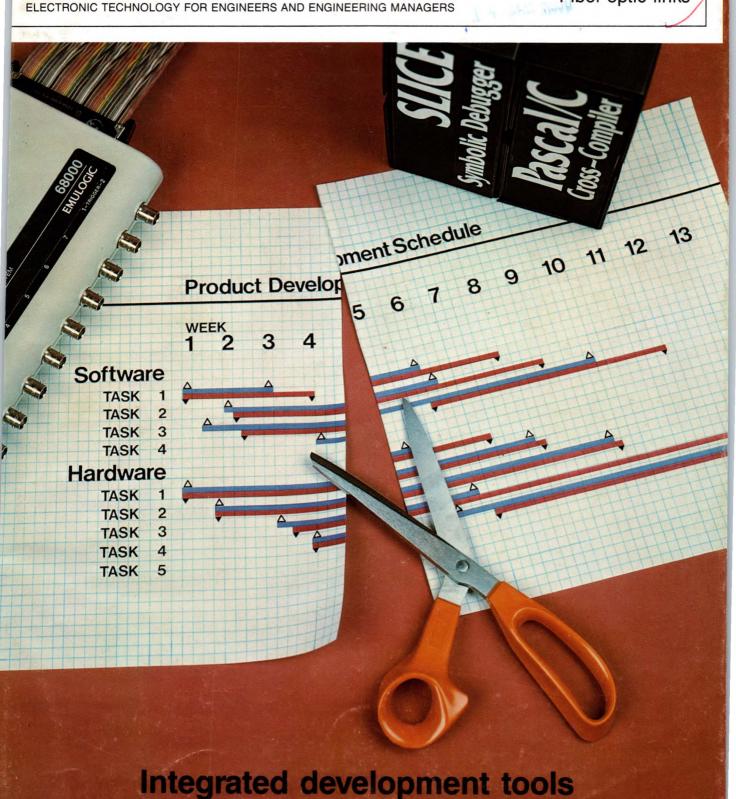
NOVEMBER 29, 1984

A CAHNERS PUBLICATION

Driver ICs simplify μP-to-display interfacing Extended processing units expand computing power Converter circuits directly

digitize low-level signals

Fiber-optic links



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National's Series 32000" (formerly known as NS16000) provides the most complete family of 32-bit CPUs, slave processors, systems peripherals, development systems and software. Today!

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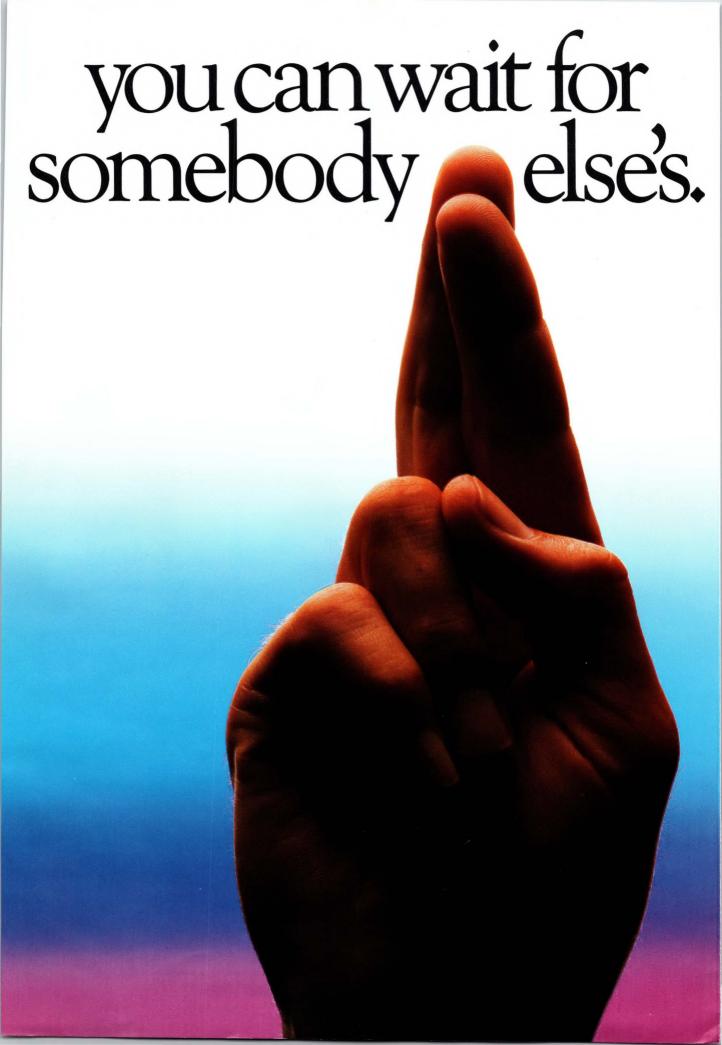
Truly a generation ahead.

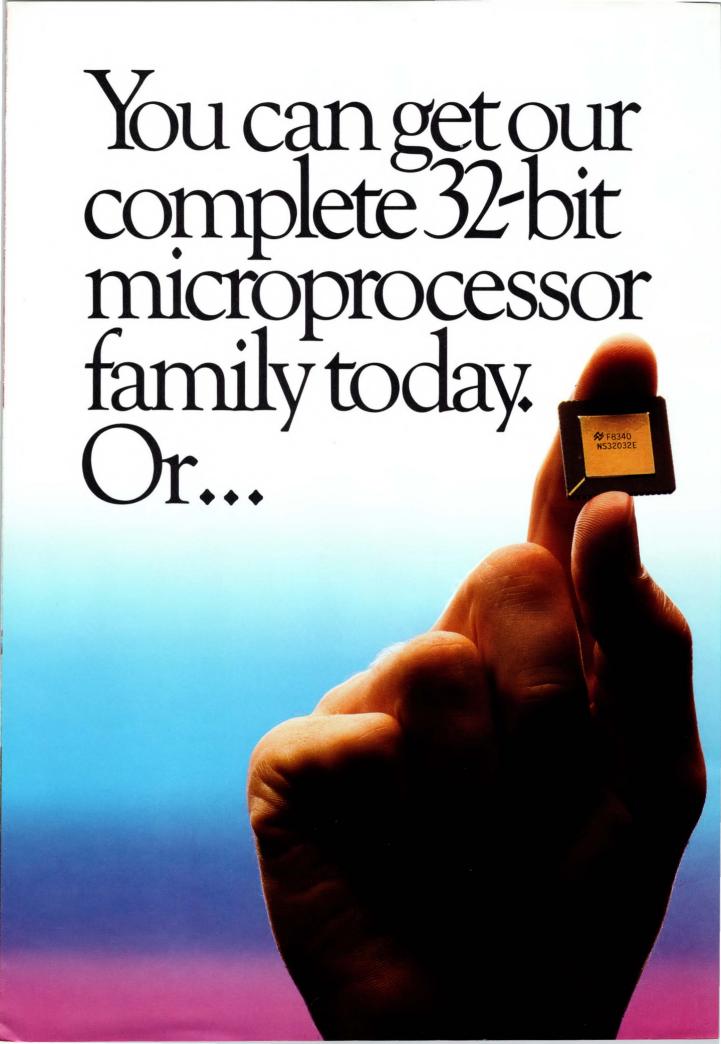
We'd like to send you a copy of our brochure entitled: "The Specifics of 32-Bit Architecture and Implementation." And to answer any questions you might have about Series 32000. Write to National Semiconductor Series 32000, 2900 Semiconductor Drive, MS23-200, Santa Clara, California 95051.

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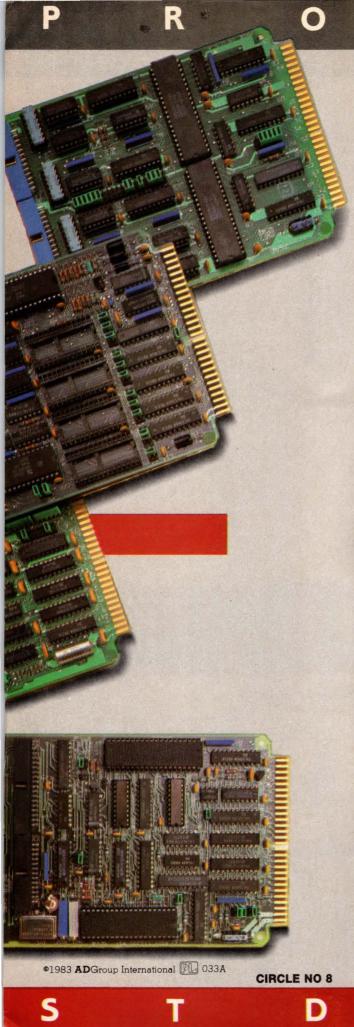
Or you can use the generator's output as a 1000:1 frequency divider for ultra-low frequency generation.

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CIRCLE NO 7





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NOT DEDICATED TO Z80? SO ARE WE.

ou're covered.
Every which way — in the STD BUS card world — which we (a) created, invented, started, and (b) influence with more cards, more versions, more solutions than anyone. Adding four new cards brings the Pro-Log card count to 59, which is a lot of ways to solve Z80 and non-Z80 problems. Speaking of Z80, one new card, the 7806, is a Z80A multifunction CPU 128K on-board memory and I/O.

The second card, a natural ally to the multifunction CPU card, is our new 128K dynamic ram card. 7707 to be exact. (64K memory is an option). The latest in high-density semiconductor memory. Compatible with Z80A, 8088, 8085A, 6809 and others.

The third card, 7606, is a versatile, four-port parallel I/O card designed specifically for Z80A-based STD BUS card systems. Starting with just these three cards gives you the nucleus of a Z80-based system.

Our fourth new card, 7388, is dedicated and not dedicated to Z80. It's a double-density floppy disk controller card with a most important — and exclusive feature. It runs 8", or 51/4" or 31/2" drives without modifying the connectors. The soft-sectored diskettes can be single-sided, single-density, double-sided, double-density, or any combination thereof.

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7707, 128K DYNAMIC RAM CARD with parity, compatible with Z80A, 8088, 8085A, 6809 and others, 64K option, cuts card count for large memory applications.

7606, PARALLEL I/O CARD, four operating modes, supports Z80 mode-2 interrupts, direct TTL interface.

7388, DOUBLE-DENSITY FLOPPY DISK CONTROLLER CARD, runs 8", 51/4", 31/2" drives, uses a DMA controller for fast memory access, three user accessible DMA channels.



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S T D B U S



NOVEMBER 29, 1984 • VOLUME 29, NUMBER 24 • ELECTRONIC TECHNOLOGY FOR ENGINEERS AND ENGINEERING MANAGERS

DESIGN FEATURES Integrated development tools
Development-system utilities that have uniform commands and compatible outputs smooth the transition from one design step to the next.
Extended-processing units expand μP computing power
Eliminating protection circuitry reduces switching-supply costs
Driver ICs interface μPs with vacuum-fluorescent displays
Circuits allow direct digitization of low-level transducer outputs
Program automates error analysis of time-interval measurements
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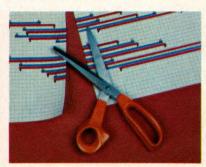
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Instrumentation tailored to CAE systems is simplifying test and verification of prototype chips. Such instruments combine stimulation, acquisition, and comparison capabilities (pg 61).



Plastic fibers offer an alternative to coaxial cable or twisted-wire pairs in applications requiring a low-cost communications link. Moreover, the fibers are easy to use (pg 91).



On the cover: Cutting product-design schedules depends on more than your choice of development-system hardware; you must also select integrated software packages that work smoothly with your hardware. See pg 116. (Photo courtesy Emulogic)

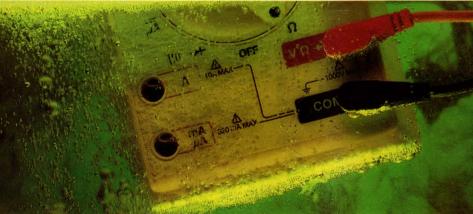
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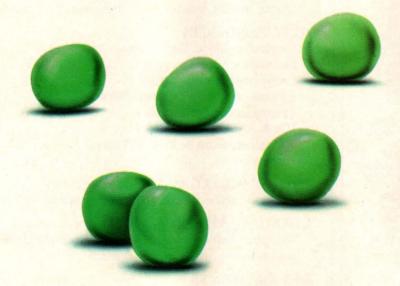
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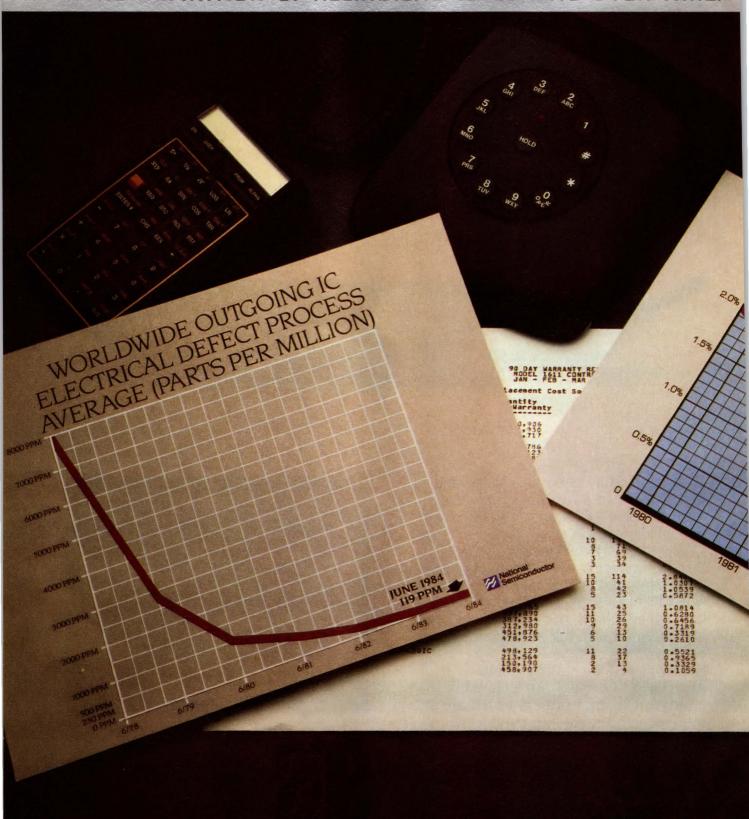
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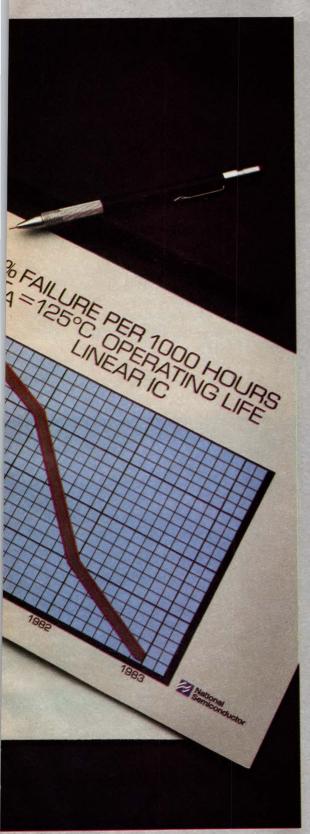




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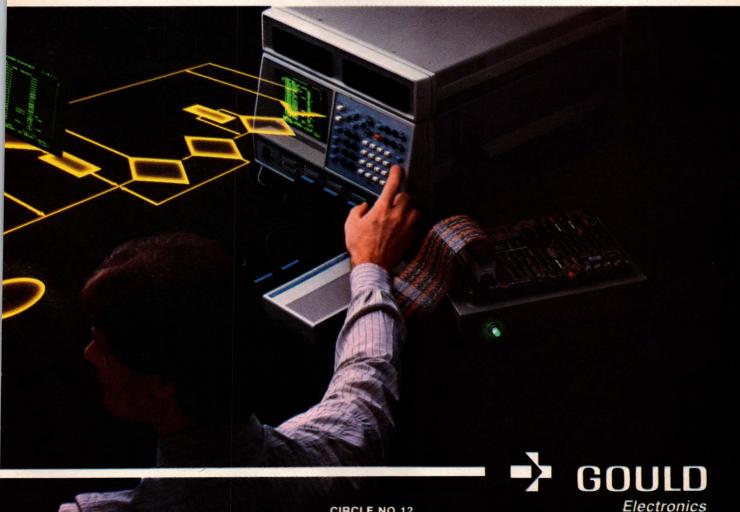
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The K105-D gives you two levels of HELP at the touch of a button. First, step-by-step operating instructions that appear along the bottom of the analyzer screen. Second, a menu that allows you to select more detailed "help" should you need it.

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CIRCLE NO 13



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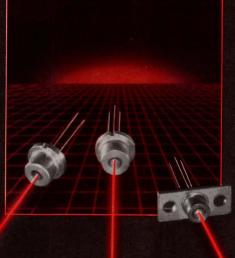
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CIRCLE NO 15

C71 Rev. Orig.

NEWS BREAKS

Edited by Joan Morrow

PORTABLE SYSTEM TESTS 54- AND 34-IN. WINCHESTER DRIVES

Flexstar's (San Jose, CA, (408) 946-1445) FS-5000 self-contained portable test system tests 5½- and 3½-in. Winchester disk drives, and it can test any Winchester drive that uses ST-505/412-type interfaces. It's designed to test two drives at a time by taking advantage of the overlap seek mode.

The FS-5000 has a built-in 2 line \times 40-column LCD, a 50-character keypad, and a 40-column printer. It also has dc power capable of powering up one disk drive. The FS-5000 performs both phase-margin and phase-margin surface-scan testing to 1-nsec resolution. It measures $15 \times 15 \times 4$ in. and weighs 15 lbs.—Chris Everett

MS-DOS OR CP/M COMPUTER HOSTS µP DEVELOPMENT TOOLS

The MPDS family of hardware/software μ P development tools from Microtek (Gardena, CA, (213) 538-5369) supports the 80186, 80188, 68000, and 14 other widely used CPUs. A portable μ C controls operation and executes the CP/M (MPDS I) or MS-DOS (MPDS II) operating system. A typical \$8595 system includes choice of computer, in-circuit emulator, and cross assembler, as well as symbolic debugging and software performance analysis.—Maury Wright

COMMERCIAL IC EMPLOYS 1-µm CMOS PROCESSING

Touted as the first commercially available product to use 1- μ m CMOS processing, the \$120 (1000) Model TMC2110 from TRW's LSI Products Div (La Jolla, CA) is a 16×16-bit multiplier/accumulator. The IC directly replaces the company's bipolar TDC1010. At full operating speed, the device performs a multiply/accumulate operation in 90 nsec; ie, it attains an 11.1-MHz throughput rate. This speed represents a 2:1 increase over the speeds of previous products. In some systems, this increased operating speed can entail the use of higher speed supportingmemory chips. Thanks to the IC's CMOS process, the device draws essentially zero power in static mode; at full operating speed, the power draw increases to slightly less than 350 mW.

The device employs a bulk ion-implanted CMOS technology that uses eight mask layers. The TMC2110 performs two's-complement or unsigned-magnitude multiplication to yield a full-precision 32-bit product.—Bill Travis

MICROWINCHESTER DISK DRIVE PROVIDES 10M BYTES OF STORAGE

Fitting the 3½-in. form factor and furnishing 10M bytes of storage, Hewlett-Packard Co's first Winchester disk drive suits the rough treatment that portable and transportable computers experience. The unit uses sputtered thin-film media and withstands as much as 50g without external shock mounts. High-quality read/write electronics ensure data integrity. The drive provides 25-msec track-to-track access times and a 75-msec average access time.—Ed Teja

VOICE-OUTPUT CARD CONTAINS OWN DEVELOPMENT SYSTEM

The M520 voice-output card from Microcontrol (Kogarah, NSW, Australia) costs less than \$400 and allows implementation of a custom vocabulary with the addition of only an RS-232C terminal and an EPROM programmer. The board contains a 6802 μ P, a 3k-byte monitor program, and audio-input and -output lines to allow recording, editing, and playing of sounds with cassette-recorder quality. On-board memory sockets allow storage of 46 sec of sound.—Gary Legg EDN NOVEMBER 29, 1984

NEWS BREAKS

SINGLE EUROBOARD FEATURES DEC J11 CHIP SET

Adding to its G-64 line of computer and peripheral boards, Gespac (Mesa, AZ, (602) 962-5559) brings DEC's 15-MHz J11 processor chip set to the single-Eurocard form factor. The on-chip memory-management unit extends the G-64 bus's physical address space to 512k bytes. The board also contains a DEC-compatible serial port, triple 16-bit timer, and interrupt controller. The interrupt controller supports 10 interrupts—four external interrupts and six on the processor board. Samples of the GESMPU-11 board cost \$1750.—Maury Wright

DMA CONTROLLER ACTS AS COPROCESSOR FOR IAPX 286 DESIGNS

Systems based on the iAPX 286 μ P can now move data blocks more efficiently by employing the 82258 advanced direct-memory-access (ADMA) controller from Intel (Santa Clara, CA, (408) 987-7197). The ADMA device functions like a coprocessor and was jointly developed with Siemens. When used with the iAPX 286 family's pipelined architecture, the 82258 specs an 8M-byte/sec data-transfer rate. The 4-channel chip supports operation with high-speed transfer on all channels, or one of the four can act as a multiplexed channel supporting 32 lower speed channels. The 82258 will cost \$170 (100).—Maury Wright

μP FAMILY OFFERED IN SURFACE-MOUNTED PACKAGES

SGS Semiconductor Corp (Phoenix, AZ) now offers its Z8, Z80, Z8000, and Z8500 product lines in quad-in-line, J-bend chip-carrier packages. The packages are one-third the size and one-fifth the weight of corresponding dual-in-line housings. The ICs come in commercial, industrial, and military temperature ranges, and in plastic or ceramic packages. In addition, versions accommodating $\pm 10\%$ power-supply variations are available.—Bill Travis

SINGLE-BOARD μ C SPORTS VME EXPANSION SLOTS

The 68010-based VSF 1605 single-board computer includes 512k bytes of RAM, demand-paged virtual memory, a memory-management unit, bootstrap PROM, I/O interfaces, and five VME Bus-compatible expansion slots. Called the VME system foundation, the \$5995 board from Interphase (Dallas, TX, (214) 350-9000) only requires peripherals to function. Disk interfaces provided include ST506, ESDI, and ST412HP Winchester devices and IBM-compatible 5¼-in. floppy disks. The board comes standard with eight serial ports that support a variety of protocols. In addition, four general-purpose programmable timers provide separate interrupt vectors to the CPU.—Maury Wright

DISK- AND TAPE-STORAGE DEVICES INTRODUCED AT COMDEX

At the COMDEX/FALL '84 show (Las Vegas, November 14 to 18), Seagate Technology (Scotts Valley, CA) was among a number of companies to announce new lines of disk-drive products. Its 10M-byte ST112, a 3½-in. Winchester drive that costs \$450 (1000), provides a 65-msec average access time; the ST225 packs 20M bytes in a 5¼-in. form factor for \$495 (1000).

The company's most significant introduction may have been its ST4000 Series, a line that uses a closed-loop servo and voice-coil actuator to achieve as much as 40M bytes of storage in a 5¼-in. package. Furnishing 960 tpi, the ST4000 Series has 977 cylinders and provides an ST412 interface that features the error-correction circuitry available in the ST412HP interface.—Ed Teja

New 4-bit raster DAC sharpens graphics

(and it's in an 18 lead DIP)

125MSPS, guaranteed, "graphics ready," just \$15*



Give yourself a head start with a monolithic DAC designed specifically for raster scan systems—the TRW TDC1034 4-bit, 125 MSPS D/A converter. It directly drives CRTs to video compatible levels. Save on circuitry-no extra registering, buffering or deglitching. Save space—the 4-bit TDC1034 is an ultra-thin 18 lead DIP.

And you get terrific performance. This monolithic 4-bit DAC is ideal for either monochromatic or RGB color raster graphics (4096 colors!). Its high speed scans more pixels per picture to produce razor sharp high resolution displays. And because it's built with TRW's OMICRON-B™ 1-micron bipolar process, you get high reliability and low power consumption (600mW).

The low-cost 4-bit TDC1034 is your one chip solution to high volume production of

CAD/CAM work stations, computer graphics, and high resolution video. If your application needs all the options that an 8-bit, 24 lead DIP offers, consider the TDC1018the first monolithic 8-bit, 125MSPS D/A converter.

Check these key performance features:

- · Blank, sync and bright video controls
- Directly drives standard 75Ω load
- · Inherently low glitch
- Registered data and control inputs
- Power supply rejection ratio>50dB
- · Differential logic for maximum speed, minimum noise
- RS-343 compatible
- · Low power dissipation
- Single -5.2V power supply
- 1/8 LSB linearity (4-bit TDC1034)
- 1/2 LSB linearity (8-bit TDC1018)
- ECL compatible data and control inputs

These DACs are available from Arrow Electronics, Hall-Mark, and Hamilton/Avnet.

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For a full data sheet or immediate information about our "graphics ready" DACs, call or write our Literature Service Department:

LSI Products Division, TRW Electronic Components Group, P.O. Box 2472, La Jolla, CA 92038, 619,457,1000

In Europe, call or write: TRW LSI Products, Konrad-Celtis-Strasse 81, 8000 Muenchen 70, W. Germany, 089.7103.115

In the Orient, phone: Hong Kong, 3.856199; Tokyo, 03.461.5121; Taipei, 751.2062

*U.S. price in 1000s: TDC1034 CERDIP \$15; TDC1018 CERDIP \$36.00 © TRW Inc. - 1984 TRS-4116



LSI Products Division

NEWS BREAKS: INTERNATIONAL

by Peter Harold

INTERNATIONAL TEST AND MEASUREMENT SHOW HIGHLIGHTS

The ITAME (International Test and Measurement Exhibition), which was held in London on October 30 to November 1, was the occasion for a variety of new-product introductions. For instance, Solartron Instruments (Farnborough, UK, TLX 858245) displayed its \$5295 7½-digit 7071 digital multimeter. The device shares the same measurement, processing, and remote-control facilities as the company's 7081, but it's specified to require no recalibration for more than 10 years. The instrument's drift is proportional to the square root of time, resulting in a 1-year dc voltage accuracy of ± 20 ppm of the reading, ± 1 ppm FS. For nine years that spec is ± 60 ppm of the reading, ± 1 ppm FS. The unit achieves accuracies per square root of one year on its other functions as low as ± 20 ppm of the reading, ± 1 ppm FS for resistance, and $\pm 0.02\%$ of the reading, $\pm 0.005\%$ FS for ac voltage.

Philips S & I Div (Eindhoven, The Netherlands, TLX 51573) displayed its \$2400 PM3302 digital storage oscilloscope. The scope features a sampling rate as high as 20 MHz and captures waveforms at time-base speeds from 10 μ sec/div to 50 sec/div with a maximum vertical sensitivity of 1 mV/div. Its dual $2k \times 8$ -bit memories, each capable of capturing 25, 50, 75 or 100% pretrigger information, can be separately displayed or updated as required. You can generate trace data to an X-Y recorder or via an optional IEEE-488 interface to compatible devices. A direct-display mode with time-base resolution from 200 nsec/div to 0.1 sec/div is also available.

The PALAS 40C50 logic analyzer, which costs approximately 13,900 DM, was exhibited by Dolch Logic Instruments (Dietzenbach, West Germany, TLX 4191550). It provides 32 channels of 1k-bit acquisition memory; 16 of those channels capture glitches as short as 5 nsec. In timing mode, it has a maximum resolution of 20 nsec (10 nsec with an optional high-speed probe). For state analysis, it operates with external clocks as fast as 25 MHz. Each 16-channel block has its own clock input and three clock qualifiers. The 40C50 has 4-level sequential triggering with eight trigger qualifiers. A full-size reference memory allows you to perform automatic trace and compare operations with optional rearming of the analyzer.

Marconi Instruments Ltd (St Albans, UK, TLX 23350) introduced the 800X incircuit tester, which tests high-density digital or hybrid circuit boards that contain VLSI devices. The 800X is equipped with 2048 nonmultiplexed test pins, each capable of performing digital stimulus/response or analog measurements. The system features a synchronous logic tester for the examination of VLSI device operation; you can synchronize the unit under test to the 800X at speeds as high as 16 MHz. For functional board testing, additional instrumentation can be connected via the system's IEEE-488 bus. The fault-report database generated is suitable for access by automated repair stations. The 800X is software and test-fixture compatible with 80X Series testers. System price starts at £176,000; delivery is 16 to 20 weeks ARO.

You Owe It To Yourself To Choose From The Best.

Choosing the right logic analyzer can be tough. But one thing is clear—you want all the advantages you know you can count on from the performance leaders.

EVEN AMONG THE LEADERS, THE DIFFERENCES CAN BE SIGNIFICANT.

For example, not all the top logic analyzers give you 200 MHz timing. Or highly sophisticated linkage and interactive analysis. Or 1000-word deep data collection and auxiliary memories. Or an easy-to-use ASCII keyboard. Or floppy disk data storage. *Only Nicolet's 800*

series gives you all these advantages. In the end, though, it's Nicolet's unmatched price/performance ratio that's the most important difference.

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Only Nicolet makes it easy and inexpensive to enhance *perform-ance*—not just add channels—any time you need it. And the NPC-800 Series gives you *five* instruments to choose from, and more options than anyone else in the industry: Waveform Recorder, Performance Analysis, CT/SA, Computer/IEEE-488 Controller, Printer Software, Non-Volatile Memory, Dot Matrix Printer, and Second Disk Drive.

PUT THE LEADERS TO THE TEST.

When you really think about it, the only way to be sure is to let the best logic analyzers prove what they can do—for *you*. When it comes to capability, versatility, and performance, there's really only one choice. For a Logic Analyzer Comparison Chart, call: (800) NICOLET or (415) 490-8300 (inside CA). Nicolet Paratronics Corporation, 201 Fourier Ave., Fremont, CA 94539.

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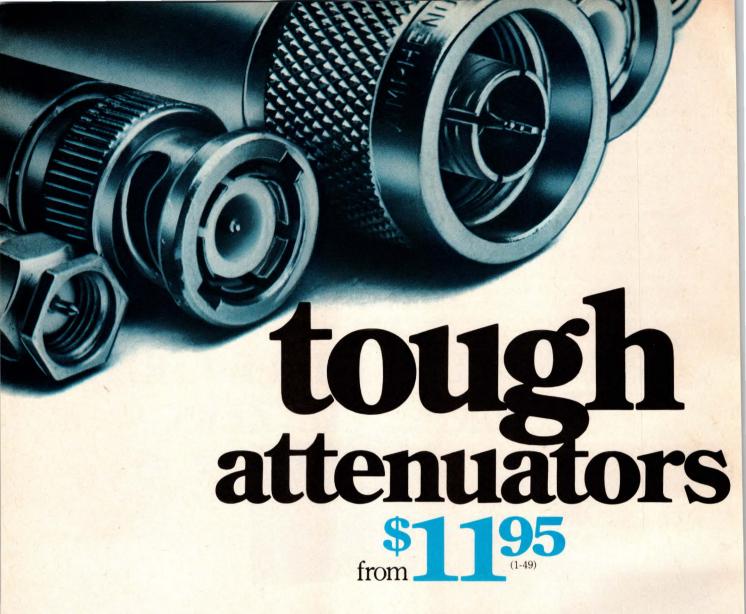


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*Freq. (MHz)	Atten. Tol. (Typ.)	Tol. Atten. Change, (Typ.) over Freq. Range				
DC-1500 MHz		DC-1000	1000-1500	DC-1000 MHz	1000-1500 MHz	

*DC-1000 MHz (all 75 ohm or 30 dB models) DC-500 MHz (all 40 dB models)

MODEL AVAILABILITY

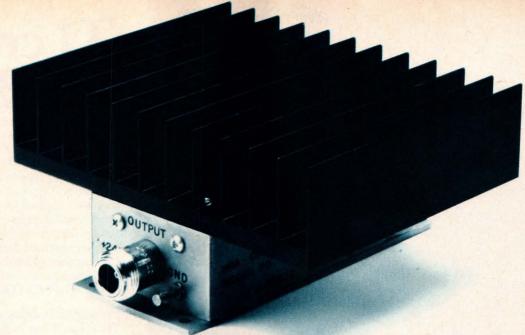
Model no. = a series suffix and dash number of attenuation. Example: CAT-3 is CAT series, 3 dB attenuation.

■ denotes 75 ohms; add -75 to model no

• denotes 50 ohms

ATTEN	SAT (SMA)	CAT (BNC)	NAT (N)	TAT (TNC)
1	•	•	•	•
2	•			
3	•		•	
4	•			
5	•			
6	•	•=		•
7	•			
8	•			
9	•			
10	•	•=	•	
12	•			
15	•			
20	•	•=	•	•
30	•	•	•	
40	•	•	•	•

PRICING (1-49 qty.): CAT (BNC)...\$11.95, SAT (SMA)...\$14.95 TAT (TNC)...\$12.95, NAT (N)...\$15.95



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These ultra-linear Class-A amplifiers are unconditionally stable and can be connected to any load impedance without amplifier damage or oscillation.

For low power (50 mW), 22dB gain and 40dB isolation, consider the ZFL-2000; for operation up to 4200MHz with 1-watt output, specify the ZHL-42.

So select the amplifier for your application from the chart below. We'll ship in one week, with, of course, our one-year guarantee.



Model	Freq.	Gain	Gain Flatness	Max. Power Output 1dBm			DCP	ower	Pric	ce
No.	MHz	dB	dB	Compression			Voltage	Current	\$ Ea.	Qty.
ZHL-32A	0.05-130	25 Min.	±1.0 Max.	+29 dBm Min.	10 Typ.	+38 dBm	+24V	0.6A	199.00	(1-9)
ZHL-3A	0.4-150	24 Min.	± 1.0 Max.	+29.5 dBm Min.	11 Typ.	+38 dBm	+24V	0.6A	199.00	(1-9)
ZHL-1A	2-500	16 Min.	±1.0 Max.	+28 dBm Min.	11 Typ.	+38 dBm	+24V	0.6A	199.00	(1-9)
ZHL-2	10-1000	15 Min.	± 1.0 Max.	+29 dBm Min.	18 Typ.	+38 dBm	+24V	0.6A	349.00	(1-9)
ZHL-2-8	10-1000	27 Min.	±1.0 Max.	+29 dBm Min.	10 Typ.	+38 dBm	+24V	0.65A	474.00	(1-9)
ZHL-2-12	10-1200	24 Min.	± 1.0 Max.	+ 29 dBm Min.	10 Typ.	+38 dBm	+24V	0.75A	599.00	(1-9)
ZHL-1-2W	5-500	29 Min.	± 1.0 Max.	+33 dBm Min.	12 Typ.	+44 dBm	+24V	0.9A	495.00	(1-9)
ZHL-42	700-4200	30 Min.	±1.0 Max.	+29 dBm Min.	7.5 Typ.	+38 dBm	+15V	0.69A	895.00	(1-9)
ZHL-7-2W	600-800	28 Min.	± 1.0 Max.	+33 dBm Min.	12 Typ.	+43 dBm	+24V	0.9A	525.00	(1-9)
ZFL-2000	10-2000	20 Min.	±1.5 Max.	+17 dBm Min.	7 Typ.	+ 25 dBm	+ 15V	0.1A	179.00	

C70 R

50 ohm impedance, input and output VSWR 2: 1 max

Price and specifications subject to change without notice.

Refer to EEM and Gold Book for detailed specs.



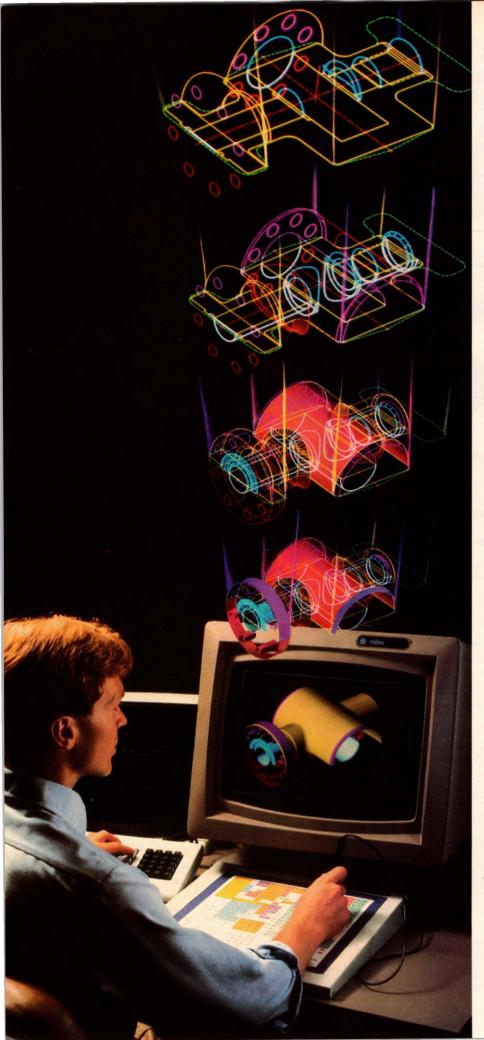
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TI creates IMPACT

These pace-setting devices from Texas Instruments operate at unprecedented clock speeds up to 50 MHz. They can cut processing time in half for such speed-critical applications as high-resolution graphics for CAD/CAM systems. New superminicomputers. Artificial intelligence machines. Wherever complex functions demand extremely large numbers of logic operations for rapid image access, use TI's new IMPACT bipolar PAL® ICs (TIBPAL-15 Series).

Propagation delay cut by 40% TI's unique 2-µm Implanted Advanced Composed Technology (IMPACT) dramatically reduces the size and the sidewall capacitance of circuit elements (see facing page). Establishes a new performance standard with propagation delay cut to 15 ns, maximum, at 180 mA—versus 25 ns at 180 mA for the fastest PAL ICs formerly available.

Space requirements cut by up to 83%

With their extremely dense circuitry, TIBPAL-15 Series devices can bridge the gap between SSI/MSI and LSI gate arrays. Now a single PAL IC can replace as many as six SSI or MSI circuits. And give you the flexibility of user-programmable logic in such fields as telecommunications and automotive control, where space constraints—as well as processing speed—are often critical.

Fast and easy programming
Programming TIBPAL-15 Series
bipolar logic circuits, with their
reliable titanium-tungsten fuses, takes
only seconds using widely available
software and inexpensive device programmers. And you can implement logicdesign changes in minutes, without
vendor retooling.

For any logic application where superspeed, high density, and immediate availability are design criteria, your best—and only—answer is a 15-ns PAL IC from Texas Instruments.

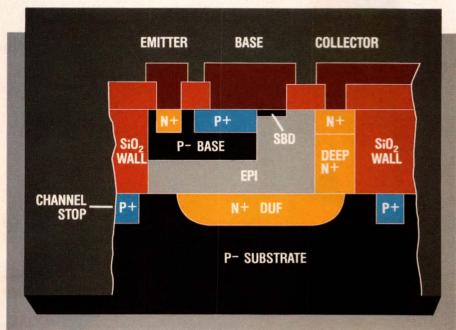
◆ Processing 50 megabits of digitized data per second, TI 15-ns PAL ICs will find widespread application in advanced, highresolution graphics for CAD/CAM systems. These new superspeed PAL ICs can enhance performance by increasing both the speed and the size of the graphics-display processor.

Demonstration software courtesy of Calma Company.

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the world's fastest PAL ICs: New process delivers 15-ns speed.



A highly significant reduction in capacitance results from the 2-um feature size which TI's IMPACT processing makes possible. Silicon dioxide is the isolation material. Switching speed is further enhanced by utilizing this silicon dioxide for emitter and base sidewalls.

TI's new IMPACT technology boosts circuit density and performance levels.

IMPACT is a unique innovation of Texas walling together contribute significantly Instruments, capitalizing on the advantages of composed-masking techniques to increase the speed and density of bipolar integrated circuits.

Composed masking vields high density

In composed masking, critical components are placed on the chip with a minimum number of masks. Thus they can be more tightly defined and more densely spaced than by conventional masking, which requires more precise registration.

The process also makes it possible to insulate critical base and emitter components with oxide walls. This insulation reduces sidewall capacitance, which at the dimensions of IMPACT features can represent as much as half the overall capacitance. Small size and oxide

to the increase in switching speed.

Other important features of IMPACT technology are independently controlled base resistance and doublelevel metal with a 7-µm pitch at the first level.

Exceptional reliability built in

The high speed, low power, and potential for large-scale integration that IMPACT makes feasible are valuable characteristics for chips used in harsh environments. Improved electrostatic-discharge (ESD) tolerance has been designed in. Copperdoped aluminum in the first-level interconnection eliminates electromigration during programming. Current densities, metal spacing, and contact sizes are all conservatively designed to add reliability to the process.

Also from TI: The world's fastest FPLAs.

In addition to superspeed TIBPAL-15 Series ICs, Texas Instruments offers the industry's fastest Field Programmable Logic Arrays (FPLAs), with

20-ns maximum gate delay.
Whereas PAL ICs have a program-

mable AND array feeding a fixed OR array, the universal structure of the FPLA includes programmable AND and OR arrays. The FPLA provides the ultimate flexibility for implementing logic functions in the "complexity gap" between standard SSI/MSI and LSI/ VLSI logic.

The wide range of programmable-logic devices available from Texas Instruments is described in the table below. In addition, military versions of the PAL16XXA/A-2 are available, with TIBPAL-15 Series and TIFPLA839/840 soon to come.

TI's Broad PAL/FPLA Family tpd(max) ICC(max) Registered (ns) (mA) Outputs PAL ICs TIBPAL16L8-15 TIBPAL16R8-15 TIBPAL16R6-15 180 180 180 15 15 15 15 TIBPAL16R4-15 180 PAL16L8A/A-2 25/35 180/90 25/35 25/35 25/35 180/90 180/90 180/90 PAL16R8A/A-2 PAL16R6A/A-2 PAL16R4A/A-2 **FPLAs** TIFPLA839 TIFPLA840

For more information on Texas Instruments PAL ICs and FPLAs, call your local TI distributor. To receive a data-sheet collection on all the new TI high-performance, user-programmable products, call Texas Instruments Incorporated at 1-800-232-3200 Ext. 201.

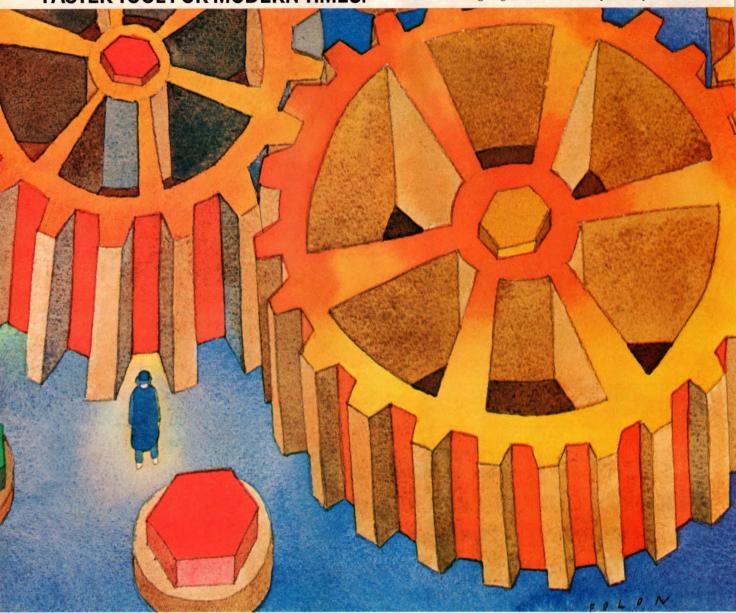


Creating useful products and services for you.

25

TURNING YOUR PC INTO A FASTER TOOL FOR MODERN TIMES.

This is the 3rd in a series of technical papers from Zilog, designed to give engineers new insights into Zilog microprocessors—what advantages they provide for particular products and why they are the choice among engineers who need optimum performance.

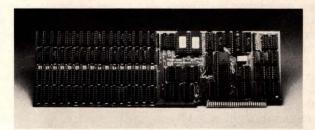


IBM® and other compatible PC computers are fast enough for general home and office use. But, for hardware and software development applications, the gears turn slowly.

What you need is a faster "gear" to co-process with the Intel 8088 inside IBM's PC. Like Zilog's Z8001® CPU. Now, there's a way to increase throughput for the IBM PC—as well as test the performance of the Z8001 CPU for your high-performance applications with a Z8001 CPU-based board called the "Trump Card" from Sweet Microsystems. And it proves dramatically how powerful Zilog's 16-bit CPU really is.

The new device is a peripheral board that plugs into any expansion slot on an IBM PC or compatible PC computer. Trump Card is addressed as an I/O device that communicates through the expansion bus. It is powered by Zilog's Z8001 CPU.

The Trump Card increases the computational power of the IBM PC, and provides maximum performance with a minimum of board space.



The Trump Card, shown from the front. The left side of the board contains 512 K-bytes of type-4164 dynamic RAM; the right side contains the Zilog Z8001 and an interface to the IBM PC I/O-expansion bus.

Z8001 COMPILER BASIC IS 80 TIMES FASTER THAN IBM INTERPRETIVE BASIC.

Essentially a monolithic minicomputer central processing unit, the Z8001 CPU is characterized by an instruction set more powerful than many minicomputers. As the programmer sees it, the 28001 contains sixteen 16-bit general-purpose registers (for addresses or data) that may also be used in groups to form as many as eight 32-bit registers or four 64-bit registers. The low-order halves of the registers may be used for byte operations, thus the Z8001 CPU is able to manipulate data in 8-, 16-, 32-, and 64-bit pieces

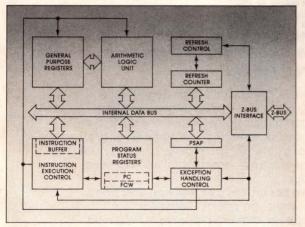
The Z8001 CPU, running at 10 MHz, can execute the same programs 4 to 10 times faster than the Intel 8088. What's more, the Z8001 CPU, with its large 8-megabyte memory range, makes the Trump Card's 512K bytes of memory easy to design with (To use this memory in the card, you simply load a BASIC, CP/M-80, or C program from PC-DOS and

type "RUN")

Apple II	Apple III	TRS-80 Model II	IBM PC	IBM PC (with Trump Card)
224	222	189	190	2.4

A comparison of execution times (in seconds). Running on IBM's interpretive BASIC, a Sieve program takes 190 seconds to execute. Running the same program under TBASIC on the Trump Card Compiler takes only 2.4 seconds.

The eight addressing modes are register, indirect-register, direct-address, indexed, immediate, base-address, base-indexed, and relativeaddress. The instruction set utilizes data types ranging from single bits to a 32-bit long word. What's more, the processor executes 110 distinct instruction types that, when permuted by all the addressing modes and data types, create a set of more than 400 instructions.



A Z8000 CPU functional block diagram of the internal structure of the Zilog Z8000 family of high-performance microprocessors.

ALL THE PROPER SUPPORT FOR 512K BYTES OF MEMORY

The wide range of software written for the Z8001 CPU is proven by all the programs you can run on the Trump Card. With the Z8001-based Trump Card, you can run the following software on your IBM or other compatible PC:

> BASIC Compiler—TBASIC is PC BASICAcompatible. Most instructions are implemented without modification.

> CP/M-80 Emulator—Allows you to run CP/M-80 Z80 assembly language programs directly. Just download your Z80 programs and run

> C-Compiler — The industry standard version of C is available.

> Debugger-Intended to aid in program development, you can examine and change memory and register contents and more. Screen-editor—Has many word processing

> features, including ASCII text file development. Multilevel Language Compiler-Allows Pascal-like control and data types, arithmetic expressions with automatic or specified

> allocations of registers, and more RAM Disk-Can allocate 128K to 387K bytes of on board memory to function as an intelligent RAM disk.

COPROCESSING IS JUST PART OF THE STORY.

The Z8001-based Trump Card is just one example of a successful application design for the Z8001 CPU. But there's far more to the Z8000 family than this

Today, Z8000 CPU's are used in a wide range of applications, from industrial and medical products to computers and graphics imaging machines. And Zilog stands behind every application with service and software support that makes your Z8000-based products get to market on time.

Find out for yourself how much power Zilog packs into every 28000 CPU by turning your IBM PC into a faster tool for modern times.

To get your own Trump Card and complete instructions, call Sweet Microsystems at (401) 461-0530.

For information about the Z8000 CPU, send for our complete overview or call our Literature Hot Line at 800-272-6560. For seminar dates and locations, or information on Zilog training, call 408-370-8091. Or write: Zilog, Inc., Technical Publications, 1315 Dell Avenue, MS C2-6, Campbell, CA 95008.

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IBM is a registered trademark of International Business Machines
Corporation.

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The Intel 286 and Pioneer's technical back-up speed you into production.

Intel's 286 Family is the new standard in 16-bit technology, and Pioneer is ready to bring it to you now.

A complete family. The family is based on the 80286 microprocessor, which offers 1-gigabyte of virtual memory and true multitasking capabilities. The 286 family also includes a full line of peripherals:

☐ The 80287 numerics co-processor, a "turbocharger" that provides high-speed processing for high-volume mathematical calculations.

