

```
display global_symbols <RETURN>
```

Listed are: address ranges associated with a symbol.
Local

When displaying local symbols, you must include the name of the source file in which the symbols are defined. For example,

```
<RETURN>
display local_symbols_in cmd_rds.src:
<RETURN>
```

Symbols in cmd_rds.src:

<table>
<thead>
<tr>
<th>Symbol name</th>
<th>Address range</th>
<th>Segment</th>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>Clear</td>
<td>001006</td>
<td></td>
<td>0006</td>
</tr>
<tr>
<td>Clear_Loop</td>
<td>001050</td>
<td></td>
<td>0050</td>
</tr>
<tr>
<td>Clear_Old</td>
<td>00104E</td>
<td></td>
<td>004E</td>
</tr>
<tr>
<td>Cmd_A</td>
<td>001028</td>
<td></td>
<td>0028</td>
</tr>
<tr>
<td>Cmd_B</td>
<td>001034</td>
<td></td>
<td>0034</td>
</tr>
<tr>
<td>Cmd_I</td>
<td>001040</td>
<td></td>
<td>0040</td>
</tr>
<tr>
<td>Cmd_Input</td>
<td>OFF800</td>
<td></td>
<td>0000</td>
</tr>
<tr>
<td>Data</td>
<td>OFF800</td>
<td></td>
<td>0000</td>
</tr>
<tr>
<td>END_Msgs</td>
<td>00002031</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Exe_Cmd</td>
<td>001018</td>
<td></td>
<td>0018</td>
</tr>
<tr>
<td>Init</td>
<td>001000</td>
<td></td>
<td>0000</td>
</tr>
<tr>
<td>Msg_A</td>
<td>002000</td>
<td></td>
<td>0000</td>
</tr>
<tr>
<td>Msg_B</td>
<td>002011</td>
<td></td>
<td>0011</td>
</tr>
<tr>
<td>Msg_Dest</td>
<td>OFF802</td>
<td></td>
<td>0002</td>
</tr>
<tr>
<td>Msg_I</td>
<td>002022</td>
<td></td>
<td>0022</td>
</tr>
</tbody>
</table>

STATUS: cws: cmd_rds.src:______________________________________________...R....

display local_symbols_in cmd_rds.src:

run trace step display modify break end ---ETC--
Displaying Memory in Mnemonic Format

You can display, in mnemonic format, the absolute code in memory. For example, to display the memory of the "cmd_rds" program,

```
display memory Init mnemonic <RETURN>
```

Notice that you can use symbols when specifying expressions. The global symbol `Init` is used in the command above to specify the starting address of the memory to be displayed.

```
Memory :mnemonic :file = cmd_rds.src:
address data
001000 7A07000FF9 MOV.L #000FF902,ER7
001006 F800 MOV.B #00,R0L
001008 6AA8000FF8 MOV.B R0L,R0F800
00100E 6A2A000FF8 MOV.B @RFF800,R0L
001014 A400 CMP.B #00,R0L
001016 6A2A000FF8 MOV.B @RFF800,R0L
001018 AA41 CMP.B #41,R0L
00101A 5870000A BEQ 001028
00101E A442 CMP.B #42,R0L
001020 58700010 BEQ 001034
001024 58000018 BRA 001048
001028 FB11 MOV.B #11,R3L
00102A 7A04000020 MOV.L #00002000,ER4
001030 58000014 BRA 001048
001034 FB11 MOV.B #11,R3L
001036 7A04000020 MOV.L #00002011,ER4

STATUS: H8/3048--Running in monitor
...
```

```
run trace step display modify break end ----ETC--
```
Displaying Memory with Symbols

You can include symbol information in memory display.

```
set symbols on <RETURN>
```

```
<table>
<thead>
<tr>
<th>Address</th>
<th>Label</th>
<th>Address</th>
<th>Data</th>
</tr>
</thead>
<tbody>
<tr>
<td>001000</td>
<td>:Init</td>
<td>7A07000FF9</td>
<td>MOV.L #000FF902,ER7</td>
</tr>
<tr>
<td>001006</td>
<td>cmd_rd:Clear</td>
<td>F800</td>
<td>MOV.B #00,ROL</td>
</tr>
<tr>
<td>001008</td>
<td>6AA8000FF8</td>
<td>MOV.B ROL,:Cmd_Input</td>
<td></td>
</tr>
<tr>
<td>00100E</td>
<td>cmd_rds:Scan</td>
<td>6A2A000FF8</td>
<td>MOV.B @:Cmd_Input,R2L</td>
</tr>
<tr>
<td>001014</td>
<td>AA00</td>
<td>CMP.B #00,R2L</td>
<td></td>
</tr>
<tr>
<td>001016</td>
<td>47F6</td>
<td>BEQ cmd_rds.src:Scan</td>
<td></td>
</tr>
<tr>
<td>001018</td>
<td>cmd_:Exe_Cmd</td>
<td>AA41</td>
<td>CMP.B #41,R2L</td>
</tr>
<tr>
<td>00101A</td>
<td>5870000A</td>
<td>BEQ cmd_rds.src:Cm d_A</td>
<td></td>
</tr>
<tr>
<td>00101E</td>
<td>AA42</td>
<td>CMP.B #42,R2L</td>
<td></td>
</tr>
<tr>
<td>001020</td>
<td>58700010</td>
<td>BEQ cmd_rds.src:Cm d_B</td>
<td></td>
</tr>
<tr>
<td>001024</td>
<td>58000018</td>
<td>BRA cmd_rds.src:Cm d_I</td>
<td></td>
</tr>
<tr>
<td>001028</td>
<td>cmd_rd:Cm d_A</td>
<td>FB11</td>
<td>MOV.B #11,R3L</td>
</tr>
<tr>
<td>00102A</td>
<td>7A04000020</td>
<td>MOV.L #00020000,ER4</td>
<td></td>
</tr>
<tr>
<td>001030</td>
<td>58000014</td>
<td>BRA cmd_rds:Write_Msg</td>
<td></td>
</tr>
<tr>
<td>001034</td>
<td>cmd_rd:Cm d_B</td>
<td>FB11</td>
<td>MOV.B #11,R3L</td>
</tr>
<tr>
<td>001036</td>
<td>7A04000020</td>
<td>MOV.L #0002011,ER4</td>
<td></td>
</tr>
</tbody>
</table>

STATUS: H8/3048--Running in monitor__________________________...R....
```

The "set" command is effective only to the window which the command is invoked. When you access the emulator from multiple windows, you need to use the command at each window.

---ETC---
Running the Program

The "run" command lets the emulator execute a program in memory. Entering the "run" command by itself causes the emulator to begin executing at the current program counter address. The "run from" command allows you to specify an address at which execution is to start.

From Transfer Address

The "run from transfer_address" command specifies that the emulator start executing at a previously defined "start address". Transfer addresses are defined in assembly language source files with the .END assembler directive (i.e., pseudo instruction). For example, the sample program defines the address of the label Init as the transfer address. The following command will cause the emulator to execute from the address of the Init label.

```
run from transfer_address <RETURN>
```

From Reset

The "run from reset" command specifies that the emulator begin executing from target system reset (see "Running From Reset" section in the "In-Circuit Emulation" chapter).

Displaying Memory Repetitively

You can display memory locations repetitively so that the information on the screen is constantly updated. For example, to display the Msg_Dest locations of the sample program repetitively (in blocked byte format), enter the following command.

```
display memory Msg_Dest repetitively blocked bytes <RETURN>
```
Modifying Memory

The sample program simulates a primitive command interpreter. Commands are sent to the sample program through a byte sized memory location labeled **Cmd_Input**. You can use the modify memory feature to send a command to the sample program. For example, to enter the command "A" (41 hex), use the following command.

```
modify memory Cmd_Input bytes to 41h <RETURN>
```

Or:

```
modify memory Cmd_Input string to 'A'
<RETURN>
```

After the memory location is modified, the repetitive memory display shows that the "THIS IS MESSAGE A" message is written to the destination locations.
Breaking into the Monitor

The "break" command allows you to divert emulator execution from the user program to the monitor. You can continue user program execution with the "run" command. To break emulator execution from the sample program to the monitor, enter the following command.

```
break <RETURN>
```

Note

If DMA transfer is in progress with BURST transfer mode, break command is suspended and occurs after DMA transfer is completed.

Using Software Breakpoints

Software breakpoints are provided with an H8/3048 special code; This special code (5770 hexadecimal) is H8/3048 undefined instruction.

When you define or enable a software breakpoint, the emulator will replace the opcode at the software breakpoint address with the special code.

Note

You must set software breakpoints only at memory locations which contain instruction opcodes (not operands or data). If a software breakpoint is set at a memory location which is not an instruction opcode, the software breakpoint instruction will never be executed and the break will never occur.

Note

Because software breakpoints are implemented by replacing opcodes with the special code, you cannot define software breakpoints in target ROM.
When software breakpoints are enabled and emulator detects a fetching the special code (5770 hexadecimal), it generates a break to background request which as with the "processor break" command. Since the system controller knows the locations of defined software breakpoints, it can determine whether the special code is software breakpoints or opcode in your target program.

If it is a software breakpoint, execution breaks to the monitor, and the special code is replaced by the original opcode. A subsequent run or step command will execute from this address.

If the special code is opcode of your target program, execution still breaks to the monitor, and an "Undefined software breakpoint" status message is displayed.

When software breakpoints are disabled, the emulator replaces the special code with the original opcode.

Unlimited software breakpoints may be defined.

**Enabling/Disabling Software Breakpoints**

When you initially enter the Softkey Interface, software breakpoints are disabled. To enable the software breakpoints feature, enter the following command.

```
modify software_breakpoints enable <RETURN>
```

When software breakpoints are enabled and you set a software breakpoint, the H8/3048 special code (5770 hexadecimal) will be placed at the address specified. When the special code is executed, program execution will break into the monitor.
Setting a Software Breakpoint

To set a software breakpoint at the address of the Cmd_A label, enter the following command.

```
modify software_breakpoints set
    cmd_rds.src:Cmd_A <RETURN>
```

Notice that when using local symbols in expressions, the source file in which the local symbol is defined must be included.

After the software breakpoint has been set, enter the following command to display memory and see if the software breakpoint was correctly inserted.

```
display memory Init mnemonic <RETURN>
```

As you can see, the software breakpoint is shown in the memory display with an asterisk.

```
As you can see, the software breakpoint is shown in the memory display with an asterisk.
```

Enter the following command to cause the emulator to continue executing the sample program.

```
run <RETURN>
```

Now, modify the command input byte to a valid command for the sample program.

```
Getting Started 2-19
```
modify memory Cmd_Input bytes to 41h <RETURN>

You will see the line of the software breakpoint is displayed in inverse-video. The inverse-video shows that the Program Counter is now at the address.

A message on the status line shows that the software breakpoint has been hit. The status line also shows that the emulator is now executing in the monitor.

To remove software breakpoint defined above, enter the following command.

modify software_breakpoints clear

The breakpoint is removed from the list, and the original opcode is restored if the breakpoint was pending.

To clear all software breakpoints, you can enter the following command.

modify software_breakpoints clear <RETURN>

The step command allows you to step through program execution an instruction or a number of instructions at a time. Also, you can step from the current program counter or from a specific address. To step through the example program from the address of the software breakpoint set earlier, enter the following command.

step <RETURN>, <RETURN>, ...

You will see the inverse-video moves according to the step execution. You can continue to step through the program just by pressing the <RETURN> key; when a command appears on the command line, it may be entered by pressing <RETURN>.
Displaying Registers

Enter the following command to display registers. You can display the basic registers class, or an individual register.

```
display registers <RETURN>
```

You can use "register class" and "register name" to display registers. Refer to the "Register Class and Name" section in Chapter 5.