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SIGNALS & NOISE

MTBASIC compiles 100 statements per sec

Dear Editor:

I was very pleased to see the review of Softaid's MTBASIC in the September 6 issue of EDN (pg 284). There was one small error, however, that I would like to correct. The review states that MTBASIC "translates the program to Z80 code and executes it at 100 BASIC statements/sec typ." In fact, MTBASIC compiles 100 BASIC statements/sec typically, making it one of the fastest compilers around. It executes far in excess of this rate.

Sincerely, Catherine L Ganssle Vice President Softaid Inc Columbia, MD

BASYS adapts BASIC to data acquisition

Dear Editor:

I have just read with interest your Technology Update regarding hardware-specific software packages that adapt BASIC to data acquisition (EDN, September 6, pg 55). I'd like to point out that ADAC Corp manufactures a family of microcomputers for data acquisition and control called the BASYS systems. These computers are compatible with DEC-11 systems and with the IBM PC/XT, and they link via an RS-232C interface. The software supplied with the system uses I/O BASIC, which includes I/O statements for analog, digital, and serial cards, timers, optically isolated boards, DMA cards, and a variety of sensors. I/OBASIC is a line-compiled language that permits A/D conversion and other I/O to proceed simultaneously, allowing A/D conversion to take place at hardware speeds of as high as 100,000 conversions/sec. The software includes a communications utility program that allows handshaking between the ADAC unit and the associated IBM or DEC computer. BASYS systems can operate as stand-alone units, hosts, or satellites.

Sincerely, Lawrence Pelavin Marketing Support Manager ADAC Corp Woburn, MA

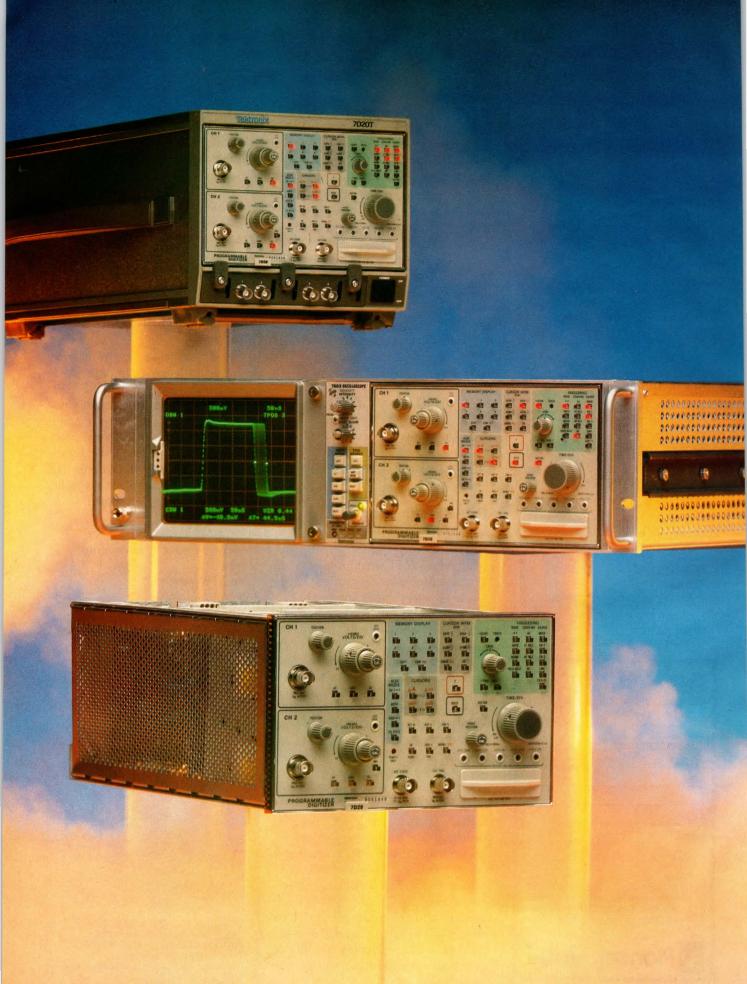
GE supplies power conditioners

Dear Editor:

It was with a great deal of interest that I read the article on line conditioners in the July 12 issue (pg 218). I was disappointed to see that General Electric was not listed among the leading suppliers. General Electric has a full line of power conditioning equipment, including line conditioners for application with desktop computing equipment.

Sincerely, J S White Manager, Power Conditioning Market General Electric Co Fort Wayne, IN





Tek's Plug-in Programmable Digitizer: dividends beyond space and time!

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Of course, Tek Standard Codes & Formats considerably simplifies your interfacing efforts. It goes far beyond the electrical and mechanical conventions defined by IEEE-488 by assuring a consistent interface between all Tek instruments and a logical, mnemonic program language syntax.

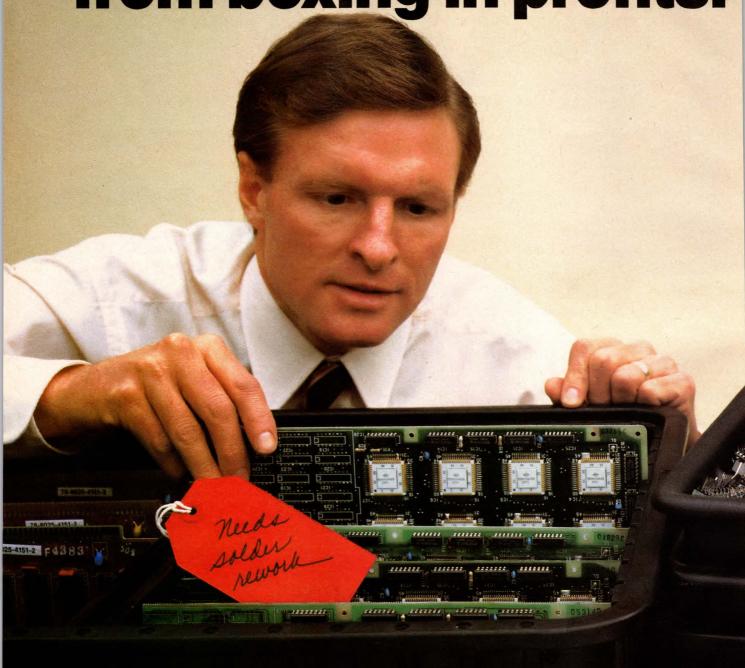
The 7D20 is designed to fit both benchtop and rackmount 7000 Series mainframes. The 7D20 and the rackmount R7603 make an excellent package for automated or computer-controlled test systems. As the 7D20T, it is mounted in a lightweight, halfrack modular package that saves space, provides rear access to inputs, improves portability. Rack two 7D20T units side by side, or one next to a monitor or other device.

Your Tek sales representative will be happy to tell you more about the 7D20. And about our many other test system components. For literature and complete technical specifications, contact:

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CIRCLE NO 21





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CALENDAR

Semicon/Japan '84, Tokyo International Trade Center, Tokyo, Japan. Semiconductor Equipment and Materials Institute, 625 Ellis St, Suite 212, Mt View, CA 94043. (415) 964-5111. December 3 to 5.

Digital Avionics Systems Conference, Baltimore Convention Center, Baltimore, MD. AIAA, 1633 Broadway, New York, NY 10019. December 3 to 6.

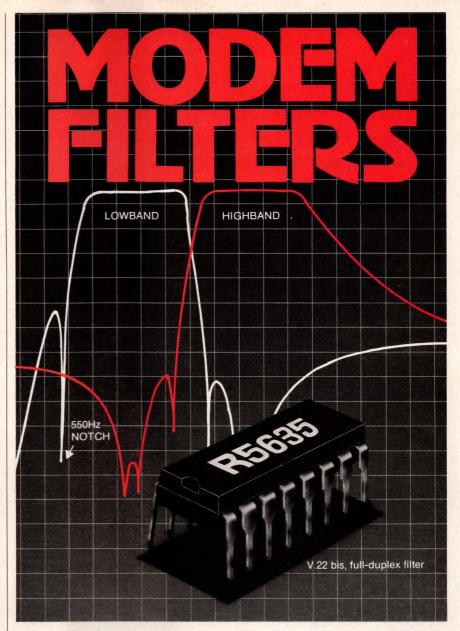
Armed Forces Communications and Electronics Association: Artificial Intelligence (unclassified), Washington, DC. AFCEA, Professional Development Center, 5641 Burke Centre Parkway, Burke, VA 22015. (703) 425-8500; (800) 336-4583. December 4 to 6.

Videodisc, Optical Disk, Compact Disc Conference & Exposition, Washington, DC. Mark Roseman, Meckler Communications, 11 Ferry Lane W, Westport, CT 06880. (203) 226-6967. December 4 to 7.

Course on Electronic Materials, Stouffer's Concourse Hotel, Washington, DC. Palisades Institute for Research Services Inc, 225 Varick St, New York, NY 10014. (212) 242-6864. December 5 to 7.

California Computer Show, Hyatt Hotel, Palo Alto, CA. Norm DeNardi Enterprises, 289 S San Antonio Rd, Suite 204, Los Altos, CA 94022. (415) 941-8440. December 6.

IEEE International Electron Devices Meeting, San Francisco Hilton Hotel, San Francisco, CA. Melissa Widerkehr, Courtesy Associates Inc, 655 15th St NW, Suite 300, Washington, DC 20005. December 9 to 12.



NEW

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R5631 CCITT V.21, full-duplex filter I.C. with MUXes.

R5632 Industry Standard, Bell 212A/CCITT V.22 full-duplex combo filter I.C.

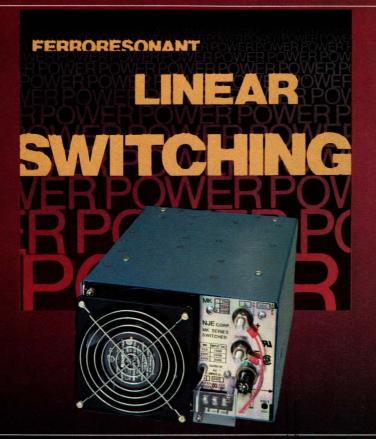
R5633 Selectable filter array I.C. for 103, V.21, DTMF and Videotex applications.

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CALENDAR

1984/1985 Strategic Issues Conference, Americana Canyon Hotel, Palm Springs, CA. InfoCorp, 20833 Stevens Creek Blvd, Cupertino, CA 95014. (408) 973-1010. December 10 to 13.

Cadcam International Show, National Exhibition Center, Birmingham, England. EMAP International Exhibitions Ltd, Durrant House, 8 Herbal Hill, London, EC1R 5JB, England. (01) 837-3699. January 8 to 10.

MOS A/D Interface Circuit Design for VLSI Digital Systems, San Francisco Airport Hilton Hotel, San Francisco, CA. University of California Extension, Continuing Education in Engineering, 2223 Fulton St, Berkeley, CA 94720. (415) 642-4151. January 9 to 11.

Microcomputers in Control Systems: Hardware, Software and Interfacing, George Washington University, Washington, DC. Chip Blouin, Continuing Engineering Education, George Washington University, Washington, DC 20052. (800) 424-9773; (202) 676-8527. January 14 to 18.

Mecom '85, Bahrain. Kallman Associates, 5 Maple Ct, Ridgewood, NJ 07450. (201) 652-7070. February 2 to 4.

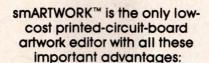
Computer Business Graphics, Bonaventure Intercontinental Hotel, Fort Lauderdale, FL. Carol Every, Frost & Sullivan, 106 Fulton St, New York, NY 10038. (212) 233-1080. February 20 to 23.

National Electrical Manufacturers Association (NEMA) Liability Seminar, Hyatt Regency Tampa, Tampa, FL. NEMA, 2101 L St NW, Washington, DC 20037. (202) 457-8400. March 4 to 5.

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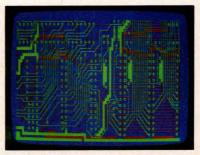
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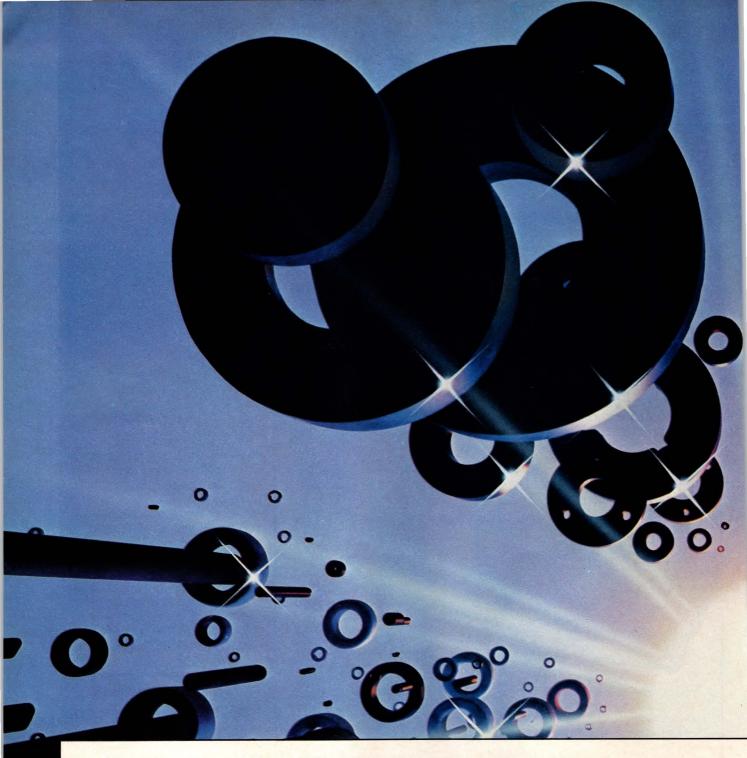
Send a purchase order, or major credit card number, and smARTWORK™ can be working for you next week.

System Requirements

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- ☐ Microsoft Mouse (optional)



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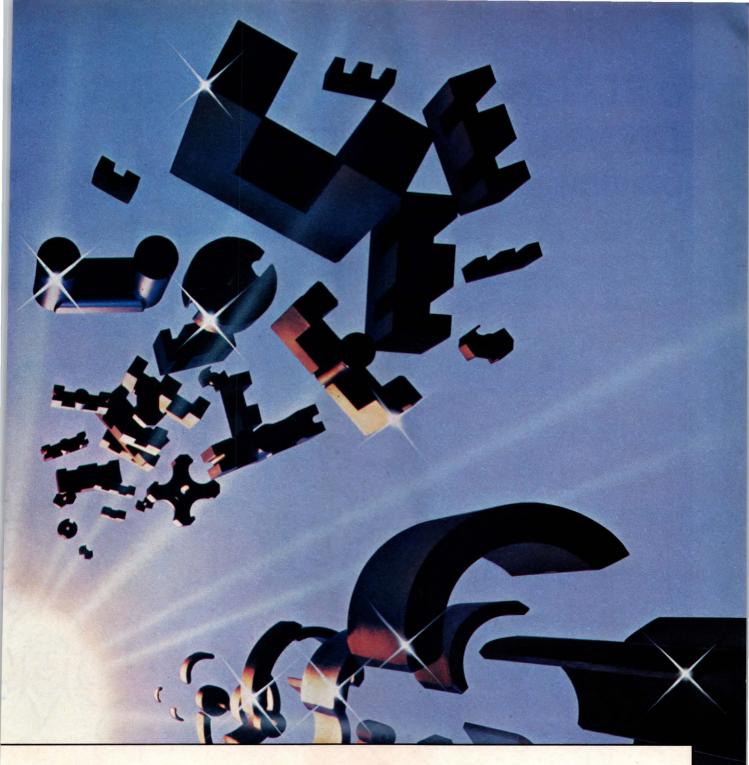
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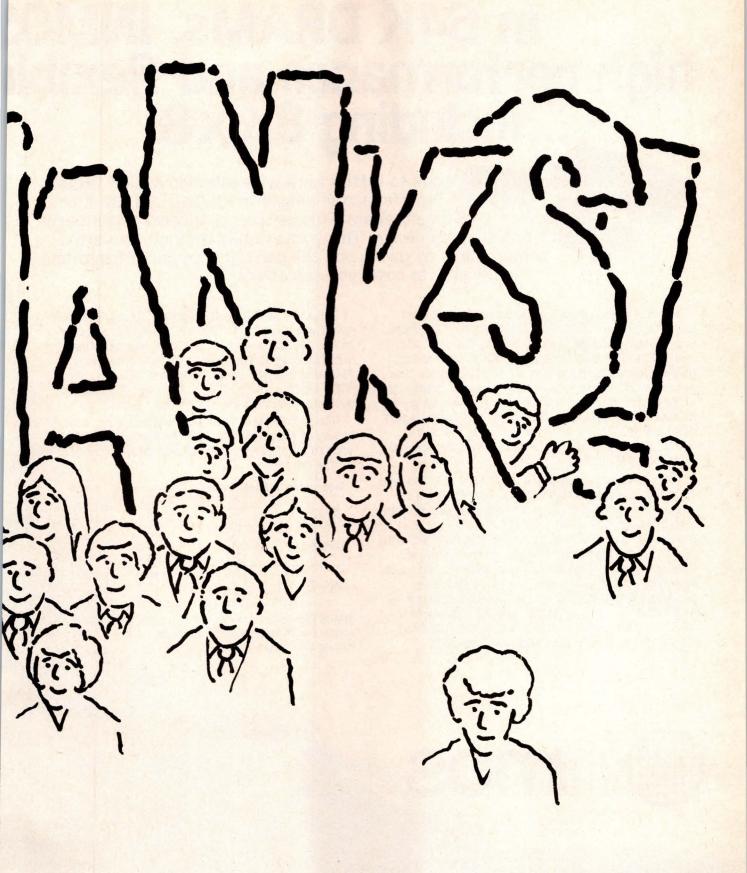
First in Ferrites

CIRCLE NO 47

PHILIPS

To EDN readers, for consistently voting EDN your favorite electronics publication.





From the staff of EDN

In 64K DRAMs, INMOS high performance and flexible ...including 8K x 8.

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8Kx8—The cost and space saver. This newest member of the INMOS 64K DRAM family, available in a plastic package, offers access times of 120 and 150ns. The by-8 organization is a natural for microprocessor designs and other applications that require word width rather than memory depth...in process controllers, intelligent terminals, and buffer memories for example. And its pin 1 refresh makes it a very attractive alternative to 8K x 8 static RAMs. Because it combines low power and low cost with minimal support circuitry.

16Kx4—The performance chip. With 100, 120, and 150ns access times, this organization makes a lot of sense in high-performance systems, such as high-resolution graphics, where high data rates are required. Packaged in plastic DIPs, the IMS2620 also gives you the right combination of cost, organization, and speed for microprocessor systems, terminals, and even arcade and home games. If you're upgrading from 16Kx1 chips, it provides a factor of four reduction in chip count. And its "CAS before RAS" refresh assist function minimizes required support circuitry for cost and space savings.

64Kx1—The big-system choice. This DRAM also gives you a choice of 100, 120, and 150ns access times. What's more, it includes "Nibble Mode," which allows effective cycle times below 85ns. Available in a variety of packages, including plastic DIPs, ceramic DIPs, and chip carriers, it's ideal for systems requiring lots of memory depth.

Check the chart. You'll find the industry's broadest family of 64K DRAMs...and the right device for your requirements. Then call an INMOS distributor for all the details.

Organization	Access Time (ns)	Cycle Time (ns)	Part No.
8Kx8	120	190	IMS2630-12
	150	240	IMS2630-15
16Kx4	100	160	IMS2620-10
	120	190	IMS2620-12
	150	240	IMS2620-15
64K x 1	100	160	IMS2600-10
	120	190	IMS2600-12
	150	230	IMS2600-15

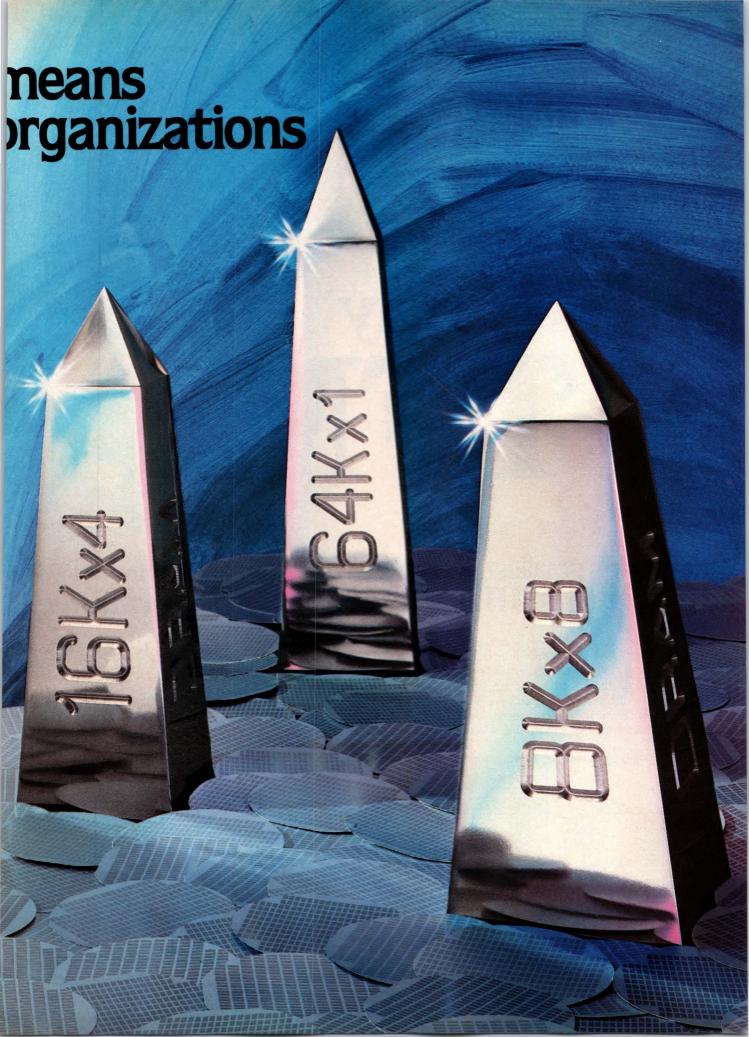
INMOS Distributors: Anthem Electronics, Arrow Electronics, Falcon Electronics, Future Electronics, Lionex Corp.



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MODEL	FREQUENCY, MHz		CONVERSION LOSS dB, TYPICAL		ISOLATION dB, TYPICAL				PRICE			
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TFM-3	.04-400	DC-400	5.3	6.0	60	55	50	45	35	35	19.95	(5-49)
TFM-4	5-1250	DC-1250	6.0	7.5	50	45	40	35	30	25	21.95	(5-49)
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CIRCLE NO 50

EDITORIAL



Automation revisited

Two months ago on this page we discussed a key benefit of automation in electronics manufacturing companies: the maintenance of a competitive edge against inexpensive foreign labor. Automation also has benefits at the personal level, though, as our just-completed trip to the Far East demonstrated very nicely. We found even in Taiwan—noted for its cheap assembly labor—that automation improves workers' jobs and lives without, in general, reducing the number of jobs available.

As related by the president of an electronics company in Taiwan, labor costs in that country have increased tenfold in the last decade. Thus, even though these costs are still low by US standards, some degree of automation is necessary to stem further increases. But in Taiwan, as in the US, automation's increased efficiencies often mean more production by the same number of workers—not less production by fewer workers. And, most important, workers' jobs become less tedious, more meaningful, and more satisfying.

Throughout history the pattern has been consistent: The use of newly developed tools, whether flint knives or robots, has improved the worker's lot. (The Industrial Revolution is a notable exception, but the worst aspects of it, fortunately, were transient.) Today's rapid changes in the work environment do create a potential for temporary injustices, but time will surely prove, as it has in the past, that improved productivity and increased freedom from boring, repetitive tasks will lead to improvements in job quality.

And so, to those who say that automation is unfair to workers, we say "Nonsense!" An adjustment period may be necessary, but the result is worth it. We should do all we can to minimize automation's problems, but otherwise we should let automation proceed on its course. There's no point in standing in the way of progress.



Jesse H Neal Editorial Achievement Awards 1981(2), 1978(2), 1977, 1976, 1975 American Society of Business Press Editors Award 1983, 1981

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Editor



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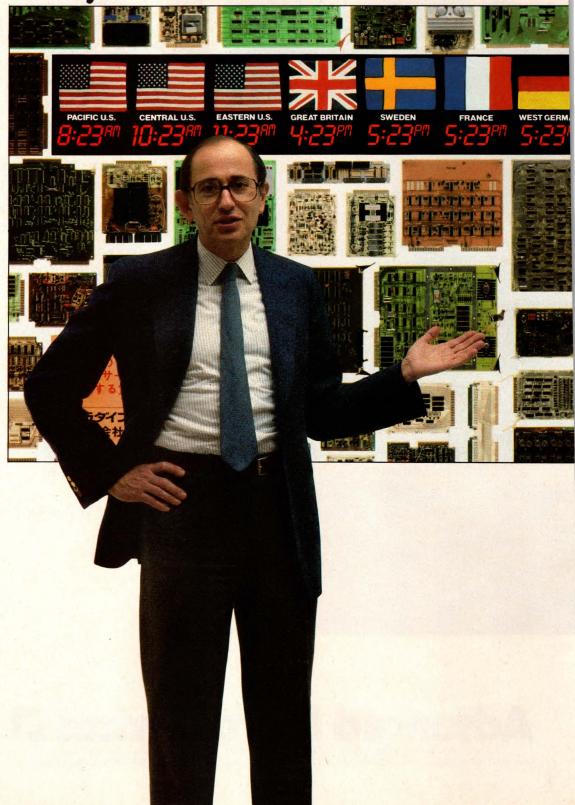
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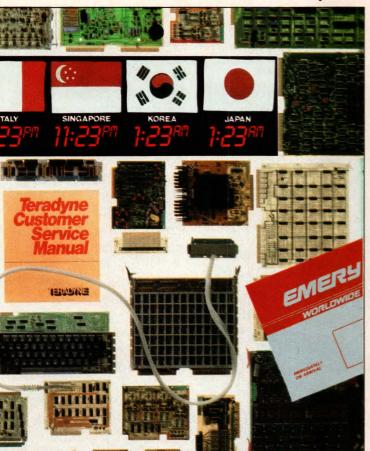
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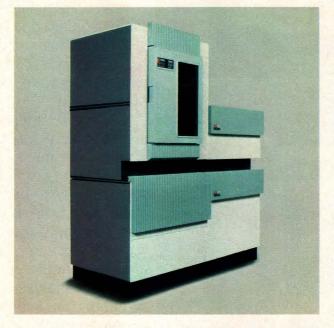
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TECHNOLOGY UPDATE

CAE design systems and functional testers combine to ease testing of prototype ICs

David Smith, Associate Editor

The growing complexity of semicustom and custom ICs is aggravating the problem of testing and verifying prototype chips. Fortunately, vendors of computer-aided engineering (CAE) systems and instrumentation systems are introducing products that simplify the solution to this problem. These products help you create and edit test patterns, and they apply the patterns to your IC. They also combine stimulation, acquisition, and comparison capabilities for less than what you would spend on a production ATE system or a GPIB-based instrument cluster. Most important, they interface to your CAE equipment so you can create, control, and evaluate your tests within your existing design system.

For the problem of the prototype test, the obvious solution would be a low-cost IC test system designed specifically to interface with CAE systems. The Logic Master Series of functional testers (formerly the Design Master; the name was changed because of trademark considerations) from Integrated Measurement Systems (Beaverton, OR) fits this description. These testers include a controlled-impedance environment for the device under test (DUT), a mainframe containing plug-in testing modules, and software that supports close interaction with many CAE systems over an RS-232C interface or a GPIB bus. (Ref 1 supplies more information about the Logic Master and describes the role of hardware verification during IC design.)

As an IC tester, the Logic Master expands to meet your I/O requirements. The mainframe accepts 16-channel modules that perform pat-



By performing tests under CAE control, the Logic Master from Integrated Measurement Systems brings prototype IC testing to the designer's workstation. Tests created on the workstation download to the Logic Master over a GPIB or RS-232C connection, while test results return to the workstation for analysis.

tern generation, data acquisition, or real-time data comparison. As many as 12 modules can fit in one mainframe, resulting in 196 testing channels. In addition, two mainframes operate in parallel to provide the ultimate system limit of 392 channels. Incidently, the mainframes are small enough to fit beside or below your desk.

The test modules operate at frequencies high enough to verify the operation of most ICs. The patterngenerator module applies test vectors at 20 MHz, but you can add an accessory that enables 40-MHz clocking. The timing resolution for all modules is 1 nsec, so the data-acquisition module can measure waveforms with the accuracy of a 1-GHz logic analyzer. If you attach a data-comparison module to a data-acquisition module, you can compare acquired data with expected results, even at 20 MHz. Therefore.

you can generate tests that not only sense but also identify bugs in your chips by including branching and triggering techniques.

The cost of using the Logic Master depends on what modules you need to provide the test capabilities that you require. The lowest price configuration, at \$29,000, offers 32 patterns of stimulation backed by 8k bits of pattern memory per channel. It also includes 32 channels of acquisition (also with 8k bits of associated memory) that compare acquired and expected data in real time.

If you need to evaluate your ICs more closely, the more sophisticated Logic Master II increases channel memory to 16k bits and supports programmable capabilities in the stimulus channels. In addition, the driver and receiver probes can operate at voltage levels defined in 10-mV increments. These added features bring the starting price to

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dard test fixture and the 178, designed to test the performance of linear ICs.

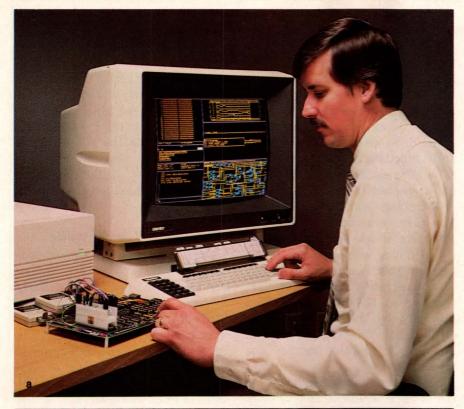
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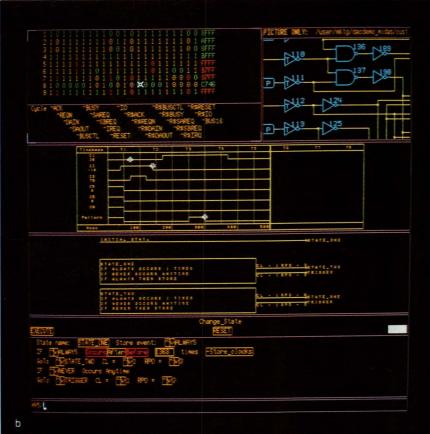
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The HVS tests prototype ICs under the control of a Mentor Graphics workstation. The setup (a) puts creation and control of the test into a window on the workstation screen (b). The similarities between the simulation and test interfaces simplify the development and analysis of the tests.

\$39,000. In comparison, Integrated Measurement Systems estimates that a GPIB-based system with a controller can cost from \$40,000 to \$80,000, not including setup time. Furthermore, a production ATE system with similar timing capabilities costs more than \$150,000.

The test-CAE interface

For the IC designer, the Logic Master's software places test generation and application within the CAE interface. This software resides on both the Logic Master mainframe and the CAE system. On the tester mainframe, the software controls each of the modules during the test procedure. In addition, it responds to a set of commands received from the CAE system over either an RS-232C interface or an IEEE-488 (GPIB) bus. The software at the CAE system allows you to control the testing (ie, issue those commands) using whatever data-entry techniques the system uses. For example, if the CAE system uses a menu-driven format, the test interface also uses it, allowing one user interface for both design and test.

To apply the CAE-supported test to the DUT, you must configure the test apparatus for your requirements. First, you select and insert the modules containing the stimulation and acquisition modules. Ribbon cables connect the I/O channels from the modules to the test fixture. allowing the mainframe to sit away from the fixture. For each I/O channel, the test fixture and ribbon cables provide a controlled impedance from the mainframe to terminals that are only centimeters from the DUT's socket. Briefly then, to configure the test fixture for the DUT, attach short wires from the socket to the terminals, and plug in the appropriate modules in the mainframe.

With the tester set up, you can create, execute, and evaluate tests on your system while sitting at your workstation. Initially, you transform your simulation patterns di-

TECHNOLOGY UPDATE

rectly into suitable test patterns and download these into the tester. Next, you identify those channels in the modules that drive specific pins on the IC. You command the tester to run the test and to return the test results over the GPIB to the CAE workstation. Finally, a conversion program can translate the test results into a format that allows automatic comparison with the outputs of your simulation.

Integration vs resolution

The Hardware Verification System (HVS) brings similar capabilities to Mentor's Ideas series of CAE workstations. It also tests under workstation control, fits beside or on top of your desk, and provides a controlled-impedance environment for the DUT. You can select the test capabilities you need with plug-in modules. The creation, control, and evaluation of tests occurs at your workstation. Of course, the HVS, built for Mentor by Northwest Instrument Systems (Beaverton, OR) operates only with Mentor products.

In comparison with the Logic Master, the HVS has a more clearly defined interface with the CAE environment. This stems from Mentor's cooperation with the testequipment supplier during the development of the product. As a result, the Idea workstation contains some of the conversion and comparison software you need to generate for the Logic Master. For example, the HVS includes the programs that both translate simulation data into test patterns and compare test output with simulation output.

In contrast, the HVS tests at lower frequencies than the Logic Master. Pattern generation proceeds at speeds to 20 MHz, and the 32-channel state (data) acquisition module operates at 10 MHz. By adding a timing-analysis option, however, you can achieve a 100-MHz sampling speed in 16 acquisition channels. Still, the sampling

resolution is less than the resolution of the Logic Master.

Your required sampling resolution depends on how specifically you must determine the timing behavior of your DUT. Purely functional testing, with ICs based on static-circuit designs, does not need full clock speed to be accurate. In this case, an IC functions in the same manner at 1 MHz as it does at 10 MHz, unless you have demanding clocking or strobing signal relationships. Therefore, you should examine the extent to which you must specify signal timing when you test prototypes in your design environment. The integration and lower cost (starting at \$24,000) of the HVS may outweigh the higher test rates of the Logic Master, particularly if you already use the Mentor Idea workstations.

The pattern-generation module in the HVS is available from Northwest Instrument Systems as an add-on to the IBM PC; it's known as the 2300 Series. One 2300 chassis offers as many as 160 channels for random-logic testing or as many as 120 channels for random-logic and memory testing. Coupled with Northwest Instrument's 2400 Series 20-MHz data analyzer, you can get 48 channels of pattern generation and 48 channels of data analysis for approximately \$22,000 (without the PC). However, until logic simulators migrate to the PC and develop interfaces to the add-ons, this approach won't provide the CAEtest interaction of the HVS, although it's certainly competitive in price.

Simulators test functionality

Other CAE vendors support prototype testing through their simulation systems. Specifically, Daisy Systems and Valid Logic offer a hardware extension to their software-simulation capabilities. The primary use for these extensions is the virtual breadboarding of systems comprising many LSI or VLSI chips (Ref 2). However, the virtual breadboard is a suitable environment for the functional testing of your ICs.

To realize a virtual breadboard, the Daisy PMX and the Valid Realchip use plug-in boards similar in



By hooking an instrumentation system to a VAX, the Tektronix DAS 9100 with the 91DVV software package links VAX Unix-based CAE tools to a variety of test configurations. The DAS (lower right) operates using local input from its own keypad or remote data from a VAX terminal.

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By adding simulation software, the Inspector 200 and 300 testers from Pragmatic Test Systems integrate CAE and testing. The Eplog software accepts net-list input, simulates the design, and generates test vectors for prototype IC test.

function to those in the Logic Master and the HVS. Driver and receiver circuits on the boards compose a simple functional-test system for the ICs you include in the system simulation. During simulation, these ICs are equivalent to IC models in software. The simulator can therefore query the IC instead of the software model for functional information. Because the IC responds more quickly than the software model, the simulation time decreases.

With regard to the functional verification of ICs, the equivalence between the IC in the virtual breadboard and its software model allows you to apply to a prototype IC the same stimulus patterns you used to functionally test the software representation of your design. In other words, by inserting your prototype into the hardware extension, you can run the same test patterns on it as you ran on your logic design.

There are some advantages to this method. First, the test patterns require no translation: If the response of the prototype differs from simulation results, translation errors are not to blame. Next, the Realchip and PMX can cost less than the Logic Master or the HVS depending on which options you purchase. They start at \$29,000 and \$15,000, respectively. Finally, you have the resources for system simulation and debugging available. The verified IC can immediately operate in a simulation of the system for which you have designed that IC.

On the other hand, these hardware extensions for simulation can provide information concerning only functional behavior. They are not test systems; you cannot analyze timing behavior. In addition, Realchip and PMX clock the ICs at 3 and 1 MHz, respectively, and these frequencies are lower than the clock rates of many IC-based systems. If your verification effort requires running the prototypes at full speed, or if you must verify signal waveforms as well as levels, you need more testing capabilities.

Integrated-instrument control

Traditionally, instrumentation manufacturers have supplied the logic analyzers that perform the waveform analysis. Now they see the CAE workstation as a direct link between their test instruments and the designers who use the work-stations for the design of complex, hard-to-test electronics. These companies have been integrating pattern generation and analysis functions into instrumentation systems for a few years. Now some are providing the interfaces that integrate the instrumentation systems with the CAE workstations.

One example, the Tektronix DAS 9100, uses a variety of instrumentation plug-ins that provide the resources for functional and timing analysis of digital ICs and boardlevel systems. In addition, it includes a local processor, a keyboard, and a built-in monitor (color optional). The plug-ins are similar to the modules previously discussed—with pattern generation, data acquisition, and timing analysis-but you can test your DUT using only the keyboard and monitor without the need for a host computer system for test entry and control. As a result, the DAS 9100 has usually operated independently of the design system.

This year Tektronix has complemented the DAS 9100 with the 91DVV software package that, over an RS-232C connection, allows you to create and control test procedures for the DAS 9100 from your VAX terminal. The software for the VAX, written in C, runs under Unix 4.1; therefore, the 91DVV software can interface with any CAE software written for the VAX Unix 4.1 environment. In particular, the 91DVV compresses simulation vectors into DAS pattern-generator programs, downloads these programs to the DAS 9100, uploads the results of the test into the VAX, and finally compares hardware responses with simulation output.

VAX governs instrumentation

This package aims at VAX-based design groups that need timing analysis as well as functional verification. For a 25-MHz maximum test rate, the DAS mainframe can support 80 pattern-generation channels

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and 96 acquisition channels. For more exact timing analysis, you can insert 91A08 data-acquisition modules for 32 channels of synchronous or asynchronous sampling at 100 MHz. You can switch to 91A04A modules for asynchronous sampling at 660 MHz (1.5-nsec sample interval) or synchronous sampling at 300 MHz of as many as 16 channels. A typical DAS 9100 system configured for IC verification costs about \$40,000.

Though these sampling rates may satisfy timing-analysis requirements, they may be excessive (and costly) for a basic functional test. Remember that you can select the modules you need for the DAS; less powerful acquisition modules cost less.

For the DAS, the more restrictive criterion is the software providing the CAE-test interface. First, you need to write a program to convert your simulator's output into the TLOGS format for the 91DVV input as well as one to translate the results of the test back into your simulator's format for comparison to sim-

ulation results. Though this is a minor task, it does require some familiarity with both formats. More importantly, if your CAE tools run under any operating system but VAX Unix, you cannot use the 91DVV. Tektronix promises to start expanding the range of compatible hosts and operating systems by the end of 1984.

Tester uses existing modules

If you use workstations made by CAE Systems (Sunnyvale, CA), Dolch Logic Instruments (San Jose, CA) offers an integrated instrumentation system that interfaces with your design system. The Caesar 400 can accept four plug-in modules of the set already offered for Dolch's Atlas and Colt instrumentation systems. These modules can put 96 channels of 20-MHz pattern generation, as well as 96 channels of 20-MHz acquisition (or 64 acquisition channels at 100 MHz, or 32 acquisition channels at 300 MHz) in one Caesar mainframe. The test procedure, including test-pattern generation, pin assignment, prototype test, and comparison with simulation data, occurs in the windows of the CAE Systems' user interface.

As a result of the close cooperation of Dolch and CAE Systems, expect the Caesar to interact closely with the CAE Systems environment, much as the HVS from Mentor does. Also, Caesar costs roughly the same (for similar capabilities) as the HVS, ranging from \$13,000 to \$25,000. Obviously, at this time, the HVS works only with Mentor products, and the Caesar only with products from CAE Systems, so the choice of functional testers depends on your choice of CAE vendors.

CAE enters test systems

Instead of depending on your CAE vendor for an interface to test equipment, you can bring the design database to a testing system. Pragmatic Test Systems (Milpitas, CA) brings a package of simulation and test software to its Inspector 200 and 300 Series test systems. This package, Eplog, simulates logic designs that you enter as net lists. Next, it converts the simula-





Four instrumentation plug-ins provide flexibility for the Caesar test system (a). When the plug-ins are connected to a CAE Systems workstation, test patterns and results appear in a test window (b). In addition, simulation results can be combined with the test results (middle window) for easy comparison.



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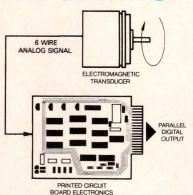
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Daisy Systems Corp 139 Kifer Ct Sunnyvale, CA 94086 (408) 773-9111 Circle No 733

Dolch Logic Instruments Inc 2029 O'Toole Ave San Jose, CA 95131 (408) 945-1881 Circle No 734

Integrated Measurement Systems Inc Tektronix Inc 9525 SW Gemini Dr Beaverton, OR 97005

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Box 500 Beaverton, OR 97077 (503) 644-0161 Circle No 738

Valid Logic Systems Inc 2820 Orchard Parkway San Jose, CA 95134 (408) 945-9400 Circle No 739

tion data into test vectors that run on Inspector test systems. Without much of the burden of test generation, you benefit from the flexibility and programmability of a test system.

Using this approach for prototype verification pays off in environments where budgets are tight and timing requirements are loose. For as little as \$50,000, you can own the hardware and software both to simulate designs and to test prototypes. In comparison, a CAE Systems design workstation without the Caesar product costs \$50,000 to \$150,000 depending on the software options. However, the Inspectors' test clocking peaks at 1 MHz, so many chips run at less than maximum frequency. Still, the Inspectors' programmable resolution (5-mV increments) and current measurement allow you to characterize IC parametrics; logic analyzers and hardware-simulation extensions don't provide this capability.

The net result of bringing CAE programs to the test computer is the same as that of introducing test capabilities into CAE systemsmaking prototype test as easy for the designer as the rest of the design process. To simplify testing, these products link integrated testing capabilities with a CAE environment. The choice of which products

to use depends on your existing CAE tools, your testing requirements, and particularly your budget. Unfortunately, predicting your future test needs can be as hard as predicting your budget, so the choice depends more on the efficiency and productivity you can achieve with a particular functional tester integrated into your design environment.

References

1. Palmquist, Steve, et al, "Hands-on IC testing aids chip designers," EDN, October 18, 1984, pg 253.

2. Freeman, Eva, "Physical modeling systems let you plug VLSt chips into your workstation's logic," EDN, November 15, 1984, pg 69.

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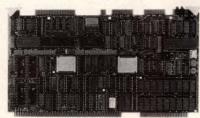
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The Logical Choice



Logic Analyzers with Multiple Functions— Simultaneous Hardware and Software Analysis/ Disassembled Mnemonic Display

When the chips (or other logic devices) are down, you need fast, accurate logic analysis, high-speed performance and multichannel capacity. Where can you get all this at a price you can afford? From Panasonic, of course. We give you a choice of 3 logic analyzers—the VP-3662A, VP-3661A and VP-3620A—to meet virtually any need in timing, state and microprocessor analysis. The sophisticated VP-3662A is the top choice with 100MHz high-speed resolu-

tion, 48 channels and real-time analysis, plus simultaneous 16-bit/8-bit microprocessor analysis and 100MHz/16-channel peripheral equipment timing analysis.

All 3 models feature an optional disassembled mnemonic display for 16-bit and 8-bit microprocessors (VP-3661A: 8-bit only), and optional RS-232-C serial data analysis. So whether you choose the VP-3620A, the VP-3661A or the VP-3662A, you can be sure that you've made the logical choice.

VP-3661A

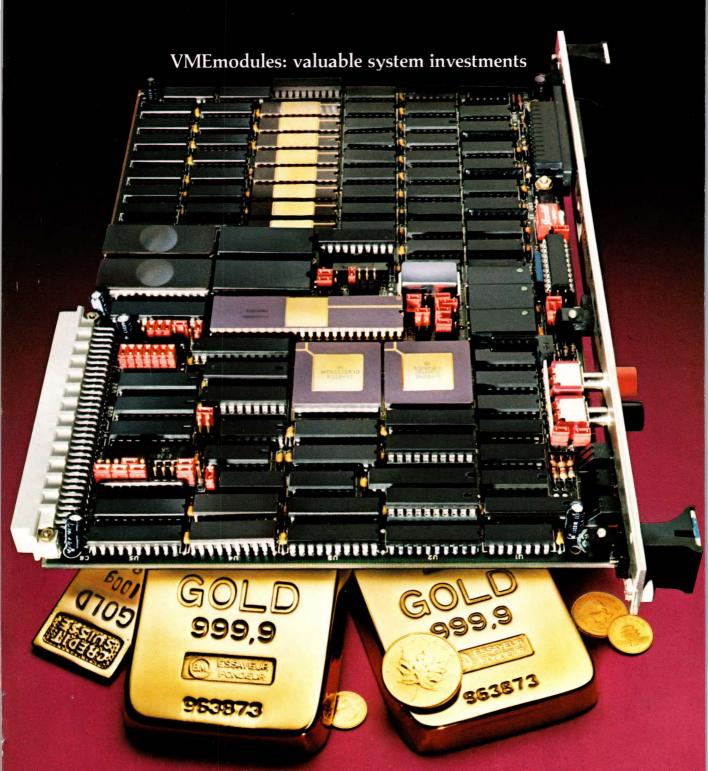
- 32-channel high-speed analysis with maximum resolution of 100MHz.
- Disassembled mnemonic code display for 8-bit microprocessor software
- 8-bit microprocessor software.
 Simplified data analysis with NAME display for each channel.
- Multiple display modes plus flexible trigger functions for easier debugging.

VP-3620A

- 32-channel high-speed analysis with maximum resolution of 20MHz.
- Disassembled mnemonic code display for 16bit/8-bit microprocessor software (optional).
- Flexible trigger and versatile display functions for powerful debugging.
- Glitch trigger function for transients as narrow as 10ns.

Mational/Panasonic

Motorola Reports NOVEMBER ISSUE 1984



- ☐ RGB encoder generates studio color
- ☐ MC68010 now on VERSAmodule monoboard
- ☐ Evaluate MC68020 with the Benchmark 20
- ☐ Software flood for VME/10 microcomputer

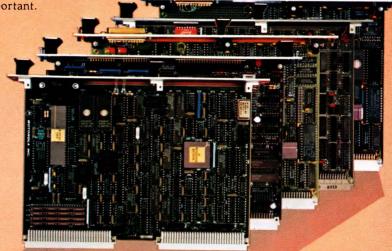


MOTOROLA



Adopting the popular Eurocard mechanical format, VMEmodules are available in two pin-out compatible sizes. Single high and double high board are used to afford a high degree of space flexibility for system Adopting the popular Eurocard mechanical format, VMEmodules are configurations. Pin/socket connectors, card cages, backplanes, and plug-in power supplies all meet rigid DIN and IEC standards, and perform especially well in applications where

resistance to shock and vibration is important.



300 Series — Peripheral Controllers GPIB, universal IPC, SASI, Winchester/floppy, Ethernet, serial and parallel I/O controllers SASI, I/O channel interfaces



700 Series - Non-Eurocard I/O wire wrap boards connectors mass storage extenders

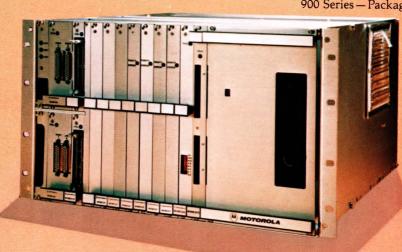
900 Series - Packaging Hardware

backplanes extender boards wire wrap boards chassis



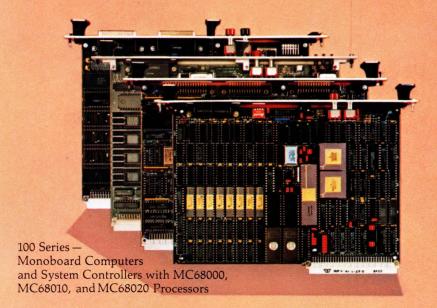
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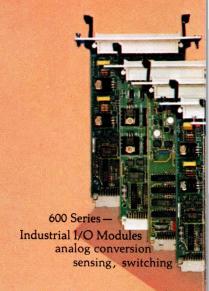
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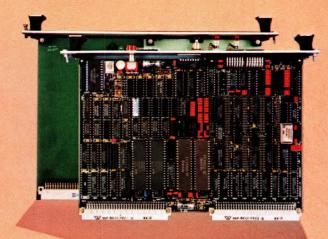




VMEsystem Components C

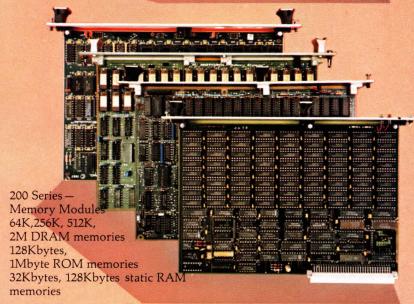






800 Series — Mass Storage Support Products 15 Mbyte Winchester 1 Mbyte DS/DD 5¼" floppy

(not shown)





400 Series — I/O Ch dual channel serial or Centronics compatible interface SASI," ½" magnetic to



Readily available cache enriches VMEmodules

Having cash handy makes good financial sense. Quick access to cache makes good computing sense. With the new VME120 monoboard microcomputer, 4 Kbytes of instruction cache are provided along with a choice of 128 or 512 Kbytes of on-board dual port RAM. The on-board cache memory increases overall system processing speed by allowing faster access and minimizing off-board activity. This is especially important in performance-sensitive applications, such as image processing and highspeed scientific data acquisition.