When you enter the "step" command with registers displayed, the register display is updated every time you enter the command.

```
step <RETURN>, <RETURN>, <RETURN>
```
Enter the following command to cause sample program execution to continue from the current program counter.

```
run <RETURN>
```

### Using the Analyzer

HP 64700 emulators contain an emulation analyzer. The emulation analyzer monitors the internal emulation lines (address, data, and status). Optionally, you may have an additional 16 trace signals which monitor external input lines. The analyzer collects data at each pulse of a clock signal, and saves the data (a trace state) if it meets a "storage qualification" condition.

### Specifying a Simple Trigger

Suppose you want to trace program execution after the point at which the sample program reads the "B" (42 hex) command from the command input byte. To do this you would trace after the analyzer finds a state in which a value of 42xxh is read from the `Cmd_Input` byte. The following command makes this trace specification.

```
trace after Cmd_Input data 42xxh status read <RETURN>
```

---

2-22 Getting Started
The message "Emulation trace started" will appear on the status line. Now, modify the command input byte to "B" with the following command.

```
modify memory Cmd_Input bytes to 42h <RETURN>
```

The status line now shows "Emulation trace complete".

### Displaying the Trace

The trace listings which follow are of program execution on the H8/3048 emulator. To display the trace, enter:

```
display trace <RETURN>
```

<table>
<thead>
<tr>
<th>Trace List</th>
<th>Depth=512</th>
<th>Offset=0</th>
</tr>
</thead>
<tbody>
<tr>
<td>Label:</td>
<td>Address</td>
<td>Data</td>
</tr>
<tr>
<td>Base:</td>
<td>symbols</td>
<td>hex</td>
</tr>
<tr>
<td>after</td>
<td>:Cmd_Input</td>
<td>42FF</td>
</tr>
<tr>
<td>:cmd_rds:+000016</td>
<td>47F6</td>
<td>BEQ cmd_rds.src:Scan</td>
</tr>
<tr>
<td>cmd_rds.:Exe_Cmd</td>
<td>AA41</td>
<td>CMP.B #41,R2L</td>
</tr>
<tr>
<td>cmd_rds.:Scan</td>
<td>6A2A</td>
<td>6A2A unused fetch mem</td>
</tr>
<tr>
<td>:cmd_rds:+00001A</td>
<td>5870</td>
<td>BEQ cmd_rds.sr:Cmd_A</td>
</tr>
<tr>
<td>:cmd_rds:+00001C</td>
<td>000A</td>
<td>000A fetch mem</td>
</tr>
<tr>
<td>:cmd_rds:+00001E</td>
<td>5870</td>
<td>BEQ cmd_rds.sr:Cmd_B</td>
</tr>
<tr>
<td>:cmd_rds:+000020</td>
<td>0010</td>
<td>fetch mem</td>
</tr>
<tr>
<td>:cmd_rds:+000022</td>
<td>0010</td>
<td>fetch mem</td>
</tr>
<tr>
<td>:cmd_rds.sr:Cmd_B</td>
<td>FB11</td>
<td>MOV.B #11,R3L</td>
</tr>
<tr>
<td>:cmd_rds:+000036</td>
<td>7A04</td>
<td>MOV.L #00002011,ER4</td>
</tr>
<tr>
<td>:cmd_rds:+000038</td>
<td>0000</td>
<td>0000 fetch mem</td>
</tr>
<tr>
<td>:cmd_rds:+00003A</td>
<td>2011</td>
<td>2011 fetch mem</td>
</tr>
<tr>
<td>:cmd_rds:+00003C</td>
<td>5800</td>
<td>BRA cmd_rds:Write_Msg</td>
</tr>
<tr>
<td>:cmd_rds:+00003E</td>
<td>0008</td>
<td>0008 fetch mem</td>
</tr>
</tbody>
</table>

```
STATUS: H8/3048--running user program
Emulation trace complete______...R....
display trace
```

Line 0 (labeled "after") in the trace list above shows the state which triggered the analyzer. The trigger state is always on line 0. The other states show the exit from the Scan loop and the Exe_Cmd and Cmd_B instructions. To list the next lines of the trace, press the <PGDN> or <NEXT> key.

---ETC---
The resulting display shows **Cmd_B** instructions, the branch to **Write_Msg** and the beginning of the instructions which move the "THIS IS MESSAGE B" message to the destination locations.

To list the previous lines of the trace, press the <PGUP> or <PREV> key.

**Displaying Trace with Time Count Absolute**

Enter the following command to display count information absolute from the trigger state.

```
display trace count absolute <RETURN>
```
The status qualifier "read" was used in the example trace command used above. The following analysis status qualifiers may also be used with the H8/3048 emulator.

<table>
<thead>
<tr>
<th>Qualifier</th>
<th>Status Bits (40..57)</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>backgrnd</td>
<td>xx x0xx xxxx xxxx xxxxB</td>
<td>Background cycle</td>
</tr>
<tr>
<td>byte</td>
<td>xx xxxx 1xxx x1xx x1xxB</td>
<td>Byte access</td>
</tr>
<tr>
<td>cpu</td>
<td>xx xxxx 1xxx x11x xxxxB</td>
<td>CPU access</td>
</tr>
<tr>
<td>data</td>
<td>xx xxxx 1xxx x1xx 1xxxB</td>
<td>Data access</td>
</tr>
<tr>
<td>dma</td>
<td>xx xxxx 1xxx x1Ix 1xxxxB</td>
<td>DMA memory access</td>
</tr>
<tr>
<td>fetch</td>
<td>xx xxxx 1x1x x110 xx01B</td>
<td>Fetch cycle</td>
</tr>
<tr>
<td>foregrnd</td>
<td>xx x1xx xxxx xxxx xxxxB</td>
<td>Foreground cycle</td>
</tr>
<tr>
<td>grd</td>
<td>xx xxxx 0x0x xxxx xxxxB</td>
<td>Guarded memory access</td>
</tr>
<tr>
<td>intack</td>
<td>xx xxxx x0xx xxxx xxxxB</td>
<td>Interrupt acknowledge cycle</td>
</tr>
<tr>
<td>io</td>
<td>xx xxxx 1xxx x1xx 0xxxB</td>
<td>Internal I/O access</td>
</tr>
<tr>
<td>memory</td>
<td>xx xxxx 1xxx x1xx 1xxxB</td>
<td>Memory access</td>
</tr>
<tr>
<td>nointack</td>
<td>xx xxxx 1xxx xxxx xxxxB</td>
<td>No interrupt acknowledge cycle</td>
</tr>
<tr>
<td>read</td>
<td>xx xxxx 1xxx x1xx xxxxB</td>
<td>Read cycle</td>
</tr>
<tr>
<td>refresh</td>
<td>xx xxxx 1xxx x01x xxxxB</td>
<td>Refresh cycle</td>
</tr>
<tr>
<td>word</td>
<td>xx xxxx 1xxx x1xx xxxxB</td>
<td>Word access</td>
</tr>
<tr>
<td>write</td>
<td>xx xxxx 1xxx x1xx xxxxB</td>
<td>Write cycle</td>
</tr>
<tr>
<td>wrrom</td>
<td>xx xx10 1xxx x1xx xxxxB</td>
<td>Write to ROM cycle</td>
</tr>
</tbody>
</table>
### Trace Analysis Considerations

There are some points to be noticed when you use the emulation analyzer.

### How to Specify Trigger Condition

You need to be careful to specify the condition on which the emulation analyzer should start the trace. Suppose that you would like to start the trace when the program begins executing `Exe_Cmd` routine:

```
trace after cmd_rds.src:Exe_Cmd <RETURN>
```

```
modify memory Cmd_Input bytes to 41h <RETURN>
```

(Actually trace will be completed before you enter "modify memory" command)

You will see:

<table>
<thead>
<tr>
<th>Trace List</th>
<th>Depth=512</th>
<th>Offset=0</th>
</tr>
</thead>
<tbody>
<tr>
<td>Label:</td>
<td>Address</td>
<td>Data</td>
</tr>
<tr>
<td>Base:</td>
<td>symbols</td>
<td>hex</td>
</tr>
<tr>
<td>after cmd_rds.:Exe_Cmd</td>
<td>AA41</td>
<td>AA41</td>
</tr>
<tr>
<td>cmd_rds.src:Scan</td>
<td>6A2A</td>
<td>MOV.B @:Cmd_Input,R2L</td>
</tr>
<tr>
<td>:cmd_rds:+000010</td>
<td>000F</td>
<td>000F</td>
</tr>
<tr>
<td>:cmd_rds:+000012</td>
<td>F800</td>
<td>F800</td>
</tr>
<tr>
<td>:cmd_rds:+000014</td>
<td>AA00</td>
<td>CMP.B #00,R2L</td>
</tr>
<tr>
<td>:Cmd_Input</td>
<td>00FF</td>
<td>00xx</td>
</tr>
<tr>
<td>:cmd_rds:+000016</td>
<td>47F6</td>
<td>BEQ cmd_rds.src:Scan</td>
</tr>
<tr>
<td>cmd_rds.:Exe_Cmd</td>
<td>AA41</td>
<td>AA41</td>
</tr>
<tr>
<td>cmd_rds.src:Scan</td>
<td>6A2A</td>
<td>MOV.B @:Cmd_Input,R2L</td>
</tr>
<tr>
<td>:cmd_rds:+000010</td>
<td>000F</td>
<td>000F</td>
</tr>
<tr>
<td>:cmd_rds:+000012</td>
<td>F800</td>
<td>F800</td>
</tr>
<tr>
<td>:cmd_rds:+000014</td>
<td>AA00</td>
<td>CMP.B #00,R2L</td>
</tr>
<tr>
<td>:Cmd_Input</td>
<td>00FF</td>
<td>00xx</td>
</tr>
<tr>
<td>:cmd_rds:+000016</td>
<td>47F6</td>
<td>BEQ cmd_rds.src:Scan</td>
</tr>
<tr>
<td>cmd_rds.:Exe_Cmd</td>
<td>AA41</td>
<td>AA41</td>
</tr>
</tbody>
</table>

### Status

```
STATUS: H8/3048--Running user program   Emulation trace complete__...R....
```

This is not what we were expecting to see. As you can see at the first line of the trace list, the address of `Exe_Cmd` routine appears on the address bus during the program executing `Scan` loop. This made the emulation analyzer start trace. To avoid mis-trigger by this cause, set the trigger condition to the second instruction of the routine you want to trace:

```
run trace step display modify break end ---ETC--
```

### 2-26 Getting Started
trace after cmd_rds.src:Exe_Cmd+2

(Since the instruction at Exe_Cmd label is two bytes instruction, the next instruction starts from Exe_Cmd+2.)

modify memory Cmd_Input bytes to 41h

If you need to see the execution of the instruction at Exe_Cmd label, use trace about command instead of trace after command. When you use the trace about command, the state which triggered the analyzer will appear in the center of the trace list.

Store Condition and Trace

When you specify store condition with trace only command, disassembling of program execution is unreliable.
The program is executing the **Scan** loop.

Now, trace only accesses to the address range **Init** through **Init+0ffh**.

```
trace only range Init thru Init+0ffh <RETURN>
```

2-28 Getting Started
As you can see the execution of CMP.B instructions are not disassembled. This occurs when the analyzer cannot get necessary information for disassembling because of the store condition. Be careful when you use the **trace only** command.

### Triggering the Analyzer by Data

You may want to trigger the emulation analyzer when specific data appears on the data bus. You can accomplish this with the following command.

```
trace after data <data> <RETURN>
```

There are some points to be noticed when you trigger the analyzer in this way. You always need to specify the `<data>` with 16 bits value even when access to the data is performed by byte access. This is because the analyzer is designed so that it can capture data on internal data bus (which has 16 bits width). The following table shows the way to specify the trigger condition by data.

<table>
<thead>
<tr>
<th>Location of data</th>
<th>Access size</th>
<th>Address value</th>
<th>Available &lt;data&gt; Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>8 bit data</td>
<td>byte/word</td>
<td>even</td>
<td>ddxx</td>
</tr>
<tr>
<td></td>
<td></td>
<td>odd</td>
<td>xxddd</td>
</tr>
<tr>
<td>16 bit data</td>
<td>byte</td>
<td>even</td>
<td>ddxx</td>
</tr>
<tr>
<td></td>
<td></td>
<td>odd</td>
<td>xxddd</td>
</tr>
<tr>
<td></td>
<td>word</td>
<td>even</td>
<td>hhll</td>
</tr>
</tbody>
</table>

*1 dd means 8 bits data
*2 hhll means 16 bits data

For example, to trigger the analyzer when the processor performs word access to data 1234 hex in 16 bit bus area, you can specify the following:

```
trace after data 1234h <RETURN>
```

To trigger the analyzer when the processor accesses data 12 hex to the even address located in 8 bit data bus area:

```
trace after data 12xxh <RETURN>
```
On the other hand, to trigger 12 hex to the odd address located in 8 bit data bus.

\texttt{trace after data xx12h <RETURN>}

Notice that you always need to specify "xx" value to capture byte access to 8 bit data bus area. Be careful to trigger the analyzer by data.

For a complete description of using the HP 64700 Series analyzer with the Softkey Interface, refer to the \textit{Analyzer Softkey Interface User's Guide}.

**Exiting the Softkey Interface**

There are several options available when exiting the Softkey Interface: exiting and releasing the emulation system, exiting with the intent of reentering (continuing), exiting locked from multiple emulation windows, and exiting (locked) and selecting the measurement system display or another module.

**End Release System**

To exit the Softkey Interface, releasing the emulator so that other users may use the emulator, enter the following command.

\texttt{end release_system <RETURN>}

**Ending to Continue Later**

You may also exit the Softkey Interface without specifying any options; this causes the emulator to be locked. When the emulator is locked, other users are prevented from using it and the emulator configuration is saved so that it can be restored the next time you enter (continue) the Softkey Interface.

\texttt{end <RETURN>}

**Ending Locked from All Windows**

When using the Softkey Interface from within window systems, the "end" command with no options causes an exit only in that window. To end locked from all windows, enter the following command.

\texttt{end locked <RETURN>}

This option only appears when you enter the Softkey Interface via the \texttt{emul700} command. When you enter the Softkey Interface via \texttt{pmon} and \texttt{MEAS_SYS}, only one window is permitted.
Refer to the Softkey Interface Reference manual for more information on using the Softkey Interface with window systems.

When you enter the Softkey Interface via `pmon` and `MEAS_SYS`, you have the option to select the measurement system display or another module in the measurement system when exiting the Softkey Interface. This type of exit is also "locked"; that is, you can continue the emulation session later. For example, to exit and select the measurement system display, enter the following command.

```
end select measurement_system <RETURN>
```

This option is not available if you have entered the Softkey Interface via the `emul700` command.
In-Circuit Emulation

When you are ready to use the H8/3048 emulator in conjunction with actual target system hardware, there are some special considerations you should keep in mind.

- installing the emulation cable
- properly configure the emulator

We will cover the first topic in this chapter. For complete details on in-circuit emulation configuration, refer to Chapter 4.
The following precautions should be taken while using the H8/3048 emulator. Damage to the emulator circuitry may result if these precautions are not observed.

**Power Down Target System.** Turn off power to the user target system and to the H8/3048 emulator before attaching and detaching the adaptor and probe to the emulator or target system to avoid circuit damage resulting from voltage transients or mis-insertion.

**Verify User Plug Orientation.** Make certain that Pin 1 of the QFP socket/adaptor and Pin 1 of the QFP probe are properly aligned before inserting the QFP probe the QFP socket/adaptor. Failure to do so may result in damage to the emulator circuitry.

**Protect Against Static Discharge.** The H8/3048 emulator and the PGA adaptor and QFP probe contain devices which are susceptible to damage by static discharge. Therefore, operators should take precautionary measures before handling the user plug to avoid emulator damage.

**Protect Target System CMOS Components.** If your target system includes any CMOS components, turn on the target system first, then turn on the H8/3048 emulator; when powering down, turn off the emulator first, then turn off power to the target system.
The H8/3048 emulator is provided without any PGA adaptor, QFP adaptor and QFP probe. To emulate each processor with your target system, you need to purchase appropriate adaptor and/or probe.

**PGA adaptor**

To emulate each processor with your target system, you can use HP 64784E 5 voltage PGA adaptor or HP 64797B low voltage PGA adaptor as shown in Figure 3-1 and 3-3. These PGA adaptors allow you to connect the emulation cable to QFP socket/adaptor on your target system using the HP 64784G QFP probe. HP 64784G QFP probe is flexible and comfortable to connect the PGA adaptor to a densely populated circuit board.

If you want to connect the PGA adaptor to your target system directly, you need to prepare PGA socket on your target system. To prepare the PGA socket, refer to Table 3-2 and Figure 3-5 to know H8/3048 pin assignment.

**QFP adaptor**

To emulate with your target system running with supply voltage 5V, you can also use HP 64784D QFP adaptor. The QFP adaptor allows you to connect the emulation cable to the QFP socket/adapter on your target system as shown in Figure 3-2.

**QFP socket/adaptor**

The QFP socket/adaptor designed for H8/3048 microprocessor is provided with the QFP adaptor and QFP probe. You must attach the QFP socket/adaptor to your target system except you connect the PGA adaptor to your target system directly.

When you use this QFP socket/adaptor, you can replace the H8/3048 emulator with actual H8/3048 microprocessor. Refer to Figure 3-4.

**Note**

You can order additional QFP socket/adaptor with part No. HP 64784-61612.
Installing into a 5 voltage target

You can select either of the followings to connect the H8/3048 emulator to your 5 voltage target.

- HP 64784D
- HP 64784E + HP 64784G

Note

The H8/3048 emulator can only operate rightly with supply voltage from 4.75V to 5.25V, when you use HP 64784E PGA adaptor or HP 64784D QFP adaptor.

Note

If you have a HP 64797B low voltage PGA adaptor, you can use this low voltage PGA adaptor instead of HP 64784E 5 voltage PGA adaptor. HP 64797B low voltage PGA adaptor can operate rightly with supply voltage from 2.70V to 5.25V.

Note

You must use a clock conforming to the specification of Table 4-1, when you configure the emulator to use external clock.
Installing 64784E PGA adaptor

1. Attach the QFP socket/adaptor to your target system.

2. Connect the PGA adaptor to the emulation cable.

3. Install the PGA adaptor to the QFP socket/adaptor on your target system through QFP probe as shown in Figure 3-1.

Figure 3-1 Installing HP 64784E/HP 64784G
4. Attach the QFP socket/adaptor to your target system.

5. Connect the QFP adaptor to the emulation cable.

6. Install the QFP adaptor to the QFP socket/adaptor on your target system as shown in Figure 3-2.

Figure 3-2 Installing HP 64784D
Installing into a low voltage target

To connect the emulator into a low voltage target, you should use HP 64797B PGA adaptor and 64784G QFP probe.

Specification

The emulator can only operate rightly with supply voltage from 2.7V up to 5.25V. You must conform input high voltage (Vih) to the specification of Table 3-1, because these DC characteristics are different from the actual processor’s specification.

Table 3-1. DC Characteristics of input high voltage

<table>
<thead>
<tr>
<th>Item</th>
<th>Minimum (V)</th>
</tr>
</thead>
<tbody>
<tr>
<td>P1 - P5, D0 - D15</td>
<td>Vcc x 0.7 or 2.4 *1</td>
</tr>
<tr>
<td>Others</td>
<td>Vcc x 0.7 or 2.0 *1</td>
</tr>
</tbody>
</table>

*1 Higher of the two.

Note

You must use a clock conforming to the specification of Table 4-1, when you configure the emulator to use external clock.
Installing 64797B
PGA adaptor

1. Attach the QFP socket/adaptor to your target system.

2. Connect the PGA adaptor to the emulation probe.

3. Install the PGA adaptor to the QFP socket/adaptor on your target system through QFP probe as shown in Figure 3-3.

Figure 3-3 Installing HP 64797B/HP 64784G

3-8 In-Circuit Emulation
Installing the H8/3048 microprocessor

You can replace the QFP adaptor/probe with the H8/3048 microprocessor.

Figure 3-4 Installing the H8/3048 processor
The H8/3048 emulator provides configuration options for the following in-circuit emulation issues.

Refer to the Chapter 4 "Configuring the Emulator" for more information on these configuration options.

**Using the Target System Clock Source**

You can configure the emulator to use the external target system clock source.

**Enabling Bus Arbitration**

You can configure the emulator to enable/disable bus arbitration.

**Enabling NMI from the Target**

You can configure the emulator to accept/ignore NMI from the target system.

**Enabling /RES signal from the Target**

You can configure the emulator to accept/ignore /RES signal from the target system.

**Selecting Visible/Hidden Background Cycles**

Emulation processor activity while executing in background can either be visible to target system (cycles are sent to the target system probe) or hidden (cycles are not sent to the target system probe).

**Selecting Target Memory Access Size**

You can specify the types of cycles that the emulation monitor uses when accessing target system memory.
Target System Interface and Timing Specification

Refer to the *H8/3048 Terminal Interface User’s Guide* for information on the target system interface and timing specification of the H8/3048 emulator.

Running the Emulator from Target Reset

You can specify that the emulator begins executing from target system reset. When the target system /RES line becomes active and then inactive, the emulator will start reset sequence (operation) as actual microprocessor.

At first, you must specify the emulator responds to /RES signal by the target system (see the "Enable /RES input from target system?" configuration in Chapter 4 of this manual).

To specify a run from target system reset, select:

```
run from reset <RESET>
```

The status now shows that the emulator is "Awaiting target reset". After the target system is reset, the status line message will change to show the appropriate emulator status.

----

Note

In the "Awaiting target reset", you can not break into the monitor. If you enter "run from reset" in out-of-circuit or in the configuration that emulator does not accept target system reset (cf trst=dis), you must reset the emulator.
PGA Pin Assignments

When you connect the PGA adaptor to your target system directly, pin assignment of your target PGA socket must be compatible with the PGA adaptor pin assignment. The following table and figure show you the pin assignment of the PGA adaptor.

Table 3-2 PGA Pin Assignment

<table>
<thead>
<tr>
<th>PGA 135 pin #</th>
<th>QFP 100 pin #</th>
<th>Function name</th>
<th>PGA 135 pin #</th>
<th>QFP 100 pin #</th>
<th>Function name</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>98</td>
<td>PA/TP5/TIOCB1/A22/CS5</td>
<td>15</td>
<td>21</td>
<td>P43/D3</td>
</tr>
<tr>
<td>2</td>
<td>1</td>
<td>Vcc</td>
<td>16</td>
<td>25</td>
<td>P46/D6</td>
</tr>
<tr>
<td>3</td>
<td>3</td>
<td>PB1/TP9/TIOCB3</td>
<td>17</td>
<td>27</td>
<td>P30/D8</td>
</tr>
<tr>
<td>4</td>
<td>nc</td>
<td></td>
<td>18</td>
<td>30</td>
<td>P33/D11</td>
</tr>
<tr>
<td>5</td>
<td>8</td>
<td>PB6/TP14/DREQ0/CS7</td>
<td>19</td>
<td>31</td>
<td>P34/D12</td>
</tr>
<tr>
<td>6</td>
<td>nc</td>
<td></td>
<td>20</td>
<td>33</td>
<td>P36/D14</td>
</tr>
<tr>
<td>7</td>
<td>nc</td>
<td></td>
<td>21</td>
<td>34</td>
<td>P37/D15</td>
</tr>
<tr>
<td>8</td>
<td>nc</td>
<td></td>
<td>22</td>
<td>nc</td>
<td></td>
</tr>
<tr>
<td>9</td>
<td>nc</td>
<td></td>
<td>23</td>
<td>37</td>
<td>P11/A1</td>
</tr>
<tr>
<td>10</td>
<td>nc</td>
<td></td>
<td>24</td>
<td>40</td>
<td>P14/A4</td>
</tr>
<tr>
<td>11</td>
<td>14</td>
<td>P92/RxD0</td>
<td>25</td>
<td>43</td>
<td>P17/A7</td>
</tr>
<tr>
<td>12</td>
<td>17</td>
<td>P95/SCK1/IRQ5</td>
<td>26</td>
<td>57</td>
<td>Vss</td>
</tr>
<tr>
<td>13</td>
<td>18</td>
<td>P40/D0</td>
<td>27</td>
<td>nc</td>
<td></td>
</tr>
<tr>
<td>14</td>
<td>nc</td>
<td></td>
<td>28</td>
<td>49</td>
<td>P24/A12</td>
</tr>
</tbody>
</table>