With an optional 12.5 MHz MC68010 MPU, the VME120 provides throughput of up to 3 million instructions per second.

Additional new VMEmodule products allow integration of powerful application systems with a minimum number of system components.

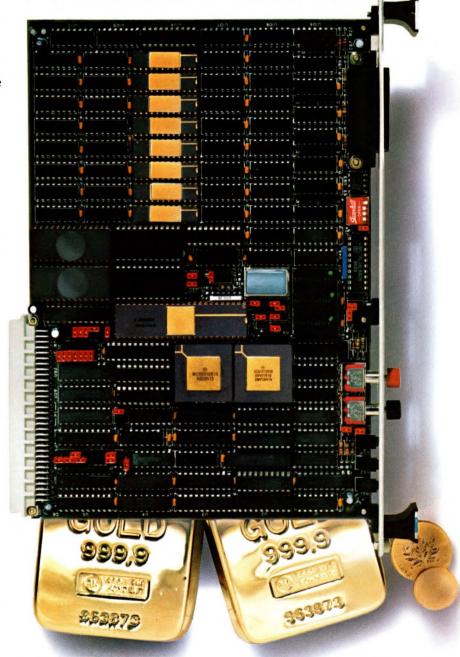
The VME050 system controller may be used with the VME120 processing module to provide global interrupt generator, system clock, serial clock and time-of-day clock functions. It also houses eight 28 pin sockets, two RS-232C serial ports and one parallel port.

The VME320 disk controller is a double-high Eurocard module for adding mass storage capacity to a VMEbus system. It provides high performance DMA data channels between system memory and Winchester hard disk drives and/or floppy disk drives. This disk controller is used in applications having intensive real-time disk I/O or multiprocessing structures to reduce VMEbus traffic and increase system throughput.

For VMEmodule applications requiring mass storage, the VME820 is an integrated module incorporating a disk controller board, plus both a Winchester and floppy disk drive, all in a convenient Eurocard format

plug-in unit.

The VME943 chassis provides 9 VMEbus slots and 6 I/O channel slots in the front, with room for 16 I/O channel or 80mm slots provided in the rear. The chassis uses a tranverse, mid-chassis 400 watt power supply. It is 19 inches deep and designed for mounting in a standard 19 inch rack.



VMEmodule software support includes VERSAdos, Motorola's realtime, multi-tasking, multi-user operating system that includes M68000 Family macro assemblers, a full screen editor, linker and symbolic debugger.

For efficient software evaluation and debug, VMEbug is one of Motorola's debug/monitor firmware products supporting various processor

modules. VMEbug provides an assembler/disassember feature, commands to examine or modify memory, and terminal I/O, disk I/O and boot capabilities.

These new boards add additional system building block features to the broadest line of VMEbus compatible boards available.

Check \square A for information.



- all 6 RS-232C or RS-422
- 128/512 Kbyte RAM
- 2 28 pin sockets

VME 050

system controller

- used with VME 115, 120, 128 and 130
- 8 28 pin sockets
- 2 RS-232C serial ports
- 2 parallel ports
- provides: interrupt handlers system clock serial clock, and time-of-day clock

VME 211 static RAM/ROM

- 16 28 pin sockets
- backed up from +5 standby
- up to 1 Mbyte ROM
- up to 128 Kbyte SRAM
- mix static RAM and ROM
- selectable access time

VME 315

intelligent SASI™ interface

- floppy controller for 4 51/4" or 8" floppies
- DMA access
- 1 RS-232C debug port

- selectable byte or burst transfers
- up to 500 Kbyte/Sec transfer rate

VME 316 VMEbus to I/O channel interface

- converts I/O channel interrupts to VME interrupts
- converts VMEbus RESET to I/O Channel RESET
- selectable address block

VME 202/222 512K/2M DRAM VME 203*/223* 512K/2M DRAM with **VMXbus**

- byte parity
- · on-board refresh
- selectable memory map

VME 320

Winchester/floppy controller

- up to 2 51/4" Winchesters
- up to 4 floppies
- DMA access
- 32 bit ECC code

*To be introduced in 1985. SASI is a trademark of Shugart Associates. Ethernet is a trademark of Xerox Corp.

monoboard microcomputer with cache

- MC68010 (12.5MHz)
- 2 28 PIN sockets
- 4 Kbyte instruction cache (optional)
- 256 Kbyte dual port RAM
- 1 RS-232C debug port
- triple programmable timer
- VMXbus interface
- uses VME 050 system controller

VME 130*

32-bit monoboard microcomputer

- MC68020 (16MHz)
- MC68851 PMMU (optional)
- MC68881 co-processor (optional)
- 2 28 pin sockets
- 512 Kbyte dual port RAM
- VMXbus interface
- uses VME 050 system controller

VME 330

Ethernet™ 2.0 LAN controller

- complete transceiver interface
- MC68000 (10MHz)
- LANCE chip and SIA devices
- 128K dynamic RAM
- 32K EPROM
- 1 RS-232C debug port

Check □ B for information.



Be the envy of your industry.

You, too, can take high-capability advanced systems to market and be the envy of your industry.

The answer lies in the rich resources of Motorola's M68000 Family of high-performance 8-, 16- and 32-bit microprocessors and system peripheral circuits. Chances are, once you design in the M68000 Family and experience the success that follows, you'll be a family friend for good.

The extensive M68000 Family of compatible, easy-to-use MPUs and peripherals is available from Motorola and the most comprehensive complement of contractual alternate sources.

Data Comm, DMA Control, Local Area Network Control, Parallel, Serial and General Purpose I/O, Memory Management, Bus Control and more are available to help you raise your systems above the competition in a hotly competitive marketplace.

Move data fast.

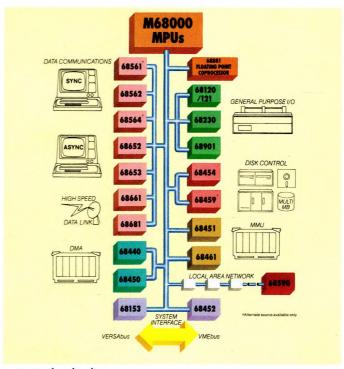
Moving data around fast with minimal intervention from the processor is the province of the 68440 Dual DMA and the 68450 DMA Controller. The two-channel 68440 is capable of 5 Mbyte/sec transfer and the 68450 offers four independent channels and extensive support for the movement of complex data structures.

Links to the outside world.

M68000 Family data communications devices link your system efficiently to the outside world, be it terminal, transmission line or another system, and free the processor for other important work in the process.

One of the most popular data comm devices available is the 68661 Enhanced Programmable Communications Interface. It's a universal synchronous/asynchronous chip that interfaces easily to M68000 MPUs and directly to most 8-bit MPUs. Another important available family communications device is the 68681 Dual UART that provides two completely independent full duplex receiver/transmitter channels.

Extensive flexibility is achieved with the 68652 Multi-Protocol Communications Controller. Basic system functions are contributed by the 68901 Multi-Function Peripheral. Other family data comm functions include Intelligent Peripheral Controllers, Polynomial Generator Checker and Parallel Interface/Timer. Additional 68000-compatible data communications parts are available or



under development at other leading VLSI manufacturers.

Memory management and disk control.

Data-storage device management is the domain of the 68454 Intelligent Multiple Disk Controller. It can control any combination of up to four single- or dual-density floppy and hard disks of various formats. Our 68451 MMU is a seasoned veteran in multi-user, multi-task systems, and now, the requirements of 32-bit demand-paged virtual environments are immediately satisfied by the 68461 Memory Management Controller.

Network and bus control.

The M68000 Family is growing to meet expanding demands in network and bus control. The 68590 is designed to meet all IEEE Ethernet™ specs for M68000 systems, and a new VME Controller will be added as VMEbus becomes a standard.

Floating point.

A companion processor to the 32-bit 68020 MPU is scheduled for introduction soon as well. The 68881 is designed to support the latest revision of the IEEE specification for floating point high-level calculations. It can also be used with the 16-bit M68000 Family processors.

You can see, now, why M68000 Family systems will make you the envy of your industry. You owe it to yourself and your customers to act now. Check □ C for information. Ethernet is a trademark of Xerox Corp.

Think of a DO-41 without leads.

....and you've pictured total flexibility of choice in surface-mount zener diodes.

No one is stronger in zeners than us and you now have easy access to this total capability and sourcing in 1 W surface-mount zeners.

This newest, most sophisticated packaging technology is revolutionizing circuit boards. Cutting cost, increasing density and speeding manufacturing operation, surfacemount is re-shaping boards of the future. And we're leading, not only in zeners but in hundreds of other discrete and IC-packaged types.

We were first with SOTs. And a full line of SOICs. Plus chip carriers.

The MLL4728-4764 zener series ranges from 3.3 to 100 V. Tolerance is 10% for the standard version and 5% for the "A" version. It's available in bulk, or in 12mm tape and reel in both T1 and T2 configurations.

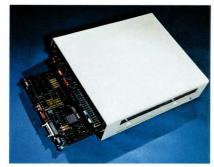
T1 — Cathode facing sprocket holes. T2 — Anode facing sprocket holes.

Even more practical placement is reflected in the pricing: it's comparable to leaded packages.

Think of them as the right stuff for your PCBs and we'll send you a data sheet and new brochure.

Check □ D for information.

Benchmark 20: First to evaluate. First to market.



System integrators thinking about using the new 32-bit MC68020 MPU now have an excellent testbed for system evaluation: Benchmark 20!

This MC68020-based system package provides a variety of hardware and software tools to allow streamlined 32-bit benchmarking, code development and debugging. Packing a lot of power into a small space, the Benchmark 20 system contains a single-board microcomputer with the

MC68020 MPU, plus an auxiliary 1 Megabyte RAM module, all configured with powerful debug/monitor firmware in a 4-slot chassis.

The result? You reduce time-to-market for your new 32-bit system product. Benchmark 20 is configured and ready to use alongside an appropriate software development host to trim your schedule for MC68020 benchmarking and code debugging.

The VM04 VERSAmodule CPU board utilizes the capacity of this new 32-bit performance standard to achieve speeds in the 2-3 million instructions per second (MIPS) category. 4K long words of on-board instruction/data cache reduces off board memory accesses to insure top performance.

The companion VM13 dynamic RAM module provides 1Mbyte of random access memory dual ported with both RAMbus and VERSAbus.

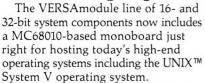
A perfect system mate for the VM04 32-bit monoboard, the VM13 RAM board has error detection and diagnostic capability.

To help you quickly evaluate the MC68020 and the VM04, the Benchmark 20™ system package incorporates the 020bug™ debug/monitor firmware package to allow you to do benchmarking and to debug code. The 020bug resident package allows full speed execution of system and user developed programs operating out of the Benchmark 20 system package. Powerful software and system debug command set allows access to all VM04 I/O, control, and memory facilities plus the full 4 gigabyte direct address range of the VERSAbus system bus.

Benchmark 20, 020bug and VERSAbus are trademarks of Motorola.

Check ☐ E for information.

Turbo-charge operating systems with MC68010 monoboard.



The VM03 monoboard utilizes an MC68010 microprocessor running at 10 MHz combined with an MC68451 memory management unit. Your choice of 256Kbytes or 1024Kbytes of on-board dynamic RAM with parity check assures outstanding local high-speed storage needed for "heavyweight" applications in image processing, artificial intelligence and supervisory control.

The optional 1 Mbyte of on-board memory increases operating system efficiency by allowing larger segments of code and data to be accessed, minimizing off-board activity. This performance benefit pays off in applications such as software development where large operating systems are used. An I/O channel interface is also provided for adding off-board resources in incremental amounts.

The VM03 monoboard is complemented by additional new support modules for high-end system applications.

Used for high speed storage in VERSAbus systems, the VM12 is a 4096Kbyte or 1024Kbyte dynamic RAM module with parity. It attains its capacity options and performance using high density HMOS 256K or



64K dynamic RAM chips. The VM12 supports the full 32-bit address of the M68000 family.

For system applications requiring high-capacity rotating mass storage, the VM22 disk controller supports 4 SMD drives and 4 SA400/800 floppy disk drives. Data transfer speeds up to 3 Mbytes/sec between system memory and hard disk drives and floppy disk drives are maintained by the direct memory access feature of the disk controller.

The VERSAmodule line is supported by both of Motorola's M68000 operating systems: the VERSAdos operating system for real-time appli-

cations, and the SYSTEM V/68 operating system where a UNIX™ operating system environment is desired. Full operating system support, including VERSAdos real-time device drivers, are available now for the MC68010-based VM03 monoboard.

Add to all this Motorola's expertise, proven products, training and service support and you can understand why VERSAmodule system components continue to be your best choice for the highest performance board-level applications.

UNIX is a trademark of AT&T Bell Laboratories. SYSTEM V/68 is a trademark of Motorola. Check \square F for information.





The MCM2833 is a 32K E²PROM, Electrically Erasable Programmable Read Only Memory, that can save time and money in many datahandling applications. And, it operates from a single +5V supply.

Where non-volatile memory and in-system programming are required

One MC1377P RGB encoder generates broadcast color, pure and simple.

Simple things are best, and nowhere is this more true than video color encoding with the unique new MC1377P.

Just one 18-pin DIP does it all. With the addition of only a crystal and a few external resistors you have what used to a boardfull of time- and cost-consuming discretes and/or ICs.

Superior phase linearity and well-controlled color vectors provide the purity of color found only in complex, high-level studio broadcast equipment. And you can design the extraordinary performance features of the monolithic MC1377P into a wide variety of color cameras, graphics computers and teletex generators for about one-tenth the cost of the "maze" approach. A major system simplification leap.

The MC1377 combines red, green and blue video information into a composite signal in either NTSC (U.S.) or PAL (Europe) formats. Used with the MC1374 color-modulated oscillator and a few components to generate a modulated RF carrier, you've actually got a miniature TV station.

Design it with the TDA3300 decoder family and you can separate, modify

the MCM2833 fits perfectly, with in-system erase and reprogram capability that can cut costs and conserve time.

In addition, the MCM2833 derives outstanding data retention and endurance from the technologically advanced Motorola floating-gate

electron tunneling MOS, FETMOS, fabrication. Data integrity is 10 years, and data is protected during power up and power down.

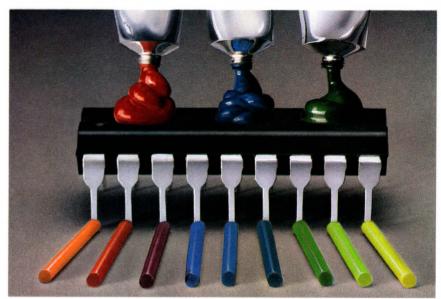
Fast access and low-power operation are characteristic. Maximum standby power dissipation is 35 mA, and max. active P_D is 125 mA. Speeds of 150 and 200 ns are available. Byte erase or write is 9 ms.

A choice of erase modes, bulk, byte, row or column, helps optimize system erase/write time and makes the MCM2833 easier to use. Latched addresses, data and controls create microprocessor-friendly operation, allowing the MPU to work on other jobs while the MCM2833 is erasing or programming.

Not the least of the MCM2833 E²PROM's attractiveness is its relationship as a member of Motorola's industry-standard byte-wide non-volatile memory family, providing opportunities for cost-effective density upgrades.

Engineering samples are available. Check

G for information.



or enhance R, G or B for a rainbow of special effects. Simply, easily, economically.

The MC1377P contains a subcarrier oscillator, voltage controlled 90° phase shifter, two double-sideband modulators, RGB input matrices and blanking level clamps. Its oscillator can be used as the "master" in a system, or it can be driven by an external source. R, G and B inputs are ac-coupled to simplify interfacing. A 1.0 V p-p input level produces full saturation of colors in the output.

The only other input required is a composite sync signal, which is

combined with the encoded video to produce the composite video output. The sync is also used to trigger the generation of color (burst) reference. Both chroma and luma signals are "looped out" of the chip to permit tailoring bandwidth and delay to the designer's taste. This permits very elegant applications as well as very simple ones.

The MC1377P production line is running. Price is in focus too.

Check ☐ H for information.

Floodgates open for VME/10 software.



Industry standard operating systems such as the UNIX™ System V allow greater than ever software portability for users of Motorola's VME/10 OEM Microcomputer system.

Software support within the UNIX™derived SYSTEM V/68 operating system includes 400-plus utilities plus an optional optimizing Pascal compiler, M68000 macroassembler, and facilities to store and update all versions of a source code module.

The SYSTEM V/68 operating system comes with full screen editors and spelling checkers for full screen text processing. The "mm" memorandum macrocommands automatically format standard footnotes; number pages, lists, and paragraphs; and produce headings and footings.

Additional application software availability will grow as agreements between Motorola and Digital Research Inc. bear fruit in coming months. These DRI agreements call for a total of 25 software packages for the M68000 Family in SYSTEM V/68, Concurrent DOS™-68K and CP/M® 68K. Nine of the packages to be developed will be supported under SYSTEM V/68.

Concurrent DOS-68K, which is written in C language, is a multiwith widowing,

LAN support and graphics. It is designed for multiuser or single user microcomputers and includes an IBM PC-DOS[™] mode. This means application programs written in standard high-level languages on the IBM PC can be re-compiled on Concurrent DOS-68K without any modification. DRI is developing a system of com-

Languages to be available on the VME/10

Under CP/M 68K

Digital Research C Pascal MT+ CBasic Compiler

Under Concurrent DOS-68K and SYSTEM V/68:

Digital Research C Pascal MT+ CBasic Compiler FORTRAN 77 **BASIC** Interpreter GSX Graphics Software pilers for a range of machines that operate under SYSTEM V/68. CP/M-68K, Concurrent CP/M and Concurrent DOS-68K.

CP/M is one of the most popular microcomputer operating systems for which hundreds of applications have been written.

Application programs written in any of the covered languages -Pascal, FORTRAN, C, BASIC and PL/I – should then run on any computer in the M68000 Family under CP/M-68K, Concurrent DOS-68K or SYSTEM V/68.

UNIX is a trademark of AT&T Bell Laboratories. CP/M is a registered trademark of Digital Research Inc.

Concurrent DOS is a trademark of Digital Research Inc.

IBM PC and PC-DOS are trademarks of IBM.

Check □ L for information.

Sharpen Macrocell Array design skills.

Two new Macrocell Array design manuals are now available from Motorola to assist you in understanding and easily generating optimized semi-custom ECL application specific ICs.

The MCA2500ECL Macrocell Array Design Manual is all new. It covers just about everything a trained MCA designer needs to carry out the design. There's a review of the Macrocell Array concept and technology, and a run-down of MCA features supplemented by an explanation of cell

Logic design considerations and performance guidelines are examined in detail. CAD layout, array option development and various hardware subjects are reviewed. A large section is devoted to the Macrocell Library and MCA2500ECL specification plus individual cell descriptions.

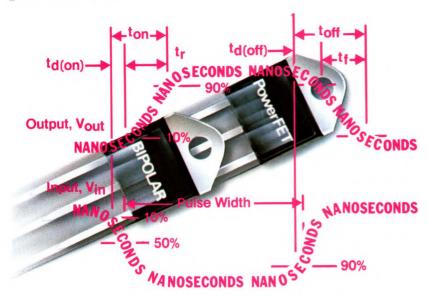
Order the MCA2500ECL Design Manual as BR165.

MCA600ECL and MCA1200 ECL are Macrocell Arrays similarly served by the eagerly awaited revised design manual, BR107/D R1. This is an updated replacement for a preliminary

Both of these Macrocell Array design manuals are available at modest cost. Please contact the appropriate Motorola sales office for prices and ordering information.



Fastest, highest-voltage bipolar pushes powerFETs.



It may not quite catch them, but it's so close you can virtually ignore the difference in speed.

The complete new MJH16000 series of 850 to 1,500 V Switchmode III bipolar power devices switches big loads in nanoseconds — about 10 times faster than other bipolars — just like power MOSFETs, without sacrificing ruggedness.

Ideally suited for high-frequency inductive switching where high-temperature RBSOA is a major concern, these 5, 8 and 15 A units feature a higher periphery-to-area ratio and hollow emitter structuring to give the designer a needed edge in ruggedness and speed and improve design efficiency and compactness.

The TO-218 packaged units are suitable for both U.S. and European power supply designs. Unique lead-spacing and package dimension features allow regulatory agency approval in both domains enabling you to design one supply accepted for both markets.

Use the 450 V units for line-operated half-bridge, full-bridge and push-pull configurations and the higher-voltage types for single transistor flyback and forward converter topologies.

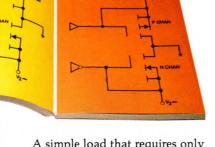
Additionally-packaged in TO-204 (TO-3), the series is molehill priced for mountains of performance.

Check ☐ M for information.

P-Channel powerFETs add new chapter to drive circuit applications.

When you want to cut power supply or charge pump requirements to your power MOSFET in bridge cascode or push-pull applications, go Motorola P-Channel.

This extension of the MTM/ MTP8PO8, -2P45 family is available from Motorola to make your design job simpler and more cost-effective.



A simple load that requires only one-side grounding to a negative bus can easily be switched with P-Channel technology eliminating extra, expensive componentry. V₃, which biases gate above source to hold the MOSFET on, is no longer necessary.

Schottkys extend efficiency to 12 V.

The world's best Schottky rectifier process introduces an expanded Schottky rectifier voltage — 60 V.

You now have the option of designing 12 V supplies with Motorola devices to improve efficiency and reduce recovery noise associated with other rectifier types.

Packaged in TO-220, the 10 A MBR1060 Schottky offers 0.7 V_F and less than 6% power loss, or 94% efficiency, at 120 W P_O . Ordinarily, you'd lose twice that with a slower rectifier, up to now your only choice for higher output power applications.

With the MBR1060, you gain the same advantages for 12 V supplies as you've enjoyed with Schottkys in 5 V supplies.

Cool by nature, calm by comparison, Motorola's broad TO-220 Schottkys exhibit lowest correlation of temperature rise vs. forward drop of any other types. You gain more, lose less with Motorola....up to 175°C operating temperature.

Add a guaranteed avalanche surge, built-in PN guard rings, freedom from trace anomalies and virtually perfect working barrier processes and you've got the highest quality going in nanosecond rectification.

Discipline power with efficiency: Motorola Schottkys.

Check \square N for information.

The new nanosecond-switching series is fabricated utilizing the same N-Channel TMOS^M III process that results in optimized cell density and cost factors. It's the best silicon utilization process in the industry and offers you the ultimate design advantage: price.

There's no sacrifice in reliability or performance. AOQ levels measure out at less than 100 ppm, guaranteed. And $r_{DS(on)}$ as low as 0.1Ω is available for very high efficiency operation.

Prices for the 50 to 500 V, 2 to 25 A family are low in hermetic, TO-204, (TO-3) or low-cost TO-218 and TO-220 plastic packaging.

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Check □ P for information.

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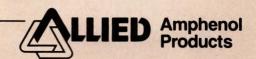
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Plastic-fiber-based optical links offer low-cost, short-haul data transfer

Tom Ormond, Senior Editor

Cost has been the barrier to using fiber-optic links in low-data-rate, short-haul applications of less than 5M baud and 300 ft. New fiber-optic links made of plastic (acrylic) fiber, however, provide a cost-effective alternative to coaxial cable and twisted-wire pairs in such applications. These large-core fibers-approximately 1000 µm-don't require the tight alignment tolerances needed in glass- or plastic-clad silica fibers for reasonable light coupling at the source and detector interfaces. Looser alignment tolerances also let manufacturers package transmitters and receivers in plastic housings, thus lowering component

In addition, plastic-fiber-based optical links are not affected by (nor do they emit) EMI or RFI. The fiber is nonconductive, so there's no operational problem in explosive atmospheres. Optical systems also provide a high degree of data-transmission security because the fiber is difficult to tap.

Acrylic fiber is also user friendly. Although most link manufacturers offer ready-to-go systems, you can buy the cable yourself. You'll find the cable-termination process quite simple, and it requires no special tools or expertise. You can cut the fiber with a razor blade, for example, and polishing requirements are minimal. Acrylic fiber is available from DuPont (Wilmington, DE) and Nissho-Iwai (Los Angeles, CA).

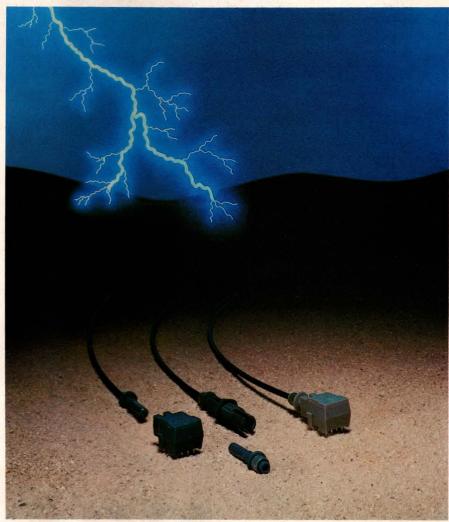
The fiber has one additional advantage: Although plastic fiber is lossy, it has a relatively low attenuation window, around 650 nm. Most link systems operate at this wavelength, and the visible-light transmissions make system troubleshoot-

ing easy: There's no optical mystique involved.

Because the fibers available from DuPont and Nissho-Iwai have similar transmission characteristics, most link manufacturers spec their systems to accommodate either one. As a result, gross link-performance specs are similar. However, there are some subtle differences in datarate and distance capabilities, and there are some not-so-subtle differences in price. An examination of current data-link offerings shows

how they measure up in these categories.

Hewlett-Packard's Snap-In optical-link line includes three transmitters (HFBR-1510, -1502, and -1512), three receivers (HFBR-2501, -2502, and -2503), simplex and duplex fiber cables in lengths of 500 to 999m (HFBR-3510 simplex costs \$0.75/m; HFBR-3610 duplex is \$1.50/m), and connectors—\$0.40 (100). When you combine the -2503 with the -1512 transmitter (with 60-mA drive current), you'll have a link that accom-



You can realize 60m transmissions at data rates to 40k baud using the transmitter/receiver components available in Hewlett-Packard's Snap-In data-link line. Over shorter distances, link components will accommodate 5M-baud (12m) and 1M-baud (24m) data rates.

Design in performance with HP's family of fiber optic components.

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What's more, HP specifies and guarantees the performance of each fiber optic component so you know what to expect every time. Our fiber optic components are easy to use, cost-

effective and provide consistent and reliable performance.

HFBR-0500 Series Plastic Snap-In Link components.

Data rates to 5 Mbaud, distances to 60 metres and low cost make this family ideal for connecting computers to peripherals and for industrial control applications. HP's Snap-In links use rugged, 1-millimetre diameter plastic fiber and have connectors that are quick and easy to attach. Introduce yourself to the advantages of this easy-to-use, low-cost family. Try



HP offers three families of products to give you solutions for a variety of distance and data rate applications.

HP's HFBR-0500 Snap-In Link evaluation kit.

HFBR-0200 Series Miniature Link components.

This family provides costeffective solutions for LANs, and computer-to-peripheral connections. The optical port design provides precision optical coupling to small diameter glass fibers. This family achieves data rates of up to 100 Mbaud. Evaluate the performance of this family with the HFBR-0200 kit.

HFBR-0010 Series High Performance modules.

This family offers transparent TTL-TTL communication independent of data format at data rates

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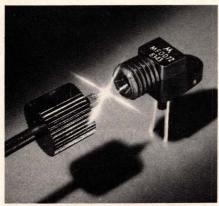
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HP: The right choices for performance in fiber optics.



TECHNOLOGY UPDATE



Significant cost reductions in Motorola's FLCS line are made possible through a combination of an all-plastic packaging system and a permanently affixed, pc-board-mountable interconnect receptacle that eases assembly.

modates 40k-baud data rates over 60m max transmission distances. You can operate this same combination with only 2 mA of transmitter drive current and realize an 8m link.

The -1512 transmitter module—\$8.10 (100)—incorporates a 665-nm LED and is easily interfaced to standard TTL devices. With a 60-mA drive current, guaranteed output power (measured at the end of a 0.5m cable) ranges from -11.2 to -5.4 dBm at 25°C and -13.6 to -4.5 dBm over 0 to 70°C. Rise and fall times (10 to 90%) spec at 50 nsec.

The -2503 receiver module—\$11.05 (100)—has a -39-dBm sensitivity spec. It features an integrated photodetector and dc amplifier for high EMI immunity. The output is an open collector with a 150-µA internal-current-source pull-up resistor and is compatible with TTL/LSTTL and most CMOS families. For minimum rise time, you should add an external pull-up resistor of at least 3.3k—V_{CC} must be greater than or equal to the supply voltage for the pull-up resistor.

Depending on the transmitter/receiver combination, you can develop 5M-baud/12m and 1M-baud/24m links with the other modules in the Snap-In line. All the active devices are housed in plastic DIPs and feature single 5V operation. For all link

combinations, bit-error rate (BER) specs at 10^{-9} .

Interoptics' 100 (simplex) and 200 (duplex) Series data links provide a 50m max transmission capability. The 100 Series consists of the OPTO101 transmitter (driver plus a 660-nm LED) and the OPTO102 receiver (photo diode and a receiver IC) for \$14.37 each. The 200 Series transceiver (\$27.47) incorporates both the LED/receiver IC and the photo diode/driver IC in one package (OPTO212). Data rates for either link range to 1.5M bps RZ and 3M bps for NRZ; BER measures 10⁻⁹.

Power coupled to the fiber at the transmitter output ranges from -15 to -10 dBm. Typical minimum and maximum receivable power levels are -30 and -13 dBm, respectively. The modules are designed for pc-board mounting, feature single-supply operation (7V max), and operate over 0 to 70°C.

The plastic-fiber cable—\$1/m (10m)—has a 0.5 numerical aperture (NA), 60-MHz bandwidth, 7-nsec/m max propagation delay time, and 0.4-dB/m attenuation at 660 nm. You install the connector with a crimping tool, so epoxying and extensive polishing are not required. The connectors, which cost \$6.26 (25) and \$10.62 for simplex and du-

plex types, respectively, have a coupling key to prevent reversedirection coupling.

The user doesn't need to know fiber-optic technology with this link design because the input and output signals are at TTL levels and require no special coding. An automatic threshold-control circuit assures constant pulse width regardless of optical power fluctuations.

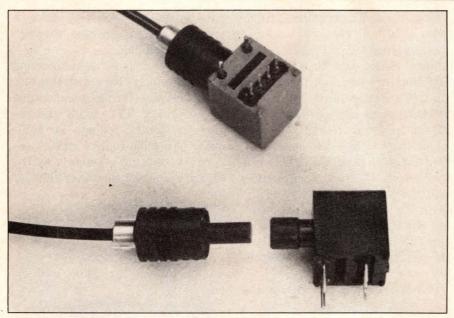


Handling analog or digital signals, Molex's fiber-optic-link components are sealed against dust and moisture. The systems transmit 40-kHz analog or 10k-baud squarewave signals over 60m.



Plug-to-plug compatible with RS-232C connectors, the FO-232E from Lightwave Communications offers an inexpensive way to get complete EMI/RFI immunity when interconnecting terminals, printers, and other peripherals with computers.

TECHNOLOGY UPDATE



Available in simplex and duplex versions, optical links from Interoptics accommodate dc to 3M-baud data rates and feature a 50m transmission capability.

Motorola recently introduced its Fiber Optics Low Cost System (FLCS), which consists of a GaAlAs infrared emitter and three detector configurations. Although the system provides high performance with greater than 10-MHz bandwidth, the design concept is simple. System application doesn't require you to have experience with fiber-optic technology.

The \$1.30 (100) MFOE71 emitter has an 820-nm peak wavelength and features a molded lens to maximize coupling efficiency. Typical launched power is 165 µW (110 µW min); optical rise and fall time measures 25 nsec.

A PIN photodiode, the MFOD71 detector costs \$0.98 (100). It has a spectral response that's matched to the MFOE71 LED, and it also features a molded lens for efficient light coupling. Dark current specs at 0.06 nA and responsivity and response time measure 0.2 µA/µW and 1 nsec, respectively. Total capacitance is 3 pF. The MFOD72— \$0.87 (100)—is a phototransistor detector. The maximum dark current is 100 nA, and the minimum collector-to-emitter breakdown voltage specs at 30V. Typical responsivity measures 125 µA/µW, and turn-on

and turn-off times are 10 and 60 μ sec, respectively. The \$0.98 (100) MFOD73 photo-Darlington detector features dark current and breakdown voltage of 100 nA max and 60V min, respectively. Typical responsivity measures 10 mA/ μ W, and turn-on and -off times are 125 and 150 μ sec, respectively.

Typical transmission distances, with 100-mA drive current through the emitter, extend to 32m for the MFOD73, 17m for the MFOD72, and 10m for the MFOD71. Each emitter/detector configuration pro-

vides trouble-free performance at the maximum specified cable lengths.

The FLCS package includes all necessary components: active device, connector, locking nut, and mounting (pc-board) flange. You don't need special tools or procedures to terminate either DuPont's or Nissho-Iwai's cable. You cut the fiber with a sharp blade or hot knife and use an 18-gauge wire stripper to expose 0.10- to 0.18-in. of bare fiber core. Then insert the prepared cable through the locking nut and into the connector on the module housing until the core tip butts against the molded lens inside the package. You tighten the locking nut to lock the cable firmly in place.

Aborn Electronics also offers a short-distance, low-cost link. The AFL 1000 uses AMP's DNP snap-in connector system to provide an easy-to-terminate, easy-to-use fiber-optic link. Available in both simplex and duplex versions, it accommodates dc to 5M-baud data rates and has a 22m maximum transmission distance. Housed in low-cost plastic DIPs, the transmitter and receiver require single 5V supplies and operate over 0 to 70°C.

Each link (\$18 for a 5m version) contains an LED transmitter with a 665-nm peak output wavelength and a Schmitt trigger receiver with an

For more information . . .

For more information on the fiber-optic-link products discussed in this article, contact the following manufacturers directly or circle the appropriate numbers on the Information Retrieval Service card.

Aborn Electronics 3675 Enochs St Santa Clara, CA 95051 (408) 746-0505 Circle No 740

Hewlett-Packard Co 640 Page Mill Rd Palo Alto, CA 94304 Phone local sales office Circle No 741

Interoptics 770 Airport Blvd Burlingame, CA 94010 (415) 347-7727 Circle No 742 Lightwave Communications Inc 650 Danbury Rd Ridgefield, CT 06877 (203) 438-3591 Circle No 743

Molex Inc 2222 Wellington Ct Lisle, IL 60532 (312) 969-4550 Circle No 744

Motorola Semiconductor Products Inc Box 20912 Phoenix, AZ 85036 (602) 244-4912 Circle No 745

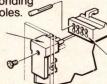
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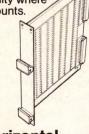
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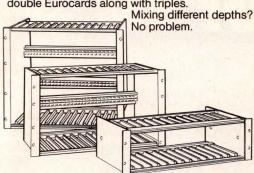
1984

9U KM6. Flexibility in Packaging Triple High Eurocards

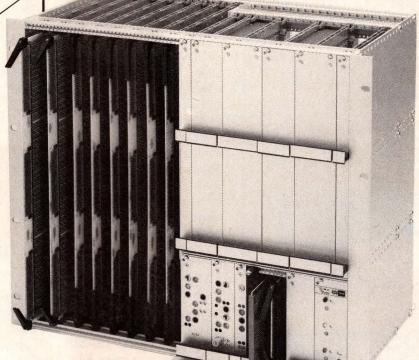
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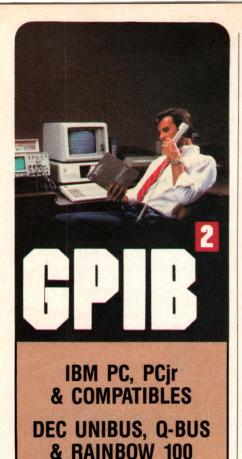




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TECHNOLOGY UPDATE

open-collector, LSTTL/TTL-compatible output. An external resistor lets you adjust receiver sensitivity (threshold). The receiver will drive eight TTL loads. Propagation delay is 140 nsec max.

Digital or analog applications

Molex specifies end-to-end electronic performance of its links so you don't have to worry about fiberoptic technology. The firm's initial TTL-compatible offering handles 40-kHz analog signals or 10k-baud square waves. Transmission capabilities range to 60m.

A proprietary connector design integrates the alignment mechanism into the optoelectronic devices and the outer jacket of the acrylic cable. The device-to-fiber interface is sealed and uses a lens to conserve optical power.

The firm offers simplex and duplex configurations. The simplex system's optoelectronic devices can be wave soldered into a pc board and then covered with a rugged cable-retention housing. The duplex system is built into a connector housing and is interfaced to external electronics through a standard Molex 7990 connector. Transmitters and receivers require 5V supplies and operate over -30 to $+80^{\circ}$ C. System BER specs at 10^{-9} .

Molex offers kits (simplex, \$30; duplex, \$60) to help you evaluate link performance. Each kit contains a transmitter, a receiver, a 3m terminated cable assembly, and a pc board that contains the electronic interface circuitry.

Providing dedicated service

The \$90 FO-232E from Light-wave Communications is a full-duplex optical modem that transmits asynchronous data. It's plug-to-plug compatible with RS-232C 25-pin connectors that meet EIA RS-232C and CCITT V.24 specs. Developed to let you interconnect terminals, printers, and other peripherals to computer equipment, the FO-232E offers a simple, inexpensive solution

to maintaining data integrity in hazardous environments, plus complete immunity to EMI/RFI, without sacrificing speed.

Housed in a 0.625×2.125×2.75in. package, the modem can transmit data over 250-ft distances at 19.2k bps. Available in both DTE and DCE versions, it specs a 10⁻⁹ BER. Operating range spans 0 to 50°C, and power requirements are 12V dc at 100 mA. Source and detector functions are provided by LED and PIN photodiodes, respectively. Receive sensitivity measures 50 nW.

Standard models feature SMAtype fiber connectors; AMP Optimate devices are optional. The electrical interface employs a male 25-pin D-subminiature connector, but female units are also available. You can also order preterminated cable assemblies.

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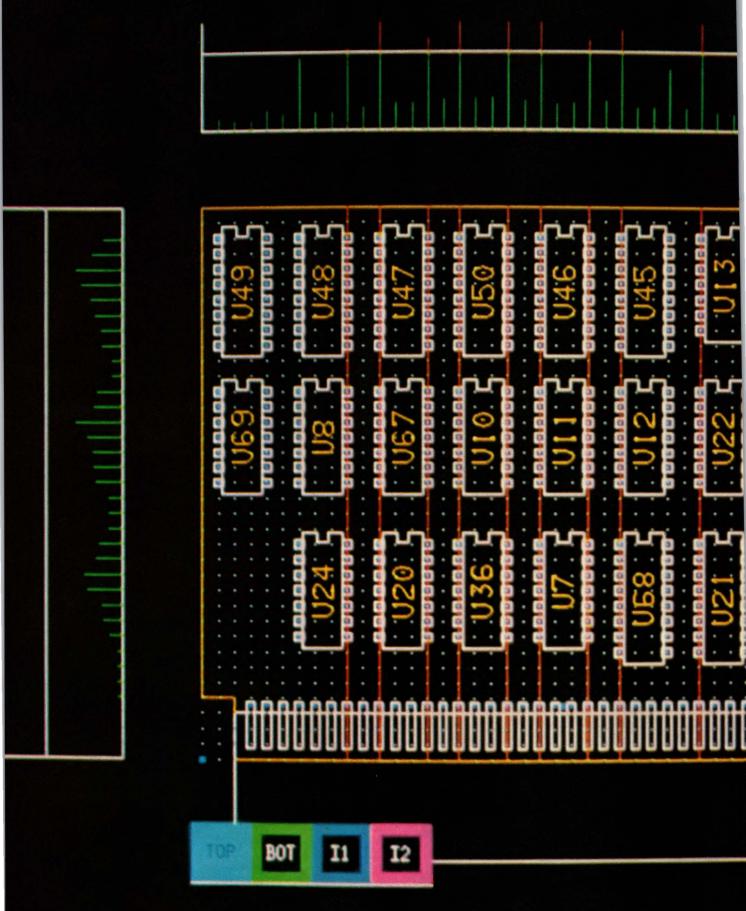
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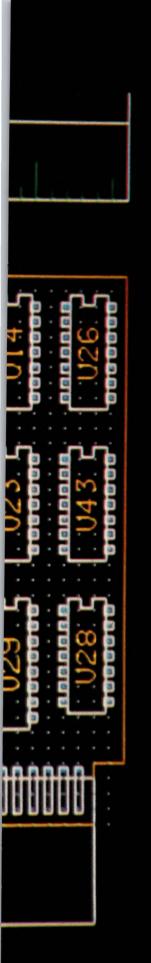
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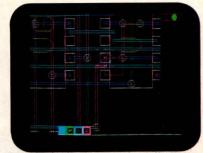
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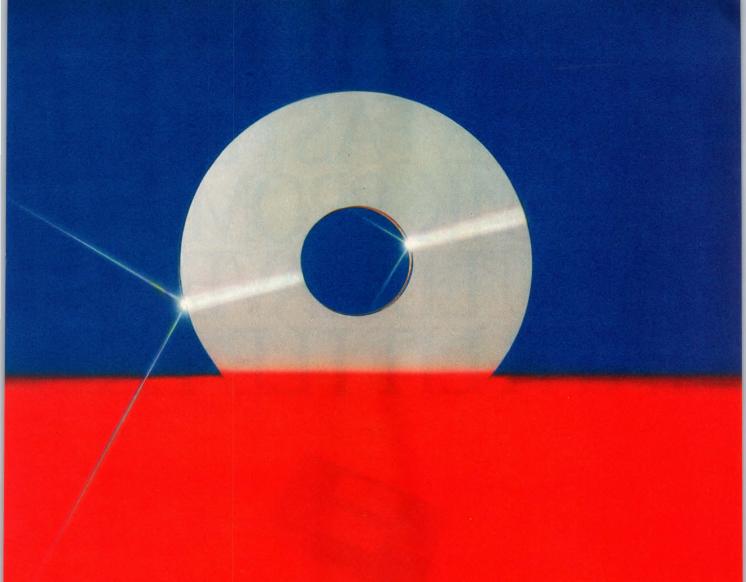
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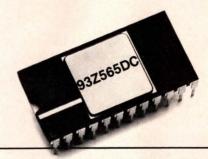
In fact, every disc we ship has survived a quality assurance program so stringent it's unparalleled in the industry. With ten major process control checks during manufacturing. We test and retest. From substrate to finished product. Then we test our tests. So you don't have to.

It takes experience to make quality thin film discs. We have more. Today, with over one million discs working in over 300,000 systems. And a \$30 million commitment to produce the volume to meet tomorrow's demand. So ride on our shoulders. We've made a name in magnetic media that's as good as gold. Ampex. Disc Media Operations, 960 Rincon Circle, San Jose CA 95131

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IF YOU WANT THE FASTEST 64K PROM, YOU'LL HAVE TO PAYA LITTLE LESS.



	Max. TAA Commercial	Max. TAA Military	Max.
64K (8Kx8)			
93Z565	55 ns	65 ns	180 mA
93Z565A	45 ns	55 ns	180 mA
16K (2Kx8)			
93Z511	45 ns	55 ns	175 mA
8K (1Kx8)			
93Z451	40 ns	55 ns	135 mA
93Z451A	35 ns	45 ns	135 mA

Available in 24-pin dual-in-line and 28-pin leadless chip carrie 8K and 16K also available in 24-pin flatpak and 300 mil DIP.

The Fairchild 93Z565A. One of the first 64K PROMs on the market and still the fastest. Giving you access time of 45 ns.

But that's not all.

Since we've been making them for over two years, we also know how to make them more cost-effective for your application. Which means you can confidently design with our 64K now and realize a lower cost-per-bit at the system level. And you'll find one 64K to be significantly more efficient than several 8K, 16K or 32K devices.

If you have an application requiring

MEMORY AND HIGH SPEED LOGIC

From Puyallup, WA.



A Schlumberger Company

high speed at a lower density, we have a 16K PROM at 45 ns and an 8K PROM at 35 ns. Both in space-saving 300 mil DIPs.

It all adds up to the fastest PROM family ever built. PROMs that use Fairchild's Isoplanar-Z™ technology. With vertical fuse technology giving you one of the highest programming yields in the industry.

Our family of high-speed, low-cost PROMs is available now. For more information, contact our local sales office or your nearest authorized Fairchild distributor today.

Fairchild Memory and High Speed Logic Division, 33309 1st Way South, Federal Way, WA 98063-9701

Isoplanar-Z is a trademark of Fairchild Camera and Instrument Corporation.





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They demand rugged bodies, super sealing, low insertion loss, precise alignment, repeatability, field termination and simplicity. The ultimate in performance.

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HUGHES

CIRCLE NO 31

Analyzer packs waveform, spectrum, and network analysis in one box

Integrated measurement tools are not unusual; however, finding one aimed at analog-circuit design is. Model 3562A dynamic signal analyzer combines a waveform recorder, spectrum analyzer, and network analyzer in a benchtop instrument that analyzes signals from near dc to 100 kHz. It doesn't stop at data collection but also does extensive data and design-parameter manipulation and display as well.

The signal analyzer itself is a dual-channel, fast Fourier transform (FFT) analyzer. Its two channels are closely matched to a ± 0.1 dB and $\pm 0.5^{\circ}$ frequency- and phaseresponse accuracy. They feed the incoming signals to two 13-bit analog/digital converters that have 80 dB of dynamic range, 10 dB better than previously available.

As a waveform recorder, the 3562A digitizes waveforms containing frequencies to 100 kHz with complete antialias protection. Each recording is 2k words long, and the instrument stores as many as 10 recordings internally. For subsequent time-domain or frequency-domain analysis, you can recall either a single time-domain record at a time or a concatenated display of as many as 10 records. The 3562A directly controls external disk drives (IEEE-488 compatible) and stores as many as 32,000 records per recording session without needing an IEEE-488 controller.

As a dual-channel spectrum analyzer, the unit achieves 25.6-µHz resolution anywhere within its 64-µHz to 100-kHz measurement range. Because it is a dual-channel unit, you can display the full 100-kHz spectrum on one channel and a magnified or "zoom" spectrum on the other for more detailed analysis. Or you can display both time and frequency traces simultaneously.



You can store as many as 32,000 recordings on disk during a single analysis session when using Model 3562A. It can extract design parameters like the open-loop or impulse response from measured data. It also serves as a design tool by accepting design parameters like pole and zero locations and generating displays like Bode plots from them.

Single-channel accuracy is ±0.15 dB with 80 dB of dynamic range. You can resolve 0.001 dB using the single-point harmonic and sideband markers. You can also do modulation analysis and demodulate AM, FM, or PM signals having carrier frequencies to 99.9 kHz.

In its role as a network analyzer, the instrument brings into play its built-in signal source. The source generates either random noise for nonlinear device testing or sine waves for linear devices. Both types of input signals are band-limited and band-translated to reduce out-of-band effects.

The instrument has three modes for frequency-response measurements: linear-resolution FFT, logarithmic resolution FFT, or true swept-sine. With the linear-resolution FFT technique, the 2k-word time records get transformed into 801-line frequency spectra. Frequency-response magnitude and phase as well as input and output power spectra get measured with 801 lines of resolution to accuracies of ± 0.1 dB and $\pm 0.5^{\circ}$ over an 80-dB dynamic range. For display of re-

sponse over two to five decades of frequency, the logarithmic-resolution FFT mode combines the linear resolution points to create 80-point/decade measurements.

To allow the instrument to function as a true swept-sine frequency-response analyzer, the source makes programmable linear or logarithmic sweeps with increasing or decreasing frequencies. An autoranging sweep function makes it possible to test active devices with more than 130 dB of dynamic range.

The computational capabilities of the 3562A are extensive. For example, you can first model the expected response of your system on the instrument before you test it. The HP 3562A will accept a system description in a pole/zero, pole/residue, or ratio-of-polynomials format and generate a display of magnitude and phase over a specified frequency span. Or you can work backwards and extract as many as 40 poles and 40 zeros from your measured frequency-response data.

Also, the built-in waveform math lets you manipulate entire blocks of data. For instance, you can convert closed-loop measurements to open-loop responses for stability analysis. Or you can use the inverse FFT function to derive the impulse response of a system from measured data.

In addition, a number of application-specific programs are provided by the manufacturer as well as by third-party vendors for structural-vibration analysis, acoustic-intensity measurements, and rotating-machinery analysis. Prices start at \$22,500. Delivery, 16 wks ARO.

-Chris Everett

Hewlett-Packard Co, 1820 Embarcadero Rd, Palo Alto, CA 94303. Phone local office.

Circle No 716



shelf. The answer shouldn't either.

It's problem-solving flexibility that brings all the major manufacturers to Chabin Corporation. Besides understanding high-speed, high-frequency data transmission and the associated problems of signal fidelity and high-density packaging,

we know how to anticipate, adapt, and move quickly in an ever-changing industry. Equally important, we're small enough to give your problem the personal attention it requires, but large enough to meet sophisticated production demands.

the design engineer. We're consultants. Supplying technical information when you need answers. We're innovators. Charting new courses in design, electrical, and packaging engineering, just like you. We're manufacturers. Offering a state-of-the-art tooling, testing, and production facility, all

in one. But more than anything else, we're people. A team of professionals who believe interconnects are more than just wire, cable, and connectors.

In the many years Chabin has been in

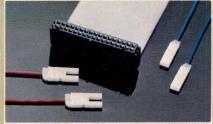
noise problems and prevented many potential disasters. In the process, we've perfected the most flexible concept in cable/connector design available to the design engineer. One that will lead you to think in terms not of limitations but of possibilities. That concept is the Transmission Line Assembly (TLA™).

Chabin's TLA™: Functionally designed, gracefully executed.

The TLA™ is no run-of-the-mill cable assembly intended for just any application. It was developed expressly to meet the complex demands of high-speed logic data transmissions, and now to tackle the uncompromising signal-purity requirements

DESIGN FLEXIBILITY.





of the electronics industry.

And Chabin's compact, elegant packaging solutions makes our TLA™ the ideal choice for any application requiring high-density cabling within strict space limitations.

Chabin's TLAs are available in "standard" configurations which can be easily adapted to your single or multiple signal applications. And because our connectors are designed to accept a wide range of cable types, we gain the flexibility to choose the perfect cabling to meet your electrical requirements and mate it to the ideal connectors to meet your mechanical requirements.

It's Chabin's design flexibility that will help you meet the rising challenge of higher speed and smaller size in advanced circuit technology. So bring us your toughest cabling requirements. We'll develop solutions — before you face even the first problem.

CIRCLE NO 32

*TLAs are a family of cable assemblies value engineered to address the needs of high-speed ditigal electronics. Impedance-controlled cabling with a high velocity of propagation is used to minimize waveform distortions. The connectors are intricately designed to allow for high-signal density and molded onto the cable to guarantee reliability.

Chabin Corporation 890 Fortress Street, Dept. E Chico, California 95926

916/891-6410



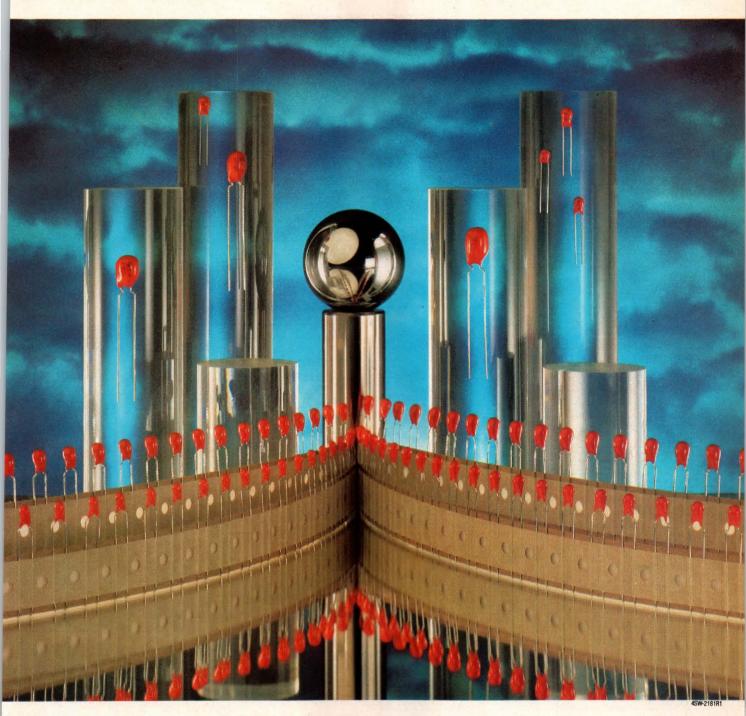
PREVENTIVE DESIGN FOR THE PROGRESSIVE ENGINEER.

*TLA is a registered trademark of Chabin Corporation



CIRCLE NO 33

CHOICE.



SPRAGUE
The choice is Sprague for solid tantalum capacitors! Sprague Type 199D
Epoxy-Coated Solid Tantalum Capacitors, the first of their kind, are now better than
ever...lower leakage current...higher operating temperature to +125°C with
voltage derating...new smaller sizes. Four lead styles to meet your needs...
also taped and reeled for low-cost automatic insertion on printed wiring boards. All
delivered on time at competitive prices. Write for Engineering Bulletin 3547C
to Sprague Electric Company, 491 Marshall St., North Adams, Mass. 01247.

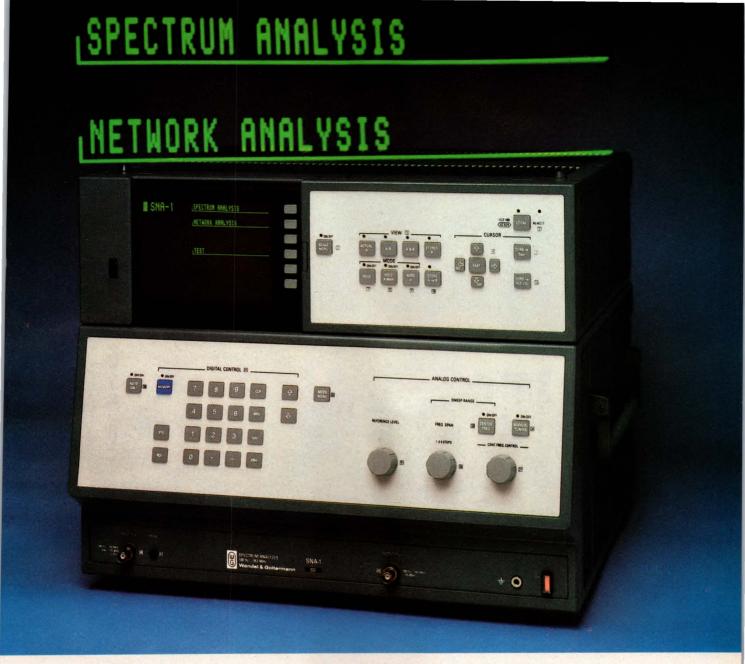
LEADTIME INDEX

Percent of respondents

1 41 M			1		0	9	Mo	
OHI	1	6.10	1,2	27.3	Net 35		THE STATE	
OH IN	SIL	Sweeks	11.20 Teeks	Th.30 weeks	Ouet 30 mens	Nee No	12.2	010
ITEM	all.	20	3	3	3	3	15 00 1	600
TRANSFORMERS	Marine S	27	33	20	7	12	12.2	110
Toroidal Pot-Core	9	18	9	28	18	18	15.8	12.5
Laminate (power)	_	18	46	12	6	18	13.1	
CONNECTORS		1		-		,,,		7
Military panel		9	35	28		28	16.1	14.9
Flat/Cable	11	47	26	5		11	7.2	6.5
Multi-pin circular		30	40	10	_	20	11.6	
PC	_	46	31	8		15	9.3	6.6
RF/Coxial		42	24	17		17	10.8	8.5
Socket	20	55	15	_	_	10	5.4	5.9
Terminal blocks	4	52	26	9		9	7.4	5.7
Edge card	6	62	13	6	-	13	7.3	7.0
Subminiature	8	50	25	_		17	8.3	8.3
Rack & panel	_	55	18	9	-	18	9.6	8.4
Power	13	26	36	-		25	11.2	5.7
PRINTED CIRCUIT E	BOA	RDS						
Single sided	-	29	42	29	-	_	8.6	8.1
Double sided	_	25	50	25	_	_	8.5	9.0
Multi-layer	_	_	33	67	-	-	13.4	14.4
Prototype	_	61	17	22	_	-	6.1	3.6
RESISTORS								
Carbon film	38	31	15	12	4	_	4.8	3.6
Carbon composition	13	25	37	21	4	-	7.9	5.7
Metal film	18	25	43	14	-	_	6.2	5.0
Metal oxide	11	37	26	26	_	-	7.0	3.8
Wirewound	-	17	54	29	_	-	9.3	7.5
Potentiometers	_	41	37	22	-	-	7.3	8.5
Networks	_	29	32	29	5	5	10.6	7.6
FUSES								
	48	29	18	5	_	-	2.8	2.5
SWITCHES								
Pushbutton	26	21	32	16	5	-	6.8	6.9
Rotary	6	41	35	18	_	-	Total Control of the	10.0
Rocker	_	50	20	30	_	-	7.4	6.6
Thumbwheel	9	18	18	55	-	-	11.0	9.8
Snap action	_	36	28	36		-	8.7	7.7
Momentary	-	33	42	25	_	-	8.0	7.2
Dual-in-line		62	13	25	-	-	6.3	6.9
WIRE AND CABLE								
Coaxial	11	50	22	11	6	-	6.1	5.9
Flat ribbon	20	45	25	5	5	-	5.0	5.2
Multiconductor	.—	31	50	13	6	-	8.3	5.7
Hookup	46	29	17	4	4	_	3.6	3.6
Wirewrap	36	29	14	14	7	-	5.8	3.1
Power cords	17	38	33	6	6	-	5.9	4.6
Other	_	20	40	20	20	_	12.0	4.7
POWER SUPPLIES								
L'AMBRED PRESENTA	0	13	42	37	4	4	11.8	11.2
CIRCUIT BREAKERS	S							
	11	16	28	39	6	-	10.4	9.4
HEAT SINKS		(X.)						

							A. J. M. R.			
					Out So Had to de la contraction de la contractio					
ITEM	,	6.7	11.20 Weeks	Tr.30 weeks	Let 3		MINS			
18		5 weeks	204	40 4		20 1	No W	101		
ITEM	20/	ex.	eks.	exs	ex5	ex.	OF SE	400		
							9	-		
RELAYS General purpose	28	22	17	33			7.1	6.		
PC board	6	22	33	39			9.3			
Dry reed	_	29	29	42	_	_	9.6	_		
Mercury		14	57	29	_	_	9.5	16.		
Solid state		20	50	20	10	-	10.2	10.		
DISCRETE SEMICON	NDU	CTOR	S							
Diode	13	30	27	10	20	_	9.6	9.		
Rectifier	_	31	31	6	26	6	12.7	8.		
Thyristor	_	37	37	14	6	6	9.4	10.		
FET	_	21	40	27	6	6		11.		
Zeners	5	30	39	13	5	8	9.6	8.		
INTEGRATED CIRCL	JITS	, DIG	ITAL		-					
CMOS	_	4	12	36	32	16	20.1	-		
TTL	_	6	11	39	22	22	19.8			
LS	4	4	4	54	17	17	18.7	17.		
INTEGRATED CIRCL	JITS	, LINI		icura						
Communication/Circuit	_	_	20	54	13	13	17.7			
OP amplifier	6	17	22	44	_	11	12.6			
Voltage regulator		19	24	33	10	14	14.5	12.		
MEMORY CIRCUITS		1 1	6	4						
RAM 16K RAM 64K	-	-	37	25	25	13	17.5			
RAM 256K	17	8	23 33	23	33	15	16.3	19.		
ROM/PROM	17		25	42	8	8	13.3	16		
EPROM	12		29	35	12	12	14.8	-		
EEPROM	_	_	50	40	_	_	10.4			
DISPLAYS		- VV								
Panel meters	8	42	25	17	8	_	7.6	9.		
Fluorescent	13	25	25	25	12	_	9.6	9.		
Incandescent	13	13	36	25	13	_	10.5	6.		
LED	6	6	52	18	18	_	11.8	7.		
Liquid crystal	_	25	34	25	8	8	11.8	13.		
MICROPROCESSOR	ICs	7.			1	N. P				
8-bit	17	6	11	33	22	11	15.4	_		
16-bit	_	10	10	40	30	10	18.3	_		
FUNCTION PACKAG	ES									
Amplifier	-	_	55	27	9	9	13.9	10.		
Converter, analog to digital			33	45	11	11	16.1	12.		
Converter, digital to analog	10	-	40	30	10	10	13.7	10.		
LINE FILTERS										
	10	10	40	30	-	10	11.3	9.		
CAPACITORS										
Ceramic	8	29	42	17	-	4	7.9	7.		
Ceramic monolithic		33	33	22	6	6	10.2	9.		
Ceramic disc	17	33	33	11	-	6	6.9	6.		
Film	_	39	39	14	-	8	8.6	7.		
Electrolytic	8	34	25	25	4	4	9.0	9.		
Tantalum	5	35	35	20	-	5	8.3	10.		
INDUCTORS			E0.	20	Taxabana a		14.0			
	-	-	50	33	100	17	14.6	11.		

Source: Purchasing magazine's electronic business survey



Spectrum <u>and</u> Network Analysis Simpler and greater accuracy, at last!

Precision, even with simpler operation? The SNA-1 Spectrum and Network Analyzer, 100 Hz to 180 MHz, offers both at the optimum.

Simple operation:

For overview measurements, the "analog" settings with three knobs for center frequency, sweep width, and level range are obviously useful. On the other hand, known parameters are best entered exactly and easily via the keypad. Thanks to the "soft-keys", the rest is easy. Complete standard setups can be stored, or else setting and evaluation are taken care of by computer via the IEC 625/IEEE 488 Interface.

Accurate measurements:

The SNA-1 offers the stability of a synthesizer and the high accuracy of our classical level measuring setups, with which we have achieved such worldwide success. Indeed, bandwidths starting at 3 Hz and a level measuring range down to -130 dBm speak for themselves.



The evaluation? Very easy: calibrated electronic graticule, parallax-free readings, two digital measurement curve stores (measurement, reference/difference), superimposed measuring traces and tolerance limits as well as alphanumeric display of all important parameters.

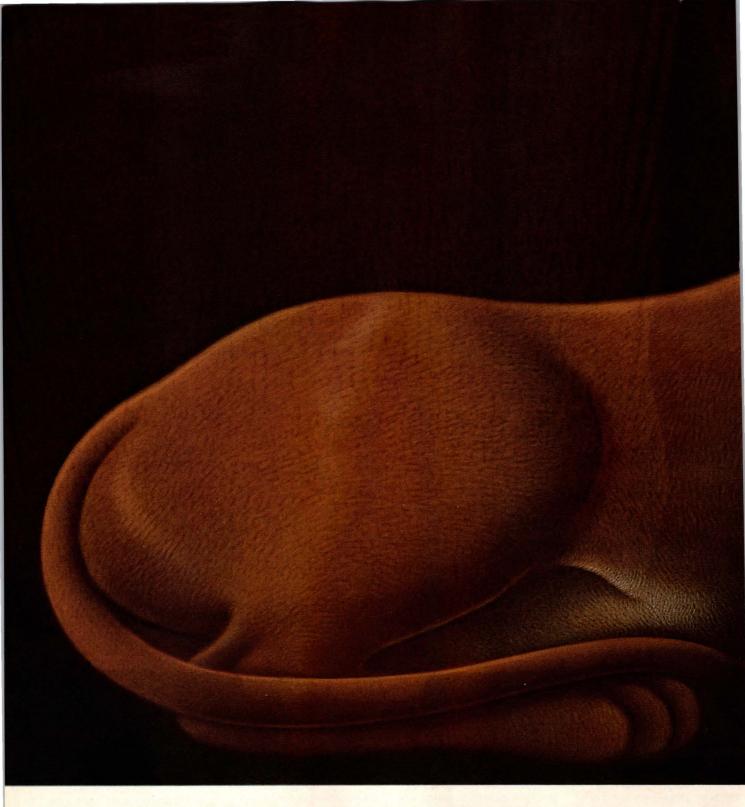
For easy documentation, the complete formatted measurement results are shown on the video screen and are available as hard-copies from a graphics/video plotter or by photographic recording. Are you looking for such an instrument? Then just request detailed information about the SNA-1 and its interesting price.

Please send me: | Information about the SNA-1 An applications engineer to advise me | Name Firm Address

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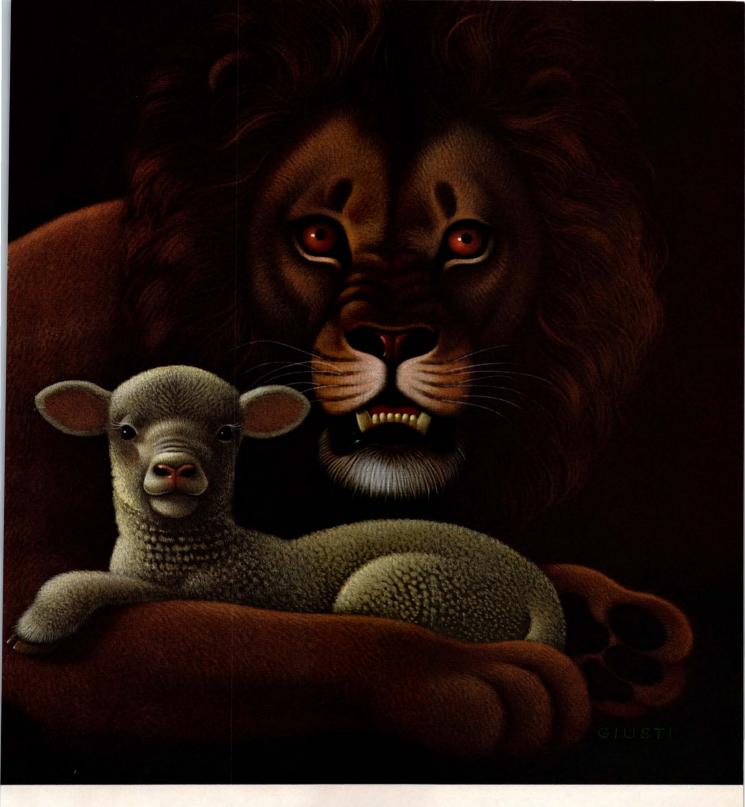
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New 5½-digit Keithley 197 DMM brightens a bench for under \$600.

51/2 IS ONLY THE START.

This Keithley starts by giving you the versatility you expect in a general-purpose meter. Then, add $1\mu V$, $1m\Omega$, 1nAsensitivity and 0.011% DCV accuracy to 5 full functions, and you've got an unexpected combination of versatility and sensitivity.

But the latest technology takes it even further beyond the expected in performance, convenience, and value.

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The 197 offers voltage measurements from 1µV to 1000 V, TRMS AC to 100 kHz, automatic 2/4 wire ohms from $1m\Omega$ to 220 $M\Omega$, and current from 1nA to 10A on 6 ranges. This extended capability is easily read on the 220,000 count display, with full annunciators for your beyond-the-ordinary measurements. Digital calibration locks in this performance.

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The fast AUTORANGING and front panel simplicity will make the 197 your favorite meter. But there's more.

The 100-point DATA LOG-GER lets you store readings at 6 different rates or by manual trigger.

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There's also MIN/MAX reading hold and directreading dB. For portability, the 197 can be ordered with a rechargeable battery option.

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Here's the low-cost way to put the 197 on the GPIB with range programmability on volts and ohms, talk/listen capability, trigger, SRQ, and other commands. Order the IEEE option alone or with the isolated analog output.

5½ + VALUE.

Add it all up. We think you'll agree the new 197 is a highly sensitive, accurate, and versatile tool that belongs on your bench. All for a base price of \$595. IEEE option: \$225

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should not be without this book and the accompanying software"**

DIGITAL SIGNAL PROCESSING SOFTWARE

with advanced applications on the

TI TMS 320 DSP MICROCHIP

consists of a 500 page, tutorially-orientated text and programming/users' manual; more than 50 tested FORTRAN, MACRO-11, and TMS 320 programs in machine readable DEC or MS/PC-DOS source floppy format; and a powerful TMS 320 cross assembler. Of course, all TMS 320 cross assemblers can assemble TMS 320 code! But, only DSPS-Macro, because it runs under MACRO-11 or Microsoft Macro, allows the user to invoke the powerful repeat [.REPT], concatenation ['], and numeric conversion [\] operators for user macros. The following examples vividly demonstrate what these capabilities buy you in terms of ease of generation of time-efficient '320 code such as DSPS' FFT's, with 64/128/256 complex point transforms executing in 0.53/2.4/6.1 msec.

128'th Order FIR Filter: Only two short macros and a 5-line repeat sequence generate the complete nucleus of a 128'th order, 400 nsec-per-tap, finite impulse response filter, assuming that a file containing COEF 1,c1; COEF 2,c2; COEF 128,c128 (where the c's are scaled, 13-bit integers) has been generated by any high level language filter design package, such as those in the *IEEE Programs for DSP* book:

.MACRO COEF I, J .MACRO TAPGEN I I = 128.
CF'I = J LTD *- .REPT 128.
.ENDM MPYK CF'I TAPGEN I I = I-1
.ENDM I = I-1
.ENDR

What could be simpler?

Variable Shift of a 32-bit Integer, plus Exponent Adjustment: In TI's Floating-Point Arithmetic DSP Application Report, the 30 required subroutines occupy about 10 pages of code (over 400 source lines) vs. only 1 page of code (about 50 lines) required for DSPS-Macro. Although both programs assemble into the same amount of object code, the compact DSPS approach is easier to write, debug, and maintain, and results in a much smaller and thus more readable source program.

10'th Order Leroux-Gueguen LPC Matrix Inversion (included in our package): The lack of indexed data addressing on the TMS 320 makes our autogen technique both attractive and realistic for programming "non-array-like", looped algorithms involving indexed data access. In the LG program, about 60 lines of clear, readable, "looped" code — which reflect the structure of the original FORTRAN prototype program — generate about 600 lines of TMS 320 in-line code which execute in 300 usec (including 10 calls to divide): nearly 3x faster than a leading \$50,000 floating-point array processor. The alternative, a "looped-at-run-time" version, would execute more than twice as slowly. And, writing a correct in-line version manually would be very difficult indeed, and totally inappropriate in view of the power of DSPS-Macro. Similarly, in our 535 usec 64 complex-point FFT (DSPS-2), about 150 source statements — which again echo the structure of the FORTRAN prototype — expand into 2900 lines of object code, with all control, addressing, and trig coefficients absorbed into the code at assembly time.

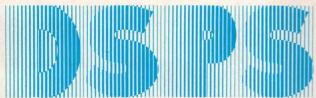
And, DSPS-Macro allows use of other powerful features such as conditional assembly, macro nesting, and macro calls within macro definitions (including recursion). Finally, while we guarantee that DSPS-Macro assembles TMS 320 code correctly, DEC and Microsoft guarantee the long-term support, stability and availability of the MACRO-11 and Microsoft Macro "supervisors".

BOOK CONTENTS/REVIEW

• Digital Signal Processing Algorithms & General Purpose Computers • PDP-11 & Macro-11 Assembler • Structures For Control, Data Access & Data Manipulation • Compilers, Computers, & High-Level DSP Software • Systematic DSP Programming & DSP Systems Programming • TMS 320 DSP Microchip: Architecture: instruction set; address modes; page, pointer, and data manipulation. Arithmetic sequence programming: data and coefficient scaling; addressing and instruction ordering strategies; utilities. Modular programming: subroutines and argument passing, case branch, threaded code, interrupt service routines, memory overlays. Input/output. Data and coefficient scaling techniques. Time/space tradeoffs via autogen. DSP case studies: A/D, D/A, ulaw mapping, windowing, FFT butterfly, convolution, biquad filter, modems, square root, software sine & divide. LPC: limited-memory, 32-bit autocorrelation (3 msec for 200 point, 10 lag); L-G matrix inversion (300 usec for 10'th order); pitch detection. Comparative performance: TI vs. Fujitsu vs. J-11. Software development systems:

Software emulators. MACRO-11 and MS-DOS cross assemblers; TI EVM board/host communication. Next generation TMS 320. A Tale of Two Architectures: PDP-11 vs TMS 320 • The Future: New Technologies •

The reviews are now in on our DSPS-3 package; in the Jan/Feb 1984 issue of *Speech Technology*, Dr. E. Randolph Cole at the Information Sciences Institute, U. of S. California, states: "People developing software for the TMS 320 . . . should not be without this book and the accompanying software"," "the software is a bargain for those who can use it", "the techniques of real-time software writing are the strength of the book", and "we're talking about powerful real-time software here", and "this is the clearest, most concise tutorial on the TMS 320 I have seen anywhere". We appreciate Dr. Cole's remarks, and we know that the hundreds of copies of the DSPS-3 book and software now in the field have easily saved their owners the purchase price in the first week or two of software development on the TI TMS 320.



Digital Signal Processing Software, Inc. P.O. Box 5348, Station F, Ottawa, Canada K2C 3J1

Complete package (DSPS-3), only US\$299. Includes 500 page book and floppy with cross assembler, EVM/XDS loader, and 50 source programs (e.g., TMS 320 windowing, IIR, FIR kernels; LPC autocorrelation, L-G matrix inversion, & lattice synthesis). Send cheque or PO specifying PDP-11/VAX-11 or MS/PC-DOS version. SPECIAL: DSPS-2, the 64/128/256 point FFT software is now only US\$199 if ordered with DSPS-3. Guaranteed off-the-shelf delivery by first class air mail upon receipt of order. Phone (613) 825-5476 for information.



INTEGRATED DEVELOPMENT TOOLS

Projects go faster if your development system is more than a disjointed collection of tools. Development-system utilities that have uniform commands and compatible outputs smooth the transition from one design step to the next.

Charles H Small, Associate Editor

You can't spot an integrated development system by looking at its hardware. A collection of hardware might plug together easily, but that doesn't mean the system's integrated. Actually, you need to be concerned with hardware compatibility only when you're hooking the development system up to your target system. From then on, it's the *software* that you use as you step through the software design cycle (**Fig 1**). Therefore, the degree of integration of the software tools determines just how integrated a development system is.

In fact, integrated software needn't be entirely dependent on hardware; many sets of integrated development utilities can run on more than one manufacturer's hardware. One product offering a high level of integration is Tektronix's suite of integrated software that runs on the firm's 8500 Series development systems, whose hardware comprises a terminal, a controlling Model 8560 computer, and an emulator box. The computer's heart is a DEC LSI 11/23, so the code also runs on the DEC VAX (although a system incorporating the VAX won't exhibit the hardware integration of the all-Tektronix system).

You can thus run the same software and do the same tasks on two vastly different physical systems. Except for the fact that the Tektronix/DEC system has greater speed and bigger disks, you can't tell if you're using the Tektronix or the DEC computer. Similarly, Motorola's development software for the firm's HDS-400 and HDS-200 emulators will run on a DEC mainframe or

the firm's VME/10. Further, Kontron makes both a Unix box that complements its KDS development system and a hard-wired link to DEC mainframes. Indeed, you can expect virtually every development-system maker who hasn't done so already to come out with DEC-compatible software tools soon.

In addition to manufacturers of complete development systems that run integrated software suites, consider firms that make stand-alone emulators: for example, Zax, Microtek Lab, Huntsville Microsystems, Relational Memory Systems, and Applied Microsystems. A simple dumb terminal can control these firms' in-circuit emulators. But they all now offer control programs that run on common personal computers. The software for these systems resembles that of early



Whether running on a DEC mainframe or on the firm's 8560 development station, the integrated software for Tektronix's 8500 series supports a project from definition through debugging.

Integrated software systems run on superminicomputers

development systems from IC vendors. You can integrate your own development system if you add the newer high-level-language compilers available for personal computers.

Whether you choose to call such a collection an integrated development system is up to you. The Sophia Systems SA700, for example, has a built-in CRT, keyboard, processor, and floppy disk. It also sports in-circuit emulators and a PROM burner. The processor can run some CP/M-based or Intel development software. Yet, the firm prefers to call it a standalone in-circuit emulator rather than an integrated development system.

ZAX (which was, until recently, considered to be a maker only of stand-alone in-circuit emulators) now also offers a controlling computer, called the Box, that runs



Combining in-circuit emulation with 100-MHz logic analysis, Intel's I²ICE handles as many as four of the firm's 16-bit processors at once.

several operating systems, including Unix. This computer controls the firm's stand-alone in-circuit emulators.

This spectrum of available products, running the gamut from superminicomputer-based systems to stand-alone emulators, can make selecting a development system a tough chore; no consensus exists relative to the best choice for specific applications, as the viewpoints expressed in the accompanying boxes indicate. Nevertheless, all recent offerings overcome many of the problems that earlier versions exhibited.

Early systems lacked focus

The first development systems were integrated physically because you could get, from a single vendor, a complete hardware/software package for μP development. The hardware comprised a more-or-less gardenvariety controlling computer with CRT, keyboard, floppy disks, and perhaps a printer, along with other equipment more specific to μP development, like a PROM burner, a logic-analyzer-like program-trace analyzer, and an in-circuit emulator (ICE). The software comprised program-development tools like assemblers and compilers and μP-development utilities for running the PROM burner, setting up the trace analyzer, and manipulating the ICE's memory and the μP's internal registers and breakpoints.

But none of the software tools was integrated. Each subsystem had its own command language and procedures. The text editors had one set of commands while the emulator and the trace analyzer used others. The linker and loader worked one way and the software that downloaded to the PROM burner had differing syntax and options. And the software wasn't particularly easy



With either a Unix box or a hardwired, high-speed link to a DEC mainframe, the Kontron KDS gains access to high-level tools previously unavailable on its 8-bit controlling computer.



Offering a choice of high-level-language software debuggers, Hewlett-Packard's 64000 system has both software emulation and real-time hardware emulation.

to use. The emulator-control software, for instance, often looked like a crude monitor. These monitor-based command languages had low-power, atomistic commands for examining and changing the contents of registers and memory locations, running and halting the program at breakpoints, and patching code.

Specs set the tone

Regardless of the development tools you choose to use, a design project begins with setting specifications. Studies of sources of error in programs consistently reveal that bad specs cause a significant percentage of all software failures. In these cases, the code performs exactly as specified; the specs themselves are out of line. Bad specifications arise partly from human limitations and partly from the way the specs are promulgated. Usually the marketing and software engineering departments get together to hammer out the initial product specs because no one person has a complete grasp of both the customers' needs and the software's possibilities. The marketing department (presumably) understands the customers' needs but doesn't understand programming. The software engineers know all

about programming but probably don't understand the end product's application very well.

For example, one emulator company had a team of experienced C software engineers develop a new software product. Following the usual C convention, the product printed out all hex numbers in lower-case



Based on the DEC Professional, the Emulogic 3200 features system-control software that resembles the C programming language.

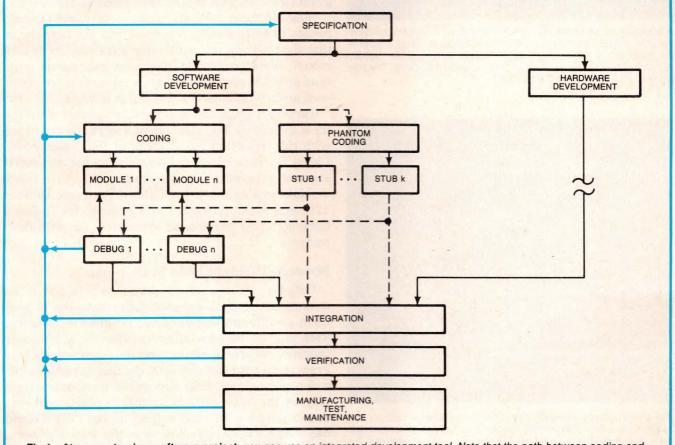


Fig 1—At every step in a software project, you can use an integrated development tool. Note that the path between coding and debugging is bidirectional. These are the stages that benefit the most from integration of software tools.

Integrated tools go beyond plug compatibility

characters: for example, "fed0." More accustomed to seeing "FED0," every beta-site evaluator complained, and the output routines had to be changed.

This is not to say that programmers and software engineers are the only ones to blame for poorly done specs; they claim with some justification that it's not uncommon for marketing departments to change the specs frequently while the software engineers are writing the code.

The other problem with specs is the form in which they're promulgated. Specs often come out loosely



A stand-alone emulator can rival integrated development systems using an IBM PC or PC clone. Microtek's MPDS currently supports the 8048/49/50, 8085, 8086, 8088, 80186, 80188, 6809, 68000, 68010, 6502, 65SC02, 65C02, 65SC802, Z80, and NSC800. The firm plans to include the 68020 and 80286.

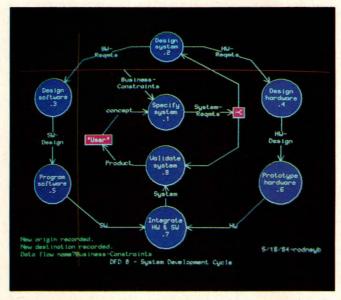


Fig 2—Structured analysis (data-flow analysis) is an efficient way to set up specs for a project. Every data structure and its contents get specified. Relationships between processes are also spelled out. The finished analysis suits structured walkthroughs, which test the project's functions before any code gets written.

worded and incompletely detailed, perhaps merely written in plain English. Such specs may look good right up to beta-site testing, but they often prove inadequate when potential customers try the product.

Hidden bugs trip you up

Such inadequacies can be prevented—many structured methods can be used to effectively detail software specs. Instead of loosely worded English, some firms employ schemes like structured English, program-description languages (PDL), or structured analysis (data-flow analysis). These more rigorous methods of expressing a program's functioning allow you to test the program in advance. Although these methods are clearly amenable to computerized checking of things like module interfaces and both data-structure patterns and usage, most firms currently do them manually.

Indeed, some *overdo* them. A recent IEEE study found some firms generating as little as 1.15 to 1.3 lines of real code for every line of pseudocode (program-description language or structured English) in the software spec. A ratio of one line of real code for one line of pseudocode would mean you've achieved a zero level of abstraction and, in essence, written the program twice. A ratio of 1.3:1 isn't much better.

None of these methods, manual or computerized, results in optimal code. The most you can hope for is that the program will work after a fashion. Studies of robust, highly optimized programs still reveal such dead ends and redundancies as variables that are never used and subroutines that are never invoked.

Curiously, of all the makers of integrated development tools, only Tektronix offers a software tool to aid with this important initial phase of the design cycle. Called SA Tools (from structured analysis), the \$9500 suite of programs runs on Tektronix's 8560 (VAX versions cost extra) and requires a Tektronix 4100- or 4110-series color terminal for its graphics. SA Tools is a semiautomated version of structured (or data-flow) analysis.

Structured analysis looks at data first

Data-flow analysis focuses not on the code, but on the data structures and on what happens to the data in them at different stages of the program's execution. This method takes a different view of a computer program; strictly speaking, you should consider a program to be both the code and the data structures the code operates on. Most debugging tools concentrate only on the code. Data-flow analysis starts with the data and leaves the code-writing till last. The method has found wide application over the last ten years. Tektronix applications engineers report that users manually maintain data-flow analysis schemes that

have more than 2000 constituent modules.

Tektronix's programs provide a graphics editor for naming modules (the blue circles in **Fig 2**) and connecting them with labeled arrows to show how they relate.

This results in a directed graph that resembles a graph for a classical finite-state machine. Clearly, there's room for only so many blue circles on a given screen. Therefore, the editor encourages you to do a top-down

Why ICE isn't enough

Terry Larson, Dolch Logic Instruments Inc

Traditional test and measurement instruments used in digital-system design are undergoing dramatic changes. The primary purpose of development aids such as logic analyzers, in-circuit emulators (ICE), and pattern generators is to increase engineers' efficiency by simplifying engineering tasks. To facilitate testing of complex designs, instrumentation systems in the past combined several standalone instruments with an IEEE-488 (GPIB) controller. However, a new breed of truly integrated instruments provides real-time testing capabilities that were previously impossible with the GPIB approach.

Typical of these is Dolch's ATLAS 960 personal-instrument workstation, which integrates digital test instruments within a single controller and allows real-time interaction between all instruments. Because the ATLAS is a modular system, you can combine a variety of instrument plug-ins.

Another example is Intel's 12ICE, which is slaved to a dedicated µP-development system to bring logic analysis and in-circuit emulation together in a fashion that allows cross-triggering between instruments. Most in-circuit emulators provide some logicstate analysis capabilities for software debugging purposes; I2ICE incorporates an asynchronous analyzer for true timing and off-thebus event tracing. Similarly, the Tektronix DAS 9100 is a configurable logic analyzer that incorporates a digital pattern (word) generator. This combination provides

the hardware stimulus for logicanalysis testing.

Although these examples are all properly termed integrated instrumentation, there are significant differences between them. I²ICE requires the host system to drive all test and debugging functions. This approach is expensive, and it lacks several instruments vital for testing. These include a digital-pattern generator, serial-data analyzer, and waveform analyzer. You are limited to a single 16-channel analyzer for each I²ICE chassis, making multiple-channel logic-analysis applications expensive.

The I²ICE approach lacks hardware-stimulus capability; for instance, there's no pattern generator to drive asynchronous circuitry or circuitry off the μP's bus. There is no logic-simulation capability, and all testing must be done under development-system control, tying up a very expensive software-development system for an often lengthy debugging effort. Finally, I²ICE has no IEEE-488 to integrate other instruments into the system. It can only supply triggers for external instruments.

Dedicated and universal development systems are being replaced by general-purpose computers running development software. I²ICE wasn't designed to be slaved to general-purpose computers (from PCs to minis and mainframes).

With the emergence of CAE systems, highly sophisticated hardware and software support for all facets of the engineering

design cycle will be included in the engineering workstation of the future. System-test instruments must be flexible enough to interface to CAE systems and be remotely controllable from the CAE system. Only with such an approach will the computer and simulation power resident in CAE systems be able to interface, in a high-level fashion, to the target system. Design and testing needs are becoming so complex that it is mandatory to remove the engineer from the mechanical loop linking the simulator to the actual target system's operation.

Admittedly, enhancing software-development systems with hardware and software troubleshooting capabilities is necessary, but it will be obsolete in a few years. A new approach to integrated digital-system testing, illustrated by the Dolch ATLAS and CAESAR systems, allows flexibility to mix and match instrumentation plug-ins to fit the application. Such an instrument can operate either as a stand-alone unit or slaved to a CAE-system workstation. It is with this approach that future systems designers will truly be able to marry the computer and simulation power to automated product-development test needs while retaining a degree of hands-on control over traditional digital-instrument test capabilities.

The author is vice president of marketing for the San Jose, CA, firm.

Specification stage produces high percentage of errors

hierarchical design by numbering all the blue circles on a given screen at the same level—say, 1.0, 2.0, 3.0, etc. To expand the hierarchy downward, you select a circle and engage the screen underlying that circle in the hierarchy. If you were to select circle 2.0, for example, all the circles underlying circle 2.0 would get labeled 2.1, 2.2, 2.3, etc. You can continue this process ad infinitum.

At your option, you can append a "minispec" to each circle. Tektronix recommends that you write this minispec using some form of structured English or program-description language (PDL). However, none of the SA Tools does any syntax checking on your structured English, though they do enforce some rules. Specifically, they check your circles and arrows for consistency, and they require you to define the contents of every data structure or item mentioned. When the analysis is complete, each member of a programming team has a complete description, either on screen or on printouts, of his module's functions and interface.

Automated spec'ing ensures consistency

The real value of this kind of automated tool becomes apparent only after you've done your initial layout and have begun to modify it. Although top-down hierarchical design sounds and looks impressive, in the real world, most hierodules (slaves in the service of a hierarchy) work not from the top down (or from the bottom up, for that matter) but from the middle out. Therefore, the structured analysis is bound to be restructured frequently as the project progresses and the software engineers find that their initial ideas need rethinking. Just like any other coordinated combination of engineering drawings and engineering documents (for example, schematics, pc-board layouts, bills of material, and net lists), a complex data-flow analysis and its accompanying minispecs and data dictionary can get hopelessly fouled if they're not modified and updated very carefully, thoroughly, and consistently. Computerized tools make a good deal of the thoroughness and consistency automatic.

Industry sources report that firms who have been using manual structured-analysis methods eagerly embrace the computerized version. Characteristically, firms that haven't don't seem to be able to grasp the value of the method.

Once you've done the structured analysis, you can try the proposed program manually with a structured walkthrough, a paper analysis of the program's operation. But specifications and structured walkthroughs are only the beginning of a project. The real grunt work begins with writing the code.

At the dawn of the μP age, most 8-bit μP code was written in assembler instead of in high-level code. And

The personal-computer development system: A less expensive alternative

Robert Hsieh, Microtek Lab Inc

A personal-computer-based development system is the least expensive way to handle system development chores. You need a computer like the IBM PC, compilers and assemblers that run on it, and standalone in-circuit emulators.

Microtek's MPDS, for example, provides the same power as full microprocessor development systems like those made by Intel, Hewlett-Packard, Tektronix, and Kontron, but at a fraction of their cost. MPDS performs emulation with easy-to-learn, single-letter commands.

The cost of a microprocessor development systems depends on the processor. The **table** shows the complete cost of a Microtek system for the $80186~\mu P$.

To emulate the 80188 on that system you need only replace the 80186 chip with an 80188. To emulate a microprocessor belonging to a different family you need a personality card and the corresponding software. The 68000 personality card, for example, costs \$2395, and the software package is \$1300.

The author is vice president of the Gardena, CA, firm.

COST OF A DEVELOPMENT SYSTEM FOR THE 80816 μP

HARDWARE \$2600 MS-DOS HOST \$2600 MICE 8086 (32k ICE) \$4395 BREAKPOINT PROCESSOR BOARD \$1795 MICE POWER SUPPLY \$250 SUBTOTAL \$9040

SOFTWARE PACKAGE (CROSS ASSEMBLER, SYMBOLIC DEBUGGER, LOGIC-STATE ANALYZER, AND SOFTWARE-PERFORMANCE ANALYZER)\$1300 TOTAL SYSTEM\$10,340

the amount of code was small enough that just a few software engineers could complete the entire project. While you can't go so far as to say that nobody writes just 4k of code and ships a product anymore (the semiconductor industry sells far too many single-chip μPs to support that claim), you can say that many μP -development projects are much larger than they were because of the new 16- and 32-bit μPs .

Software projects getting bigger

The move to more powerful μPs profoundly affects the way you must organize your project and the tools you need. The tools include:

- Software-version control
- Target-system simulation
- Assemblers
- Compilers
- Target-compilation utilities
- Symbolic debuggers
- Program trace and trap utilities
- Software verification tools.

Version-control systems are familiar to software engineers who work on large projects; Unix's "sccs" (source-code control system) is the best known. These systems keep track of program modules as they evolve. They record the identity of the person who modifies a module and the date and time of the modification. After the initial entry of a module, the version-control systems record only the changes to a module; they don't overwrite the old version with new versions. That way, you can reconstruct any previous version of a module.

Version control keeps modules on tap

Coupled with a "make" utility that reconstructs and links selected versions of modules, version-control systems have obvious value for large projects. Engineers who write small test programs to exercise hardware usually don't think they need an elaborate softwarecontrol system. That is, they don't think so until a member of their team takes off for a long weekend and leaves his floppy disk-containing a critical modulelocked up in his desk. Version control also proves useful for keeping track of the "phantom code" (or "stubs") that gets written to stand in the place of real modules that aren't working yet. These stubs are essential for getting segments of a large project running well enough to check them out. Yet despite their importance, few projects make allowances for the time it takes to write and debug the stubs or provide for keeping track of them.

Intel's I²ICE has a version-control system that has a novel feature you can't get on mainframe systems. It links version control with electronic mail. When a module comes due, the manager gets an electronic-mail reminder of the fact. And if a module is updated, all members of the team who depend on that module get notified that it's been changed.

Although some engineers might doubt that they need

version control, there's no doubt that in-circuit emulation is currently accepted (although complex systems offer a wider view into the target system than ICE provides). In today's large, modularized development programs, the integrated development system's ability to mimic the eventual target system is important because hardware and software development often proceed in parallel. Therefore, in the early stages of the project, the software engineers may have no working target system on which to try out their code.

Development system mimics target

The integrated development system's mappable memory is the primary mechanism for simulating the target system. With this scheme, the address and data lines of the emulator's μP get switched back and forth from the target system's memory to the overlay memory in the development system. Further, all integrated development systems can make portions of their RAM read-only, thereby simulating the target system's ROM. In the limiting case, you can have all memory reads and writes occur in the integrated development system's memory and none in the target system's. In other words, you need no target system at all. No target system at all, that is, if your project communicates only with memory.

Most µP projects don't communicate exclusively with memory, however. Most integrated development systems, by virtue of their monitor heritage, have little routines embedded in their operating systems for doing character-by-character I/O to the development system's CRT. It's not too hard to embed a small routine in your code that first initializes the necessary registers and memory location that the development system's I/O routines need and then jumps out of your program into the development system's ROM. Some systems have disk I/O routines you can jump to as well. Tektronix's 8500 integrated development systems have a more regular mechanism. They allow you to patch the integrated development system's terminal and disk I/O into your target system's programs. The price you pay is eight consecutive memory locations that you load with a Tektronix-specified array of information.

The Emulogic ECL-3200 Series provides, on the other hand, no patchable I/O routines. The firm claims that this points up the difference in application between Tektronix and Emulogic systems. Applications for the Tektronix integrated development systems presuppose a conventional general-purpose computer with the usual sort of terminal, printer, and disk I/O. Emulogic integrated development systems, the firm says, suit target systems with embedded processors that don't do such I/O—a robot, for example. I/O simulation for these kinds of systems is necessarily very application dependent.

Walkthroughs stamp out hidden bugs

dent, and it must be done by each user. Emulogic further notes that its 16-bit emulators don't usurp or share any target-system resources.

Some systems intrude

Not all integrated development systems can make the claim that they don't usurp or share any target-system resources. For example, both Tektronix 8500 series and HP 64000 series 16-bit emulators need a small chunk of target-system memory—about 2k—for their own routines. You can't use this space for your code because that's where routines like the ones for dumping the μ P's registers reside. Further, the Tektronix and HP emulators, as well as ones made by Zax, share the μ P's nonmaskable interrupt (NMI) pin with the target system. That's how their emulators regain control of the emulator's μ P from the clutches of the target system's code. Emulogic 16-bit integrated development systems put no code in the target system's space and don't use the NMI pin.

In defense of their schemes, HP and Tektronix point out that not using any target-system memory is important for 8-bit μPs with their limited memory space. For 16-bit μPs , with their extensive memory space, usurping a small relocatable chunk of target-system memory isn't so bad. Also, the firms claim that most engineers don't use the NMI pin for ordinary run-time functions. Instead, the NMI gets hooked to the power-up reset or watchdog timer. In these cases, they claim, the user has no problem distinguishing whether the integrated development system stopped the processor or whether the power failed.

But where does the code you're trying out come from? Industry sources estimate that 80% of all code for 8-bit μPs is written in assembler, while the remaining 20% is written in high-level languages. They expect the percentages to reverse for 16- and 32-bit μPs . But engineers aren't likely to use just any high-level language; they're more likely to write time-critical code than the average programmer is. Engineers are also more likely to use cross assemblers and cross compilers than are applications programmers. That is, engineers will write code on one computer that will eventually run on some other machine.

Engineers eschew protection

This means that engineers now need more than mere assemblers. They also need powerful system-implementation languages that don't attempt to protect programmers from making mistakes or from encountering the actual hardware of the native machine. Software engineers need these low-level facilities because the target machine often doesn't have an operating system. Therefore they cannot depend on an existing operating

system's routines to handle the work of I/O, scheduling, intertask communication, and the like; instead they must write these low-level facilities themselves.

Software tools ignore time

But even though assemblers and certain high-level languages supposedly suit system implementation, a critical element is missing: time. All software-oriented tools suppress time. Yet time is critical in much of the software that engineers write. There's no intrinsic reason why software tools can't deal with time. It's not hard to conceive of a software simulator that would calculate a routine's run time, or an assembler directive that would pad out a module with NOPs (dummy execution cycles) so that the module would execute in a preset amount of time. But these things don't exist. That's why software engineers turn to hardware-based simulation. They write the code, try it out, measure critical timing parameters, and then return to the software domain and amend their code. In fact, speeding up this iterative, cyclic process of writing, loading, running, and amending lies at the heart of all claims that integrated development systems are powerful.

However, no two manufacturers have exactly the same view of just what steps make up the software-design cycle. Take target compiling, for instance: For a program written on a development system to run on a different target system, many things must be done to match the program to the new hardware. You have to assign some code to RAM and some to ROM, load interrupt vectors, assign stacks, and so on. Of all the firms making integrated development systems, only Tektronix views this target compilation as a task in itself. Tektronix supplies a specific utility that matches the software to the hardware. Other firms spread target compilation over three areas: assembling or compiling, linking, and loading.

Target compiling hits the mark

Tektronix's ICS (Integration Control System) is a part of the LANDS (LAnguage Development System) package. it prompts you for all the information the linker needs to assign code and data properly. It also handles patches for resets, I/O and other interrupt-driven processes that you might want to simulate back in the development system rather than in your target system. Finally, it goes beyond target compilation to include emulator setup. After you answer all the prompts, ICS yields a command file that links and loads your code as well as initializing the emulator.