3-12 In-Circuit Emulation
<table>
<thead>
<tr>
<th>PGA 135 pin #</th>
<th>QFP 100 pin #</th>
<th>Function name</th>
<th>PGA 135 pin #</th>
<th>QFP 100 pin #</th>
<th>Function name</th>
</tr>
</thead>
<tbody>
<tr>
<td>29</td>
<td>52</td>
<td>P27/A15</td>
<td>47</td>
<td></td>
<td>nc</td>
</tr>
<tr>
<td>30</td>
<td>54</td>
<td>P51/A17</td>
<td>48</td>
<td>88</td>
<td>P81/CS3/IRQ1</td>
</tr>
<tr>
<td>31</td>
<td></td>
<td>nc</td>
<td>49</td>
<td>89</td>
<td>P82/CS2/IRQ2</td>
</tr>
<tr>
<td>32</td>
<td>58</td>
<td>P60/WAIT</td>
<td>50</td>
<td>91</td>
<td>P84/CS0</td>
</tr>
<tr>
<td>33</td>
<td>61</td>
<td>ø</td>
<td>51</td>
<td>95</td>
<td>PA2/TP2/TIOCA0/TCLKC</td>
</tr>
<tr>
<td>34</td>
<td>64</td>
<td>NMI</td>
<td>52</td>
<td>97</td>
<td>PA4/TP4/TIOCA1/A23/CS6</td>
</tr>
<tr>
<td>35</td>
<td>65</td>
<td>Vss</td>
<td>53</td>
<td></td>
<td>nc</td>
</tr>
<tr>
<td>36</td>
<td>68</td>
<td>Vcc</td>
<td>54</td>
<td>2</td>
<td>PB0/TP8/TIOCA3</td>
</tr>
<tr>
<td>37</td>
<td></td>
<td>nc</td>
<td>55</td>
<td>5</td>
<td>PB3/TP11/TIOCB4</td>
</tr>
<tr>
<td>38</td>
<td>72</td>
<td>P66/LWR</td>
<td>56</td>
<td>7</td>
<td>PB5/TP13/TOCXB4</td>
</tr>
<tr>
<td>39</td>
<td>75</td>
<td>MD2</td>
<td>57</td>
<td>11</td>
<td>Vss</td>
</tr>
<tr>
<td>40</td>
<td>76</td>
<td>AVcc</td>
<td>58</td>
<td></td>
<td>nc</td>
</tr>
<tr>
<td>41</td>
<td>80</td>
<td>P72/AN2</td>
<td>59</td>
<td></td>
<td>nc</td>
</tr>
<tr>
<td>42</td>
<td>81</td>
<td>P73/AN3</td>
<td>60</td>
<td></td>
<td>nc</td>
</tr>
<tr>
<td>43</td>
<td>84</td>
<td>P76/AN6/DA0</td>
<td>61</td>
<td>12</td>
<td>P90/TxD0</td>
</tr>
<tr>
<td>44</td>
<td></td>
<td>nc</td>
<td>62</td>
<td>15</td>
<td>P93/RxD1</td>
</tr>
<tr>
<td>45</td>
<td>92</td>
<td>Vss</td>
<td>63</td>
<td></td>
<td>nc</td>
</tr>
<tr>
<td>46</td>
<td></td>
<td>nc</td>
<td>64</td>
<td>19</td>
<td>P41/D1</td>
</tr>
</tbody>
</table>

In-Circuit Emulation 3-13
<table>
<thead>
<tr>
<th>PGA 135 pin #</th>
<th>QFP 100 pin #</th>
<th>Function name</th>
<th>PGA 135 pin #</th>
<th>QFP 100 pin #</th>
<th>Function name</th>
</tr>
</thead>
<tbody>
<tr>
<td>65</td>
<td>nc</td>
<td>83</td>
<td>nc</td>
<td></td>
<td></td>
</tr>
<tr>
<td>66</td>
<td>24</td>
<td>P45/D5</td>
<td>84</td>
<td>70</td>
<td>P64/RD</td>
</tr>
<tr>
<td>67</td>
<td>44</td>
<td>Vss</td>
<td>85</td>
<td>73</td>
<td>MD0</td>
</tr>
<tr>
<td>68</td>
<td>28</td>
<td>P31/D9</td>
<td>86</td>
<td>nc</td>
<td></td>
</tr>
<tr>
<td>69</td>
<td>32</td>
<td>P35/D13</td>
<td>87</td>
<td>79</td>
<td>P71/AN1</td>
</tr>
<tr>
<td>70</td>
<td>35</td>
<td>Vcc</td>
<td>88</td>
<td>83</td>
<td>P75/AN5</td>
</tr>
<tr>
<td>71</td>
<td>36</td>
<td>P10/A0</td>
<td>89</td>
<td>86</td>
<td>AVss</td>
</tr>
<tr>
<td>72</td>
<td>38</td>
<td>P12/A2</td>
<td>90</td>
<td>nc</td>
<td></td>
</tr>
<tr>
<td>73</td>
<td>41</td>
<td>P15/A5</td>
<td>91</td>
<td>nc</td>
<td></td>
</tr>
<tr>
<td>74</td>
<td>45</td>
<td>P20/A8</td>
<td>92</td>
<td>87</td>
<td>P80/RFSH/IRQ0</td>
</tr>
<tr>
<td>75</td>
<td>48</td>
<td>P23/A11</td>
<td>93</td>
<td>90</td>
<td>P83/CSI/IRQ3</td>
</tr>
<tr>
<td>76</td>
<td>51</td>
<td>P26/A14</td>
<td>94</td>
<td>93</td>
<td>PA0/TP0/TEND0/TCLKA</td>
</tr>
<tr>
<td>77</td>
<td>nc</td>
<td>95</td>
<td>nc</td>
<td></td>
<td></td>
</tr>
<tr>
<td>78</td>
<td>55</td>
<td>P52/A18</td>
<td>96</td>
<td>99</td>
<td>PA6/TP6/TIOCA2/A21/CS4</td>
</tr>
<tr>
<td>79</td>
<td>nc</td>
<td>97</td>
<td>nc</td>
<td></td>
<td></td>
</tr>
<tr>
<td>80</td>
<td>59</td>
<td>P61/BREQ</td>
<td>98</td>
<td>4</td>
<td>PB2/TP10/TIOCA4</td>
</tr>
<tr>
<td>81</td>
<td>63</td>
<td>RES</td>
<td>99</td>
<td>6</td>
<td>PB4/TP12/TIOCA4</td>
</tr>
<tr>
<td>82</td>
<td>66</td>
<td>EXTLAL</td>
<td>100</td>
<td>9</td>
<td>PB7/TP15/DREQ1/ADTRG</td>
</tr>
</tbody>
</table>

3-14 In-Circuit Emulation
Table 3-2 PGA Pin Assignment (Cont’d)

<table>
<thead>
<tr>
<th>PGA 135 pin #</th>
<th>QFP 100 pin #</th>
<th>Function name</th>
<th>PGA 135 pin #</th>
<th>QFP 100 pin #</th>
<th>Function name</th>
</tr>
</thead>
<tbody>
<tr>
<td>101</td>
<td>nc</td>
<td>119</td>
<td>60</td>
<td>P62/BACK</td>
<td></td>
</tr>
<tr>
<td>102</td>
<td>nc</td>
<td>120</td>
<td>62</td>
<td>STBY</td>
<td></td>
</tr>
<tr>
<td>103</td>
<td>RESO</td>
<td>121</td>
<td>67</td>
<td>XTAL</td>
<td></td>
</tr>
<tr>
<td>104</td>
<td>P91/TxD1</td>
<td>122</td>
<td>69</td>
<td>P63/AS</td>
<td></td>
</tr>
<tr>
<td>105</td>
<td>P94/SCK0/IRQ4</td>
<td>123</td>
<td>71</td>
<td>P65/HWR</td>
<td></td>
</tr>
<tr>
<td>106</td>
<td>Vss</td>
<td>124</td>
<td>74</td>
<td>MD1</td>
<td></td>
</tr>
<tr>
<td>107</td>
<td>P42/D2</td>
<td>125</td>
<td>78</td>
<td>P70/AN0</td>
<td></td>
</tr>
<tr>
<td>108</td>
<td>P44/D4</td>
<td>126</td>
<td>82</td>
<td>P74/AN4</td>
<td></td>
</tr>
<tr>
<td>109</td>
<td>P47/D7</td>
<td>127</td>
<td>85</td>
<td>P77/AN7/DA1</td>
<td></td>
</tr>
<tr>
<td>110</td>
<td>P32/D10</td>
<td>128</td>
<td>nc</td>
<td></td>
<td></td>
</tr>
<tr>
<td>111</td>
<td>nc</td>
<td>129</td>
<td>nc</td>
<td></td>
<td></td>
</tr>
<tr>
<td>112</td>
<td>P13/A3</td>
<td>130</td>
<td>94</td>
<td>PA1/TP1/TEND1/TCLKB</td>
<td></td>
</tr>
<tr>
<td>113</td>
<td>P16/A6</td>
<td>131</td>
<td>96</td>
<td>PA3/TP3/TIOCB0/TCLKD</td>
<td></td>
</tr>
<tr>
<td>114</td>
<td>P21/A9</td>
<td>132</td>
<td>100</td>
<td>PA7/TP7/TIOCB2/A20</td>
<td></td>
</tr>
<tr>
<td>115</td>
<td>P25/A13</td>
<td>133</td>
<td>nc</td>
<td></td>
<td></td>
</tr>
<tr>
<td>116</td>
<td>P50/A16</td>
<td>134</td>
<td>47</td>
<td>P22/A10</td>
<td></td>
</tr>
<tr>
<td>117</td>
<td>nc</td>
<td>135</td>
<td>77</td>
<td>Vref</td>
<td></td>
</tr>
<tr>
<td>118</td>
<td>P53/A19</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td></td>
</tr>
</tbody>
</table>
Figure 3-5 PGA Adaptor Pin Assignment
Configuring the Emulator

Introduction

Your H8/3048 emulator can be used in all stages of target system development. For instance, you can run the emulator out-of-circuit when developing your target system software, or you can use the emulator in-circuit when integrating software with target system hardware.

You can use the emulator’s internal clock or the target system clock. Emulation memory can be used in place of, or along with, target system memory.

You can execute target programs in real-time or allow emulator execution to be diverted into the monitor when commands request access of target system resources (target system memory, register contents, etc).

The emulator is a flexible instrument and may be configured to suit your needs at any stage of the development process. This chapter describes the options available when configuring the H8/3048 emulator.

The configuration options are accessed with the following command.

```
modify configuration <RETURN>
```

After entering the command above, you will be asked questions regarding the emulator configuration. The configuration questions are listed below and grouped into the following classes.
General Emulator Configuration:

- Specifying the emulator clock source (internal/external).
- Selecting monitor entry after configuration.
- Restricting to real-time execution.
- Selecting the microprocessor to be emulated.
- Selecting the microprocessor operation mode.

Memory Configuration:

- Mapping memory.

Emulator Pod Configuration:

- Enabling emulator bus arbitration.
- Enabling NMI input from the target system.
- Enabling reset input from the target system.
- Allowing the emulator to drive background cycles to the target systems.
- Setting up the reset value for the stack pointer.
- Selecting target memory access size.