However a given development-system maker structures its software and hardware, speeding through the design cycle means scaling successive levels of abstraction as painlessly as possible. Even the most elementary assembler allows you the abstraction of labels. High-level languages expand this repertory of abstractions to include not only symbolic names for various segments of your program but also various data constructs and special objects (linked entities of code and

data, such as arrays defined by a DIM command). By the time you run the code with the aid of your integrated development system's in-circuit emulator, all these abstractions have long since been converted to machine code and machine-readable data. Consequent-

An integrated approach to microprocessor development

John Marshall, Hewlett-Packard Inc

Today's competitive environment demands that new products move quickly through the design cycle. Conflicting with this demand is the growing complexity of and increasing emphasis on quality and maintenance for both hardware and software. Design teams are responding to this need by using automated design tools that accelerate the design process and help locate and eliminate errors at the earliest stage possible.

Cross assemblers and compilers, for example, are essential automated software-design tools that have been available for a long time. Unfortunately, because software-design automation seldom extends beyond this point, software analysis and system integration are now the major throughput bottlenecks. While individual simulators, emulators, and logic analyzers are available to address the problems of software debugging and system integration, in most cases the process is as disjointed as the instruments themselves, and it's far from automated. Instead, the process is labor-intensive and prone to error, and it often fails to identify bugs early in the design cycle. (The later in a design cycle you find a bug, the more expensive it is to eliminate.)

The Hewlett-Packard Model 64000 logic-development system automates the entire process of software design and system integration. For this purpose, not only are the necessary software-design, debugging, and analysis tools provided, but they're tightly

linked into an integrated design and analysis system. Because it is a modular system, the 64000 has no fixed price. Generally, however, a 6-station system with a fast hard disk costs about \$12,500 per user (two users per station). The advantage of this approach becomes apparent as we trace through a typical design cycle.

The workstation does program assembly and compilation at high speed, which provides fast turnaround from source-code editing to native object code. You can begin software debugging immediately with the emulator before target hardware exists, and you can analyze a separately compiled module in terms of the C or Pascal source code. You can also do software-performance analysis to get an overview of program activity or to optimize the module's performance. Meanwhile, the emulator can control the processor and observe activity in registers within the processor. You can also simulate nonexistent I/O with the workstation's I/O devices. Program changes and enhancements are made and bugs are removed at the source-code level; the tight coupling of the instruments allows rapid context switching between the software-design and systemintegration environments.

As the design progresses and hardware is developed, emulation provides a vital link between the target system and the software-design environment. Now it becomes important to observe the cause-and-effect relationship be-

tween the program running on the target processor and corresponding activity at I/O ports, coprocessors, or peripheral devices.

You can evaluate even complex multitasking software with an integral state-analysis subsystem. The analyzer's trace specifications and displays get labeled similarly to the high-level source code because the tight coupling provides the integral state analyzer with access to the software's symbol tables. An integral high-speed timing analyzer verifies critical timing specifications and identifies glitches. You can correlate the analyzer's and emulator's displays to help identify problems.

The key advantage to the integrated approach is that you find bugs early in the design cycle, where you can remove them at the lowest cost. You can produce accurate documentation quickly because you make all changes and repairs at the source-code level instead of the assembler level. As a result, software-maintenance costs are lower. Designer efficiency is greatly increased because all the compatible softwaredesign and system-integration tools are accessed from the same keyboard with a common syntax. Software is designed and debugged and measurements are made in terms of the same highlevel language.

The author is a product manager for the firm's Logic Systems Divin Colorado Springs, CO.

Structured analysis leaves coding till last

ly, the makers of integrated development systems have tried to provide a path back from the bit patterns to your initial abstractions with symbolic debuggers. Symbolic debuggers make it easier to backtrack from what's happened in your hardware simulation to your original code.

Symbols get plugged in

The simplest symbolic debuggers work with assemblers and linkers. If, for example, you ask your incircuit emulator to disassemble a string of activity it captured in your target system, it can ask the controlling computer to see if any disassembled op codes' arguments correspond to labels in your program. That way, the disassembled stream of program activity will show your original labels as arguments of the disassembled op codes instead of uninformative hex numbers. This scheme works fine for jump addresses or declared constants. But it can sometimes blow up. Take, for example, a jump table comprising the starting addresses of subroutines. These simple symbolic debuggers can't do a dump of the table and translate the raw addresses into their corresponding labels. The best they could do would be to try to disassemble the jump table. The resulting output wouldn't be executable code, it would just be garbage.

Symbolic debuggers that work with high-level languages have considerably more power. Instead of working with just raw addresses or labels of addresses, you can set a breakpoint corresponding to specific lines of code in your source program. Many, like HP's 64000 system, can print out and display a mixed listing of high-level code along with the compiled assembly-level codes and machine codes. They all disassemble executed code in terms of the high-level labels, and some allow you to examine and change the physical target-system memory using the high-level terms.

For example, Tektronix's LANDS works with C and Tektronix's enhanced Pascal. LANDS takes advantage of Pascal's strong type checking. Suppose, for instance, you define a data type DOG that embraces the set of TERRIER, BOXER, and POMERANIAN and then define a variable of the type DOG named DOGHOUSE. You can then interrogate DOGHOUSE to find out what dog is currently in the DOGHOUSE. You can also, with simple commands, kick the BOXER out of the DOGHOUSE and replace it with, say, the POMERANIAN.

If you were to look at the actual code compiled by the Pascal compiler, you'd find that it probably assigned the numbers 1, 2, and 3 to TERRIER, BOXER, and POMERANIAN. And if you got the address of DOG-HOUSE from a cross-listing and inspected the contents at DOGHOUSE's address, you'd simply find a 1, 2, or 3 and not some DOG's name. The simpler symbolic de-

buggers could find DOGHOUSE all right, but they wouldn't be able to tell you what kind of DOG was in the DOGHOUSE.

Of course, debugging high-level code involves more than looking at variables. High-level languages and elaborate operating systems employ things like dynamically defined variables and overlays, which baffle simple debuggers. Simple debuggers expect a given memory location always to be used for the same purpose. Smarter symbolic debuggers handle these cases. For instance, Emulogic's SLICE (Source Language In-Circuit Emulator) debugging system works with C and Pascal. SLICE has tools for determining how modules get called. For example, the first thing a C routine does when it gets called is to allocate space on the stack for its local variables. It also puts a link on the stack so that subsequently called modules can return control to the calling module. After the Emulogic emulator recognizes a breakpoint and freezes the target system, SLICE can analyze the stack's contents. Then it can display a list of module names in the order in which they were called. This allows you to backtrack from the observable symptoms to the offending module.

Symbolic debuggers go slowly

HP offers high-level symbolic debugging with both a software simulator and a hardware execution-vehicle. The 64330 software simulator is similar to Tektronix's LANDS system and can trace, trap, and break on changes to high-level constructs like variables and arrays as well as by program lines or modules. It doesn't run in real time.

The software that runs HP's 64620S logic-state/ software-analyzer module in a 64000 system accomplishes these tasks in a slightly different manner. You can set up trace, trap, and breakpoint sequences on fixed addresses or definable states of the target µP using some, but not all, high-level constructs-much like a logic analyzer. You can also set up what HP calls "windows" to troubleshoot overlays. Simple debuggers would trace, trap, or break if the processor accessed a preset memory area. They can't distinguish among overlays operating in a common area. The HP window feature recognizes activity of a certain kind in a certain area of memory and thereby deduces that a particular overlay is active. The trace, trap, and breakpoint commands for a given window become active only if the appropriate overlay is running.

When the analyzer finally halts the process, the 64000 system first displays the disassembled code of the captured trace along with a column showing elapsed time. Then, right under the assembly code, the system displays a segment of the source code that corresponds to the decompiled captured activity. The system can do

this because it keeps a table of pointers from the source code to the assembled code. The net effect is similar to that of software-based high-level debuggers: You can get back and forth quickly from the high-level code to the low-level machine code.

Furthermore, the software supplies a setup screen that the firm claims allows you to coordinate the 64620A with virtually any compiler and not just the C and Pascal compilers that HP supplies with the 64000 system.

Meanwhile, Intel's PSCOPE also solves problems inherent in debugging high-level languages that dynamically assign variables on the stack. While languages like FORTRAN preassign fixed memory locations to each data construct, languages like Pascal and

C keep local variables in temporary stack locations. When the module using the local variables quits, its local variables get popped off the stack and dropped. A simple symbolic debugger couldn't find a given dynamically defined variable, but PSCOPE can trace, trap, and break on dynamically defined variables.

Dynamic variables befuddle debuggers

While simpler monitor-based debuggers can single-step through an assembly-code program, PSCOPE—like most other high-level debuggers—can single-step by source-code line or by module. You can command most simple debuggers to execute a given number of lines of code. Similarly, PSCOPE will execute a given number of lines of source code or a given number of

Using superminicomputers for µP-software development

Michael P Kendall, Digital Equipment Corp

The key points of a superminicomputer approach to μP development are as follows:

- Cross-development tools -Many companies sell cross-development software for superminis. The tools support a wide range of µPs, including the latest 16and 32-bit products. Cross-development tools include relocatable macro cross assemblers; compilers such as Pascal, C, PL/M, and FORTRAN; language-syntaxchecking editors; symbolic and high-level-language debuggers (not in real time); utilities such as linkers, cross-reference librarians, version-control systems, and program profilers; object-format converters and peripheral interfaces; and bit-slice development tools. Various emulator and analysis tools are also available.
- Computing power—Superminis can quickly handle computationally intensive activities such as compiling and linking the large 16- and 32-bit μP-development tasks.
- Large disks—Superminis' large, high-speed disks can store the numerous files from complex projects. Available disk capacities

range to tens of gigabytes.

- Multitasking/multiuser operating systems—Because superminis have multitasking and multiuser operating systems and large address spaces, they support software-development teamwork. The team can easily share program, documentation, and specification files.
- Revision control systems
 —Because sharing occurs under one operating system, you can employ a revision-control system.
 DEC has DEC/Code Management System and DEC/Module Management System software under the VMS operating system. In addition, software-revision-control systems are also available under Unix.
- Multiple application support—Because superminis are general-purpose machines, they can run other software that complements and augments μP-software development. Available software includes project-management and CAD/CAM. CAD/CAM packages can include those for pc-board layout and routing, logic and circuit simulation, IC layout, and mechanical design. Oth-

ers offer electronic mail and word processing.

• Low cost per user—For the supermini approach, cost per development station compares favorably to other methods of μP-software development.

Relative to this last point, consider that a VAX 11/750 computer with 4M bytes of physical memory, 456M bytes of disk storage, a ½-in. magnetic tape, a 300-LPM printer, 16 CRTs, and an operating system handles 16 simultaneous developers. The cross-development software includes a C or Pascal compiler, cross assemblers, utilities such as linker and cross-reference checker, debugger, and integration link to emulation hardware. The total typical cost of such a system is about \$150,000—\$9375 per user.

In comparison, emulators range from approximately \$4,200 (for simpler units) to \$24,000 or more. For four developers per emulator, total per-user cost can range from \$10,425 to \$15,375.

The author is a senior marketing specialist for the firm's CAE/ CAM group in Marlboro, MA.

Computer-aided updating achieves thoroughness

modules. That way you can single-step line-by-line to get a detailed view of one portion of your program's execution and then execute a group of lines or modules to jump over known-good or uninteresting portions of the program.

But even the fanciest debuggers can't handle some of the problems posed by powerful computer systems. The reason is that some so-called high-level programming constructs are actually in hardware. For example, National Semiconductor's 16000 and 32000 family of 16and 32-bit µPs and peripheral chips includes an external memory-management chip that supports demandpaged virtual memory. The µP itself includes hardware that simplifies multitasking context switching. The external memory-management chip imposes a propagation-delay penalty on the series compared to µPs that have their memory management on board. Therefore, National could not build a full-speed emulator without having the µP, memory-management, and clock chips in the emulator. Only National's SYS32 hydra-headed development system emulates all of these chips in one unit.

Debuggers have limits

The timing constraints that dictated the layout of the emulator have a beneficial side effect for tracing and trapping high-level software systems. Because the SYS32 integrated development system can see the pins of both the μP and the memory-management chip, the emulator can trace and trap on physical as well as virtual addresses. Other emulators see only the address lines coming out of the emulated μP ; therefore, unless your emulator has some nondedicated inputs that you can hook to the memory-management circuitry, you can't be sure just what portion of memory the μP is accessing.

Similarly, if your multitasking software system swaps tasks into and out of off-line memory, the μP 's address lines again do not uniquely define the state of the system. You must also factor in the state of the multitasking system's pointers and tables to figure out which module is running. In other words, memory management renders the μP 's state ambiguous with respect to the linear memory space; multitasking renders it ambiguous with respect to time.

Other areas where hardware does software-like functions include dedicated I/O processors (especially ones that run asynchronously to the main processor), hardware floating-point processors, multitasking context switchers, and multiprocessor architectures.

Although it is true that you can run multiple emulators in a multiprocessor system using Intel's I²ICE, for example, the emulators are only loosely linked. Most emulators have output lines incorporated in their word-

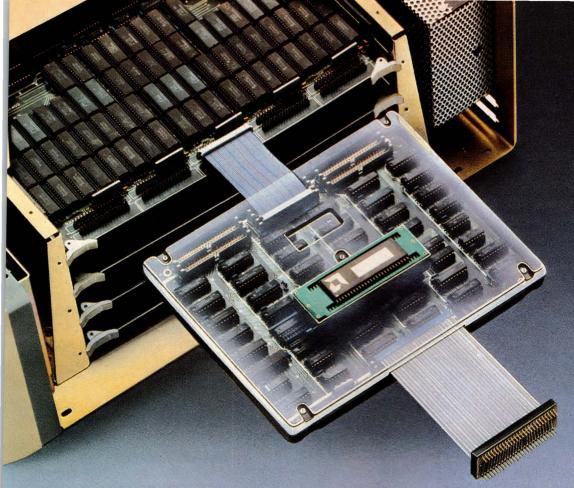
recognizer circuitry that can cross-trigger another emulator. If one emulator's word recognizer sees a predefined machine state, it can toggle its output line. You can use this output line from one emulator as an input to another emulator's trace, trap, and breakpoint word recognizers. Further, Intel's systems also have a high-speed time stamp so that you can reference the events captured in the multiple emulators to a common time base. At present, Intel doesn't have a utility that will take this raw information and display the activity of multiple, asynchronous processers in a time-aligned manner, the way the Tektronix 1240 dual-time-base logic analyzer does; with the Intel device you have to puzzle that out for yourself.

Math coprocessors are no problem

While custom hardware floating-point processors are a headache, math coprocessors aren't. In the case of Intel processors, most firms' emulator pods have a socket for a math coprocessor. The pods do not, however, provide a bond-out emulating coprocessor. The firms having 8087 sockets in their emulators' pods claim that the math coprocessor is so tightly coupled to the main processor that you can do all the tracing, trapping, and breaking by monitoring the main processor's interaction with the coprocessor; you don't need to emulate the 8087 itself. National makes the same claim for the math coprocessor in the SYS32.

Because of the limited view that emulators have of the total software system, complete, real-time symbolic debugging is at present beyond the capability of existing hardware. Consider high-level symbolic debuggers like Kontron's or Zax's. These are actually software simulators running on the host development-system computer. Although these debuggers can easily get at all the high-level constructs of the program, they do not run at anything approaching real time. Tektronix's LANDS and HP's 64330 are software simulators that run on the target system's $\mu P.$ But to get at the high-level constructs, they sometimes have to interrupt execution.

Therefore, although you get access to all the target-system resources, the code still doesn't run in real time. HP's 64620 analyzer (which works in real time) and some postcapture processing give you a pointer back into your source-code file. For C programs that aren't highly type-checked, this is not much of a penalty. (A type-checking compiler makes sure that the data written into a data construct is the kind of data that's been defined previously as allowable for that construct.) But for Pascal programs, HP's 64620 can't work forward from the source file to read and write from data constructs using high-level objects as Tektronix's LANDS can.



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CIRCLE NO 63

New μPs generate larger software projects

The solution to all the problems of real-time symbolic debugging of high-level software systems awaits a rather strenuous hardware-design effort. The solution might be something like a dual-ported stack or perhaps a phantom stack area operating in parallel with the real stack. You could switch the phantom stack off line as needed and analyze its state while the real stack continues to operate. While this provides you with one look at the stack, multiple looks leave you the problem of updating the phantom stack to correspond to the present state of the real stack and putting the phantom stack back on line. Similar phantom hardware could prove useful for other hardware that handles high-level software-system tasks like context-switching hardware.

Although such features await future designs, designers have expended considerable effort on user interfaces for the development systems. In fact, the user interfaces that control trace, trap, and break hardware exhibit the greatest range of ingenious design of any aspect of these instruments. No two manufacturers' setup and control schemata are at all alike. Each system has myriad possibilities, tricks, and wrinkles. Instead of getting bogged down in a welter of specs and claims that don't correspond to one another, you can evaluate each manufacturer's schema beter if you keep in mind what it is you actually do when debugging code.

Debugging mirrors initial analysis

How you actually debug software is very similar to the data-flow analysis (structured analysis) method of software design. With data-flow analysis, a program gets defined in terms of both the data constructs and the code that operates on them. Most of the features of a debugger concentrate on the sequential execution of the code and deal with data structures inferentially or secondarily. However, this bias doesn't concur with the way a lot of debugging gets done. Very often, the symptom of bad code is corrupted data or improper outputs. Therefore, debugging begins with finding the bad data or identifying the improper outputs and then trying to find the code that's at fault. This is especially true in large modular programs where many different modules operate on common data structures or output ports.

This software debugging situation is similar to considering glitches as a symptom during hardware debugging. Logic analyzers can trigger either upon recognizing defined states in a digital machine or upon spurious, short-duration signals (glitches). Every digital machine has lots of glitches. It's hard to find a point to probe that doesn't have some. Most glitches don't cause problems. Therefore, it doesn't pay to trigger on glitches and look for problems. Rather, you have to trigger on the

problem and look for suspicious glitches around the problem.

Similarly, you can single-step forever through a piece of code without figuring out which portion is the culprit. It's far better to run the code and trap or break on its erroneous outputs. If you've done your initial design using data-flow analysis, you'll find it easy to check the program's functioning against the design. Most debugging tools (Kontron's is the exception) aren't set up to do explicit data-flow monitoring; they are set up to do program-flow monitoring. You have to build your own data-flow system on top of the program-flow primitives of the development system. So that you can appreciate the enhancements of integrated systems, consider how you'd monitor data flow with a simple, monitor-based debugger.

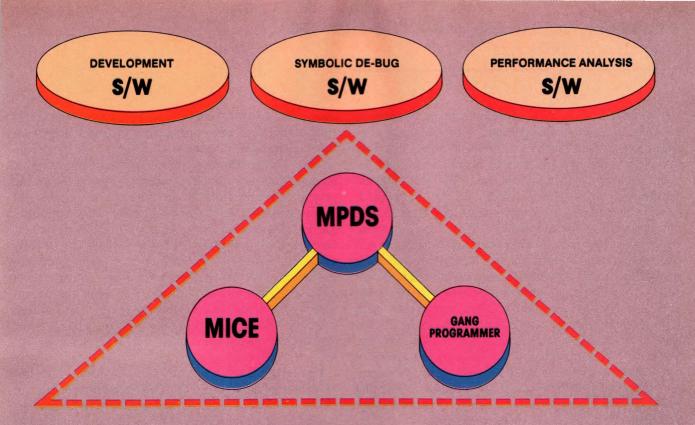
Begin with basic monitor

These debuggers usually allow you to execute to a breakpoint or to single-step. They also have commands for examining and changing sequential memory locations. So you'd step through your program—one line at a time or perhaps many lines at a time—and after each step you'd dump the relevant memory areas on screen. As you'd probably repeat this sequence many times, hitting the same sequence of keystrokes over and over could prove annoying and lead to errors.

Therefore, even a simple monitor-based emulator like the Gould 9508A has a command buffer that you can load with a command string that does your data-flow monitoring. That way you can repeat the sequence you need over and over with just one command. And with one keystroke, the 9508A can redirect its input to the output of a host computer. That way, the host computer can send it a long string of commands as well. With some effort, you could program your host computer to send a command string to the 9508A that would download code, set up the emulator's memory and CPU registers, and command it to run. Then your host program could wait for the emulator to break. After the break, your program could send further command strings to interrogate the emulator. Based on an analysis of the results of the interrogation, your host program could restart the cycle or branch to another setup-and-test routine.

You really don't have to write all this software yourself anymore because most of the current crop of stand-alone in-circuit emulators, such as those made by Applied Microsystems, now have driver programs for common personal computers that do just these jobs. In addition, most of these emulators incorporate a simple assembly-language symbolic debugger.

The integrated-development-system makers go beyond these rudimentary facilities. They have three



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Emulators open a window into circuit under test

basic things to work with: program listings, instrument setup screens, and captured data. Each company massages these elements into a different form. The Tektronix LANDS system tries to make the target system's captured data look as much like the program listing as possible. Intel's I²ICE, on the other hand, tries to make the instrument setups look as much like the program editor as possible. With Intel's system, about 80% of the editor's commands and procedures will also manipulate objects on the emulator's and logic analyzer's control screens. In keeping with Intel's concept of blurring the distinction between writing code and testing it, you can patch your targeted code with high-level constructs using the editor right in the middle of an emulation session. With other systems, you'd have to exit emulation and fire up the editor to patch your program in high-level code. If you've done a lot of patches directly to the program image in machine code, you would have to use utilities like Motorola's that reconcile the source code to such changes.

Emulogic also seeks to make writing the program and testing it as much alike as possible. The firm has two ways to do instrument setup. One way is via the usual sort of simulated instrument front panel displayed on a CRT, where fields take the place of knobs and switches on a physical instrument. You move the cursor around on the screen to these areas and enter the setup information. The other method is to enter command strings. In Emulogic's case, these command strings look very much like C programs. The commands have some of the attributes of Unix command-shell utilities. You can redirect the input and output for your commands to various areas of the screen, disk, or printer. You can keep a log of all your command entries in a file. When you get a command sequence you like, you can edit the log and subsequently use it for a command file.

Kontron's control software comes set up for data-flow analysis, and it can dump data structures to a variety of predefined windows on the CRT's screen. Setup menus let you choose from several combinations of windows of different sizes. You also select the data format for each window. When the Kontron emulator breaks, you automatically get a look at the state of your data constructs. In other development systems you have to enter an explicit command string in order to get data dumps of various areas printed on the CRT's screen.

Integration shades into verification

As you test and integrate more and more of the project's modules, software integration merges imperceptibly into software verification. Most software gets tested with other software. But there are other ways to test software—ways that are very important to time-

conscious software engineers. For years mainframe computers have had software-performance hardware that unintrusively monitored activity on the mainframes' buses. These parasitic gadgets kept track of memory use and run times without slowing down the programs running on the computer. You can now get hardware-based software verification along with integrated development systems, as well as with most logic analyzers. But although software analysis is widely available, industry sources say that many software engineers don't yet understand or see the utility of software-performance analysis. The technique proves useful for identifying frequently used modules that could benefit from optimization. Even better, it can spot orphan modules, modules that aren't being used at all.

Hewlett-Packard alone offers a range of softwareperformance hardware. For a 64000 system, you can get either a 64620S (combination logic-state/software-performance analyzer board) or the 64310A (dedicated software-performance analyzer). The combination 64620S logic/software board shows that there's considerable overlap in function and hardware between a logic-state analyzer and a software-performance analyzer. Both machines look at the target system's address bus. Both also look at qualifiers to determine what kind of bus cycle is going on. The difference between the two is that the logic-state analyzer's primary purpose is to capture bus activity while the software analyzer's primary purpose is to count various classes of bus events. Of course, most logic-state analyzers have at least one counter (Emulogic's integrated development system has four, for example), so they can do software-performance analysis as well.

HP's 64310A dedicated software-analysis board is optimized for software analysis and hence can do some tricks that logic analyzers can't. The board's hardware is not too complex; it has a pair of word recognizers that toggle a bank of counters. The 64000 system automatically sets up the board to correspond to the target system's μP . You can program the board to monitor as many as 12 address ranges. Because the board has only one pair of word recognizers, it obviously can't look for all 12 ranges simultaneously. Instead, the board periodically (you choose the period) gets its word recognizers reloaded with a new pair of address-range limits.

Software analysis takes time

This is why you may have to run a software analysis for hours or even days; the software has to run long enough for the software analyzer to be sure to get a statistically valid sample of activity for each range—especially if some of the ranges are used infrequently.

You program the board to look for various classes of

Manufacturers of integrated development tools

For more information on integrated development systems, circle the appropriate numbers on the Information Retrieval Service card or contact the following manufacturers directly.

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Tektronix Inc Box 500 Beaverton, OR 97077 (503) 627-7111 Circle No 730

ZAX Corp 2572 White Rd Irvine, CA 92714 (800) 421-0982 **Circle No 731**

events—reads, writes, instruction fetches, etc. Because the target-system's clock rate is known, the integrated development system's computer can calculate time from the number of bus cycles captured. Then you decide how you want them counted. The board's word recognizers and counters can count events or bus cycles basically three ways: They can count the number of events or bus cycles either within a given range of addresses or outside a given range, and they can count the number of times two given addresses were accessed in a specific order.

From this relatively simple data, the 64000 can calculate a number of interesting statistics on your program and display the results in histograms labeled with module names right from your source program. It can calculate statistics (for as many as 12 modules) on how often an individual module gets used, how long the module takes to run, and how much time *isn't* consumed by a module. And, using the software analyzer's ability to increment its counters when it sees two particular addresses occur in succession, you can determine the order in which modules run and thereby get statistics on which modules are calling which other modules.

Thus, software verification is the last step in an integrated development system's suite of tools. Once

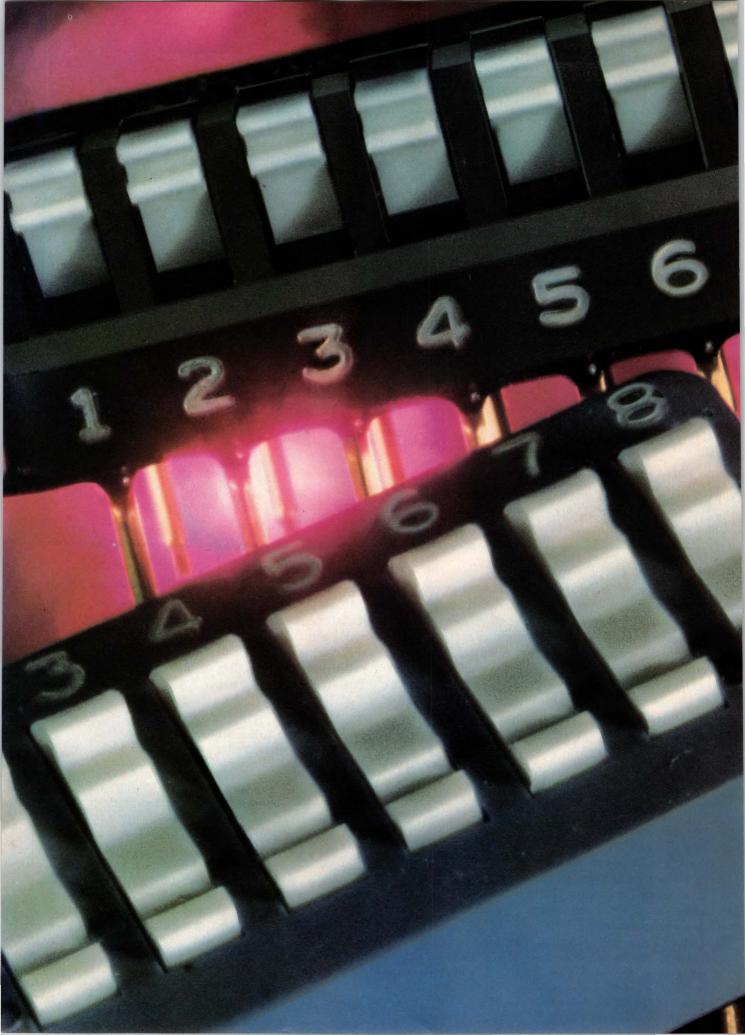
started, the design cycle never really ends. The verification step can feed right back all the way to the initial-specification stage and start the cycle all over again. And after the initial shipments of the product, the design cycle doesn't end; it's just renamed—it's called *maintenance*. But whatever the name, the cycle's steps remain the same.

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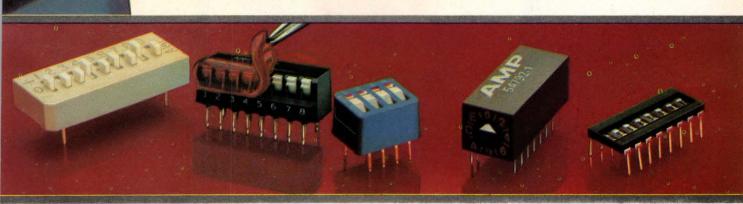
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Extended-processing units expand µP computing power

Specialized parallel-processing chips tied to a Z8000 CPU let you get more computing power from the µP, and the Z8000 family's extended-processing architecture increases the speed of slave interfaces.

Stephen R McMahan, Olympic Synthesis

The extended-processing architecture of Zilog's Z8000 provides a flexible, modular approach for expanding CPU hardware and software capabilities with parallel-processing add-on chips called extended-processing units (EPUs). When you tie an EPU like the Z8070 arithmetic-processing unit to the CPU, the Z8070 performs floating-point mathematics while the CPU operates in parallel. By adding interface hardware, instruction coding, and timing logic, you can also create a generalized hardware EPU interface that is separate from memory or I/O spaces. This interface can be used for data and instruction passing to slave processors, for system-overhead control, and for other such functions.

In addition, you can use the EPU block move in a LAN Controller for Ethernet (LANCE) interface to provide a generalized memory-to-memory transfer mechanism. The EPU block move lets the CPU share a pair of RAM buffers with the LANCE and still transfer data continuously by running the buffers in an interleaving mode.

The EPU structure, combined with the EPU flag in the Z8000's flag and control-word (FCW) register, is a special type of instruction trap. When you reset the EPU flag (EPU not selected), the Z8000 recognizes certain instructions as EPU instructions, and it vectors to a preset point in the software. This vectoring allows the software either to emulate an EPU (for example, one floating-point software package emulates the Z8070) or to execute a program (such as a system-overhead routine).

With a Z8002 CPU or a Z8004 virtual-memory processing unit (VMPU), this vector point resides in the program-status-area header, +0002H, and consists of two words—the new FCW and the new program counter. With a Z8001 CPU or a Z8003 VMPU, the vector point is located at the program-status-area header,

TABLE 1—EPU INSTRUCTION FORMATS

FCW TO EPU	
:1000:1110:NU	:10:XX:
: NU :0000: NU	:00 00:
EPU TO FCW	
:1000:1110:NU	:00:XX:
: NU :0000: NU	:00 00:
CPU TO EPU	
:1000:1111:0:NU	: 10:XX:
: NU : DST : NU	: N-1 :
EPU TO CPU	
:1000:1111:0:NU	:00:XX:
: NU : SRC : NU	: N-1 :
MEMORY TO EPU	
: Md: 0 0 : 1 1 1 1 : SRC	: 01:XX:
:NU :NU :NU	: N-1 :
EPU TO MEMORY	
: Md: 0 0 : 1 1 1 1 : DST	:11:XX:
:NU :NU :NU	: N-1 :
EPU INTERNAL INSTRUCTION	
:1000:1110:NU	: 1 : X X :
; NOT USED	:: N-1 :

EDN NOVEMBER 29, 1984

Parallel operation speeds peripherals

+0004H, and consists of four words. Three of these words contain the FCW, the program-counter segment, and the program-counter offset; the first word is reserved by the manufacturer for internal use.

When you set the EPU flag, the CPU recognizes EPU instructions and acts on them accordingly. Each EPU monitors the instruction-fetch cycle and recogniz-

TABLE 2—EPU ASSEMBLER STATEMENTS

INTERNAL OPERATION—

XCTL EPU0—3, #BYTE, #BYTE
EPU TO CPU MULTIPLE—

XLDM dstREG, EPUO—3, # OF WORDS, #BYTE
CPU TO EPU MULTIPLE—

XLDM EPUO—3, srcREG, # OF WORDS, #BYTE
EPU TO MEMORY MULTIPLE—

XLDM dst REG,EPUO—3,#of words,#byte
Memory to EPU multiple—

SLDM EPUO—3, srcREG, # OF WORDS, #BYTE
FCW TO EPU

XLDCTL EPUO—3, FLAGS, # BYTE
EPU TO FCW

XLDCTL FLAGS, EPUO—3, # BYTE

es its own instructions; then it performs the internal setup required to implement the instructions. As shown in the following EPU instruction structure, all EPU instructions are in double-word format.

M1 CYCLE-:XXXX :XXXX :XXXX :XX:XX-EPU ID#
Mn CYCLE-:XXXX :XXXX :XXXX :XXXX:

C B A N
NIBBLE NIBBLE NIBBLE FIELD

The two least significant bits (LSB) of the first word make up the EPU ID number; this leaves room for four EPUs in a system. Generally, the C and A nibbles don't affect EPU instructions. However, you can use these nibbles to expand the capabilities of a hardware extended-processing unit (HEPU). The N field holds the number of words moved (expressed as N-1) in transfers either between the memory and the EPU or between the CPU and the EPU. For transfers between the memory and the EPU, the E field designates the CPU register that points to the memory position at which the transfer initializes. For transfers between the CPU and the EPU, the B nibble specifies the

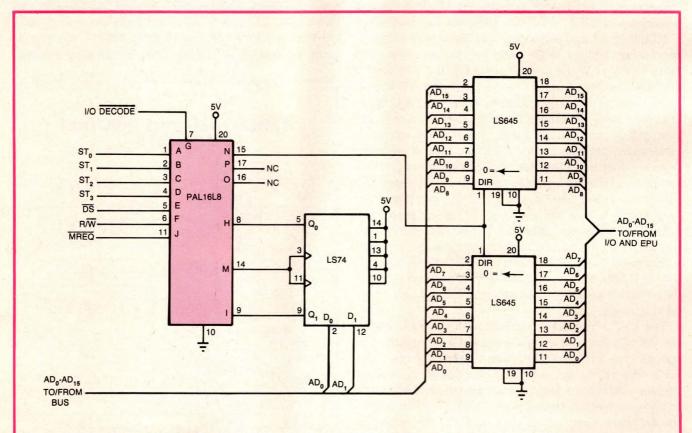


Fig 1—Instead of being included with the CPU buffers, an EPU can share a board with I/O. A PAL controls this simple circuit.

starting register from which (or to which) the transfer occurs. The multiple register transfers shift through the registers (R0-R15) and then wraps around, so that R0 follows R15.

Table 1 provides the specific formats of each of the EPU instructions. Table 2 lists the Western Wares (Placerville, CO) ZAS 2.0 assembly-language statements for these EPU instructions. The first byte (#byte) following the source in each statement corresponds to the C and A nibbles. The second byte refers to the B-nibble, N-field combination.

Plan your timing and control signals

The main timing and control signals for the EPU are Read/Write (R/W) and Data Strobe (\overline{DS}). Timing and control during FCW and CPU transfers are much the same as in a normal I/O or memory transfer. The difference between them is that you must code the CPU status (ST_0 through ST_3) for EPU transfers. The difference between CPU cycle timing and the timing for the transfers between the CPU and the EPU is that the

CPU doesn't recognize any wait states for EPU transfers.

When the EPU resides outside the CPU buffers, EPU decoding must also control the EPU buffer direction and data strobing. But the situation changes for transfers between memory and the EPU; R/\overline{W} is now referenced to the memory end of the transaction. When memory is the source, R/\overline{W} is High; when memory is the destination, R/\overline{W} is Low. The CPU provides timing and status for the transfer and transfers the data between the EPU and the memory in flyby fashion. The CPU also provides the address, which is relative to the memory end of the transfer, and sets the address/data lines (AD₀ through AD₁₅) to 3-state during the data transfer. When the EPU resides outside the CPU buffers, you must set the CPU buffers to 3-state during the data transfer.

When memory is the source, the EPU grabs the data on the rising edge of \overline{DS} . When the EPU is the source, it must put the data on the bus prior to the falling edge of \overline{DS} .

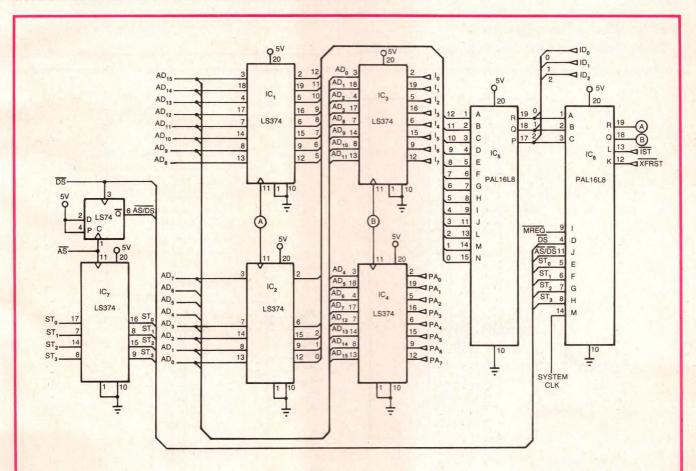


Fig 2—You can use EPU architecture to build a generalized hardware EPU interface. Flag and control-word transfers are not permitted in this circuit.

Hardware EPUs must decode EPU instructions

The code must specify which EPU is going to be active. This look-ahead function, combined with the ST_0 -through- ST_3 decode and R/\overline{W} , steers the data path. The status codes, ST_3 through ST_0 , for calling EPUs are:

1010 DATA MEMORY REQUEST 1011 STACK MEMORY REQUEST 1110 CPU, EPU TRANSFER.

The status lines do not indicate EPU internal operations, which may require as many as 16 cycles to execute. The N field determines the instruction length.

Internal operation is typically synchronized with the nth machine cycle, Mn. At the end of each T3 (a full machine cycle) during an EPU internal instruction, the CPU monitors the Stop line. By pulling the Stop line low, the EPU forces the CPU to wait until the EPU has finished its internal instruction. The CPU runs through a series of memory-refresh cycles until the EPU releases the Stop line, enabling the CPU to download a process to the EPU and wait for the result without an interrupt.

EPU decoding is straightforward

For an example of EPU decoding, look at the coding

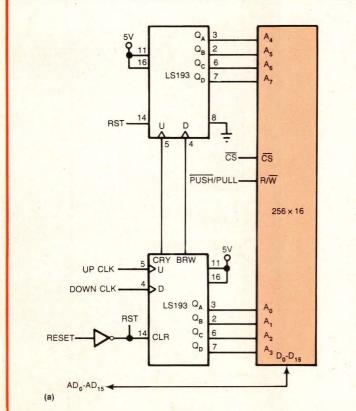
for an EPU that resides outside the CPU buffers and shares a board with I/O. Fig 1 illustrates such an interface. To catch the EPU ID number, the interface must latch AD_0 and AD_1 on the rising edge of \overline{DS} during the M1 cycle. By clocking the LS74 with the PAL output M, you can latch the EPU ID number.

You can assign the EPU an ID of 0. If you use an EPU like the Z8070, the EPU will respond to all instructions directed to EPU #0.

During transfers between memory and the EPU, the

TABLE 3—PAL EQUATIONS FOR FIG 1 CIRCUIT

PAL16L8
EPU/DEC1
A B C D E F G H I GND
J K L M N O P Q R VCC
/M = /E + /F + /A + B + /C + /D
/N = /E * /G * F + /O
/P = B * /C * D * /F * /J * /H * /I
/O = /P + /A * B * C * D * F * /E * /H * /I



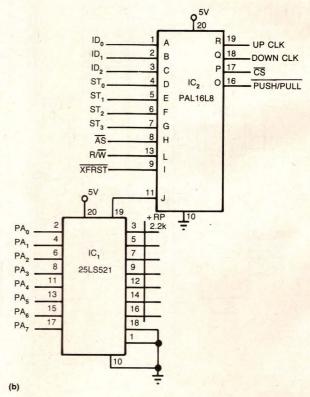


Fig 3—A simple push-pull stack is easily built with a hardware EPU interface (a). The interface between the HEPU interface and the push-pull stack is illustrated in b.

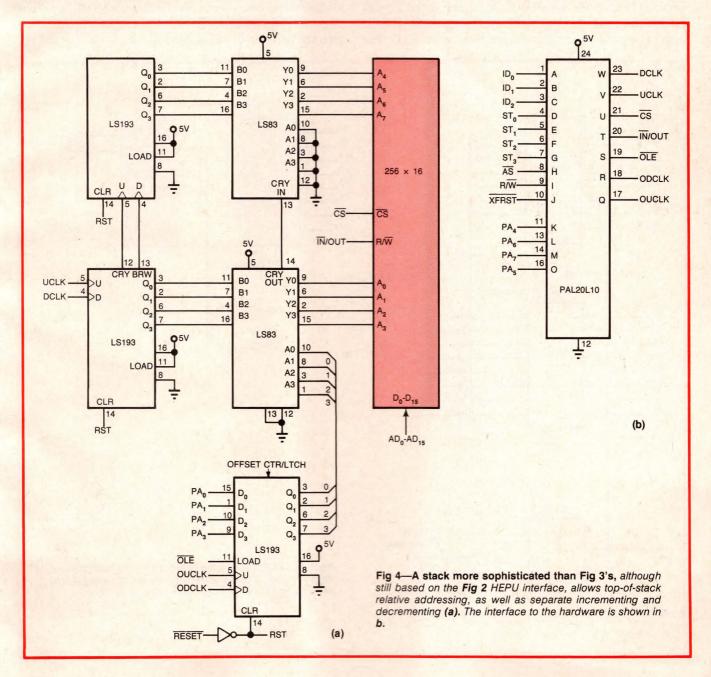
data flows counter to the direction of the R/\overline{W} line. When the EPU is the source, it feeds data onto AD_0 through AD_{15} prior to the falling edge of \overline{DS} (but after the address floats). During transfers between the CPU and the EPU, the data follows the direction of R/\overline{W} , with \overline{DS} gating the data out of the buffer.

PAL output N (Fig 1) controls the data direction. When the EPU is the source for a memory transfer, the P—O—N chain delays Memory Request (MREQ) to prevent a bus contention. Table 3 gives the PAL equations.

In the /N equation, the /E*/G*F term steers the I/O data and the /O term steers the EPU data. The /P term

steers the EPU memory data. In the /O term, gates in the PAL delay /P. The rest of the equation controls data between the EPU and the CPU.

After you've worked with the EPU decoding, you can try using the EPU structure to do some non-EPU work. With the addition of some instruction decoding and timing logic, you can create a generalized HEPU interface. You can use such an interface to facilitate data and instruction passing to slave processors, implement system-overhead control, provide a parallel-processing interface to dedicated processors (such as I/O processors or high-efficiency bit-slice peripherals), establish a workspace outside of memory or I/O, create



Establish a workspace outside of memory or I/O

multiple stacks, and support RAM and ROM disks. These are only a few examples; you'll find many more uses for HEPU interfaces.

For non-EPU hardware, the interface must monitor and decode the EPU instructions, provide timing and control to the hardware, and pass pertinent information to the hardware. Fig 2 shows a generalized HEPU interface operating in EPU₃ space. Disallowing FCW transfers is the only restriction on this HEPU interface. Table 4 lists the PAL equations used to build the circuit in Fig 2.

On the falling edge of T3, during M1, the CPU clocks the AD lines into the first set of latches (IC₁, IC₂). IC₅ decodes these lines to indicate the presence and type of HEPU instruction. The CPU encodes these HEPU instructions onto the three output lines of the PAL. The

identification lines (ID2-ID0) are encoded below.

000 HEPU TO MEMORY

001 MEMORY TO HEPU

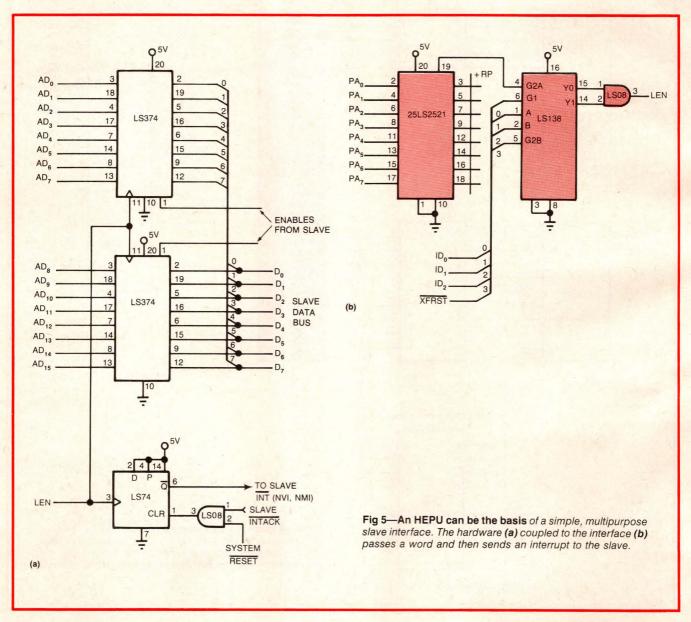
010 HEPU TO CPU

011 CPU TO HEPU

110 HEPU INTERNAL INSTRUCTION

111 NO HEPU INSTRUCTION

The CPU passes these lines to the HEPU bus and the second stage of the HEPU interface. For transfer instructions, this status arrives three clock cycles before the actual transfer if the CPU doesn't use any wait states during the instruction-fetch cycles. On the falling edge of T3, during Mn, the CPU clocks the AD lines into the second set of latches (IC₃, IC₄). The second set



of latches passes all the lines to the HEPU bus.

 IC_6 provides the timing for the HEPU bus and interface. For an internal instruction, IC_6 generates the internal instruction strobe (\overline{IST}) that goes low with the rising edge of \overline{DS} and high with the falling edge of the address strobe, (\overline{AS}). The transfer strobe (\overline{XFRST}) is the gated result of \overline{DS} and the EPU transfer decode from the CPU status lines.

HEPU interfaces transfer data to CPU

For memory-to-HEPU transfers, IC₆ generates XFRST with the output from \overline{DS} gated with $\overline{R/W}$ and the CPU status. Generating \overline{XFRST} for the HEPU-to-memory operation is not as straightforward as the reverse operation. You need to gate R/\overline{W} and either EPU memory request or EPU stack request with MREQ, creating both a delay to avoid contention with the address output from the CPU and a data setup time for the memory. The HEPU interface outputs pass to the HEPU bus, which you can add to the mother bus or the backplane. The HEPU bus comprises the following signals:

HEPU INSTR. ID	$\mathrm{ID}_{\mathrm{o}}\text{-}\mathrm{ID}_{\mathrm{2}}$
HEPU PORT ADDRESS	PA ₀ -PA ₇
HEPU PORT INSTR.	PI_0-PI_7
TRANSFER WORD COUNT	XW_0-XW_3
INTERNAL INSTR. STROBE	IST
TRANSFER STROBE	XFRST
ADDRESS-DATA STROBE	AS-DS.

Using the internal HEPU instructions, you can design your own instruction set. The following are assembly-language mnemonics for the internal instruction.

XCTL EPU 3, #(PA-7), #(PI-7)

The parentheses highlight the immediate bytes but are not part of the ZAS 2.0 syntax. This instruction lets you pass 16 bits as two bytes. The HEPU interface passes both bytes in the second word of the instruction fetch. The first byte contains the C and A nibbles; the second byte contains the B nibble and N field. You can split these bytes into any field configuration at the destination, so you can pass 16 bits throughout the system or eight bits to 256 ports. You can also pass 12 bits to 16 ports, and so on. The application determines the format, rather than the converse.

LIFO interfaces feature high performance

Now that you have completed the interface, you can try a few applications. The simplest stack is the classic push-pull, last-in/first-out (LIFO) structure. The hardware includes up/down counters and RAM. Fig 3a illustrates such a push-pull stack; Fig 3b gives the interface to the stack from the HEPU interface. The PAL equations are presented in Table 5.

ZAS 2.0 defines a push as

XLDM EPU3, SRC, #(NO WORDS PUSHED), #7F and a pull as

XLDM DST, EPU3, #(NO WORDS PULLED), #7F.

Before each push, the up clock cycles once. AS, gated

TABLE 4—PAL EQUATIONS FOR FIG 2 CIRCUIT

PAL16L8 HEPU PAL1 ABCDEFGHIGND JKLMNOPQRVCC /R = N * M * /A * /C * /D * E * F * G * H * J * L + N * M * A * /B * /C * /D * E * F * G * H * /I * /J * /L + N * M * A * /B * /C * /D * E * F * G * /H * L /Q = N * M * /A * /C * /D * E * F * G * H * L + N * M * A * /B * /C * /D * E * F * G * H * L /P = N * M * /A * /C * /D * E * F * G * H * L + N * M * A * /B * /C * /D * E * F * G * H * /l * /L PAL16L8 HEPU PAL2 ABCDEFGHIGND JKLMNOPQRVCC /R = D + /E + F + /G + /H/Q = D + E + F + /G + /H/L = /A * B * C * /J /K = A * /C * /D * F * /G * H + /A * /C * /I

TABLE 5—HEPU SIMPLE STACK PAL EQUATIONS

PAL16L8

STACK 1

A B C D E F G H I GND

J K L M N O P Q R VCC

/R = /J * /H * /C * A * E * /F * G

/Q = /J * /I * /C * /A * E * /F * G

/P = /J * /C * B * /I

+ /J * /C * /B * /A * /I

/O = /L * /C * B

+ L * /C * /B * /A

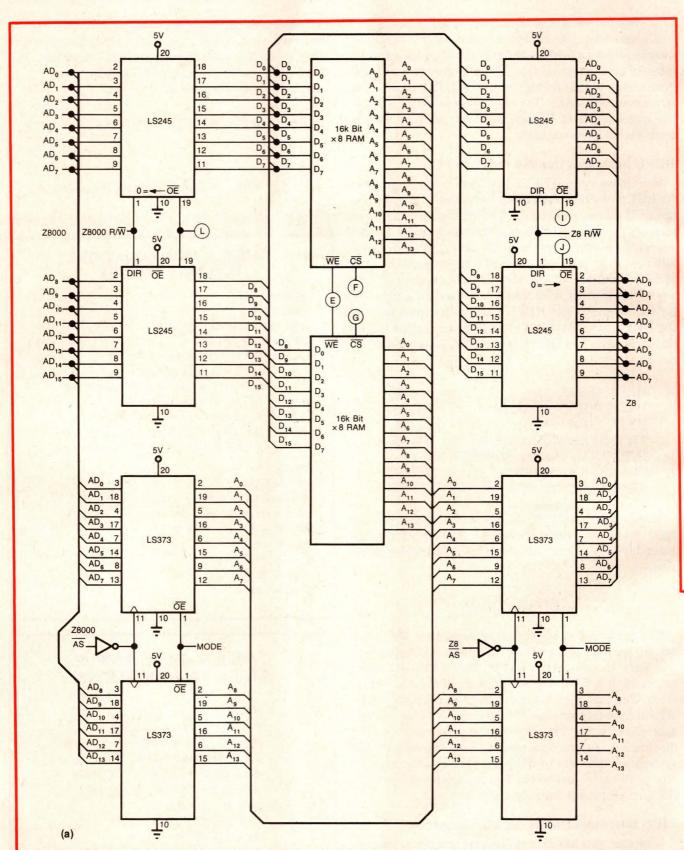


Fig 6—Although more sophisticated, this slave buffer is functionally similar to Fig 5's interface. The hardware is illustrated in a, the interface in b.

with the look-ahead status and decode—and in conjunction with the correct CPU status decode—generates the up-clock signal. The down clock cycles once after each pull. XFRST, in conjunction with the correct decode, creates the down clock.

Combined with the correct stack decode, XFRST creates the Chip Select (CS). The RAM needs to be less than 70 nsec.

Top of stack reads/writes relatively

A more complicated stack permits Top-Of-Stack (TOS) relative addressing and separate increment and decrement handling. Fig 4a illustrates the core of such a stack; Fig 4b shows the interface to the stack. Table 6 lists the PAL equations for this stack.

This type of stack can function as a normal push-pull

TABLE 6—TOP OF STACK PAL EQUATIONS

PAL20L10
STACK 2
A B C D E F G H I JK GND
J K L M N O P Q R STUV VCC
/V = /O * A * E * /F * G * /C * L * /H * K * M
/W = /O * /A * E * /F * G * /J * K * /C * L * M
/U = L * /J * /C * B * M
- + L * /C * /J * /B * /A * M
/T = /I * /C * B
+ I * /C * /B * /A
/S = /D * /E * F * G * I
/R = O * /K * L * A * /C * E * /F * G * M

stack and as a stack that allows multiple read/writes in TOS relative mode—without affecting the TOS. You structure the immediate byte (PA₀-PA₇) as:

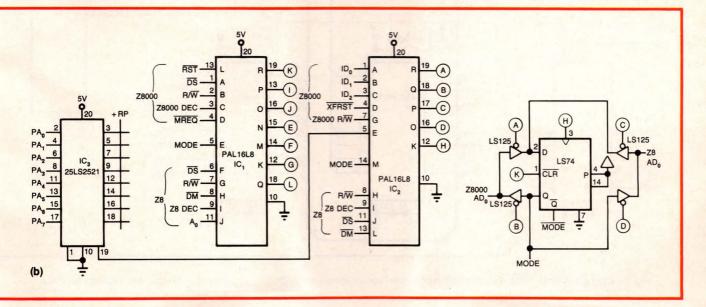
	OFFSET	TOS	OFFSET
STACK	INC/DEC	INC/DEC	
DECODE	ENABLE	ENABLE	
XX	X	X	XXXX-LSB.

A Forth-based system is a good application for an auxiliary stack. **Table 7** shows how you would code typical Forth stack manipulations.

Next, you can try slave interfacing. The simplest

TABLE 7—TYPICAL FORTH MANIPULATIONS

DUP		EX	R2,R3
XLDM	R2,EPU3,#%00,#%C0	XLDM	EPU3,R2,#%01,#%D0
xLDM	R2,EPU3,#00,#D0	2SWAP	
SWAP		XLDM	R3,EPU3,#%03,#%E0
XLDM	R2,EPU3,#%01,#%D0	EX	R3,R4
EX	R3,R2	EX	R5,R6
XLDM	EPU3,R2,#%01,#%D0	XLDM	EPU3,R3,#%03,#%E3
ROT		2ROT	
XLDM	R2,EPU3,#%02,#%D0	XLDM	R2, EPU3,#%05,#%E0
LD	R5,R4	EX	R6,R7
LD	R4,R2	EX	R2,R5
XLDM	EPU3,R3,#%02,#%D0	EX	R3,R4
OVER		XLDM	EPU3,R2,#%05,#%E5
XLDM	R2,EPU3,#%00,#%C1	20VER	
XLDM	EPU3,R2,#%00,#%D0	XLDM	R2, EPU3,#%01,#%E2
2DUP		EX	R2,R3
XLDM	R2,EPU3,#%01,#%E0	XLDM	EPU3,R2,#%01,#%D0



slave interface (Fig 5a) passes one word and then interrupts the slave. Typical slave operations include local-area-network (LAN) controllers and intelligent disk controllers. Fig 5b is an example of an interface decoder.

Using this type of slave interface has one advantage over direct CPU or DMA access—it doesn't create holes in the memory map. Fig 6a shows a more realistic slave buffer than the simple one in Fig 5a. Fig 6b gives the interface decoder for this improved slave buffer, and Table 8 provides the programs for both PALs.

CPU polls parallel boards

The structure for transferring data between the CPU and the HEPU allows the CPU to test or set bits on the Z8000 side of the buffer. At power-up, the mode latch resets to Z8000 mode. The CPU can test the mode latch on the Z8000 side at data bit 0 in an HEPU-to-CPU transfer. The CPU can set the mode latch to Z8 mode by a CPU-to-HEPU transfer. When the interface

is in the Z8000 mode, data bit 0 provides the data for the mode latch.

The Z8000 can poll and set as many as 16 parallel boards, each of which has been assigned to a different data bit. On the Z8 side of the buffer, the Z8 performs the test and reset functions, and it reads and writes the data in a single memory location. As before, the Z8 uses data bit 0 to pass data. The Z8000 and Z8 may poll the mode latch in either mode, but they can only set the mode latch in their respective modes.

The circuitry described to this point works with either a 4- or a 6-MHz CPU, but the timing is incompatible with a 10-MHz CPU. Fig 7 shows an HEPU interface modified to run at 10 MHz with the PAL codes listed in Table 9.

You can see several changes to the interface, compared with the original. The PALs perform basically the same functions, but Schottky parts pass the timing, with the PALs providing a look-ahead function to the timing. Some other components included are Am29845s

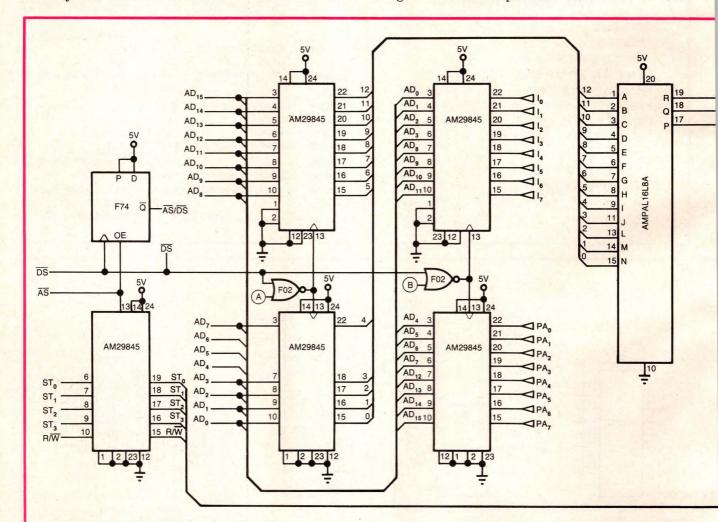


Fig 7—Operating at 10 MHz, this modified HEPU interface improves performance with Schottky devices and high-speed PALs.

and AmPAL16L8As. The Am29845s are fast transparent latches, optimized for suppressing metastates. The AmPAL16L8As are also fast devices.

10-MHz HEPUs

The next HEPU application targets 10-MHz Z8000 applications. The Z8000 family doesn't have a direct-memory-access (DMA) chip that runs at 10 MHz. That leaves you with three options: You can adapt the Z8016A for use at 5 MHz, rely on the CPU block-transfer instructions, or use the EPU structure. The first choice requires extensive hardware modification and provides a throughput of only about 1.7M bytes/sec. The second choice offers a throughput of about 2.2M bytes/sec. The third choice is capable of giving you a throughput of about 3.9M bytes/sec. (Throughput figures are calculated based on a transfer of 32k bytes in word mode, assuming the Z8016A runs in a flow-through mode.)

In an application such as a LANCE interface, the

EPU block move allows the CPU to share a pair of RAM buffers with the LANCE and still transfer data continuously by running the buffers in an interleaving mode. The speed of the EPU block transfer permits the CPU to fill one buffer and load the task to the LANCE. While the LANCE is transmitting from one buffer, the CPU can monitor the buffer's status and fill the other buffer. The same holds true for the receive mode. The only interruption in the process arises when the LANCE issues an interrupt to the CPU.

This application is a generalized memory-to-memory transfer mechanism. Fig 8 is a schematic of the hardware that implements a fast block transfer between the EPU and memory.

EPUs access parallel blocks

You might think that **Fig** 8 shows a lot of hardware for just 64k bits of RAM. But keep in mind the speed of transfer and the cost of 55-nsec RAM. By adding two more PALs and appropriate RAM decoding, you can

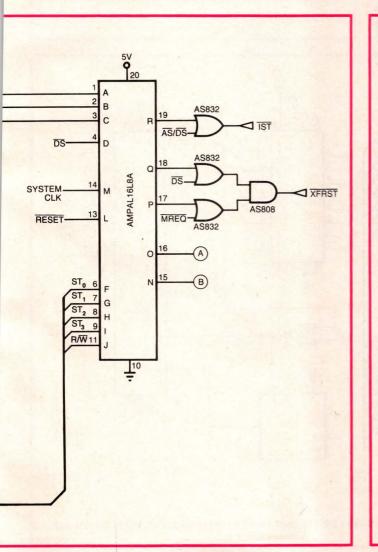


TABLE 8—Z8000 - Z8 BUFFER PAL EQUATIONS

PAL16L8 Z8K-Z8PAL1 ABCDEFGHIGND JKLMNOPQRVCC /P = E * J * L * /I * /H * /F * G + E * L * /G /O = E * /J * L * /I * /H * /F * G + E * L * /G /N = /E * /A * /B * /C * D+ E * /F * /G * /H * /I /M = /E * /A * /B * /D+ E * /F * /H * /I * J /K = /E * /A * /B * /D + E * /F * /H * /I * /J /Q = /E * /A * /C * B * L + /E * /B * /C * /D * L PAL16L8 Z8K-Z8PAL2 ABCDEFGHIGND JKLMNOPQRVCC /R = /M * /G * A * B * /C * /E

/P = M * /L * /H * /I /O = M * /L * /H * /I * /J /N = M * /L * /J * /I * /H

/Q = /M * G * /A * B * /C * /E * /D

32-bit processors implement extended processing

access 256 of these 64k-bit RAM disks.

The interface works as a RAM disk, using the EPU structure for setup and accesses. When it's not enabled by mode decode, the bus accesses the RAM in normal memory space. The HEPU interface latches the mode decode signal from the I_0 HEPU line using the \overline{IST} signal in conjunction with the P_0 - P_7 decode. The mode decode is active-Low, which enables transfers between the CPU and the HEPU and between the HEPU and the memory. The interface always responds to its internal operation.

When mode decode enables data exchange, a transfer between the CPU and a HEPU port loads the counters with the origin address. (When not enabled, the counters act as address latches.) From then on (until the bus disables mode decode), the CPU transfers data between memory and the HEPU in flyby fashion, with the PAL in Fig 8 automatically incrementing the RAM disk address. The XFRST signal compensates for the destination, source (dst,src) differential in timing.

The manufacturer plans to include EPU capabilities on the Z800 and Z80,000 processors. Because of the

TABLE 9—10 MH HEPU INTERFACE PAL EQUATIONS

PAL16L8
10MPAL1
A B C D E F G H I GND
J K L M N O P Q R VCC
/R = N * M * /A * /C * /D * E * F * G * H * J * L
+ N * M * A * /B * /C * /D * E * F * G * H * /I * /J * /L
+ N * M * A * /B * /C * /D * E * F * G * /H * L
/Q = N * M * /A * /C * /D * E * F * G * H * L
+ N * M * A * /B * /C * /D * E * F * G * H * L
/P = N * M * /A * /C * /D * E * F * G * H * L
+ N * M * A * /B * /C * /D * E * F * G * H * L

PAL16L8

10MPAL2

A B C D E F G H I GND

J K L M N O P Q R VCC

/R = L * J * /A * B * C * /F * /G * H * I

/Q = /C * /B * L * G * /H * I

/P = /C * /B * L * G * /H * I

/O = L * J * /D * F * /G * H * I * M

/N = L * J * /D * /F * /G * H * I * /A * B * C * M

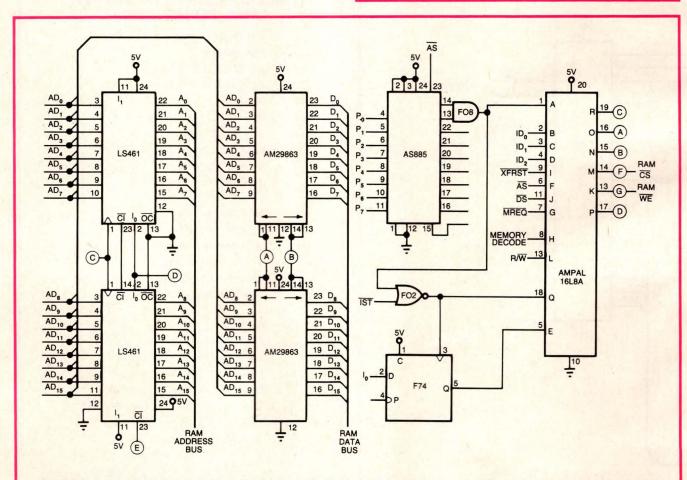


Fig 8—This block-transfer circuit speeds communication between the EPU and memory. The design is related to a RAM-disk circuit.

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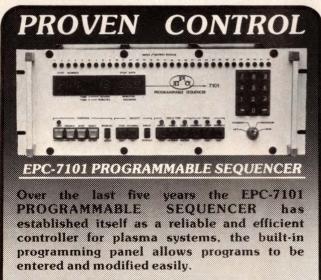


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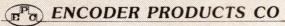


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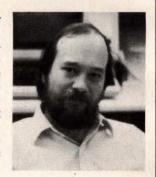
design of their respective instruction-fetch cycles, HEPU interfaces are most easily implemented on the Z8000; the Z80,000 implementation is more difficult, and the Z800 is the most complex.

Acknowledgments

The author wishes to thank Gary Beals of Zilog Inc for information and technical review and Rich Hollenbeck of Western Wares for improvements to the design of the ZAS assembler.

Author's biography

Stephen McMahan is owner of Olympic Synthesis (Seattle, WA), a firm specializing in digital audio and synthesizer designs. He has worked for the past three years as a design technician in the market development products department at Data I/O Corp (Redmond, WA). Stephen enjoys music composition and electronic music.



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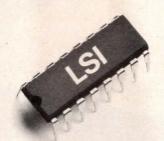
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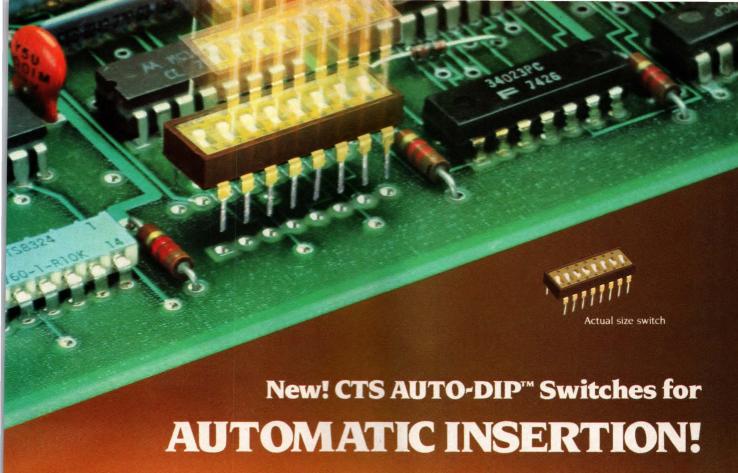
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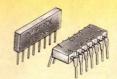
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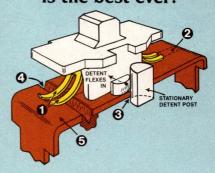


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Eliminating protection circuitry reduces switching-supply costs

Crowbar-type overvoltage and foldback-mode current-limit circuits are needless in many switching-supply applications.

A study of supply circuitry shows why you can often eliminate such protection functions.

D J Becker, Lorain Products

If you design or specify switching-regulator-based power supplies, you can often realize cost savings by eliminating the crowbar-type overvoltage and foldback-characteristic current-limiting circuitry used in many such supplies. What's more, you can dispense with these circuits without compromising the safety of the supply or its load.

The cited protection schemes owe their existence to previous necessity; they were generally an outgrowth of linear-power-supply characteristics. A comparative study of the attributes and failure mechanisms of linear and switching-regulator supplies shows why the costly protection circuits are often unnecessary in switching supplies.

Linear-supply development

To see why voltage and current limiting are needed in linear supplies, it's important to understand how these supplies operate—specifically, how they relate to their respective loads. The linear power supply (Fig 1) has a single series element that's responsible for the output regulation. This element is usually a bipolar transistor or a power MOSFET. The supply regulates the output by using some kind of electronic control to vary the conductivity of the series transistor.

The transistor is in series with the unregulated input line; it continuously adjusts the excess voltage between input and output. Some of the linear supply's advantages are that it regulates well, it's relatively simple, and it has very low output noise. A major drawback, however, is that if the series pass element fails (and bipolar transistors usually fail dead short), the total

potential of the unregulated input source appears across the supply's output terminals. This high voltage can result, for example, in the failure of all logic elements connected to the supply. This dead-short failure mechanism is the reason for the development of the crowbar circuit.

Crowbar overvoltage limiting

You can consider the crowbar circuit the last-resort effort by the power supply to protect any critical load connected to the output terminals. Fig 2a shows that failure of the series-pass element results in a rapid voltage rise across the load. Failure to contain this voltage within a specified limit (eg, 6V for TTL circuits) is catastrophic: Excess voltage can burn out the load circuitry. The purpose of Fig 2b's crowbar circuit is to

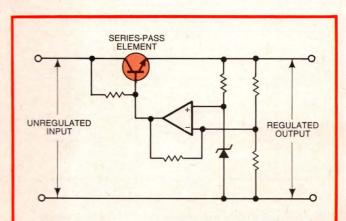


Fig 1—A linear power supply's series-pass element is subject to dead-short failure if overloaded. This fact mandates foldback current limiting (to protect the pass element) and crowbar overvoltage protection (to protect the load).

Linear power supplies need crowbars, foldback limiting

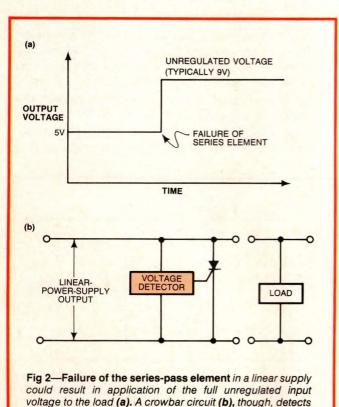
detect the fast-rising voltage front and provide a highconductivity path to the return.

The conductive path is designed to draw enough current from the unregulated input source to prevent the voltage from damaging the load. The crowbar must be of sufficient size to handle the large current drawn from the unregulated line, for at least the time it takes for some sort of protection device (eg, a fuse or circuit breaker) to activate. The conditions that trigger a crowbar circuit are rarely caused by any supply-electronics fault other than failure of the series-pass element itself. Typical causes of failures of the series device are thermal breakdowns caused by excess power dissipation.

Foldback current limiting

A second consideration in linear supplies is the use of a foldback current-limiting circuit. As **Fig 3a** shows, the nomenclature "foldback current limiting" is appropriate: The output current folds back in value, and the output voltage decreases when the load demands exceed a preset value. The foldback characteristic owes its development to the needs of the series-pass element, which dissipates most of the power during a fault condition.

Consider, for instance, the condition shown in Fig 3b.



the series-pass element's failure and immediately short cir-

cuits the power-supply output.

OUTPUT CURRENT 2A

TURNING ON INTO A CONSTANT-CURRENT LOAD CAN LOCK UP POWER SUPPLY

CURRENT-LIMIT SET POINT

OUTPUT CURRENT 2A

(b)

OUTPUT CURRENT 2A

Fig 3—Foldback (a) and straight (b) current limiting differ markedly. In the former, exceeding the preset rated current causes both the supply's output voltage and the current to decrease according to the load line. The straight limiter, on the other hand, allows the full input-output differential to appear across the series-pass element at currents as high as the full-load limit.

Assuming a 24V raw input voltage, the drop (the difference between output and raw input voltages) across the series device is 6V. If the supply is delivering 2A, the power dissipation in the series-pass element is 12W. In providing for this 12W power, you must consider the capabilities of the selected series-pass device and also the thermal path necessary to keep the device's dissipation within the specified limits.

A standard TO-3 transistor (eg, the 2N3054) has a 7°C/W junction-to-case thermal-resistance specification. You must therefore select an appropriate heat sink to keep the transistor's junction temperature within operational limits. If you choose a heat sink with 2°C/W thermal resistance, the total junction-to-air thermal resistance is 9°C/W. This resistance results in a temperature rise of 108°C (9°C/W×12W) from junction to air. For a device that operates at 40°C ambient temperature, the 108°C gradient produces a 148°C junction temperature, roughly 74% of the 2N3054's operating-temperature capability.

Consider now a thermal analysis for a short circuit. The total 24V unregulated input voltage appears across the series-pass element. If, under these conditions, you use a nonfoldback scheme (**Fig 3b**) that limits current to 110% of the nominal 2A full-load current, the total power dissipation in the series-pass device is 52.8W. Assuming use of the previously described transistor and heat-sink system, the total gradient from air to junction is 475°C, and the transistor fails quickly.

The short-circuit example demonstrates the reason for the development of foldback current limiting. In this protection mode, a fault forces a reduction in output voltage; the output current is also forced back to some lower value, thereby keeping the junction temperature of the series-pass transistor within the manufacturer's ratings. If, in the example given here, the junction-temperature rating is 200°C, you can calculate what the short-circuit current limit must be to maintain the 200°C limit.

The allowable rise in a 40°C ambient temperature is 160°C. Using the 9°C/W transistor/heat-sink thermal

UNREGULATED INPUT CONTROL CIRCUIT

Fig 4—A chopper-type switching power supply needs no transformer between input and output. Like linear supplies, the chopper supply uses a series-pass element. Therefore, a crowbar protection circuit could be required to protect the series element.

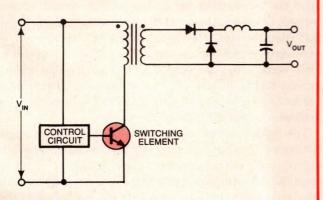


Fig 5—In forward-converter switching supplies, the transformer provides inherent protection that eliminates the need for crowbar and foldback current-limiting circuitry.

resistivity, the total power allowed in the series-pass element comes to only 17.7W. With 24V unregulated input voltage, the total allowable output current in a short-circuit condition is thus 0.74A. These figures indicate that the current-limiting circuitry must start its foldback action at approximately 2.2A; by the time the output voltage falls to 0V, the current must decrease to about 0.75A.

Remember that during a short-circuit condition, the foldback current-limiting circuit's purpose is to protect the linear power supply's series-pass element and not the critical load. Even if your power-distribution system has some sort of fuse protection, the fuses are not able to sense the fault condition because the foldback circuit limits the available current and thus prevents the fuses from operating.

Although linear supplies by nature need either crowbar-type overvoltage or foldback-mode current-limiting protection, switching power supplies generally don't. However, you should consider two types of switching-regulator topologies in your assessment of the need for one or both of the protection options. The first topology is embodied by the chopper-type circuit in Fig 4, in which there is no transformer connection between the unregulated input and the regulated output.

The schematic shows that there can be a direct connection between the input and output, similar to that of the previously discussed linear (series-pass) supply. If the switching element in series with the load fails in short-circuit mode, the unregulated voltage appears across the output leads. In this case, the protective features of the crowbar are beneficial.

The chopper circuit, however, differs from the linear regulator in its requirement for foldback current limiting. As explained earlier, foldback current limiting controls the temperature rise in the dissipative linear element. In the chopper's case, though, the series element serves as a switch with variable duty cycle for regulation purposes.

Should an external fault occur, the switching element sees little difference between a short-circuit and normal-load condition: Peak currents for the short-circuit condition are slightly higher, and the duty cycle is shorter. When the series element switches on, there is little voltage drop across it. Therefore, the increased current during the short-circuit period has little or no adverse effect on the series-pass device's junction temperature. Of course, when the switching device is not conducting, the temperature doesn't rise.

For the chopper circuit, the considerations that usually lead to the requirement for foldback current limiting do not apply. Many specification writers, however, aren't familiar with the derivation of foldback-mode current limiting and automatically include it in a

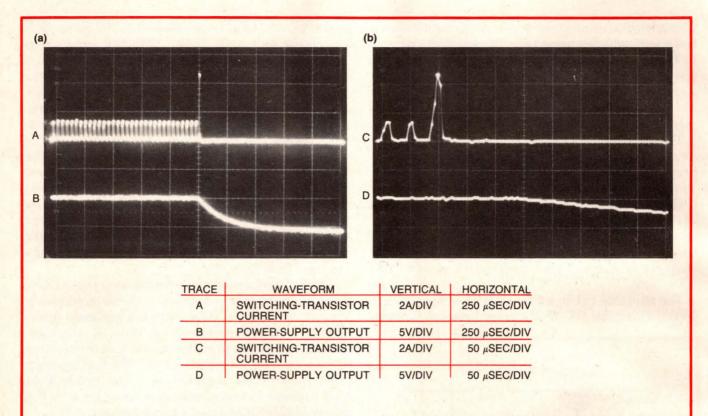


Fig 6—A failed switching transistor in Fig 5's circuit produces no excess voltage at the load. The short circuit results in a large current spike (trace A) in the transformer primary; magnetic saturation prevents the transmission of the overload to the load. The traces in (b) are those of (a) with a fivefold expanded time scale.

switching supply's specifications. The result is increased parts cost and lowered reliability with no attendant system benefits.

Eliminate crowbar with a forward converter

Having determined that a chopper-type switching power supply could need a crowbar but no foldback limiting, consider a different switching-supply topology: the simple forward converter in Fig 5. This supply uses a transformer between the regulator's input and output portions. The transformer plays a key role in eliminating the need for crowbar and current-limiting circuits.

Recall that the crowbar circuit was developed to protect the load against failure of the series-pass element in the power supply. The counterpart to the crowbar in **Fig 5**'s switching regulator is the switching device itself. In the case where a transformer is connected between the circuit's input and output sections, the failure of the switching element does not cause the same kinds of problems as does the failure of a series-pass element.

Should the switching transistor fail in the shortcircuit mode, the result is the application of the full bus voltage across the primary of the power transformer. If this transformer is designed according to standard practices, it takes slightly more than one switching period for the transformer to saturate and draw a large current from the input. Typically, the result is the activation of whatever input-protection device (eg, fuse or circuit breaker) is in the power supply.

If the supply has no input-protection device, the wire bonds in the power transistor blow open and thereby open the circuit. As far as the output circuit is concerned, however, the shorted transistor produces minimal disturbances. The application of one period of excessive current to the transformer does not result in high voltage at the output. The oscilloscope photographs in Fig 6 bear out this contention: Note that a current spike of approximately 5A vs the nominal 1.5A produces no output-voltage increase.

The major problem to guard against in forward-converter supplies is a runaway control circuit, resulting in high output voltage. This problem is easily resolved with a simple shutdown of the primary transistor; large and expensive high-current-SCR circuits are not needed.

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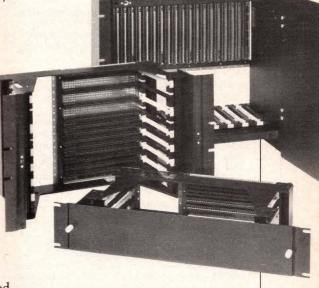
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Foldback current limiting protects series-pass element

fails in the event of either a control-circuit or powerswitch failure, a crowbar circuit is not needed to protect the load against high voltages.

Foldback limiting still not needed

The previous discussion of foldback current limiting applies equally well to forward-converter switching power supplies. In the presence of a short circuit on the output terminals, the current passing through the switching device naturally increases. However, because the switching device operates as a switch (either fully On or Off), the power dissipated in that device is a very small portion of the overall power in the supply. For this reason, foldback current limiting is unnecessary in this or any type of switching supply.

Freedom from the need for foldback limiting gives the switching regulator certain advantages over linear power supplies. For example, the switching regulator is capable of delivering enough current to blow protective fuses under most conditions. Moreover, foldback current limiting has a disadvantage in that it can cause a power supply to lock up in a low-output-current mode if the supply encounters a constant-current load during turn-on. In this case, the intersection of the load line and the regulation line are such that the supply can become trapped in a low-voltage, low-current mode and cannot exit from this mode. This situation can arise, for example, during an attempt to charge a capacitor upon the initial voltage application. Because a switching regulator itself runs in a constant-current-limit mode, you can drop foldback limiting and thereby avoid the possibility of lock-up.

Author's biography

D J Becker is manager of research and development at Lorain Products. Employed by Lorain for 14 years, he holds BSEE and MSEE degrees from Cleveland State University and an MBA from Baldwin Wallace University. He is a member of the IEEE and Eta Kappa Nu; his free-time pursuits include sailing, personal computing, reading, strategic games, and camping.

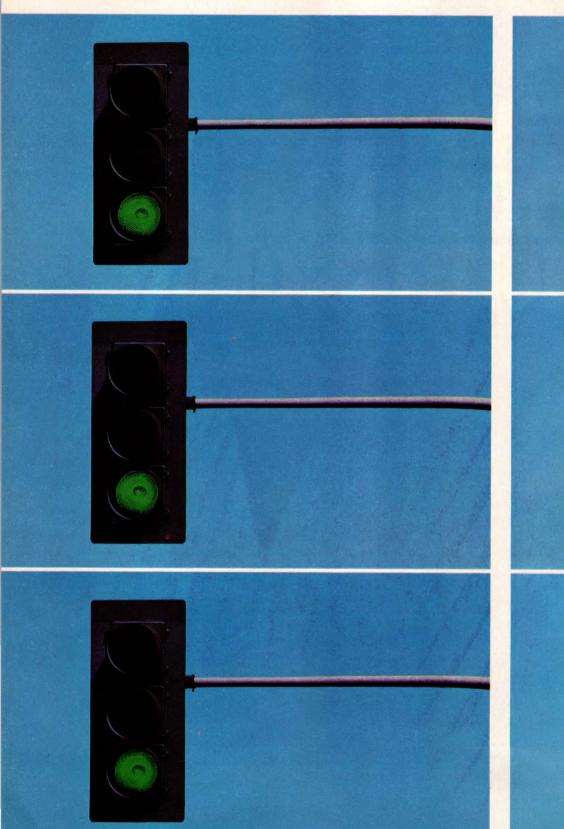


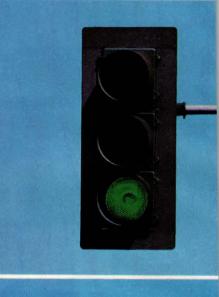
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Driver ICs interface µPs with vacuum-fluorescent displays

Vacuum fluorescent displays suit a variety of commercial and industrial applications, and sequence- and segment-driver ICs make it easy to use the display devices in μ P-based systems.

Antonio Rodrigues, RCA

When developing a μP -controlled vacuum-fluorescent-display (VFD) system, you can employ sequence- and segment-driver chips to interface the low-level μP circuitry with the display devices. Such a system has relatively low power requirements and a minimal number of components. The μP provides the code to generate characters and graphics, and it refreshes the display. The sequence and segment drivers increase the typical 5V μP -supplied power to a 35 to 55V level, suitable for VFDs used in such applications as audio equipment, appliances, digital clocks, and automotive displays. To optimize μP efficiency, the μP can execute the display code when not occupied with tasks unrelated to display control.

VFD principles

The VFDs now being manufactured include 7-segment patterns, starburst 14-segment grids, and 5×7-dot matrices. Operating in much the same way as a triode vacuum tube, the VFD consists of three electrodes: a cathode, an anode, and a grid. The cathode is a small-diameter, oxide-coated tungsten filament that is heated to emit electrons; the anode is an array of segments, dots, or symbols formed on an insulating base and coated with fluorescent phosphor; and the grid is a thin screen of metal that accelerates the electrons toward the anode. A vacuum-sealed glass envelope encloses the three electrodes.

The VFD functions when a voltage that's positive with respect to the filament is applied to the grid and anode. The resulting electrical field accelerates the electrons emitted by the filament toward the grid. Because the grid is a mesh, most of the electrons pass through it and are accelerated toward the anode. When electrons strike the phosphor coating, it emits a bright light, which is typically blue-green, although other colors are available.

Static and dynamic driving

VFDs operate in static or dynamic driving modes (Fig 1). In static driving modes, used with nonmultiplexed displays, the grids are continuously biased at a certain level. In dynamic driving modes, used with multiplexed displays, each grid is pulsed at a rate high enough so that the resulting illumination appears to be continuous.

Displays suitable for static-drive circuits are formed with each anode and grid independently driven; thus, multiplexing is not required. With this construction, one pin is needed for each display element. For complex, multiple-character displays, the common segments of each character are connected, and the independently driven grids are used to address individual characters. In dynamic-drive circuits, the grids are sequentially pulsed at a flicker-free rate to allow for multiplexing. The phosphor-coated anode segments are individually biased in both types of displays.

VFDs operate in staticor dynamic-driving modes

A CDP1802 μP is suitable for controlling these displays, as are other popular μPs . You can use a serial-to-parallel driver to provide the input voltage and current that VFDs require at levels greater than the typical 5V μP -supplied power. The CA3207 sequence driver and the CA3208 segment driver (see box, "VFD driver ICs") fulfill the VFD voltage and current requirements, as do similar devices. Fig 2 illustrates a μP -based scheme for both multiplexed and nonmultiplexed displays.

Multiplexed display circuits

Fig 3 shows a 28-character multiplexed display with one CA3207 and two CA3208 drivers controlled by a CDP1802 μ P. The display consists of 14 grids, each addressing two characters simultaneously and each connected to an output of the CA3207 sequence driver. Each of the 14 segments of the starburst-display characters is driven by the output from one of the CA3208 segment drivers.

Fig 4 illustrates the interface circuit used between

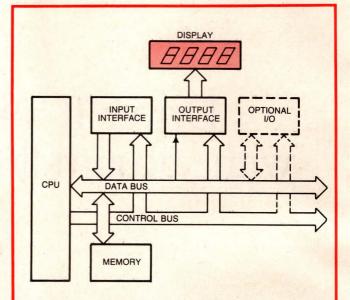


Fig 2—This basic μP-controlled display system provides serial input to the segment drivers for use in both multiplexed and nonmultiplexed displays.

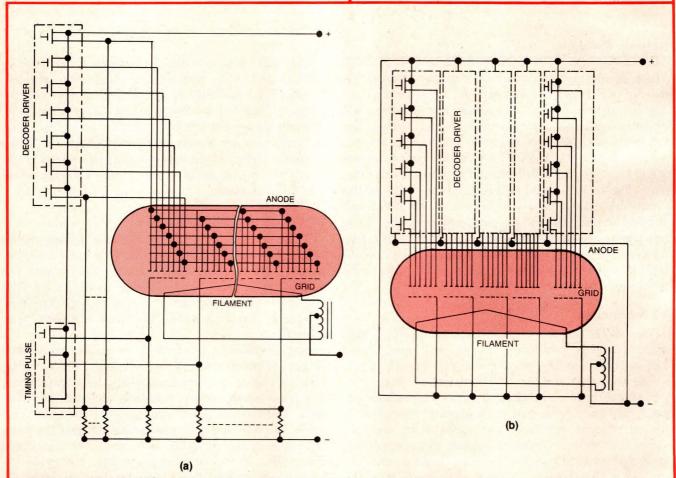


Fig 1—Vacuum-fluorescent-display devices come in multiplexed and nonmultiplexed versions, which can operate in dynamic-drive (a) and static-drive (b) circuits, respectively.

the displays and the μP . The segment drivers, IC₂ and IC₃, control the 14 segments of the upper and lower rows, respectively. When data representing a character is strobed, all the characters in that row have the same anodes biased.

The sequence driver, IC_1 , drives one of the grids so that only one character per row is displayed at any time. IC_2 and IC_3 are connected so that each driver is alternately enabled and disabled. This step is accomplished by connecting the strobe signal to the IC_2 active-Low Clock Enable (\overline{CE}) and to the IC_3 active-High Clock Enable (\overline{CE}).

The strobe signal is obtained from the output of the 4013 flip flop, IC₅, which is toggled On every fourteenth clock pulse by the 4516 counter, IC₆. The strobe signal is also the clock input to the IC₁ sequence driver; it runs at $\frac{1}{14}$ th of the IC₂ and IC₃ clock rates. To obtain the signal, outputs from the N₁, TPB, and $\overline{\text{MRD}}$ pins of the controlling microprocessor are combined through an AND gate (IC₇).

IC₁'s Sync input is the Q-Flag output of the μP and is under software control. The Q-Flag output is also the Preset Enable input of IC₆ and the Reset input of IC₅.

Fig 5 depicts the pertinent waveforms. The \overline{TPB} positive pulse occurs in each machine cycle. The \overline{MRD} pulse appears during a memory-write cycle. The N_1 line is activated by execution of an "Out" instruction to Port 1. Line N_1 remains Low at all other times. Upon execution of the "Out" Port 1 instruction, the IC₆ counter receives a clock pulse when the AND gate's output is a positive pulse equal to the union of the N_1 , TPB, and MRD outputs. The IC₆ clock pulse toggles flip flop IC₅ on every fourteenth pulse decoded by IC_{4B}, while IC_{4A} resets counter IC₆.

The data that represents the 28 display characters is stored in 56 adjacent memory locations. Each character code is 14 bits long and requires two locations per code because the CDP1802 provides only 8-bit processing. Each location holds seven bits of the code, and this results in a simpler display subroutine.

The display subroutine

The subroutine starts by setting and then resetting the Q-Flag output. This pulse syncs the sequencer IC_1 so that the last grid is on. This pulse also resets IC_5 and presets IC_6 . An output loop routine determines the

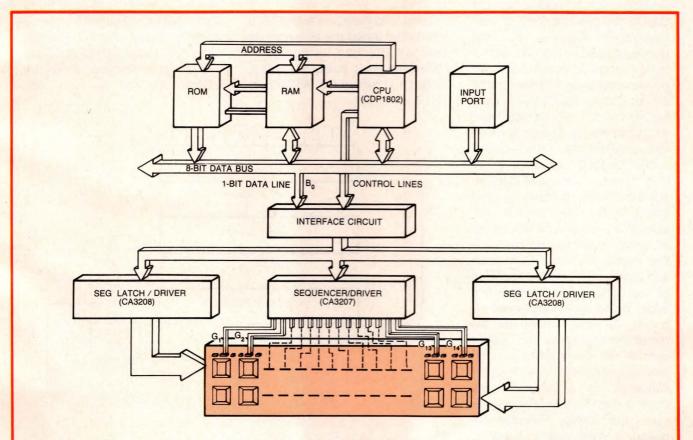


Fig 3—To drive a 28-character multiplexed display, one sequence driver and two segment drivers are controlled by a μP. The sequence driver controls the 14 display grids by simultaneously addressing two characters per grid. Each segment driver controls the 14 segments of a VFD character.

Serial-to-parallel drivers increase voltage and current

least significant digit of the code. The first-out instruction toggles the flip flop's output High, which enables the upper-row segment driver IC₂. IC₃ is simultaneously disabled, while the output loop shifts the code and consecutively presents each bit.

After all 14 bits are generated, IC₆ toggles IC₅'s output Low and thus enables IC₃ and disables IC₂. When the next 14 bits are clocked into IC₃, the output from IC₅ is toggled High. This causes a positive pulse edge to strobe the data in both the IC₂ and IC₃ shift-registers to the output drivers, biasing the 14 segments of all the characters in the upper and lower rows.

The pulse edge also clocks the sequence driver, IC_1 , advancing it by one count and turning on the first grid. As a result, the first characters in both the upper and lower rows are displayed. IC_2 is now enabled to receive the next 14 bits, and all remaining characters are displayed in the same manner.

The display subroutine used by the CDP1802 μ P to generate the codes corresponding to the 28 characters is shown in Fig 6. The subroutine starts by setting and then resetting the Q-Flag output to ensure that each character is displayed in the proper position.

The starting location of the section of memory that holds the codes is stored in register R₇. The two counters for registers RE and RF are then initiated. Register RE is set to 56 (38₁₆), the number of locations. Register RF is set to 7, the number of code bits per location.

The output loop furnishes one bit and shifts the contents so that each bit is individually presented. When there is output for only half of a character, two additional shifts are required before the original data can be restored to its memory location. The 7-bit counter is reset, the character counter is decremented, and the location pointer is incremented so that the next

VFD driver ICs

The CA3207 sequence driver and CA3208 segment-latch driver are BiMOS devices that drive vacuum fluorescent displays requiring anode and grid voltages in the 35-to 55V range. Both devices incorporate low-power CMOS logic to accept CMOS- and TTL-compatible input and control signals; bipolar output stages furnish the high voltage levels that VFDs require.

The CA3207 sequence driver (Fig A) creates a sequential output for display multiplexing from the G₁ to G₁₄ driver pins. It consists of a 7-stage Johnson counter, which is clocked on the positive transitions of the CLK pulse and reset by the positive transition of the Sync pulse. The positive edge of the Sync input turns on output G₁ while turning off the remaining 13 outputs. The counter outputs are decoded to turn on one output driver at a time, in sequence, for a period of one clock pulse. This sequence provides the voltage increase required to drive one of the VFD grids: Each output is normally connected to the grid of the VFD

and is capable of sourcing 40 mA at 55V.

Gate₁ and Gate₂ are active-High inputs that inhibit the shift register without affecting its contents. When the Sync pulse is applied, output 1 is turned On. All outputs

are turned Off if a High level is present at either Gate₁ (pin 5), or Gate₂ (pin 6), although the counter operation is not affected. You can delay the falling edge of the Gate₁ signal by connecting a resistor between R_D and V_{DD} to provide

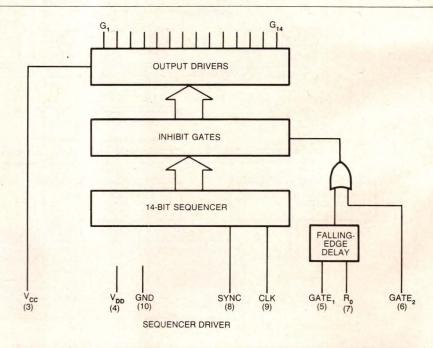


Fig A—The CA3207 sequence driver selects a display character by driving only one display grid High at any time. It is particularly suited to use with multiplexed displays.

half-character can be processed. When all 56 locations are processed, the program counter returns to the main program.

The program structure

The main program controls the display by providing the proper information and control signals. In a nonmultiplexed display, the μP addresses the display only when a digit or a character needs to be updated. All digits remain displayed because the outputs of the segment drivers are latched; thus, they continuously bias the anodes. In a multiplexed display, however, the μP must dedicate a considerable amount of processing time to refresh the display at a flicker-free rate because only one grid is biased at any time by the sequence driver.

You can minimize μP display-related overhead by interleaving the display subroutine's execution with the

execution of other subroutines. Fig 7 shows the difference between the program structures for a multiplexed and a nonmultiplexed display. The simple routines shown drive the display of a digital thermometer.

The major difference is that in a nonmultiplexed display, the subroutine needs to be addressed only with each change in temperature. The μP is thus available most of the time for additional processing, such as controlling other peripherals whose operation depends on a specific temperature. Conversely, in a multiplexed display, the subroutine must be addressed even when the temperature remains constant. The μP must control any peripheral in conjunction with the processing of the display routine.

Frequency requirements

Several factors dictate the minimum frequency for VFD operation: type of display, number of characters,

proper shutdown timing. You can also apply a pulse signal to Gate₂ for display dimming. Variations in the duty cycle result in variations in brightness.

The CA3208 segment driver (Fig B) drives any combination of

the 14 segments selected by the data input. A 14-bit shift register that has latched outputs addresses the 14 output drivers with serial-to-parallel data conversion. The output drivers then alter each of the 14 segment-driver outputs (a

through *n*) to the voltage level required to control each associated display anode; maximum output current equals 7.5 mA at 55V.

The signal at the data input is shifted through the 14-bit shift register with every positive edge of the clock signal. Input from a positive-edge-triggered strobe provides a parallel shift of the data from the register to the 14-bit latch, which turns each of the 14 outputs On or Off according to the control data. The Clock Enable lines (CE and CE) are especially useful for driving a multiplexed display: CE operates as an active-High input and CE is active Low.

In combination, the CA3207 and CA3208 can drive a 14-character starburst, multiplexed display. The CA3208 turns on the desired segments of any character, although all 14 characters have the same segments activated by the driver. The CA3207 selects the desired character by driving only one of the grids at any time. Nonmultiplexed VFDS can also be driven by the CA3208.

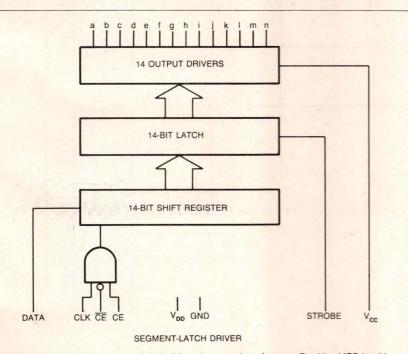
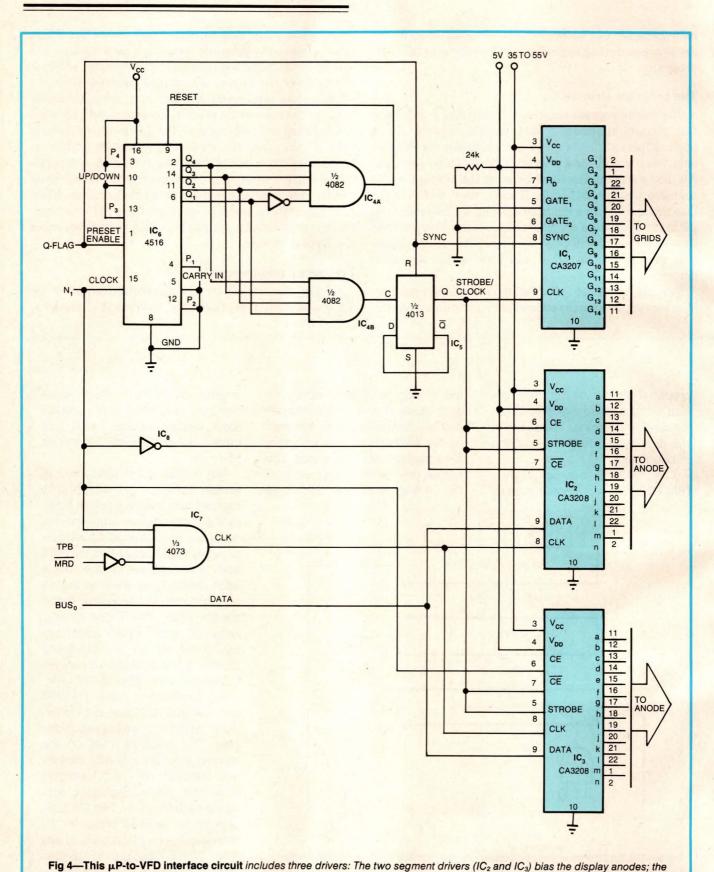


Fig B—The CA3208 segment-latch driver lets you interface a μP with a VFD in either a multiplexed or a nonmultiplexed configuration.



number of segments, and the program routines themselves. Because VFDs have a high persistence, frequencies lower than those required in other types of displays can yield flicker-free performance.