Debug/Trace Configuration:

- Enabling breaks on writes to ROM.
- Specifying tracing of foreground/background cycles.
- Enabling tracing internal DMA cycles.
- Enabling tracing refresh cycles.
Simulated I/O Configuration: Simulated I/O is described in the Simulated I/O reference manual.

Interactive Measurement Configuration: See the chapter on coordinated measurements in the Softkey Interface Reference manual.

External Analyzer Configuration: See the Analyzer Softkey Interface User’s Guide.

General Emulator Configuration

The configuration questions described in this section involve general emulator operation.

Micro-processor clock source? This configuration question allows you to select whether the emulator will be clocked by the internal clock source or by a target system clock source.

- **internal**: Selects the internal crystal oscillator as the emulator clock source. Internal crystal oscillator is 8MHz.
- **external**: Selects the clock input to the emulation probe from the target system. You must use a clock input conforming to the specifications of Table 4-1.
<table>
<thead>
<tr>
<th>Emulation Memory</th>
<th>Clock Speed</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>With HP64784D</td>
</tr>
<tr>
<td>64726A, 64727A, 64728A</td>
<td>From 1 up to 16MHz (System Clock)</td>
</tr>
<tr>
<td>64729A</td>
<td>From 1 up to 18MHz (System Clock)</td>
</tr>
</tbody>
</table>

**Note**

Internal crystal oscillator frequency is 8MHz.

**Note**

Changing the clock source drives the emulator into the reset state. The emulator may later break into the monitor depending on how the following "Enter monitor after configuration?" question is answered.

---

4-4 Configuring the Emulator
Enter monitor after configuration?

This question allows you to select whether the emulator will be running in the monitor or held in the reset state upon completion of the emulator configuration.

How you answer this configuration question is important in some situations. For example, when the external clock has been selected and the target system is turned off, reset to monitor should not be selected; otherwise, configuration will fail.

When an external clock source is specified, this question becomes "Enter monitor after configuration (using external clock)?" and the default answer becomes "no".

**yes**

When reset to monitor is selected, the emulator will be running in the monitor after configuration is complete. If the reset to monitor fails, the previous configuration will be restored.

**no**

After the configuration is complete, the emulator will be held in the reset state.

Restrict to real-time runs?

The "restrict to real-time" question lets you configure the emulator so that commands which cause the emulator to break to monitor and return to the user program are refused.

**no**

All commands, regardless of whether or not they require a break to the emulation monitor, are accepted by the emulator.

**yes**

When runs are restricted to real-time and the emulator is running the user program, all commands that cause a break (except "reset", "break", "run", and "step") are refused. For example, the following commands are not allowed when runs are restricted to real-time:

- Display/modify registers.
- Display/modify internal I/O registers.
- Display/modify target system memory.
- Load/store target system memory.

Configuring the Emulator 4-5
Caution  🟢

If your target system circuitry is dependent on constant execution of program code, you should restrict the emulator to real-time runs. This will help insure that target system damage does not occur. However, remember that you can still execute the "reset", "break", and "step" commands; you should use caution in executing these commands.

Processor type?

This configuration defines the microprocessor type to be emulated.

3044 When you are going to emulate H8/3044 microprocessor, select this item.

3047 When you are going to emulate H8/3047 microprocessor, select this item.

3048 When you are going to emulate H8/3048 microprocessor, select this item.

3048f When you are going to emulate H8/3048F microprocessor, select this item.

Note  🟢

Configuring this item will drive the emulator into the reset state.

4-6 Configuring the Emulator
Source for processor operation mode?

This configuration defines operation mode in which the emulator works.

<table>
<thead>
<tr>
<th>Operation mode</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>internal</strong></td>
<td>The emulator will work in selected operation mode regardless the setting by the target system.</td>
</tr>
</tbody>
</table>

| mode_1         | The emulator will operate in mode 1. (expanded 1M bytes mode without internal ROM: 8 bit data bus) |
| mode_2         | The emulator will operate in mode 2. (expanded 1M bytes mode without internal ROM: 16 bit data bus) |
| mode_3         | The emulator will operate in mode 3. (expanded 16M bytes mode without internal ROM: 8 bit data bus) |
| mode_4         | The emulator will operate in mode 4. (expanded 16M bytes mode without internal ROM: 16 bit data bus) |
| mode_5         | The emulator will operate in mode 5. (expanded 1M bytes mode with internal ROM: 8 bit data bus) |
| mode_6         | The emulator will operate in mode 6. (expanded 16M bytes mode with internal ROM: 8 bit data bus) |
| mode_7         | The emulator will operate in mode 7. (single chip advanced mode) |
The emulator will work using the mode setting by the target system. The target system must supply appropriate input to MD0, MD1 and MD2.

**Note**
It is recommended to configure this item as internal mode and select operation mode, since the emulator dose not work fine when MD0, MD1 and MD2 are not steady.

**Note**
Configuring this item will drive the emulator into the reset state.
Memory Configuration

The memory configuration questions allow you to select the monitor type and to map memory. To access the memory configuration questions, you must answer "yes" to the following question.

Modify memory configuration?

Mapping Memory

The H8/3048 emulator contains high-speed emulation memory (no wait states required) that can be mapped at a resolution of 512 bytes.

The memory mapper allows you to characterize memory locations. It allows you specify whether a certain range of memory is present in the target system or whether you will be using emulation memory for that address range. You can also specify whether the target system memory is ROM or RAM, and you can specify that emulation memory be treated as ROM or RAM.

The memory mapper allows you to define up to 16 different map terms.

Note
Direct memory access to emulation memory using external DMAC are not allowed.

Note
The default emulator configuration maps location 0 hex through FFFF hex as emulation ROM.

Note
When you use internal ROM/on-chip flash memory area, you must map that area as emulation memory. If you don’t map internal ROM properly, you cannot access that area.
You don’t have to map internal RAM as emulation RAM, since the H8/3048 emulator automatically maps internal RAM as emulation RAM and this area is behaved like internal RAM. However, emulation memory system does not introduce internal RAM area in memory mapping display.

If you map internal RAM area as emulation memory, this area is behaved like external memory overlapped with internal RAM and the H8/3048 emulator is always accessed internal RAM area mapped by the emulator. And if you map internal RAM as guarded memory, the emulator prohibits to access to this area by display/modify memory commands.

Blocks of memory can also be characterized as guarded memory. Guarded memory accesses will generate "break to monitor" requests. Writes to ROM will generate "break to monitor" requests if the "Enable breaks on writes to ROM?" configuration item is enabled (see the "Debug/Trace Configuration" section which follows).

For example, you might be developing a system with the following characteristics:

- input port at 0f000 hex
- output port at 0f100 hex
- program and data from 1000 through 2fff hex

Suppose that the only thing that exists in your target system at this time are input and output ports and some control logic; no memory is available. You can reflect this by mapping the I/O ports to target system memory space and the rest of memory to emulation memory space.
When mapping memory for your target system programs, you may wish to characterize emulation memory locations containing programs and constants (locations which should not be written to) as ROM. This will prevent programs and constants from being written over accidentally, and will cause breaks when instructions attempt to do so.

---

**Note**

You should map all memory ranges used by your programs **before** loading programs into memory. This helps safeguard against loads which accidentally overwrite earlier loads if you follow a [map/load](#) procedure for each memory range.

---

**Note**

Configuring memory mapping will drive the emulator into the reset state.
Emulator Pod Configuration

To access the emulator pod configuration questions, you must answer "yes" to the following question.

Modify emulator pod configuration?

Enable bus arbitration?

The bus arbitration configuration question defines how your emulator responds to bus request signals from the target system during both foreground and background operation.

**yes**
When bus arbitration is enabled, the /BREQ (bus request) signal from the target system is responded to exactly as it would be if only the emulation processor was present without an emulator. In other words, if the emulation processor receives a /BREQ from the target system, it will respond by asserting /BACK and will set the various processor lines to tri-state. /BREQ is then released by the target; /BACK is negated by the processor, and the emulation processor restarts execution.

**Note**
You cannot perform DMA (direct memory access) transfers between your target system and emulation memory by using external DMA controller on your target system; the H8/3048 emulator does not support such a feature.

**no**
When you disable bus arbitration, the emulator ignores the /BREQ signal from the target system. The emulation processor will never drive the /BACK line true; nor will it place the address, data and control signals into the tri-state mode.

4-12 Configuring the Emulator
Enabling and disabling bus master arbitration can be useful to you in isolating target system problems. For example, you may have a situation where the processor never seems to execute any code. You can disable bus arbitration to check and see if faulty arbitration circuitry in your target system is contributing to the problem.

---

**Note**

This question does not appear when you select mode_7.

---

**Note**

The commands which cause the emulator to break to monitor are ignored during the processor releases bus cycles.

---

**Note**

Configuring this item will drive the emulator into the reset state.

---

**Enable NMI input from target system?**

This configuration allows you to specify whether or not the emulator responds to NMI (non-maskable interrupt request) signal from the target system during foreground operation.

**yes**

The emulator will respond to the NMI request from the target system.

**Caution**

While the emulator is executing the boot program of H8/3048F, the NMI must not occur. Because the emulator cannot prohibit the NMI at this time.

**no**

The emulator will not respond to the NMI request from the target system.
The emulator does not accept any interrupt while in background monitor. Such interrupts are suspended while running the background monitor, and they will occur when context is changed to foreground.

---

Note

Configuring this item will drive the emulator into the reset state.

---

Enable reset input from target system?

This configuration allows you to specify whether or not the emulator responds to /RES and /STBY signals from the target system during foreground operation.

While running the background monitor, the emulator ignores such signals except that the emulator’s status is "Awaiting target reset" (see the "Running the Emulation from Target Reset" section in the "In-Circuit Emulation" chapter).

**yes**

The emulator will respond to /RES and /STBY inputs during foreground operation.

**no**

The emulator will not respond to /RES and /STBY inputs from the target system.

---

Note

The H8/3048 emulator does not support hardware standby mode, and /STBY input will be given the emulator /RES input.

---

Note

Configuring this item will drive the emulator into the reset state.

---

4-14 Configuring the Emulator
**Drive background cycles to the target system?**

This configuration allows you specify whether or not the emulator will drive the target system bus on background cycles.

<table>
<thead>
<tr>
<th>Setting</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>no</strong></td>
<td>Only emulation processor’s address cycles are driven to the target system during background monitor.</td>
</tr>
<tr>
<td><strong>yes</strong></td>
<td>Specifies that background cycles are driven to the target system. Emulation processor’s address and control strobes (except /HWR and /LWR) are driven during background cycles. Background write cycles won’t appear to the target system.</td>
</tr>
</tbody>
</table>

---

**Note**

Refresh cycles, internal DMA cycles and target memory accesses are always driven to the target system regardless of this configuration.

---

**Note**

If you specify that the emulator will not drive background cycles to the target system, the emulator can’t respond to /WAIT signal during background monitor.

---

**Note**

This question does not appear when you select mode_7.

---

**Note**

Configuring this item will drive the emulator into the reset state.
**Reset value for stack pointer?**

This configuration allows you to specify a value to which the stack pointer will be set upon the transition from emulation reset into the emulation monitor.

The address specified in response to this question must be a 32-bit hexadecimal even address outside internal I/O register area. Default value of stack pointer is fffffff10 hex.

---

**Note**

Without a stack pointer, the emulator is unable to make the transition to the run state, step, or perform many other emulation functions. However, using this option does not preclude you from changing the stack pointer value or location within your program; it just sets the initial conditions to allow a run to begin.

---

**Target memory access size?**

This configuration allows you to specify the types of cycles that the emulation monitor uses when accessing target system memory.

- **any**
  - Access size is depends upon a display/modify target memory command option. If option "long" is specified, access size is will be set to "words". Other target memory commands such as "load" and "store" will use as access size of "bytes".