In the Fig 4 circuit, a minimum frequency of 60 Hz is suitable. This is the rate at which each grid must be pulsed. Because the display contains 14 grids, the minimum clock frequency for the sequencer is 14×60 , or 840 Hz. Within one period of this signal, 28 pulses are required to furnish data to the shift registers of both segment drivers.

Eight instructions are required for each half-character that responds to loop 1 in Fig 6. In loop 2, 18 additional instructions are required to restore the first half character into memory and retrieve the second half for processing. In total, 264 instructions are used to load each character code into the two drivers.

LOCATION	INSTRUCTION	MNEMONIC	COMMENTS		
	E7	SEX R7			
	7B	SEQ			
	7A .	REQ	SYNC OUT		
	F8 XX	LDI XX			
	A7	PLO R7	SET STARTING LOCATION XX		
	FE 38	LDI 38			
	AE	PLO RE			
LOOP 2	F8 07	LDI 07			
	AF	PLO RF	7 BITS PER LOCATION		
LOOP 1	61	OUT 01	OUTPUT BIT BO		
	27	DEC R7			
	07	LDN R7			
	76	SHRC	SHIFT RIGHT		
	57	STR R7			
	2F	DEC RF			
	8F	GLO RF			
	3A	BNZ LOOP 1			
	07	LDN RF			
	76	SHRC			
	76	SHRC	TWO ADDITIONAL SHIFTS		
	57	STR R7	RE-STORE		
	17	INC R7	INCREMENT POINTER		
	2E	DEC RE	DECREMENT COUNTER		
	8E	GLO RE			
	3A	BNZ LOOP 2			
	D5	SEP R5	RETURN		

Fig 6—This display subroutine, by processing 56 memory locations, can be used by a microprocessor to produce display codes corresponding to 28 characters.

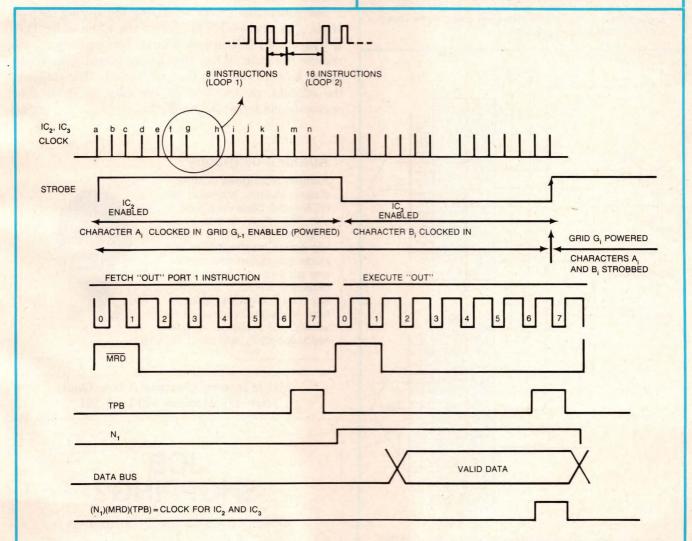


Fig 5—These waveforms illustrate the μ P/driver-IC timing relationships for the Fig 5 circuit. Note that the clock that drives IC₂ and IC₃ is derived from the N₁, TPB and MRD signals; execution of an Out to Port 1 instruction activates N₁.

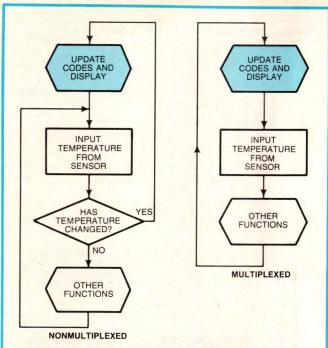


Fig 7—These temperature-display flowcharts show the major differences between a multiplexed and a nonmultiplexed display routine. Note that, with a nonmultiplexed display, the subroutine needs to be called only when temperature changes.

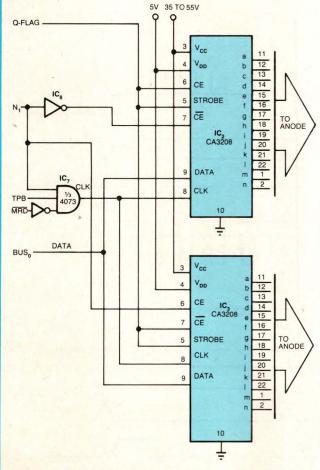


Fig 8—In this μ P-to-VFD interface circuit, two CA3208s drive a 4-digit, 7-segment, nonmultiplexed display. Note that the clock signal for IC_2 and IC_3 is obtained by combining the N_1 , TPB, and MRD outputs via an AND gate (IC_7).

Subroutine ensures that characters are displayed in proper positions

In the CDP1802 μP , each instruction requires 16 clock cycles for fetching and executing an instruction. Therefore, during two consecutive positive edges of the sequencer clock signal, 4224 clock cycles are used. So for the display routine to remain flicker-free, the minimum frequency needed to drive the μP is 4224×840 or 3.5 MHz.

A nonmultiplexed design

Fig 8 illustrates the use of two CA3208s to drive a 4-digit, 7-segment, nonmultiplexed display. Because multiplexing is not required, the circuit is relatively simple. The clock signal is obtained by combining the N_1 , TPB, and \overline{MRD} outputs via an AND gate. The Q-Flag output from the μP provides the strobe signal. The μP is also connected to the CE input of IC₂ and the CE input of IC₃. The data representing the digits is stored in eight adjacent locations.

The subroutine starts by setting the Q-Flag output High. This enables IC_2 to receive the 14-bit code. The Q-Flag output is then pulled Low, thus enabling IC_3 to receive the code. When the Q-Flag output goes High again, both IC_2 and IC_3 data is strobed. This changes the outputs, as specified by the data, to drive the segments and form the four digits.

Author's biography

Antonio Rodrigues is an assistant design engineer at RCA's Solid State Div (Somerville, NJ) where he has been employed for the last 3 years. His design responsibilities include automotive and consumer products. He holds a BS degree in electrical engineering and computer science from Fairleigh Dickinson University. His hobbies include



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3/4 Mbyte DRAM	PME 256EA		•	8/16/32	150	300
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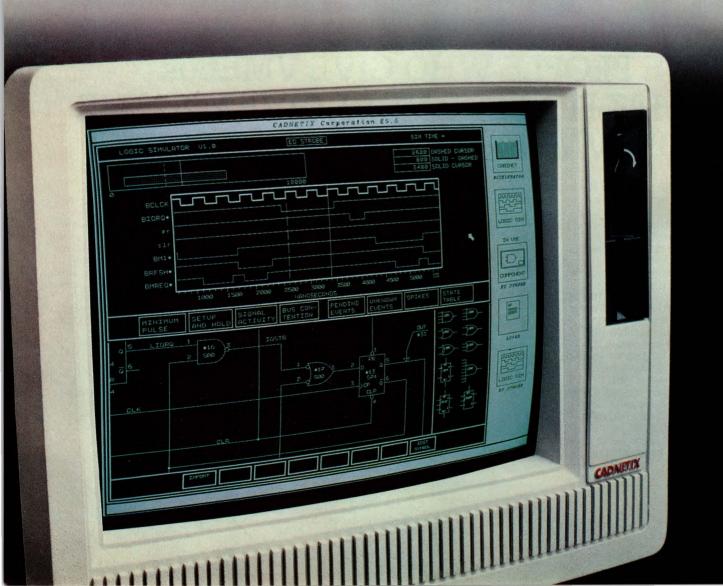
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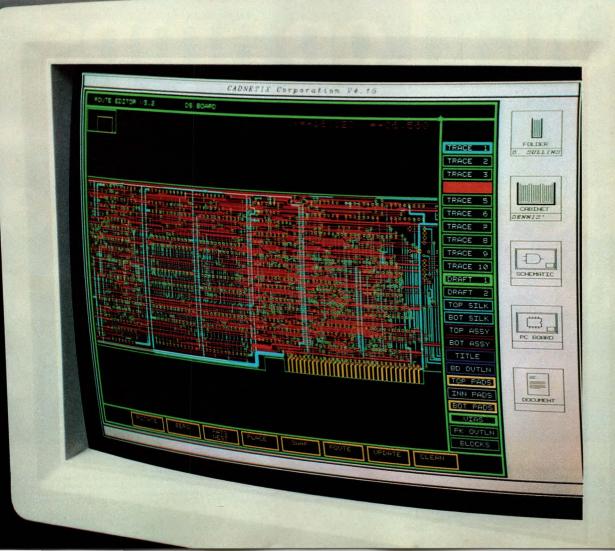


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CIRCLE NO 84

0840





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	LS404	RM4156	SE5532A	TL084	LM324 (Low Cost
Quality Factor (B _w)	9	3.1	2.5	2.1	2.1
Max input Noise voltage (nV/√Hz) R _g = 10kΩ	15	14	6	25	-
Harmonic Distortion (%)	0.04% max (a 1kHz 0.03% typ (a 20kHz	Not Specified	Not Specified	Not Specified	Not Specified
	—0.5V (protected against inversion)	2V _{BE}	V _{BC} +V _{CESAT} 2V _{BE}		_0.3V
Current Consumption I _s (mA)	1.3	4.5	8	5.6	1.5
Cost	Med	Med	High	Med	Low

total harmonic distortion of 0.04% at 1kHz.

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And an output current limiting capability that protects against short-circuits.

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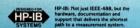
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CIRCLE NO 86



0801405



Circuits allow direct digitization of low-level transducer outputs

Designers like to digitize analog signals as far forward in the signal chain as possible, but many believe that dc preamps are mandatory. Part I of this 2-part series describes circuits that digitize low-level signals without preamplification.

Jim Williams, Linear Technology Corp

Almost all transducers produce low-level signals, and designers typically use signal-conditioning amplifiers to boost the output prior to further processing or transmission. However, many systems now transmit transducer outputs digitally to reduce noise and eliminate the inaccuracy problems associated with analog transmission over long cable runs. In fact, designers want to digitize signals as far forward in the signal chain as possible, and although you might believe that depreamplification of transducer outputs is still mandatory, such is not the case: New components and design techniques allow you to digitize directly at the transducer.

This 2-part series details such circuit techniques, which you can use to digitize low-level transducer outputs and eliminate the traditional dc gain stage without sacrificing performance. The circuits produce serial frequency outputs that you can transmit over one wire with the characteristic noise immunity of digital systems. Part I discusses methods of handling the most common transducer quantities: temperature and force. Part II (scheduled for January 10, 1985) will discuss similar methods for handling light, humidity, level, and acceleration.

Obviating dc preamplification

Before moving on to these techniques, it's worthwhile to examine the reason why most designers feel dc preamplification is necessary. Classical A/D-conversion techniques emphasize high-level input ranges to keep LSB step sizes as large as possible and thus minimize offset and noise errors. For this reason, A/D LSB size is almost always greater than a millivolt, with 100- to $200-\mu V/LSB$ step sizes in some 10V FS devices.

Now consider the minimum A/D-converter step size required for direct digitization of the output of a typical strain-gauge transducer. The device's full-scale output is 30 mV, so a 10-bit A/D converter must have an LSB increment of only 30 μ V. Performing a 10-bit conversion on a type-K thermocouple monitoring a 0 to 60°C environment proves even more stringent. The thermocouple generates 41.4 μ V/°C over the 0 to 60°C range. The following equation determines the LSB increment:

$$\frac{41.4 \ \mu\text{V/}^{\circ}\text{C} \times 60^{\circ}\text{C}}{1000} = 2.48 \ \mu\text{V/LSB}.$$

These step sizes are far smaller than those found in commercially available A/D converters, leading some designers to conclude that it's impossible to digitize the step sizes without dc preamplification. But circuitry designed specifically for that task directly digitizes the outputs from these transducers (and others) to stable 10-bit resolution.

Start with an IC temperature sensor

The straightforward circuit shown in Fig 1 converts an LM134 temperature sensor's current output to a corresponding output frequency. The sensor pulls a temperature-dependent current (0.33%/°C) from IC₁'s positive input node. This point, biased from the LM329-driven resistor string, responds with a temperature-dependent voltage that varies the operating point of IC₁, which is configured as a self-resetting integrator. IC₁ integrates the LM329-referenced current into its summing point and produces a negative ramp. When the ramp amplitude becomes large enough, the transistors turn on, thereby resetting the feedback capacitor and forcing IC₁'s output to zero. When the capacitor's reset current goes to zero, the transistors turn off, and

Designers like to digitize early in the signal chain

IC1 again begins to integrate negatively.

This oscillation's frequency depends on IC₁'s dc operating point, which varies with the LM134's temperature. The circuit's dc biasing values are such that a 0 to 100°C temperature excursion produces a 0- to 1-kHz output. In addition, a voltage of only 2V appears across the LM134, minimizing sensor errors related to power dissipation.

For interfacing purposes, the differentiator/transistor network at IC₁'s output provides a TTL-compatible output. To calibrate this circuit, place the LM134 in a 0°C environment, and trim the 0°C adjustment for a 0-Hz output. Then put the sensor in a 100°C environment and set the 100°C adjustment to a 1-kHz output. Repeat this process until both points are fixed. When properly constructed and calibrated, this circuit achieves a stable 0.1°C resolution with 1°C accuracy.

If you prefer thermocouples to IC temperature sensors, consider the temperature/frequency converter shown in Fig 2, which uses the popular type K thermo-

couple. That sensor's extremely low output (41.4 $\mu V/^{\circ}C$) and the requirement for cold-junction compensation make it one of the most difficult transducers to digitize directly. This approach uses the 50-nV/°C input offset drift of the LTC1052 chopper-stabilized amplifier (IC₁). Besides providing cold-junction compensation for the thermocouple over a 0 to 60°C range, the design achieves $\pm 1^{\circ}C$ accuracy with 0.1° resolution.

In this approach, the thermocouple biases IC₁'s positive input. IC₁ then drives a crude V/F converter (IC₂) comprising several 74C04 inverters and associated circuitry. Each V/F output pulse causes the 100-pF capacitor to dispense a fixed charge into the 1-µF capacitor via the LTC1043 switch. The larger capacitor integrates the charge packets and produces a dc voltage at IC₁'s negative input. That amp's output forces the V/F converter to run at a frequency that balances its inputs. This feedback action eliminates drift and nonlinearities in the V/F converter, and the output frequency is a function only of the dc conditions at the amp's inputs.

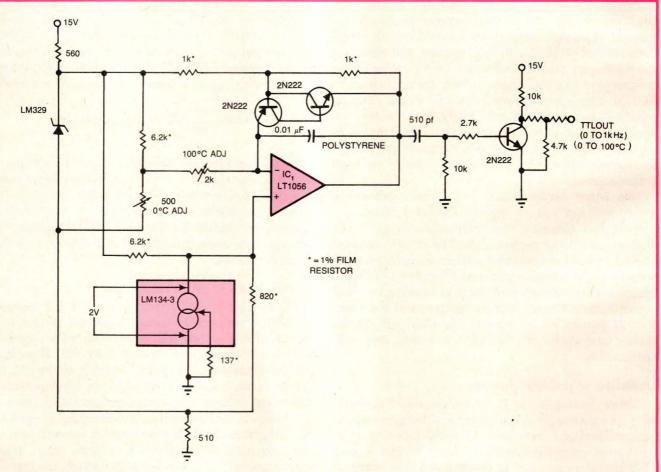


Fig 1—IC₁'s dc operating point determines oscillation frequency, causing the transistors to toggle and produce an output that corresponds to the sensor's temperature. This design directly digitizes the sensor's output and maintains 0.1°C resolution with 1.0°C accuracy.

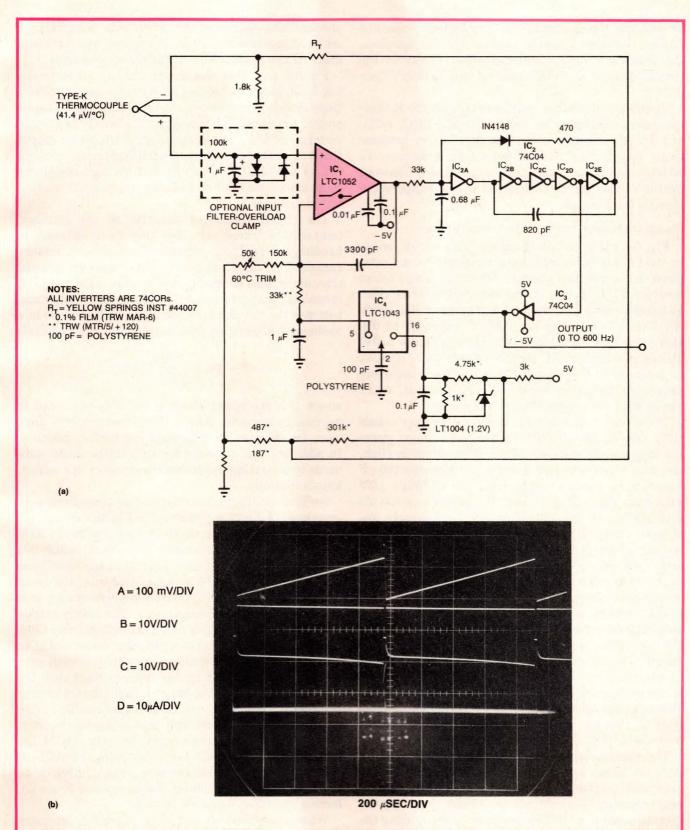


Fig 2—The low output levels and cold-junction compensation requirements of K thermocouples render those devices' outputs tough to digitize directly. This circuit relies on IC₁'s low input offset drift to accomplish that task. The thermistor and several resistors perform the cold-junction compensation and offsetting functions.

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Sensor outputs are much lower than typical A/D LSB size

To stabilize the feedback loop, the 3300-pF capacitor forms a dominant response pole for IC₁. Furthermore, the amp's low drift eliminates offset errors in the circuit, despite an LSB value of only 4.14 μV (per 0.1°C).

To effect cold-junction compensation for the K thermocouple, thermistor R_T and the 1.8-k Ω , 187 Ω , 487 Ω , and 301-k Ω resistors form a compensation network that's biased from the LT1004's 1.2V reference. In addition to cold-junction compensation, the network provides offsetting so that a 0°C sensor temperature yields a 0-Hz output.

Ramp frequency varies with temperature

Fig 2b details circuit operation. IC₁'s output drives the 33-kΩ/0.68- μ F combination, which produces a ramp (trace A) across the capacitor. When the ramp crosses inverter IC_{2A}'s threshold, the cascaded inverter chain switches to produce a low output at inverter IC_{2E} (trace B). This action causes the 0.68- μ F capacitor to discharge through the diode, resetting the capacitor to 0V. To ensure a clean reset, the 820- μ F unit sends positive ac feedback to IC_{2B}'s input (trace C). This ramp/reset sequence's frequency varies with IC₁'s output, which varies with the temperature at the sensor.

The inverter not located in the V/F converter's chain (IC₃) controls the LTC1043 switch and thereby closes the loop around the amp. When IC₃'s output is High, the switch connects pins 2 and 6, allowing the 100-pF capacitor to receive charge from the LT1004's 1.2V reference. When IC₃ goes Low, the switch connects pin 2 to pin 5, and the 100-pF capacitor completely discharges (trace D) into the 1- μ F unit. Because the amount of charge the capacitor delivers is constant for each cycle (Q=CV), the voltage to which the 1- μ F capacitor charges is a function of frequency and discharge-path resistance.

This voltage is summed with the LT1004-derived offsetting potential at IC₁'s negative input, thus closing the amplifier loop. The -120-ppm/°C drift of the 100-pF, charge-dispensing polystyrene capacitor is compensated by the opposing temperature coefficient of the resistors in the 1-μF capacitor's discharge path. This selection achieves a typical circuit gain drift of 20 ppm/°C, allowing less than 1 LSB (0.1°C) output drift over a 0 to 70°C ambient operating range.

The thermocouple's characteristics, combined with IC₁'s low offset and the components specified for the cold-junction/offsetting network, eliminate the need for zero trimming. You calibrate the circuit by placing the thermocouple in a 60°C environment and adjusting the 50-k Ω potentiometer for a 600-Hz output. Beyond 60°C, the cold-junction network departs from the thermocouple's response, and output error increases rapidly. And,

although the digital output varies with thermocouple temperature over hundreds of degrees, you must still linearize the system with a monitoring processor.

Finally, note that this circuit directly converts any low-level, single-ended signal. By removing the offsetting/cold-junction network and tying the $50\text{-k}\Omega$ potentiometer to ground, you can apply inputs to IC_1 's positive terminal as well. The design then produces an output that accurate to 10 bits with a full-scale range of only 1 mV (1 $\mu\text{V/LSB}$). Furthermore, IC_1 's high-impedance input allows you to filter or clamp input signals without introducing error.

The circuits discussed thus far all use standard temperature transducers, but they have difficulty in handling such extreme conditions as wide temperature ranges. The circuit shown in Fig 3 uses an unusual transducer that accommodates a wide input range; it measures temperature by exploiting the relationship between the temperature and the speed of sound in a medium. The equation representing this relationship is

$$C = 331.5 \sqrt{\frac{T}{273}} \text{ M/SEC},$$

where C is the speed of sound and T is expressed in degrees Centigrade. Such acoustic thermometry finds uses, for example, in cryogenics and nuclear reactors. In addition, you can build acoustic temperature standards by operating the acoustic transducer in a sealed, known medium.

An acoustic thermometer's inherent time-domain operation suits direct digitization. In Fig 3a's circuit, IC₁ and the inductor form a simple flyback, regulated 200V source that biases the acoustic transducer, which is a Polaroid ultrasonic element. You mount the transducer at one end of a sealed, 6-in.-long Invar tube; the Invar material minimizes mechanical tube deformation that occurs as a function of temperature. The medium inside the tube is dry air. In this configuration, you may think of the ultrasonic element as a capacitor, composed of an insulating disk with a conductive coating on each side.

The circuit operates in this fashion: Each time the TTL clock (trace A in Fig 3b) goes High, the transducer receives ac drive from the 0.22- μF capacitor. This drive causes the disk to move and emit ultrasonic energy. Simultaneously, the clock input sets the 74C74 flip flop's output (trace E) Low and pulls the 0.01- μF capacitor to ground. This discharge cuts off drive to the comparator IC₃'s 3-k Ω output pullup resistor (trace C), forcing its output (trace D) to zero.

When the clock's output is positive, IC₂ saturates (trace B). When the clock pulse returns to zero, IC₁ amplifies in a linear manner. The ultrasonic transducer now acts like a capacitance microphone, with the 200V

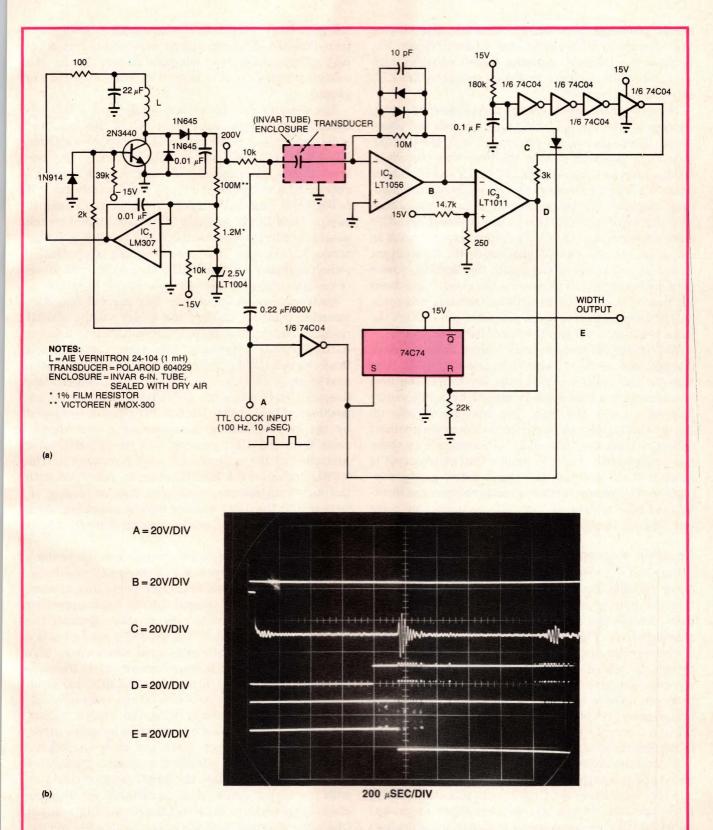


Fig 3—An ultrasonic sensor measures temperature by exploiting the relationship between the speed of sound in a medium and temperature. The sensor uses an ultrasonic element as its active transducer element. The flip flop's output pulse width varies with temperature, and you can use digital circuitry to convert it to temperature information.

K thermocouples' low output levels complicate digitization

supply providing bias voltage. Residual disk ringing now appears at IC₂'s output, but it can't trigger IC₃, because the 0.01- μ F capacitor hasn't charged high enough to allow the inverter chain's output to bias IC₃'s output pullup resistor.

The emitted ultrasonic energy travels down the tube, bounces off the far end, and heads towards the transducer. Before the energy returns, though, the $0.01\text{-}\mu\text{F}$ capacitor's potential crosses the inverter's threshold, and the inverter chain applies 15V to IC₃'s $3\text{-}k\Omega$ resistor (trace C). Upon returning, the sonic energy mechanically displaces the transducer to force a capacitance shift. This shift causes a charge displacement into IC₂'s summing point, and the amp's output responds with an amplified version of this signal (trace B). IC₃'s output (trace D) now triggers and resets the flip flop, whose output pulse (trace E) represents the transit time down the tube. This time varies with temperature according to the earlier equation, and a processor can convert the pulse width into temperature information.

You can see the second return bounce, which is lower in amplitude, at the extreme right side of trace B. Also note the increased detected noise level after the first bounce returns; this noise is caused by sonic-energy dispersion inside the tube. The transducer picks up energy that's phase shifted from the desired signal and deflected from the tube walls. IC₃ responds to these unwanted signals, but the circuit's final pulse output is unaffected. In addition, the time-window gating supplied to IC₃'s pullup resistor greatly reduces the likelihood of false triggering that may be caused by noise coming from outside the tube.

No strain to measure force

One final example deals with another common transducer variable: force. Strain-gauge transducers, which typically handle pressure or force, are often bridge-based sensors that produce full-scale outputs of 3 mV/V of bridge drive. Fig 4 shows one way to digitize directly a strain-gauge bridge's output to 10-bit accuracy, although the bridge's differential output complicates the required converter input structure. With this resolution, you achieve a 25- μV LSB increment for a 7.5V bridge drive, which is considerably larger than that of the thermocouple examples but is still far below the requirements of conventional A/D converters.

IC₁ and the 2N2905 transistor drive the bridge. One of the bridge's outputs connects to IC₁'s negative input, and that amp drives the transistor to bias the bridge at a voltage that brings its negative input to ground potential. Voltage drops from the diodes in the bridge's -5V return line allow the transistor to force the voltage on the bridge's positive end high enough to balance IC₁'s inputs. This arrangement permits sensing of the

bridge's other output in a single-ended, ground-referred fashion. Although a slight error exists because of IC₁'s offset voltage, you eliminate it by referring the converter's input to IC₁'s negative input rather than to ground.

The design's A/D converter, which uses a current-balancing technique, consists of IC₂, a flip flop, and some gates. Again, you rely on the chopper-stabilized LTC1052's 50-nV/°C input drift to implement the low-level input A/D function. To examine the circuit's operation, assume that the flip flop's Q output (trace B in Fig 4c) is Low and connects LTC1043 pins 11 and 12 to pins 7 and 13, respectively. The main current switch passes no current because a 3.3-M Ω resistor is placed across IC₂'s inputs. The current-loading compensation switch also puts a 3.3-M Ω value across the 1-k Ω divider/resistor, reducing the voltage across it by 0.03%.

Under these conditions, the only current into IC2's summing point comes from the bridge via the 470-k Ω resistor. This positive current forces IC2's output (trace A) to integrate negatively. This ramp continues and finally passes the flip flop's switching threshold. At the next clock pulse (trace C), the flip flop changes state (trace B) and causes the LTC1043 to reverse switch positions. At this point, the 3.3-M Ω resistor controlled by the current-loading compensation switch disconnects from the 1-k Ω resistor, but the 3.3-M Ω value controlled by the main current switch replaces it. The 0.03% loading of the 3.3-M Ω resistor, combined with this switching scheme, eliminates sags or loading effects across the 1-k Ω resistor during switching. As a result, a quickly rising, precise current flows from IC2's summing point.

This current, scaled to be greater than the bridge's maximum output, forces IC_2 to integrate positively. Switching occurs at the first clock pulse that appears after IC_2 's output has crossed the flip flop's triggering threshold, and the entire cycle repeats. Because the reference current is fixed, the flip flop's duty cycle is a function only of the bridge's signal current into IC_2 's summing point. The reference current comes from the bridge drive indirectly through the 22.3-k Ω /1-k Ω divider. Consequently, the A/D converter's reference current varies ratiometrically with the bridge output, eliminating errors caused by variations in bridge drive.

The flip flop's output gates the clock to produce output A (trace D). To eliminate spurious output pulses caused by flip-flop delay, the $10\text{-k}\Omega$ resistor combines with the output gate's input capacitance to delay the clock signal slightly. To extract the circuit's data output (the ratio of output A to the clock frequency), you can use counters.

You must observe several facts when setting up and using this circuit. First, because the output is ex-

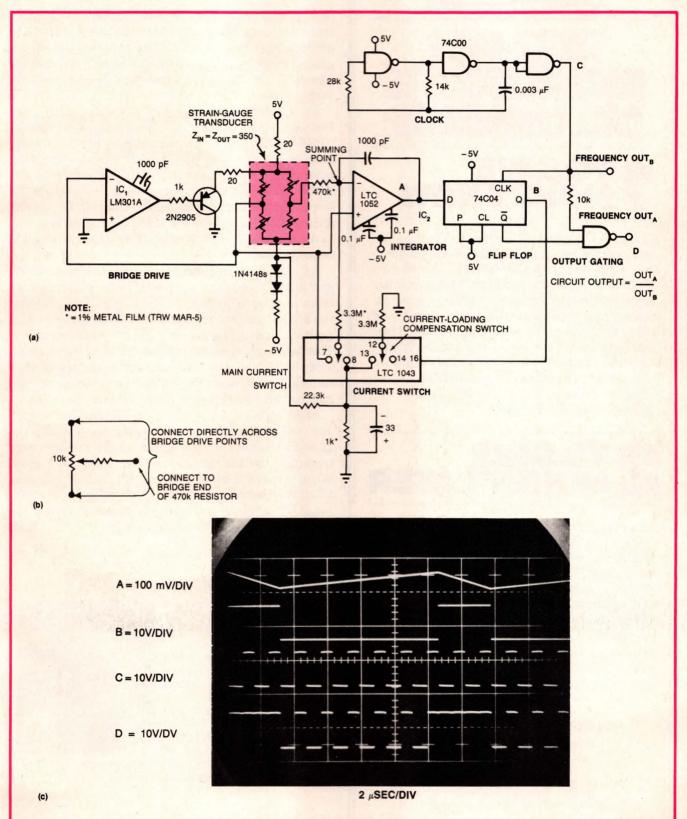


Fig 4—Although a strain-gauge bridge transducer's output is larger than that of a thermocouple, it's still too small for most A/D converters. This direct-digitization circuit maintains 10-bit accuracy, and if your transducer requires it, you can accomplish transducer zero trimming with an optional network (b).

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Use the medium's speed of sound to measure temperature

pressed as a ratio, clock frequency stability is unimportant. Next, you select a 470-k Ω input resistor at IC₂ to produce less than 1-LSB loading error on the straingauge bridge, which receives only about 7.5V of drive because of the deliberate resistor and diode drops in its supply lines.

At a 3-mV output per volt of bridge drive, the full-scale signal is 22.5 mV, producing a current of $0.0225 \, \text{V}/470 \, \text{k}\Omega$, or 48 nA. To maintain 10-bit accuracy, leakage and amplifier bias current into A2's summing point must be less than 0.1% of this figure, or 48 pA. Although IC2's bias current is much lower than this level, board leakage can cause trouble. Be careful during layout, and keep the board clean. The best way to do so is to use a Teflon standoff for all summing-point connections.

As another layout consideration, place the 470-k Ω and 3.3-M Ω resistors associated with IC₂'s negative input as close as possible to the IC pin. Note also that the 3.3-M Ω current-summing resistor switches to IC₂'s positive input when not sourcing the summing point. This seemingly unnecessary connection prevents small, stray 60-Hz and noise currents from coupling to IC₂'s summing point when the current reference is off; not making this connection produces jitter in the LSB.

After laying out the circuit, you'll want to trim it. You can accomplish gain trimming by varying the 22.3-kΩ resistor. If your strain gauge requires zero trimming, use the optional network shown in Fig 4b. When properly trimmed, the circuit typically maintains 10-bit outputs within 1-LSB accuracy over the 0 to 70°C range. This small error arises primarily from the tracking errors of the starred resistors.

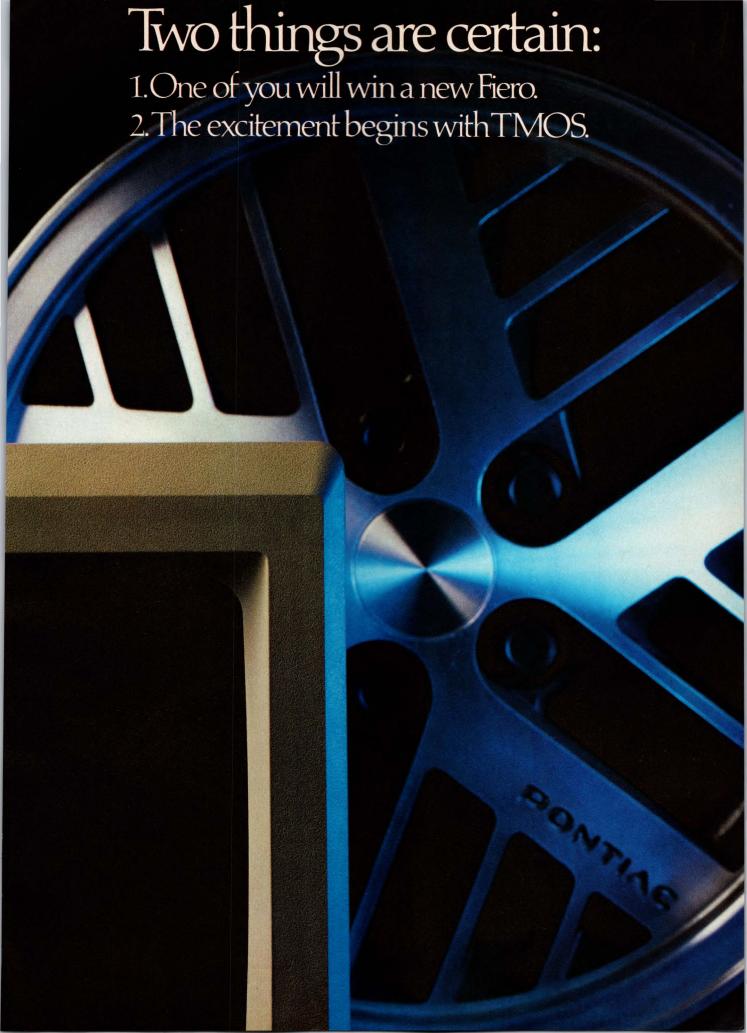
Author's biography

Jim Williams, staff scientist at Linear Technology Corp (Milpitas, CA), specializes in analog-circuit and -instrumentation design. He has served in related capacities at National Semiconductor Corp, Arthur D Little Inc, and the Instrumentation Development Lab at the Massachusetts Institute of Technology. Jim is a former student of psychology at



Wayne State University, and he enjoys tennis, art, and collecting antique scientific instruments.

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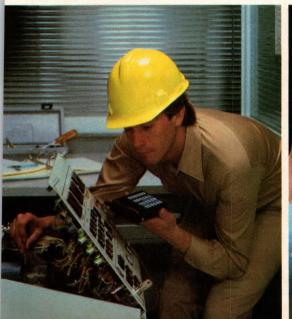


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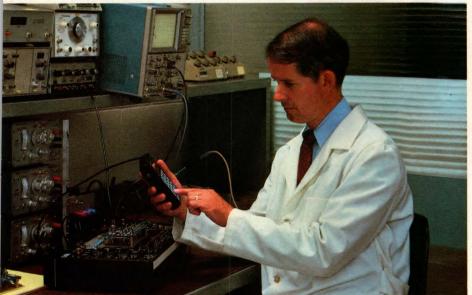
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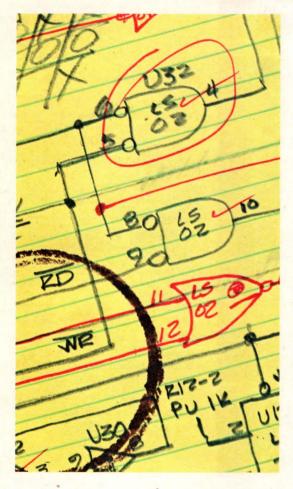
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Program automates error analysis of time-interval measurements

Calculating resolution and accuracy for a programmable counter's time-interval error can be a big job if done by hand. A program that's adaptable to any counter can relieve much of the burden.

Johnnie Hancock, Hewlett-Packard Co

When using a counter to make time-interval measurements, you often need information about a measurement's resolution and accuracy as much as you need the measurement itself. Most counters don't provide such information, and to determine worst-case error for a single measurement by hand, you might have to spend days studying theory and working through an equation with 20 or 30 factors. You can save considerable time and effort, though, if you implement an error-analysis program in your counter.

Error analyses can be deceptively complex. Time-interval specifications consist of many components; each contributes error to varying degrees under different conditions. Counter users often assume that a time-interval measurement's accuracy approximately equals the systematic error spec (the difference between the delays of each input channel) on the counter's data sheet. Although true in some cases, this assumption doesn't always hold, because the real world doesn't contain infinitely fast rise- and fall-time waveforms. Consequently, you're forced into analyzing your setup's accuracy and taking other factors into account.

Error-analysis program for any counter

A programmable counter that has a built-in erroranalysis program measures and computes resolution and accuracy for any time-interval measurement. Such error-analysis programs often reveal facts about timing accuracy that users usually don't consider. Recognizing these facts can save time and money by eliminating redesign and rework. You can take this capability one step further by using a computer with your programmable counter and the error-analysis program.

Such a program can find time-interval errors on any counter; a program written for the HP 1965A gated universal counter (an expansion module for the HP 1980 oscilloscope measurement system) demonstrates the calculations required for time-interval error analysis. (The program is one of 49 subprograms that constitute the HP 19800/19801 waveform-measurement library.)

The 1965A gated universal counter includes built-in features—for example, internal measuring of trigger hysteresis and trigger-level offset—that enhance error analysis and eliminate some error components. Although these features aren't in all counters, you should have little trouble writing an error-analysis program for your particular unit.

PROGRAM VARIABLES

Ti	TIME INTERVAL			
Ace	ACCURACY			
Res	RESOLUTION			
Lsd	LEAST-SIGNIFICANT-DIGIT ERRO			
Se	SYSTEMATIC ERROR			
Ne	NOISE ERROR			
He	HYSTERESIS ERROR			
Tle	TRIGGER-LEVEL ERROR			
Nea	NOISE ERROR OF A			
Neb	NOISE ERROR OF B			
Sra	SLEW RATE OF A			
Srb	SLEW RATE OF B			
На	HYSTERESIS OF A			
Hb	HYSTERESIS OF B			
Osa	OFFSET ERROR OF A			
Osb	OFFSET ERROR OF B			

You need resolution and accuracy as well as the measurement itself

The program comprises subroutines for measuring and computing each component of the time-interval specification. The entire time-interval specification consists of the following components:

resolution = ± least-significant-digit error

± noise error

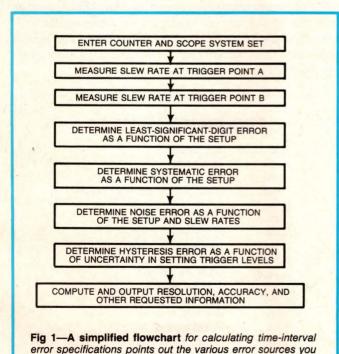
accuracy = ± least-significant-digit error

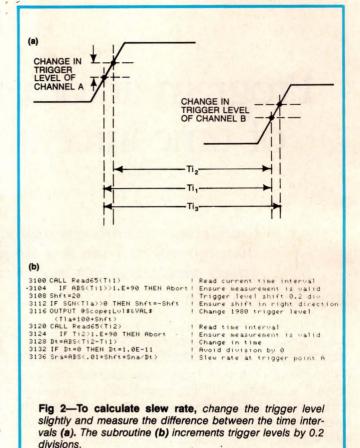
± noise error ± time-base error

± hysteresis error ± systematic error.

Time-base error is negligible in nearly all time-interval measurements. You can easily see why it's often insignificant: The accuracy of a typical oscillator's counter is spec'd at one part in 10⁶, yielding a 0.0001% error in a time-base measurement. Time-base error does play a significant role, though, in frequency measurements and in those time-interval measurements requiring an interval that's seconds long.

Each component in the time-interval equation is a function of various test-setup conditions. A component varies with such factors as the number of averages, the trigger levels, and input conditioning. In the 1980 measurement system, the system controller determines the instrument's setup with a Learn string that defines the instrument status. You can enter variable settings directly with an IEEE-488 commmand (the nearby table lists the variables used in the program). If your counter doesn't offer these Learn strings, you must define setup conditions as inputs in the erroranalysis program.





Though some components depend solely on instrument setup, others are affected primarily by the characteristics of the signals under test. Therefore, prior to computing the specifications, you must describe the system setup and characterize the signal under test. The flowchart in Fig 1 can guide you in writing a program that measures and computes time-interval specifications.

Adjust triggers to measure slew rates

Because most error components are functions of the system setup and the input slew rates of the reference system's A and B input channels, you must measure those slew rates first. Some counters provide built-in slew-rate routines, but you should read the spec sheet carefully to see whether the slew-rate figure those routines determine is a function of a small incremental change at the trigger-level point or of the 10 to 90% rise and fall times. Remember, a 10 to 90% calculation doesn't really yield slew rate and can introduce inaccuracies into your results; the slew rate represents the instantaneous rate of change at one point, not the average rate over 80% of the waveform range. For best results, you must determine the slew rates at the trigger points of the signals in channels A and B.

must take into consideration.

Measuring the slew rate in this manner is a simple process: You perform only three time-interval measurements (Fig 2a). First, you measure the time interval for the current setup and label this answer Ti1. Second, you change the A input's trigger level by a small incremental voltage relative to the input signal's peak-to-peak amplitude and measure the time interval; label it Ti2. Finally, return the A input's trigger level to its original setting and change the B input's trigger level by a small incremental amount. Measure the time interval and label it Ti3.

As you can infer from Fig 2a, the slew rates are defined as follows:

$$slew \ rate_A = \frac{\Delta \ V}{Ti2 - Ti1}$$

$$slew \ rate_B = \frac{\Delta V}{Ti3 - Ti1}.$$

The portion of the error-analysis program that measures and determines the slew rate (Fig 2b) uses this setup information for determining the channel A signal's slew rate. In the code,

- Tla stands for the trigger level of A.
- Sna stands for the input sensitivity of A in volts per division.
- Lv1\$ is the string that indicates which trigger level to adjust.

This subroutine increments trigger levels by 0.2 div. The reference system's controller reads input vertical scaling to convert trigger-level changes into volts. Furthermore, the 1980's continuous vertical scaling ensures that the 0.2-div trigger-level change is small

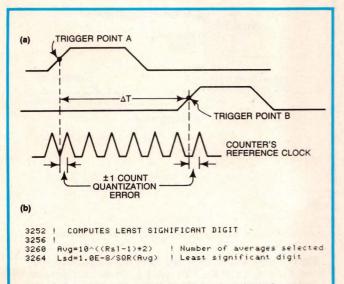
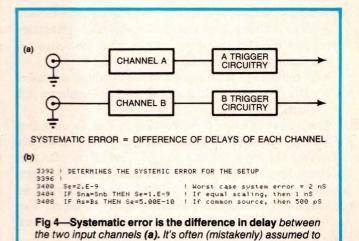


Fig 3—Least-significant-digit error arises from the counter's reference clock or single-shot time-interval capability (a). Averaging can reduce the error if you avoid coherence with the counter's clock.



relative to the peak-to-peak waveform. For example, if you scale the input waveform so that the screen displays 10 div, then 0.2 div is only 2% of the peak-to-peak

be approximately equal to the counter's time-interval error.

waveform. Also note that **Fig 2b**'s listing determines the slew rates' absolute values; before the program ends, however, it assigns the proper signs to the slew rates of A (variable Sra) and B (variable Srb).

Averaging reduces LSD error

The next step is to find the least-significant-digit error (Fig 3a); you determine this error level from the counter's reference clock or single-shot time-interval specs. Averaging can statistically reduce least-significant-digit error if the signals aren't coherent (see references). In the test setup used here, the 1965A's reference clock is phase modulated to break coherence every time it occurs.

The following equation determines least-significantdigit error:

least-significant-digit error =
$$\pm \frac{\text{reference-clock period}}{\sqrt{\text{number of averages}}}$$

The 1965A's system reference-clock period is 10 nsec, and you can select a single-shot mode or one, 100, 10,000, or 1,000,000 averages, resulting in resolution as high as ± 10 psec. The counter also has an autoresolution feature that automatically selects the most averages possible without exceeding a maximum waiting time of 2.3 sec for an updated measurement.

Fig 3b shows the error-analysis subroutine that calculates the least-significant-digit error (variable Lsd). Rsl is a setup variable, ranging from 1 to 4, that defines the number of averages selected.

Systematic error is often predefined

Next you examine systematic error, which is the difference between the delays of each channel (Fig 4a).

Time-interval error equations can contain 30 factors

For most counters, systematic error is a single factor, like ± 1 or ± 2 nsec. The 1980/1965 system's systematicerror specification, however, varies with the setup:

- Common source: ±500 psec
- Dual source with equal vertical scaling: ±1 nsec
- Dual source with unequal vertical scaling: ±2

The systematic-error subroutine in Fig 4b uses the following variables to define the setup: Sna and Snb stand for the input sensitivities of A and B in volts per division, and variables As and Bs stand for the trigger sources of A and B (main or delayed). The subroutine as shown accounts for the 1980/1965 system's setup. For other counters, you can simplify the subroutine to add one term regardless of the setup conditions.

Noise error from trigger circuitry

The noise component in the error equation arises from noise in the input signal and the counter's trigger circuitry (Fig 5a). The error-analysis subroutine in Fig 5b is based on the assumption that input noise is minimal, and it uses the following equations to compute the error caused by system noise:

noise error =
$$\sqrt{\text{(noise error}_A)^2 + (\text{noise error}_B)^2}$$

where

noise error_A =
$$\pm \frac{\text{noise of A (in volts)}}{\text{slew rate}_A \times \sqrt{\text{number of averages}}}$$

noise of B (in volts)

 $noise \ error_B = \pm \frac{noise \ of \ B \ (in \ volts)}{slew \ rate_B \times \sqrt{number \ of \ averages}}$

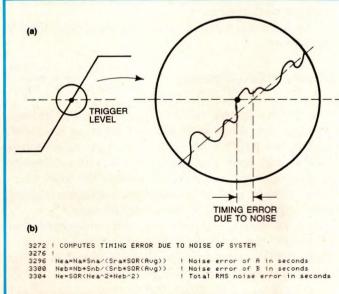


Fig 5—Noise error arises from noise in the input signal and the counter's trigger circuitry (a). The subroutine (b) assumes that noise is minimal.

In reviewing the subroutine that determines timing error caused by noise (variable Ne), add the following setup variables to those previously defined:

- Na and Nb stand for the noise in channels A and
- Sra and Srb stand for the slew rates of A and B in volts per second.

The reference system's worst-case noise specification is 0.02 div. The 1980's actual noise in each trigger channel is typically less than 0.02 div, so the controller can measure it and enter it into the program. If you don't include the noise data, the program defaults to the 0.02-div worst-case specification.

Equal slew rates don't cancel hysteresis

Hysteresis error—the timing error induced by the trigger circuitry's inherent hysteresis—is more difficult to calculate. Although hysteresis prevents false triggering on noise, it produces a timing error that varies with the slew rates (Fig 6a):

$$\text{hysteresis error} = \frac{\text{hysteresis}_{\text{A}}/2}{|\text{slew rate}_{\text{A}}|} - \frac{\text{hysteresis}_{\text{B}}/2}{|\text{slew rate}_{\text{B}}|}$$

Some counter manufacturers don't publish hysteresis specifications, and most don't distinguish possible differences in the hysteresis of A- and B-channel triggering circuitry. In many cases, the difference in hysteresis contributes most significantly to the error, especially when the slew rates of A and B are equal.