- **bytes**
  - Specify that the emulator will access target system memory by byte access.

- **words**
  - Specify that the emulator will access target system memory by word access.
When the access size is **words**, modifying target memory will fail if you try to modify memory from an odd address or with data which byte count is odd. Also, you can’t load file which byte count is odd. Therefore, it is recommended to use the emulator with the default **any** or **bytes** in this configuration.

---

### Debug/Trace Configuration

The debug/trace configuration questions allows you to specify breaks on writes to ROM, and specify that the analyzer trace foreground/background execution, and bus release cycles. To access the trace/debug configuration questions, you must answer “yes” to the following question.

**Modify debug/trace options?**

This question allows you to specify that the emulator break to the monitor upon attempts to write to memory space mapped as ROM.

**Break processor on write to ROM?**

- **yes**: Causes the emulator to break into the emulation monitor whenever the user program attempts to write to a memory region mapped as ROM.

- **no**: The emulator will not break to the monitor upon a write to ROM. The emulator will not modify the memory location if it is in emulation ROM.
The `wrrom` trace command status options allow you to use "write to ROM" cycles as trigger and storage qualifiers. For example, you could use the following command to trace about a write to ROM:

```
trace about status wrrom <RETURN>
```

If the emulator writes to the memory mapped as ROM or guarded area in internal DMA cycles, the emulator will not break to the monitor regardless of this configuration.

This question allows you to specify whether the analyzer traces only foreground emulation processor cycles, only background cycles, or both foreground and background cycles. When background cycles are stored in the trace, all mnemonic lines are tagged as background cycles.

- **foreground**
  - Specifies that the analyzer traces only foreground cycles. This option is specified by the default emulator configuration.

- **background**
  - Specifies that the analyzer traces only background cycles. (This is rarely a useful setting.)

- **both**
  - Specifies that the analyzer traces both foreground and background cycles.

This question allows you to specify whether or not the emulator traces internal DMAC cycles.

- **yes**
  - Specifies that the analyzer traces internal DMAC cycles.

- **no**
  - Specifies that the analyzer does not trace internal DMAC cycles.
Note

Some internal DMA cycles may be traced regardless of this configuration in order to disassemble the trace list correctly.

Trace refresh cycles?

This configuration allows you to specify whether or not the emulator traces refresh cycles.

<p>| | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>yes</td>
<td>Specifies that the analyzer traces refresh cycles.</td>
</tr>
<tr>
<td>no</td>
<td>Specifies that the analyzer does not trace refresh cycles.</td>
</tr>
</tbody>
</table>

Note

Some refresh cycles may be traced regardless of this configuration in order to disassemble the trace list correctly.

Note

This configuration does not appear when you select mode_7.

Simulated I/O Configuration

The simulated I/O feature and configuration options are described in the Simulated I/O reference manual.
## Interactive Measurement Configuration

The interactive measurement configuration questions are described in the chapter on coordinated measurements in the *Softkey Interface Reference* manual. Examples of coordinated measurements that can be performed between the emulator and the emulation analyzer are found in the "Using the Emulator" chapter.

## External Analyzer Configuration

The external analyzer configuration options are described in the *Analyzer Softkey Interface User's Guide*.

## Saving a Configuration

The last configuration question allows you to save the previous configuration specifications in a file which can be loaded back into the emulator at a later time.

**Configuration file name? <FILE>**

The name of the last configuration file is shown, or no filename is shown if you are modifying the default emulator configuration.

If you press <RETURN> without specifying a filename, the configuration is saved to a temporary file. This file is deleted when you exit the Softkey Interface with the "end release_system" command.

When you specify a filename, the configuration will be saved to two files; the filename specified with extensions of ".EA" and ".EB". The file with the ".EA" extension is the "source" copy of the file, and the file with the ".EB" extension is the "binary" or loadable copy of the file.

Ending out of emulation (with the "end" command) saves the current configuration, including the name of the most recently loaded configuration file, into a "continue" file. The continue file is not normally accessed.
Loading a Configuration

Configuration files which have been previously saved may be loaded with the following Softkey Interface command.

```
load configuration <FILE> <RETURN>
```

This feature is especially useful after you have exited the Softkey Interface with the "end release_system" command; it saves you from having to modify the default configuration and answer all the questions again.

To reload the current configuration, you can enter the following command.

```
load configuration <RETURN>
```
4-22 Configuring the Emulator
Using the Emulator

Introduction

In the "Getting Started" chapter, you learned how to load code into the emulator, how to modify memory and view a register, and how to perform a simple analyzer measurement. In this chapter, we will discuss in more detail other features of the emulator.

This chapter discusses:

- Features available via "pod_command".
- Register classes and names.
- Debugging C Programs
- Accessing target system devices using E clock synchronous instruction.

This chapter shows you how to:

- Store the contents of memory into absolute files.
- Make coordinated measurements.
- Use a command file.
Features Available via Pod Commands

Several emulation features available in the Terminal Interface but not in the Softkey Interface may be accessed via the following emulation commands.

```
display pod_command <RETURN>
pod_command '<Terminal Interface command>' <RETURN>
```

Some of the most notable Terminal Interface features not available in the softkey Interface are:

- Copying memory.
- Searching memory for strings or numeric expressions.
- Performing coverage analysis.

Refer to your Terminal Interface documentation for information on how to perform these tasks.

Note

Be careful when using the "pod_command". The Softkey Interface, and the configuration files in particular, assume that the configuration of the HP 64700 pod is NOT changed except by the Softkey Interface. Be aware that what you see in "modify configuration" will NOT reflect the HP 64700 pod’s configuration if you change the pod’s configuration with this command. Also, commands which affect the communications channel should NOT be used at all. Other commands may confuse the protocol depending upon how they are used. The following commands are not recommended for use with "pod_command":

- **stty, po, xp** - Do not use, will change channel operation and hang.
- **echo, mac** - Usage may confuse the protocol in use on the channel.
- **wait** - Do not use, will tie up the pod, blocking access. **init, pv** - Will reset pod and force end release_system. **t** - Do not use, will confuse trace status polling and unload.

5-2 Using the Emulator
Using a Command File

You can use a command file to perform many functions for you, without having to manually type each function. For example, you might want to create a command file that loads configuration, loads program into memory and displays memory.

To create such a command file, type "log" and press TAB key. You will see a command line "log_commands" appears in the command field. Next, select "to" in the softkey label, and enter the command file name "sample.cmd". This sets up a file to record all commands you execute. The commands will be logged to the file sample.cmd in the current directory. You can use this file as a command file to execute these commands automatically.

Suppose that your configuration file and program are named "cmd_rds". To load configuration:

```
load configuration cmd_rds <RETURN>
```

To load the program into memory:

```
load cmd_rds <RETURN>
```

To display memory 1000 hex through 1020 hex in mnemonic format:

```
display memory 1000h thru 1020h mnemonic
```

Now, to disable logging, type "log" and press TAB key, select "off", and press Enter. The command file you created looks like this:

```
load configuration cmd_rds
load cmd_rds
display memory 1000h thru 1020h mnemonic
```

If you would like to modify the command file, you can use any text editor on your host computer.

To execute this command file, type "sample.cmd", and press Enter.
Debugging C Programs

Softkey Interface has following functions to debug C programs.

- Including C source lines in memory mnemonic display
- Including C source lines in trace listing
- Stepping C sources

The following section describes such features.

Displaying Memory with C Sources

You can display memory in mnemonic format with C source lines. For example, to display memory in mnemonic format from address `main` with source lines, enter the following commands.

```
display memory main mnemonic <RETURN>
set source on <RETURN>
```

You can display source lines highlighted with the following command.

```
set source on inverse_video on <RETURN>
```

To display only source lines, use the following command.

```
set source only <RETURN>
```

Specifying Address with Line Numbers

You can specify addresses with line numbers of C source program. For example, to set a breakpoint to line 20 of "main.c" program, enter the following command.

```
modify software_breakpoints set main.c: line 20 <RETURN>
```

Displaying Trace with C Sources

You can include C source information in trace listing. You can use the same command as the case of memory display. For example, to display trace listing with source lines highlighted, enter the following command.

```
display trace <RETURN>
set source on inverse_video on <RETURN>
```

Stepping C Sources

You can direct the emulator to execute a line or a number of lines at a time. For example, to step one line from address `main`, enter the following command.

5-4 Using the Emulator
To step 1 line from the current line, enter the following command.

```
step source from main <RETURN>
```

You can specify the number of lines to be executed. To step 5 lines from the current line, enter the following command.

```
step 5 source <RETURN>
```

---

**Storing Memory Contents to an Absolute File**

The "Getting Started" chapter shows you how to load absolute files into emulation or target system memory. You can also store emulation or target system memory to an absolute file with the following command.

```
store memory 1000h thru 1042h to absfile <RETURN>
```

The command above causes the contents of memory locations 1000 hex through 1042 hex to be stored in the absolute file "absfile.X". Notice that the ".X" extension is appended to the specified filename.

---

**Coordinated Measurements**

For information on coordinated measurements and how to use them, refer to the "Coordinated Measurements" chapter in the *Softkey Interface Reference* manual.
Register Classes and Names

Summary

H8/3048 register designators. All available register class names and register names are listed below.

<table>
<thead>
<tr>
<th>&lt;REG_CLASS&gt;</th>
<th>&lt;REG_NAME&gt;</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>BASIC</td>
<td>PC</td>
<td>Program counter</td>
</tr>
<tr>
<td></td>
<td>CCR</td>
<td>Condition code register</td>
</tr>
<tr>
<td></td>
<td>ER0</td>
<td>Register ER0</td>
</tr>
<tr>
<td></td>
<td>ER1</td>
<td>Register ER1</td>
</tr>
<tr>
<td></td>
<td>ER2</td>
<td>Register ER2</td>
</tr>
<tr>
<td></td>
<td>ER3</td>
<td>Register ER3</td>
</tr>
<tr>
<td></td>
<td>ER4</td>
<td>Register ER4</td>
</tr>
<tr>
<td></td>
<td>ER5</td>
<td>Register ER5</td>
</tr>
<tr>
<td></td>
<td>ER6</td>
<td>Register ER6</td>
</tr>
<tr>
<td></td>
<td>ER7</td>
<td>Register ER7</td>
</tr>
<tr>
<td></td>
<td>SP</td>
<td>Stack pointer</td>
</tr>
<tr>
<td></td>
<td>MDCR</td>
<td>Mode control register (Read Only)</td>
</tr>
</tbody>
</table>

5-6 Using the Emulator
### SYS (System control)

<table>
<thead>
<tr>
<th>Register</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>MDCR</td>
<td>Mode control register (Read Only)</td>
</tr>
<tr>
<td>SYSCR</td>
<td>System control register</td>
</tr>
<tr>
<td>DASTCR</td>
<td>D/A standby control register</td>
</tr>
<tr>
<td>DIVCR</td>
<td>Clock divider control register</td>
</tr>
<tr>
<td>MSTCR</td>
<td>Module standby control register</td>
</tr>
<tr>
<td>CSCR</td>
<td>Chip select control register</td>
</tr>
</tbody>
</table>

**Note**

Even if PSTOP bit of the MSTCR register is set to 1, the emulator can not stop the Ø clock output.

### INTC (Interrupt controller)

<table>
<thead>
<tr>
<th>Register</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>ISCR</td>
<td>IRQ sense control register</td>
</tr>
<tr>
<td>IER</td>
<td>IRQ enable register</td>
</tr>
<tr>
<td>ISR</td>
<td>IRQ status register</td>
</tr>
<tr>
<td>IPRA</td>
<td>Interrupt priority register A</td>
</tr>
<tr>
<td>IPRB</td>
<td>Interrupt priority register B</td>
</tr>
</tbody>
</table>

### BUSC (Bus controller)

<table>
<thead>
<tr>
<th>Register</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>ABWCR</td>
<td>Byte/Word area control register</td>
</tr>
<tr>
<td>ASTCR</td>
<td>2/3 state area control register</td>
</tr>
<tr>
<td>WCR</td>
<td>Wait control register</td>
</tr>
<tr>
<td>WCER</td>
<td>Wait controller enable register</td>
</tr>
<tr>
<td>BRCR</td>
<td>Bus release control register</td>
</tr>
</tbody>
</table>

### RFSHC (Refresh controller)

<table>
<thead>
<tr>
<th>Register</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>RFSHCR</td>
<td>Refresh control register</td>
</tr>
<tr>
<td>RTMSCR</td>
<td>Refresh timer control/status register</td>
</tr>
<tr>
<td>RTCNT</td>
<td>Refresh timer counter</td>
</tr>
<tr>
<td>RTCOR</td>
<td>Refresh time constant register</td>
</tr>
</tbody>
</table>

*Using the Emulator 5-7*
DMAC0 (DMA controller 0)

- MAR0A: Memory address register 0A
- ETCR0A: Transfer count register 0A
- IOAR0A: I/O address register 0A
- DTCR0A: Data transfer control register 0A
- MAR0B: Memory address register 0B
- ETCR0B: Transfer count register 0B
- IOAR0B: I/O address register 0B
- DTCR0B: Data transfer control register 0B

DMAC1 (DMA controller 1)

- MAR1A: Memory address register 1A
- ETCR1A: Transfer count register 1A
- IOAR1A: I/O address register 1A
- DTCR1A: Data transfer control register 1A
- MAR1B: Memory address register 1B
- ETCR1B: Transfer count register 1B
- IOAR1B: I/O address register 1B
- DTCR1B: Data transfer control register 1B

5-8 Using the Emulator
### PORT (I/O port)

<table>
<thead>
<tr>
<th>Register</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>P1DDR</td>
<td>Port 1 data direction register (Write Only)</td>
</tr>
<tr>
<td>P2DDR</td>
<td>Port 2 data direction register (Write Only)</td>
</tr>
<tr>
<td>P3DDR</td>
<td>Port 3 data direction register (Write Only)</td>
</tr>
<tr>
<td>P4DDR</td>
<td>Port 4 data direction register (Write Only)</td>
</tr>
<tr>
<td>P5DDR</td>
<td>Port 5 data direction register (Write Only)</td>
</tr>
<tr>
<td>P6DDR</td>
<td>Port 6 data direction register (Write Only)</td>
</tr>
<tr>
<td>8DDR</td>
<td>Port 8 data direction register (Write Only)</td>
</tr>
<tr>
<td>9DDR</td>
<td>Port 9 data direction register (Write Only)</td>
</tr>
<tr>
<td>ADDR</td>
<td>Port A data direction register (Write Only)</td>
</tr>
<tr>
<td>BDDR</td>
<td>Port B data direction register (Write Only)</td>
</tr>
<tr>
<td>P1DR</td>
<td>Port 1 data register</td>
</tr>
<tr>
<td>P2DR</td>
<td>Port 2 data register</td>
</tr>
<tr>
<td>P3DR</td>
<td>Port 3 data register</td>
</tr>
<tr>
<td>P4DR</td>
<td>Port 4 data register</td>
</tr>
<tr>
<td>P5DR</td>
<td>Port 5 data register</td>
</tr>
<tr>
<td>P6DR</td>
<td>Port 6 data register</td>
</tr>
<tr>
<td>P7DR</td>
<td>Port 7 data register (Read Only)</td>
</tr>
<tr>
<td>P8DR</td>
<td>Port 8 data register</td>
</tr>
<tr>
<td>P9DR</td>
<td>Port 9 data register</td>
</tr>
<tr>
<td>PADR</td>
<td>Port A data register</td>
</tr>
<tr>
<td>PBDR</td>
<td>Port B data register</td>
</tr>
<tr>
<td>P2PCR</td>
<td>Port 2 input pull up MOS control register</td>
</tr>
<tr>
<td>P4PCR</td>
<td>Port 4 input pull up MOS control register</td>
</tr>
<tr>
<td>P5PCR</td>
<td>Port 5 input pull up MOS control register</td>
</tr>
</tbody>
</table>

**Note**

The emulator cannot support input pull up MOS control function of the P2PCR, P4PCR, and P5PCR.
ITUG (16 bit integrated timer pulse unit general)

TSTR  Timer start register
TSNC  Timer synchro register
TMDR  Timer mode register
TFCR  Timer function control register
TOER  Timer output master control register
TOCR  Timer output control register

ITU0 (16 bit integrated timer pulse unit 0)

TCR0  Timer control register 0
TIOR0 Timer I/O control register 0
TIER0 Timer interrupt enable register 0
TSR0  Timer status register 0
TCNT0 Timer counter 0
GRA0  General register A0
GRB0  General register B0

ITU1 (16 bit integrated timer pulse unit 1)

TCR1  Timer control register 1
TIOR1 Timer I/O control register 1
TIER1 Timer interrupt enable register 1
TSR1  Timer status register 1
TCNT1 Timer counter 1
GRA1  General register A1
GRB1  General register B1

ITU2 (16 bit integrated timer pulse unit 2)

TCR2  Timer control register 2
TIOR2 Timer I/O control register 2
TIER2 Timer interrupt enable register 2
TSR2  Timer status register 2
TCNT2 Timer counter 2
GRA2  General register A2
GRB2  General register B2

5-10 Using the Emulator
ITU3 (16 bit integrated timer pulse unit 3)

TCR3  Timer control register 3
TIOR3 Timer I/O control register 3
TIER3 Timer interrupt enable register 3
TSR3  Timer status register 3
TCNT3 Timer counter 3
GRA3  General register A3
GRB3  General register B3
BRA3  Buffer register A3
BRB3  Buffer register B3

ITU4 (16 bit integrated timer pulse unit 4)

TCR4  Timer control register 4
TIOR4 Timer I/O control register 4
TIER4 Timer interrupt enable register 4
TSR4  Timer status register 4
TCNT4 Timer counter 4
GRA4  General register A4
GRB4  General register B4
BRA4  Buffer register A4
BRB4  Buffer register B4

TPC (Programable timing pattern controller)

TPMR  TPC output mode register
TPCR  TPC output control register
NDER  Next data enable register
NDRA  Next data register A (address: 0xffa5h)
NDRA0 Next data register A (address: 0xffa7h)
NDRB  Next data register B (address: 0xffa4h)
NDRB2 Next data register B (address: 0xffa6h)

WDT (Watch dog timer)

WDTCSR Timer control/status register
WDTCNT Timer counter
RSTCSR Reset control/status register
sci0 (Serial communication interface 0)

SMR0 Serial mode register 0  
BRR0 Bit rate register 0  
SCR0 Serial control register 0  
TDR0 Transmit data register 0  
SSR0 Serial status register 0  
RDR0 Receive data register 0 (Read Only)  
SCMR0 Smart card mode register 0

SCII1 (Serial communication interface 1)

SMR1 Serial mode register 1  
BRR1 Bit rate register 1  
SCR1 Serial control register 1  
TDR1 Transmit data register 1  
SSR1 Serial status register 1  
RDR1 Receive data register 1 (Read Only)  
SCMR1

ADC (A/D converter)

ADDRA A/D data register A (Read Only)  
ADDRB A/D data register B (Read Only)  
ADDRC A/D data register C (Read Only)  
ADDRD A/D data register D (Read Only)  
ADCSR A/D control/status register  
ADCR A/D control register

DAC (D/A converter)

DADR0 D/A data register 0  
DADR1 D/A data register 1  
DACR D/A control register

5-12 Using the Emulator
## FLASH (flash memory)

<table>
<thead>
<tr>
<th>Register</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>FLMCR</td>
<td>Flash memory control register</td>
</tr>
<tr>
<td>EBR1</td>
<td>Erase block appoint register 1</td>
</tr>
<tr>
<td>EBR2</td>
<td>Erase block appoint register 2</td>
</tr>
<tr>
<td>RAMCR</td>
<td>RAM control register</td>
</tr>
</tbody>
</table>

---

**Note**

These registers cannot control the flash memory. But the emulator can display or modify these registers except for the RAMCR register. The RAMCR register is always FF'H.
The following register names are not included in any register class.

<table>
<thead>
<tr>
<th>Register</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>R0</td>
<td>Register R0</td>
</tr>
<tr>
<td>R1</td>
<td>Register R1</td>
</tr>
<tr>
<td>R2</td>
<td>Register R2</td>
</tr>
<tr>
<td>R3</td>
<td>Register R3</td>
</tr>
<tr>
<td>R4</td>
<td>Register R4</td>
</tr>
<tr>
<td>R5</td>
<td>Register R5</td>
</tr>
<tr>
<td>R6</td>
<td>Register R6</td>
</tr>
<tr>
<td>R7</td>
<td>Register R7</td>
</tr>
<tr>
<td>E0</td>
<td>Register E0</td>
</tr>
<tr>
<td>E1</td>
<td>Register E1</td>
</tr>
<tr>
<td>E2</td>
<td>Register E2</td>
</tr>
<tr>
<td>E3</td>
<td>Register E3</td>
</tr>
<tr>
<td>E4</td>
<td>Register E4</td>
</tr>
<tr>
<td>E5</td>
<td>Register E5</td>
</tr>
<tr>
<td>E6</td>
<td>Register E6</td>
</tr>
<tr>
<td>E7</td>
<td>Register E7</td>
</tr>
<tr>
<td>R0H</td>
<td>Register R0H</td>
</tr>
<tr>
<td>R0L</td>
<td>Register R0L</td>
</tr>
<tr>
<td>R1H</td>
<td>Register R1H</td>
</tr>
<tr>
<td>R1L</td>
<td>Register R1L</td>
</tr>
<tr>
<td>R2H</td>
<td>Register R2H</td>
</tr>
<tr>
<td>R2L</td>
<td>Register R2L</td>
</tr>
<tr>
<td>R3H</td>
<td>Register R3H</td>
</tr>
<tr>
<td>R3L</td>
<td>Register R3L</td>
</tr>
<tr>
<td>R4H</td>
<td>Register R4H</td>
</tr>
<tr>
<td>R4L</td>
<td>Register R4L</td>
</tr>
<tr>
<td>R5H</td>
<td>Register R5H</td>
</tr>
<tr>
<td>R5L</td>
<td>Register R5L</td>
</tr>
<tr>
<td>R6H</td>
<td>Register R6H</td>
</tr>
<tr>
<td>R6L</td>
<td>Register R6L</td>
</tr>
<tr>
<td>R7H</td>
<td>Register R7H</td>
</tr>
<tr>
<td>R7L</td>
<td>Register R7L</td>
</tr>
</tbody>
</table>
Using the On-chip Flash Memory

Introduction

The H8/3048 emulator is equipped with functions for the on-chip flash memory of H8/3048F microprocessor. So you can direct the on-chip flash memory using the H8/3048 emulator.

The following pages will describe differences between actual on-chip flash memory and the H8/3048 emulator. You need to pay attention for following contents.

Memory Mapping

The H8/3048 emulator uses emulation memory instead of actual on-chip flash memory of the H8/3048F microprocessor. So you need to map this area as emulation ROM in the emulator configuration before using the H8/3048 emulator. And also, you need to configure the H8/3048 emulator as H8/3048F and mode 5/6/7 in the emulator configuration to use flash memory functions.

Note

When you use the on-chip flash memory on the H8/3048 emulator, you must map that area as emulation ROM. When you power on the emulator, all memory space except internal RAM is mapped as target RAM. Therefore, if you don’t map this area properly, you can not use the flash memory functions.
Flash Memory Registers

You don’t need to take care of FLMCR, EBR1, EBR2 and RAMCR registers, since the H8/3048 emulator uses emulation memory instead of actual on-chip flash memory and does not use these registers.

Note

You cannot direct these registers to control the flash memory functions. These registers are not effective for the on-chip flash memory operation on the H8/3048 emulator.

Note

The H8/3048 emulator can display or modify these registers except for the RAMCR register. RAMCR is always FF'H.

Note

You cannot do flash memory emulation by RAM using RAMCR register.

Programming/Erasing Flash Memory

Programming Data

To write data onto the on-chip flash memory, you need to supply 12V to Vpp/RESO pin. When you supply 12V correctly, write to ROM break does not occur even if write to ROM break is enabled in the emulator configuration.

6-2 Using On-chip Flash Memory
You need only to write data to the destination address only once. The H8/3048 emulator can program data correctly and therefore it is not necessary to repeat writing unless you prefer.

---

**Note**  
If you don’t supply 12V to Vpp/RESO pin correctly, the H8/3048 emulator does not write data to destination address. And if write to ROM break is enabled in the emulator configuration, write to ROM break will occur when you write date onto on-chip flash memory.

---

**Erasing Data**  
To erase data onto the on-chip flash memory, you need to supply 12V to Vpp/RESO pin.

You cannot use FLMCR, EBR1 and EBR2 registers. These registers aren’t effective in the emulator operation. As a result, you cannot use block-erase to erase your data of the on-chip flash memory.

Also, you cannot prewrite the data using inverted data. If you write inverted data onto on-chip flash memory, the H8/3048 emulator will write inverted data onto on-chip flash memory area (i.e data can never be 00'H, it can be inverted data).

---

**Note**  
It is recommended to write 00'h to destination address directly, when you want to prewrite the data of the on-chip flash memory.

---

**Protection Mode**  
The H8/3048 emulator does not support the following protection modes.

- Block protection
- Emulation protection
- Error protection

---

Using On-chip Flash Memory  6-3
The H8/3048 emulator never detects errors such as read cycle to on-chip flash memory area, exceptions, and execution of "SLEEP" instruction during writing/erasing on-chip flash memory area.

**Boot Mode**

The H8/3048 emulator drives into the boot mode, when the emulator accepts reset signal from target system and you supply 12V to MD2 and Vpp/RESO pin. Then, emulation status becomes Running user program. Emulation reset does not cause the boot mode.

While the boot program on internal PROM is in progress, break command is suspended and occurs after the boot program is completed. If you want to discontinue the boot program, you need to reset the emulator.

The H8/3048 emulator does not trace execution of the boot program on internal PROM.

While the emulator is executing the boot program on internal PROM, NMI must not occur. Because the emulator cannot prohibit the NMI at this time.

6-4 Using On-chip Flash Memory
Index

1 5 voltage adaptor
   installation, 3-4
   specification, 3-4

A absolute file
   loading, 2-11
   storing, 5-5
   analyzer
      configuring the external, 4-20
      H8/3048 status qualifiers, 2-25
      triggering by data, 2-29
      using the, 2-22
   assembling the getting started sample program, 2-6

B background cycles
   tracing, 4-18
   blocked byte memory display, 2-15
   boot mode, 6-4
   Break
      write to on-chip flash memory, 6-2
   breaks
      break command, 2-17
      break during DMA transfer, 2-17
      guarded memory accesses, 4-10
      software breakpoints, 2-17
      write to ROM, 4-10, 4-17
   bus arbitration
      using configuration to isolate target problem, 4-13

C C program
   debugging, 5-4
   displaying in mnemonic memory display, 5-4
   displaying in trace listing, 5-4
   caution statements
      real-time dependent target system circuitry, 4-6
      characterization of memory, 4-9
   clearing software breakpoints, 2-20
clock source
   external, 4-3
   internal, 4-3
command file
   creating and using, 5-3
configuration
   /WAIT signal, 4-15
   hardware standby, 4-14
   select microprocessor type, 4-6
configuration options
   background cycles to target, 4-15
   enable /BREQ input, 4-12
   enable NMI input, 4-13
   honor target reset, 4-14
   in-circuit, 3-10
   memory access size, 4-16
   processor mode, 4-7
   trace refresh cycles, 4-19
convert SYSROF absolute file to HP Absolute, 2-6
converter
   h83cnvhp, 2-6
coordinated measurements, 4-20, 5-5
copy memory, 5-2
coverage analysis, 5-2

D  Debugging C programs, 5-4
display command
   memory mnemonic, 2-13
   memory repetitively, 2-15
   registers, 2-21
   symbols, 2-11
   trace, 2-23

E  EBR1,EBR2 register, 6-2
emul700
   command to enter the Softkey Interface, 2-7
emul700, command to enter the Softkey Interface, 2-30
emulation analyzer, 2-22
emulation memory
   External DMA access, 4-9
   loading absolute files, 2-11
   RAM and ROM, 4-9
size of, 4-9
Emulator
  before using, 2-2
  configuration, 4-1
  DMA support, 4-12
  memory mapper resolution, 4-9
  prerequisites, 2-2
  purpose, 1-1
  running from target reset, 3-11
emulator configuration, 2-8
  break processor on write to ROM, 4-17
  clock selection, 4-3
  default mapping, 2-8
  internal RAM, 4-10
  loading, 4-21
  monitor entry after, 4-5
  restrict to real-time runs, 4-5
  saving, 4-20
  stack pointer, 4-16
  trace background/foreground operation, 4-18
  Trace internal DMAC cycles, 4-18
Emulator features, 1-3
  analyzer, 1-5
  breakpoints, 1-6
  clock speeds, 1-4
  easy product updates, 1-6
  emulation memory, 1-5
  processor reset control, 1-6
  register display/modify, 1-5
  restrict to real-time runs, 1-6
  supported microprocessors, 1-3
Emulator limitations, 1-7
END assembler directive (pseudo instruction), 2-15
end command, 2-30, 4-20
erasing flash memory, 6-2
Evaluation chip, 1-7
exit
  Softkey Interface, 2-30
external analyzer, 2-22
  configuration, 4-20
external clock source, 4-3
F  file extensions
   .EA and .EB, configuration files, 4-20
   FLMCR register, 6-2
   foreground operation
   tracing, 4-18
   function codes
   memory mapping, 4-9

G  getting started, 2-1
   prerequisites, 2-2
   global symbols, 2-13
   displaying, 2-11
   grd
   memory characterization, 4-10
   guarded memory accesses, 4-10

H  h83cnvhp
   convert, 2-6
   hardware installation, 2-2
   help
   on-line, 2-9
   pod command information, 2-10
   softkey driven information, 2-9

I  in-circuit configuration options, 3-10
   In-circuit emulation
   installing the PGA adaptor, 3-4, 3-7
   PGA adaptor, 3-3
   QFP adaptor, 3-3
   QFP probe, 3-3
   QFP socket/adaptor, 3-3
   installation
   hardware, 2-2
   software, 2-2
   Installing target system probe
   target system probe, 3-2
   interactive measurements, 4-20
   internal clock source, 4-3
   internal DMA cycles, 4-15
   internal RAM
   mapping, 2-8, 4-10
internal ROM
  mapping, 2-8, 4-9

L  limitations
  DMA support, 1-7, 4-9
  Hardware standby mode, 1-7, 4-14
  Interrupts in background, 1-7
  Sleep/standby mode, 1-7
  Watch dog timer in background, 1-7
  linking the getting started sample program, 2-6
  loading absolute files, 2-11
  loading emulator configurations, 4-21
  local symbols, 2-19
    displaying, 2-12
  locked
    end command option, 2-30
  logging of commands, 5-3
  low voltage adaptor
    installation, 3-7
    specification, 3-7

M  mapping memory, 4-9
  mapping of internal RAM, 2-8, 4-10
  mapping of internal ROM, 2-8, 4-9
  measurement system, 2-31
  memory
    characterization, 4-9
    copying, 5-2
    mapping, 4-9
    mnemonic display, 2-13
    mnemonic display with C sources, 5-4
    modifying, 2-16
    repetitively display, 2-15
    searching for strings or expressions, 5-2
  memory characterization, 4-9
  memory mapping
    function codes, 4-9
    on-chip flash memory, 6-1
    ranges, maximum, 4-9
    sequence of map/load commands, 4-11
  mnemonic memory display, 2-13

modify command

Index - 5
configuration, 4-1
memory, 2-16
software breakpoints clear, 2-20
software breakpoints set, 2-19
module, 2-31
monitor
  breaking into, 2-17

N
  non-maskable interrupt, 4-13
nosymbols, 2-11
notes
  "debug" option must need to generate local symbol information, 2-6
  /STBY input will give the emulator /RES input, 4-14
  Break during DMA transfer, 2-17
  default mapping of memory, 4-9
  DMA to emulation memory not supported, 4-12
  External DMA accesses to emulation memory, 4-9
  map memory before loading programs, 4-11
  mapping of internal RAM, 4-10
  mapping of internal ROM, 4-9
  pod commands that should not be executed, 5-2
  refresh and internal DMA cycle in background, 4-15
  selecting internal clock forces reset, 4-4
  software breakpoints not allowed in target ROM, 2-17
  software breakpoints only at opcode addresses, 2-17
  Trace internal DMAC cycles, 4-19
  Trace refresh cycles, 4-19
  use the "set" command at each window, 2-14
  write to ROM analyzer status, 4-18
  write to ROM in DMA cycles, 4-18

O
  On-chip Flash Memory, 1-7
    boot mode, 6-4
    flash memory registers, 6-2
    memory mapping, 6-1
    protect mode, 6-3
    on-line help, 2-9

P
  PATH, HP-UX environment variable, 2-7
  PGA adaptor, 3-3
    installation procedure, 3-4, 3-7
  PGA pin assignment, 3-12
User Interface Software, 2-30
pod_command, 2-10
features available with, 5-2
help information, 2-10
predefining stack pointer, 4-16
prerequisites for using the emulator, 2-2
processor operation mode, 4-7
programming flash memory, 6-2
protection mode, 6-3
Purpose of the Emulator, 1-1

Q
QFP adaptor, 3-3
QFP probe, 3-3
QFP socket/adaptor, 3-3

R
RAM
mapping emulation or target, 4-10
real-time execution
restricting the emulator to, 4-5
refresh cycle, 4-15
REGISTER CLASS, 5-6
register display/modify, 2-21
REGISTER NAME, 5-6
registers
classes, 2-21
release_system
end command option, 2-30, 4-20 - 4-21
repetitive display of memory, 2-15
reset (emulator)
running from target reset, 2-15, 3-11
restrict to real-time runs
emulator configuration, 4-5
permissible commands, 4-5
target system dependency, 4-6
ROM
mapping emulation or target, 4-10
writes to, 4-10
run command, 2-15
run from target reset, 3-11
sample program description, 2-2
sample program, linking, 2-6
saving the emulator configuration, 4-20
simulated I/O, 4-19
softkey driven help information, 2-9
Softkey Interface
  entering, 2-7
  exiting, 2-30
  on-line help, 2-9
software breakpoints, 2-17
  clearing, 2-20
  enabling/disabling, 2-18
  setting, 2-19
software installation, 2-2
special code
  software breakpoints, 2-17
stack pointer, defining, 4-16
status qualifiers, 2-25
step command, 2-20
  with C program, 5-4
string delimiters, 2-10
symbols
  displaying, 2-11
  in memory display, 2-14
system overview, 2-2

target memory access, 4-15
target memory, loading absolute files, 2-11
target reset
  running from, 3-11
target system
  dependency on executing code, 4-6
PGA adaptor, 3-3
QFP adaptor, 3-3
Target system probe
  installation, 3-2
Terminal Interface, 2-10
trace
  display with C source lines, 5-4
  displaying the, 2-23
  displaying with time count absolute, 2-24
internal DMAC, 4-18
  specifying trigger condition, 2-26
trace about, 2-27
tracing background operation, 4-18
tracing refresh cycles, 4-19
transfer address, running from, 2-15
  trigger
    specifying, 2-22
  trigger condition, 2-26
  trigger state, 2-23
U  undefined software breakpoint, 2-18
  user (target) memory, loading absolute files, 2-11
V  visible background cycles, 4-15
W  window systems, 2-30
    write to ROM break, 4-17