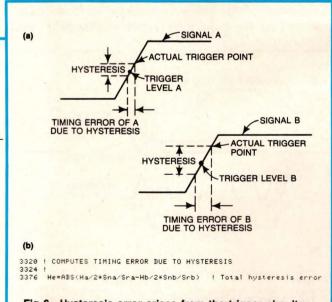


Fig 6—Hysteresis error arises from the trigger circuitry and is a function of the slew rate (a). It's the difference in hysteresis of each channel's triggering circuitry that contributes most to the error equation. After the subroutine (b) computes the error, the counter stores the hysteresis values in nonvolatile RAM.

```
3420 ! COMPUTE TIMING ERROR DUE TRIGGER LEVEL ERROR
3424 !
3428 Tle=ABS(.03*Tla*Sna/Sra)+ABS(.03*Tlb*Snb/Srb)+ABS(.0sa*Sna/Sra-Osb*Snb/Srb)
3432 IF As=Bs THEN Tle=0 ! No timing error if common source
```

Fig 7—The timing error caused by the uncertainty in setting trigger levels can be the largest error component for signals with slow slew rates. You can use the hysteresis and offset values that this routine calculates to provide trigger-level compensation and eliminate their error contributions.

According to some counter specifications, if the slew rates were equal, the hysteresis-error component would always cancel out. This condition obtains only when both the A and B inputs use the same trigger circuitry, which is the case for common-source measurements taken by the reference counter.

Fig 6b's error-analysis subroutine computes the error stemming from hysteresis (variable He). To use the subroutine, define the following setup conditions and parameters and combine them with those previously defined:

- Ha is the hysteresis of trigger channel A in divisions.
- Hb is the hysteresis of trigger channel B in divisions.

The reference system automatically measures the actual hysteresis of each trigger channel of the 1980 and stores those values in nonvolatile memory. These values are accessible over the IEEE-488 bus and are used in this error-analysis subroutine. You can also use hysteresis values to provide trigger-level compensation and, as a consequence, reduce the hysteresis-error component.

From the setup conditions, you can determine not only the proper hysteresis values but also the proper offset levels for A and B (variables Osa and Osb), which you need to determine trigger-level error. Uncertainty in setting trigger levels can generate timing errors. Most time-interval specs don't include this component as a part of the accuracy, but you must add it for a true error analysis. In fact, for signals with slow slew rates, the error caused by uncertainty in setting trigger levels can be the largest component of time-interval error. Fig 7's subroutine generates this component as a separate variable and makes it available to the user.

Autocompensate for trigger-level error

You can determine trigger-level error with the following equation: $\begin{array}{c} \text{trigger} \\ \text{trigger-level error} = \pm \ \frac{\text{trigger}}{\text{accuracy}_{A}} \pm \ \frac{\text{trigger}}{\text{accuracy}_{B}} \end{array}$

Note that, for common-source measurements taken by

the reference-system counter, the trigger-level error is

The subroutine uses variables already defined plus the following setup data and measured parameters:

- Tla and Tlb stand for the trigger levels of A and B in divisions.
- Osa and Osb stand for the offset error of A and B in divisions.

The reference system automatically measures and stores trigger-offset errors in RAM. This subroutine uses these actual error values in computing the trigger-level error (variable Tle).

Hysteresis and offset values are also accessible over the IEEE-488 bus. You can use these values to provide

```
3444 ! TOTAL ERROR COMPUTATION
3448 !
3452 Acc=Lsd+Ne+He+Se ! Total possible error
3456 Res=Lsd+Ne ! Measurement resolution
```

Fig 8—To calculate total error you merely sum up the contributions of the individual sources determined earlier.

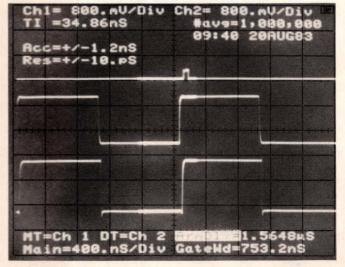


Fig 9—This CRT output from the error-analysis program shows the resolution and accuracy for a typical propagation-delay measurement taken by the reference system (1980 oscilloscope and 1965A gated universal counter).



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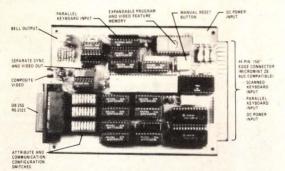
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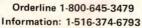
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Systematic error alone doesn't define total system error

trigger-level compensation and thereby eliminate timing errors caused by the uncertainty in setting trigger levels. The following formulas show how to determine trigger levels that compensate for errors induced by trigger-level offset errors and hysteresis:

Tl (to set) = Tl (desired) + offset error
$$-\frac{\text{hysteresis}}{2}$$
(for a positive slope)

Tl (to set) = Tl (desired) + offset error +
$$\frac{\text{hysteresis}}{2}$$
 (for a negative slope).

Complete program generates any variable

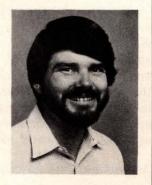
At this point, you can take all the individual components derived thus far and execute the complete erroranalysis program. It measures, calculates, and displays resolution and accuracy specifications on the oscilloscope's CRT. Fig 8 shows the part of the program that computes the final resolution and accuracy and sends that data to the CRT. Fig 9 shows a typical propagation-delay measurement made using the error-analysis program. You can send the analysis of any variable to a CRT screen for immediate evaluation, and you can easily modify the program to generate other specified information.

References

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Author's biography

Johnnie Hancock is an R&D hardware-design engineer for Hewlett-Packard's Colorado Springs Div, where he is currently working on the analog and digital design of digitizing oscilloscopes. He has a BSEE degree from the University of South Florida and is a member of Tau Beta Pi. In his spare time, Johnnie enjoys skiing.



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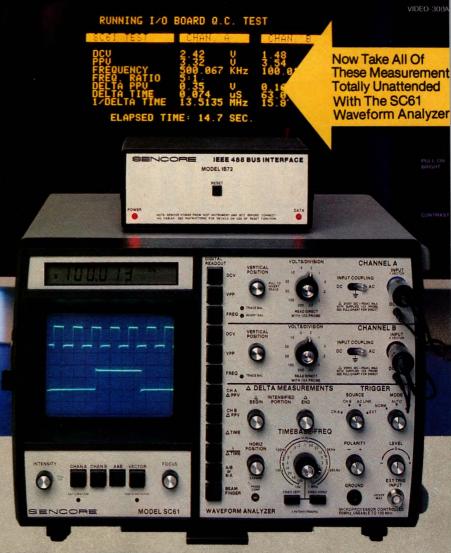


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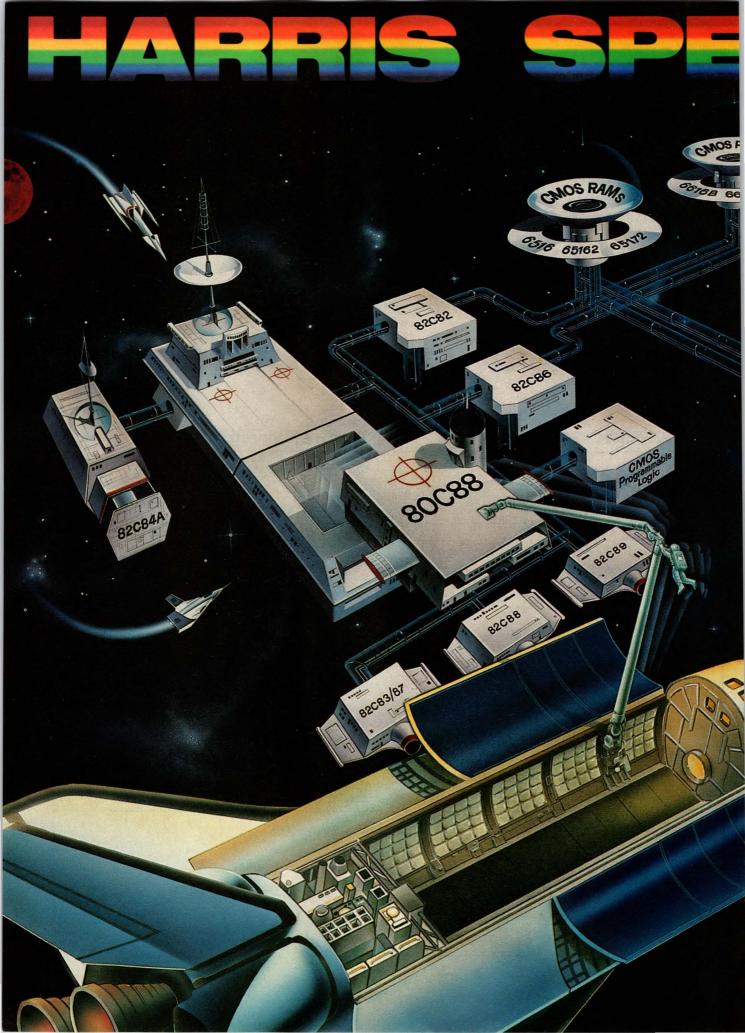
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Get the new Harris 80C88 8/16-bit CMOS CPU into your system. It's fully compatible with your present NMOS 8088 designs, yet consumes only 10% of the power. And the 80C88 16-bit architecture interfaces with memory and I/O via an 8-bit bus, making system design simple and efficient.

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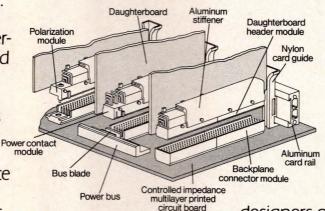
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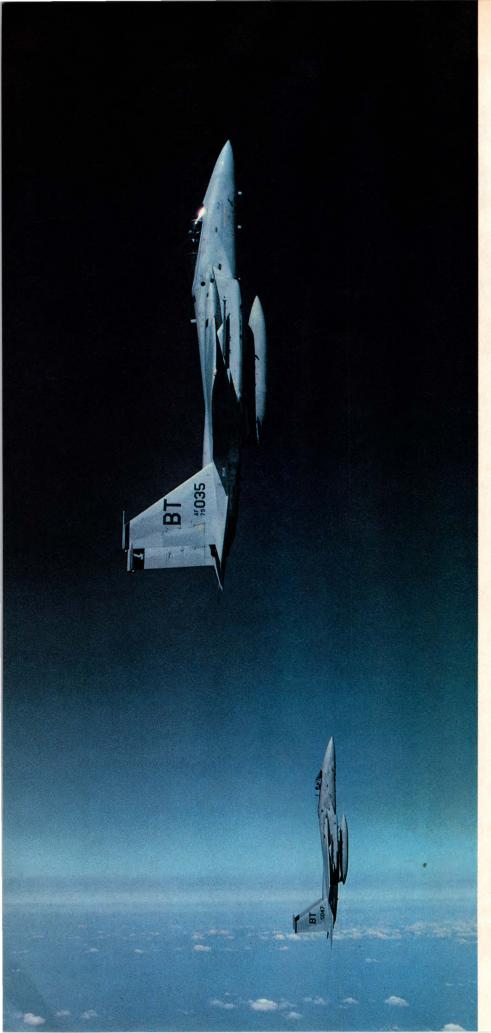
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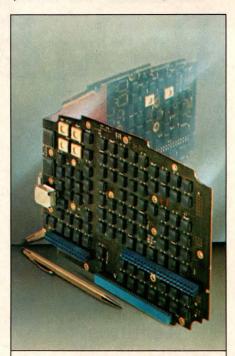


Texas make

As Collins Avionics and Singer-Kearfott developed JTIDS*, the new communications system for the F-15 fighter, Texas Instruments helped solve a severe circuitry packaging problem.

The new system utilizes the most advanced chip packaging technology, the

*Joint Tactical Information Distribution System



Successful application of high-density packaging was achieved in the PC boards of the F-15's new communications equipment. Tl's clad metal system solved thermal expansion mismatch. This mirror reflection photo shows how ICs were mounted on both sides of the PC boards.

leadless chip carrier. Design objectives called for 191 components to be surface mounted on both sides of a $6" \times 8.5"$ printed circuit (PC) board—and to dissipate up to 40 watts of power.

But, during thermal cycling tests, the difference in the thermal coefficient of expansion (TCE) between the ceramic chip carriers and the conventional PC

■ Improved reliability in the F-15's new communications system (JTIDS) is achieved with TI's copper-clad Invar used to prevent solder joint breakage on densely populated PC boards. TI teamed up with Collins Avionics and Singer-Kearfott to meet the demanding packaging requirements of the fighter's receiver/transmitter.

Instruments and Collins Avionics dense circuit reliability soar.

board caused the solder joints attaching the components to the board to break.

TI's solution: A composite metal core of low-TCE Invar that is clad on both sides with copper. Thin, polyimide-glass, multilayer boards were bonded to each side of the metal, to provide the circuitry function.

With a TCE match between the board and the chip carriers, the PC boards easily passed the exacting thermal cycling tests.

And the metal core in the board dramatically improved thermal conductivity and overall rigidity.

Solves thermal mismatch problems

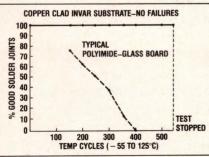
As Collins Avionics discovered, the advantage of using chip carriers to achieve high-density, high-performance circuitry also imposes stringent demands for increased thermal management, structural integrity, as well as TCE compatibility—demands met by Texas Instruments copper-clad Invar.

By combining TCE compatibility with high lateral thermal conductivity. And mechanical rigidity.

All at lower cost than alternate approaches.

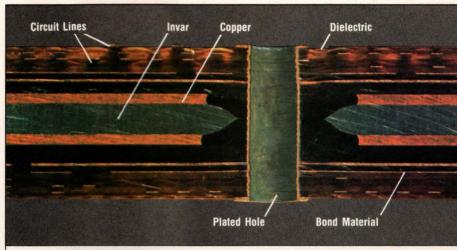
The solution is a trilayer metal.

TI's process involves roll bonding copper foil to Invar—a 36% nickel/64% iron



After 540 thermal cycles from -55° to 125°C failed to break chip carrier solder joints, Collins Avionics halted tests of PC board used in F-15 communications system. Reliability goals had been surpassed by a wide margin.

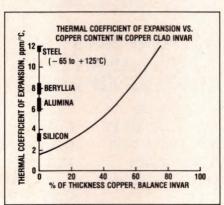
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Effective thermal management is achieved with a copper-clad Invar core that acts as a support for circuitry in the PC board. Heat dissipation characteristics of the copper are excellent, and the Invar contributes rigidity and strength.

alloy. The bonding to each side of the Invar is accomplished by the same process used to make thermostat metal and coins. No adhesives or brazing alloys are required to achieve a permanent bond.

By varying the ratios of the high thermal conductivity copper to the ultralow TCE Invar, the TCE of the clad metal can be tailored to match that of silicon, alumina, or beryllia.



Matching the TCE of the metal core of a PC board to chip carrier ceramic is accomplished by bonding the correct ratio of copper to Invar.

This material is available in thicknesses from 5 to 62 mils (.13 to 1.57 mm). You can get it in widths up to 24 inches (610 mm).

Copper-clad Invar is being developed for many other applications: From ground and power planes in multilayer boards,

to heat sinks and covers for multichip ceramic modules, and more.

A clad remedy to packaging challenges

TI's innovative clad metal solutions can solve your circuitry packaging problems—with a variety of materials.

You can get copper-cored electron tube materials; nickel-clad stainless steel transistor can materials; copper-clad stainless steel lead frame materials; precious metal, aluminum, and solder selective cladding on base metals for lead frame and connector applications; copper-clad steel, aluminum, and Alloy 42 wire products; and high-speed precision stamping and assembly.

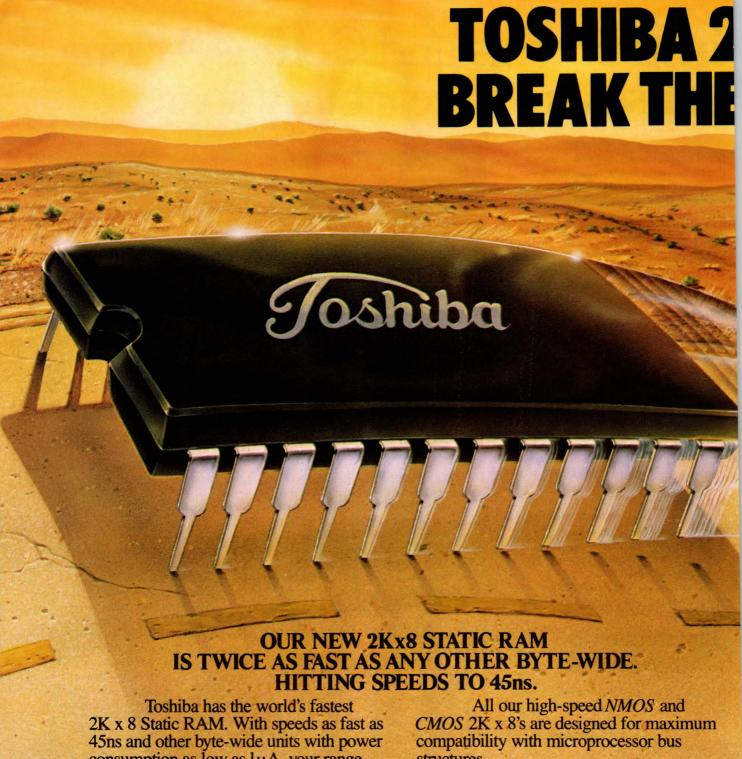
In fact, TI—the world's leading clad metals manufacturer—can help you develop a clad metal solution to many electronic materials problems.

For information, contact Texas Instruments Incorporated, Dept. MMJ9Ø3ED, P.O. Box 401560, Dallas, TX 75240. 1-800-341-5202.

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2016AP-12	NMOS	120ns	65mA	7mA
2016AP-15	NMOS	150ns	. 65mA	7mA
*2015AP-90	NMOS	90ns	80mA	7mA
*2015AP-10	NMOS	100ns	65mA	7mA
*2015AP-12	NMOS	120ns	65mA	7mA
*2015AP-15	NMOS	150ns	65mA	7mA
*2018D-45	NMOS	45ns	120mA	20mA
*2018D-55	NMOS	55ns	120mA	20mA
**5516AP	CMOS	250ns	55mA-	30μΑ
**5516AP-2	CMOS	200ns	55mA	30 µ A
**5516APL	CMOS	250ns	55mA	1μΑ
**5516APL-2	CMOS	200ns	55mA	1μΑ
**5517AP	CMOS	250ns	55mA	30 μΑ
**5517AP-2	CMOS	200ns	55mA	30 µ A
**5517APL	CMOS	250ns	55mA	1μΑ
**5517APL-2	CMOS	200ns	55mA	IμA
5517BP-20	CMOS	200ns	25mA	30 µA
5517BPL-20	CMOS	200ns	25mA	IμA
5518BP-20	CMOS	200ns	25mA	30μA
5518BPL-20	CMOS	200ns	25mA	IμA

**Also available in a plastic flat pack (small outline package).

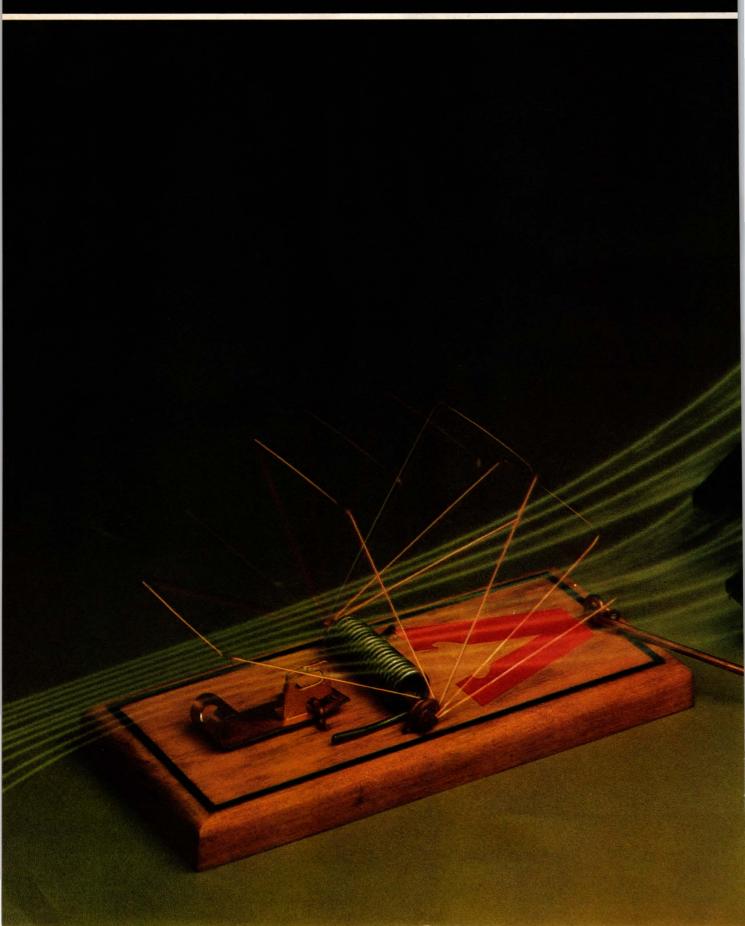
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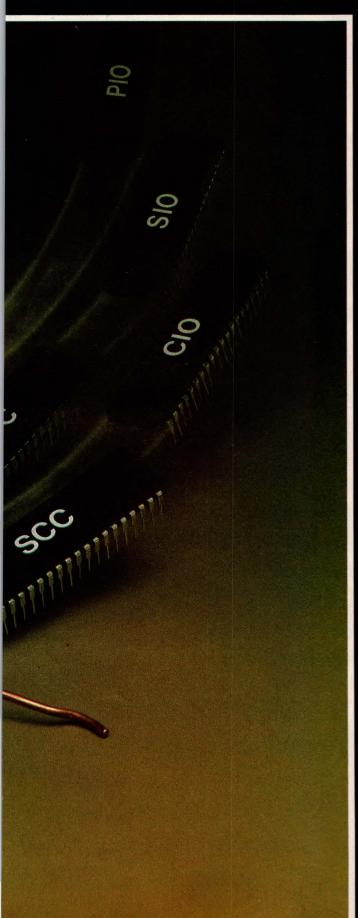
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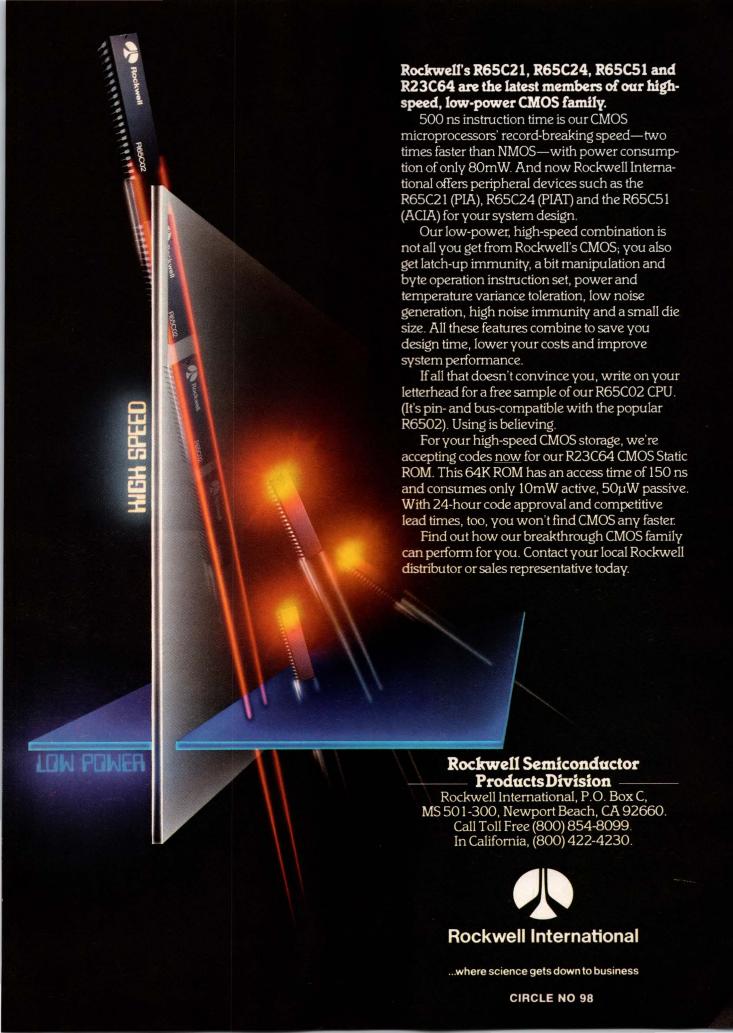
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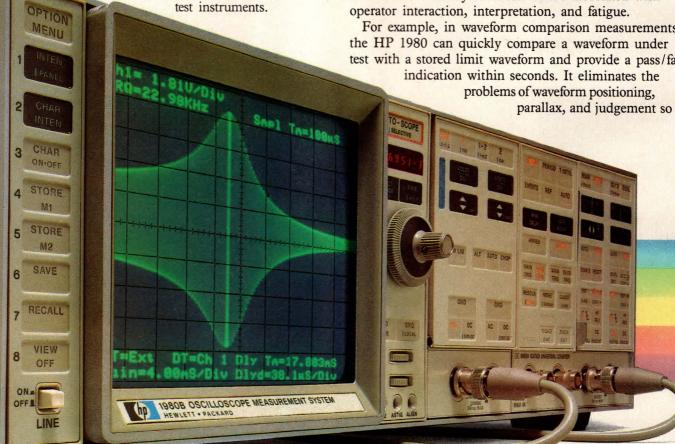
It eliminates or greatly reduces the time you spend in system integration effort and software development. And the HP 1980 reduces test equipment space requirements.



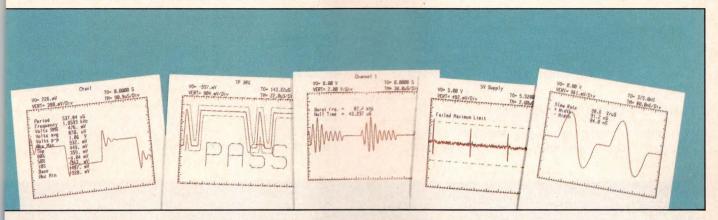
The HP 1980 System saves test time and assures high product quality through consistent waveform comparison and characterization.

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For example, in waveform comparison measurements, the HP 1980 can quickly compare a waveform under test with a stored limit waveform and provide a pass/fail indication within seconds. It eliminates the problems of waveform positioning, parallax, and judgement so



mprove product quality measurements.



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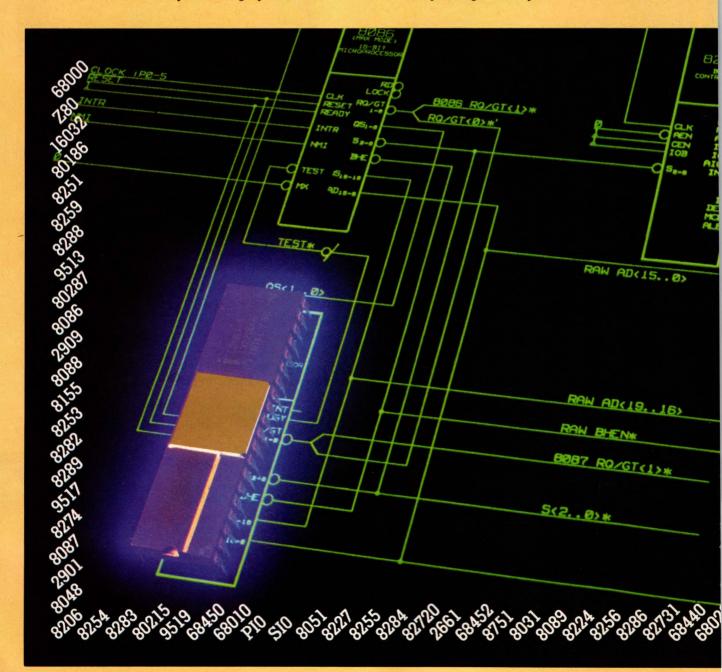
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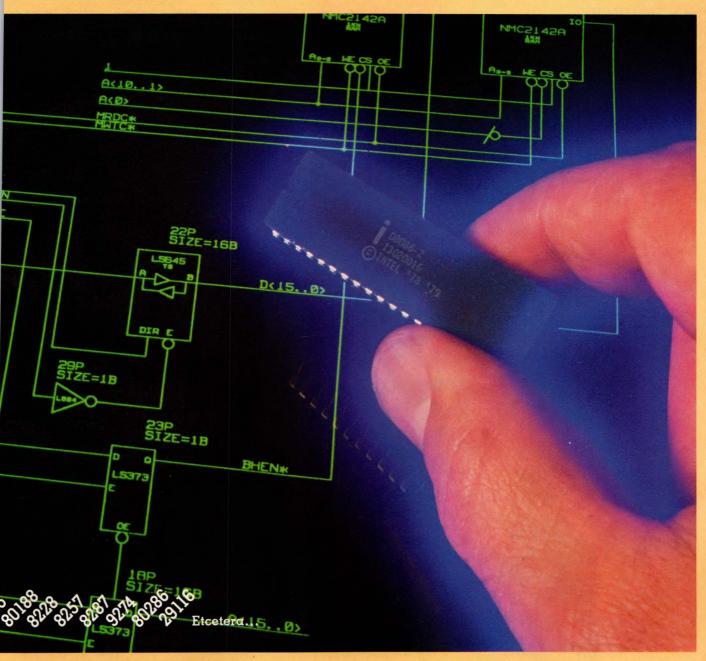
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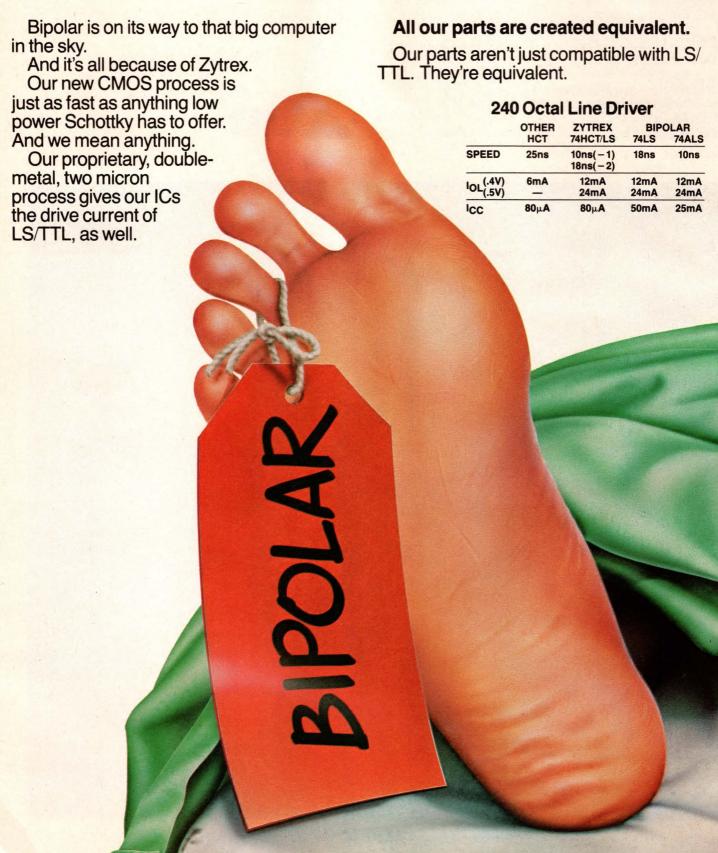
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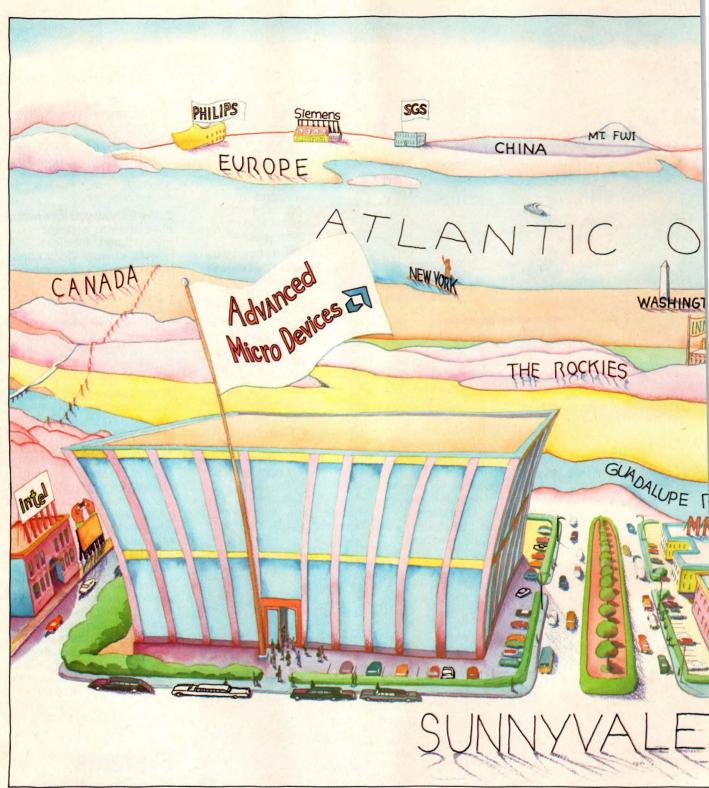
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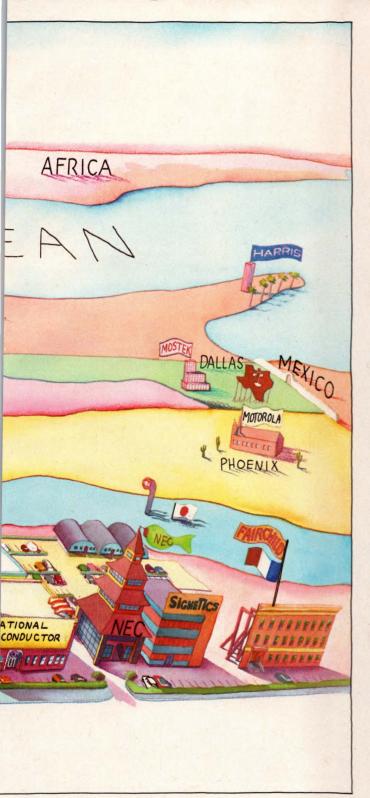


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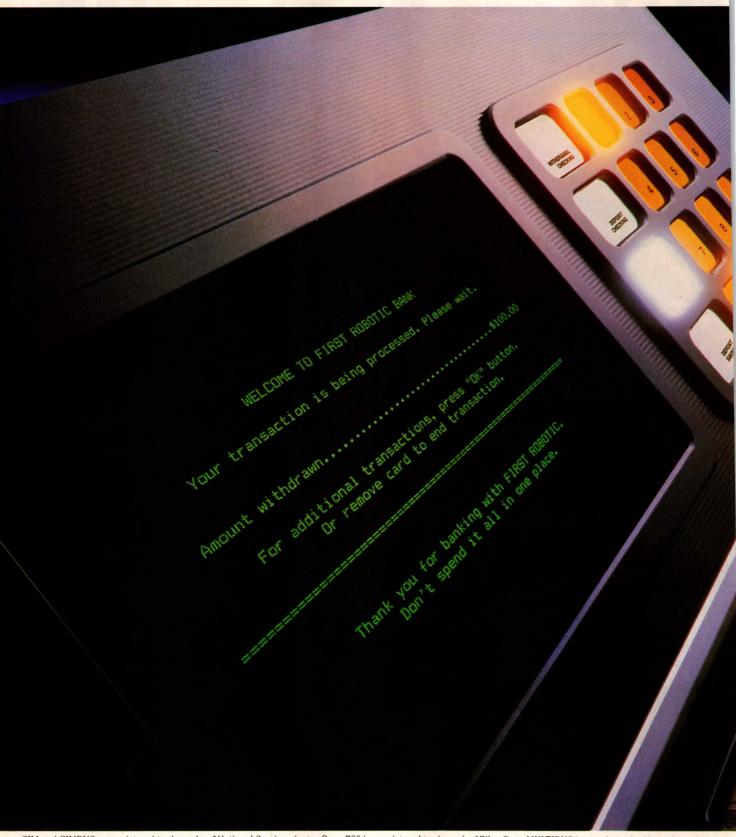
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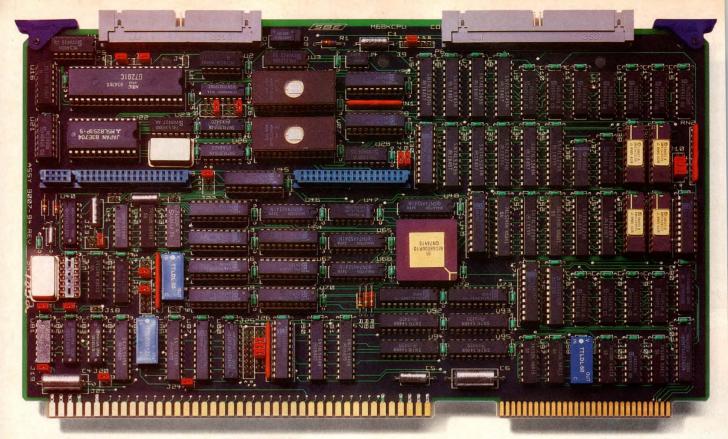
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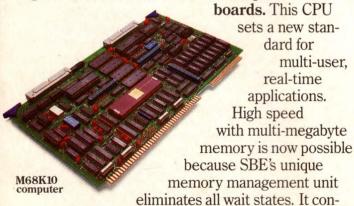




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DESIGN IDEAS

Edited by Robert M Clarke

Reduce display codes to byte-size pieces

Kenneth Knaell

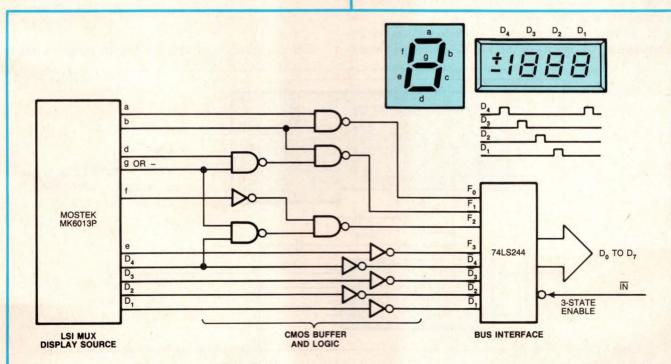
Silver Spring, MD

You can use logic to eliminate the redundant information in 7-segment display codes (figure); transmitting the resulting data to a computer then becomes as efficient as transmitting BCD. This display-to-computer interface handles suppressed leading zeros and decodes sixes and nines with or without horizontal tails (Table 1).

As the figure shows, you can transmit a 3½-digit DMM's TDM display over a byte-wide bus. The display provides a sync pulse for each digit. The computer's software polls the input port; it reads and stores the four bytes—one per digit—and then decodes them per Table 1. Because the leading digit is a special case, its transmission code is modified slightly and is decoded according to Table 2.

To Vote For This Design, Circle No 746

TABLE 1— DISPLAYS D ₃ , D ₂ , D ₁		TABLE 2— DISPLAY D ₄		
DISPLAY BLANK 0 1 2 3 4 5 6 6 7 8 9 9	F ₃ F ₂ F ₁ F ₀ (HEX) B 4 9 2 A D F 7 7 8 6 C E	BLANK + BLANK - BLANK 1 + 1 - 1	F ₃ F ₂ F ₁ F ₀ (HEX) B B F 9 D	
*NOTE: $F_3 = \overline{e}$ $F_2 = F + D$ $F_1 = \overline{b} + d$ $F_0 = \overline{a \cdot b}$				



Eliminating redundant information from 7-segment codes lets you transmit data to a computer at one byte per digit, simplifying this display-to-computer interface.

Build a two-IC programmable power supply

Philip Burton

National Institute for Higher Education, Limerick, Ireland

You can use a CMOS D/A converter and an LM723 voltage regulator to make a digitally programmable power supply. This design uses a bootstrap technique to eliminate the dual supplies often required in these applications and, in its simplest form, requires no additional active components.

The design's AD7548 12-bit D/A converter has TTL-compatible inputs and interfaces directly with most μP buses. You can use a different D/A converter, but you should be sure that it has separate analog and digital ground terminals and TTL-compatible inputs.

The Fig 1 circuit can produce outputs from 7.15 to 14.3V. The LM723's internal 7.15V reference, $V_{\rm REF}$, drives the LM723's noninverting input through R_1 and fixes the AD7548 D/A converter's analog ground ($A_{\rm GND}$) reference at 7.15V. (Note that although both the LM723 and AD7548 have terminals designated $V_{\rm REF}$, this discussion refers only to that of the LM723.) The AD7548's supply voltage must be at least 5V higher than $V_{\rm REF}$ for the IC to operate correctly, and the voltage shouldn't exceed 17V.

R₁ minimizes errors caused by different source impedances at the inputs of the LM723's internal amplifi-

er. The converter's internal feedback resistor, $R_{\rm F}$, and the converter itself form a voltage divider across the circuit's output between $V_{\rm OUT}$ and $A_{\rm GND}$. This divider, controlled by a digital input to the converter, provides the feedback from the supply's output to the inverting input of the LM723's internal amplifier. When the LM723 regulates, it tries to force the noninverting input of its amplifier to $V_{\rm REF}$. Thus, the D/A converter operates with OUT₁ and $A_{\rm GND}$ at the same potential—a necessary condition to insure converter linearity.

The D/A converter's input resistance at the OUT $_1$ node (pin 1) is equal to $R_{DAC}\div D$, where D is the fractional binary input to the D/A converter (eg, D=2048/4096 when the input is 1000 0000 0000 and D=4095/4096 when the input is 1111 1111 1111) and R_{DAC} is the D/A converter's input resistance. The equation for the circuit's output voltage is thus

$$V_{OUT} = \frac{V_{REF} (1 + R_F D)}{R_{DAC}},$$

and, because the R_F and R_{DAC} values usually match within 0.5%, this expression reduces to

$$V_{OUT} = V_{REF}(1 + D).$$

You can change the supply's output range to 3.6 to

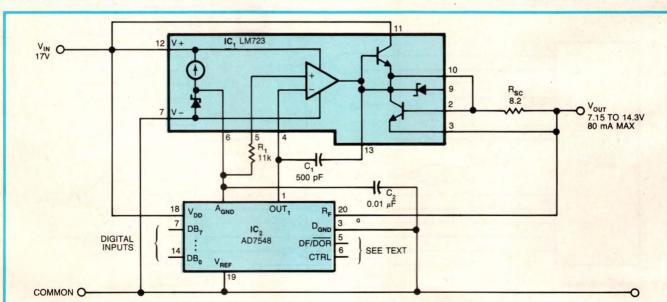
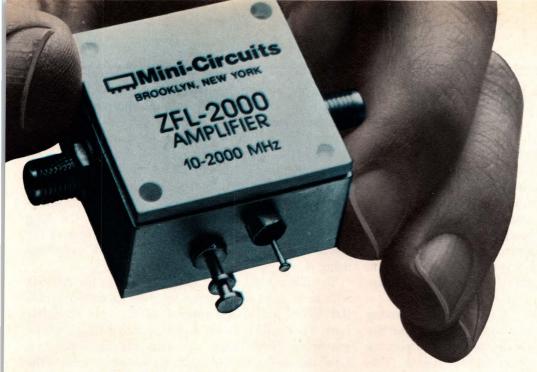


Fig 1—By using two ICs and several discrete components, you can build a digitally programmable power supply that furnishes outputs to 14.3V at 80 mA.



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ZFL-2000 SPECIFICATIONS

FREQUENCY	10-2000 MHz
GAIN	20 dB
GAIN FLATNESS	±1.5 dB
OUTPUT POWER (1 dB compression)	+17 dBm
NOISE FIGURE	7.0 dB
INTERCEPT POINT (3rd order)	25 dBm
VSWR, 50 OHMS	2:1
DC POWER volt, current	+ 15 V, 100 mA
HEAT SINK	Internal
OPERATING TEMP	-55°C to $+100$ °C



C98 REV. A

DESIGN IDEAS

7.15V by connecting the voltage divider—the D/A converter—between $V_{\rm REF}$ and ground, with the divider's center tap connected to the noninverting input of the LM723's amplifier. $A_{\rm GND}$ (pin 2 of the AD7548), the output voltage $V_{\rm OUT}$, and the amplifier's inverting input (pin 4 of the LM723) are tied together.

The LM723's maximum power-dissipation spec limits the circuit's output current. The value shown for $R_{\rm SC}$ limits the current to the recommended 80-mA value for the plastic LM723 when it operates without a heat sink at a 25°C ambient temperature. You can increase the supply's output current by placing a heat sink on the LM723 and, as in Fig 2, using an external pass transistor.

To compensate for the $V_{\rm REF}$ variation among LM723s, you can include a provision for calibrating the power supply. Fig 2 shows a circuit that incorporates this provision as well as other improvements. This supply operates from input voltages as high as 35V, and you can program its output in the range from 4.096 to 20.48V (ie, 16 mV per bit for 10-bit resolution). The $R_{\rm SC}$ value limits the output current to 100 mA, but you can change its resistance value to limit at other current levels using the expression

$$R_{SC} = \frac{0.675}{I_{SC}}$$
 for $T_A = 25^{\circ}C$.

If you increase the output current level, you must ensure that the external pass transistor can handle the necessary power dissipation.

The Fig 2 circuit includes a dual op amp, the AD644 (IC_{3A} and IC_{3B}), and a pass transistor, a TIP 31A (Q_1). IC_{3A}, configured as a noninverting amplifier with a gain of 2.1, supplies 15V to the V_{DD} input of the D/A converter. IC_{3B}, connected as a noninverting, unity-gain buffer, supplies a 4V reference to both the A_{GND} input of the AD7548 and the noninverting input of the LM723's amplifier. You can adjust the 4V reference using R_7 .

To calibrate the power supply, program the AD7548 with an all-zero digital input by tying its data-override (DF/ \overline{DOR} —pin 5) and control (CTRL—pin 6) inputs Low. Then adjust R_7 for 4.096V at pin 2 (A_{GND}) of the converter. Next, leave the data-override input tied Low, but tie the control input High—this programs the chip with an all-one digital input. Now adjust R_8 so that V_{OUT} equals 20.476V, which is the supply's maximum output. Finally, set the AD7548 for normal operation by tying both the data-override and control inputs (pins 5 and 6) High by connecting them to a 5 to 15V supply.

EDN

To Vote For This Design, Circle No 747

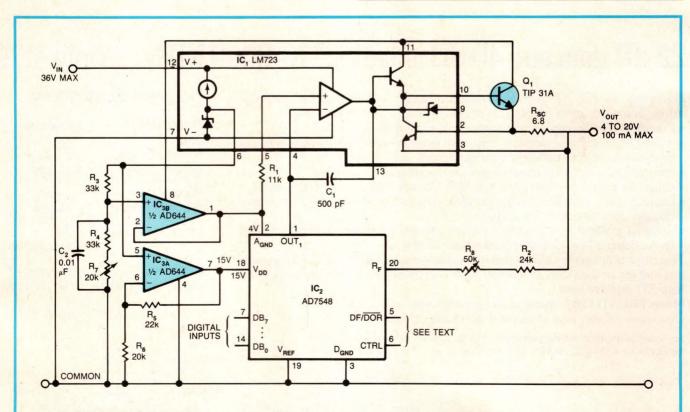


Fig 2—You can increase the Fig 1 programmable supply's output current and voltage range by adding a dual op amp (IC_3) and a pass transistor (Q_1).

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Dual-mode timer serves many applications

Bob Neidorff

Unitrode Integrated Circuit Corp, Merrimack, NH

Long-term timers can serve many applications. They can operate sprinkler systems periodically, maintain machines regularly, and turn lights on and off in homes to discourage burglars. A dual-mode timer, like the circuit in Fig 2, suits these applications better than a common 24-hour mechanical timer does.

As Fig 1 shows, the dual-mode timer activates a load cyclically, with an individually controllable Output Enable and Off times; during the Output Enable time the output pulses On and Off at a programmable duty cycle.

Consider one application for such a circuit: an underground irrigation system for watering trees. The best way to water trees is to leave the water flowing for 12 hours at an extremely slow rate so the trees' roots absorb all the water, leaving no standing water, which can cause root decay. You could use a pipe that emits water through small holes, but a tree's feeder roots would clog these quickly. Temperature change also affects such devices, making the holes expand and contract, which causes shifts in the flow rate.

To eliminate the problems associated with emitters that have small holes, you can use an emitter with large holes and make the water flow faster, pulsing it on and off for 5 min every hour. The actual volume of water delivered to the tree would be the same. The circuit in Fig 2 produces such a timing sequence.

Referring to **Fig 2**, note that the dual-mode timer consists of a power supply, a 60-Hz waveform shaper, a divider string, data-selector latches, and a load control. Three switches control the timer's operation: an On/Off switch, an optional reset switch, and 12 programming

switches. The logic ICs are MC14000 Series CMOS devices, and the triac is a T2301PB. To furnish isolation, you can add an MOC3011 optotriac to the circuit.

The power supply accepts 24V ac at 60 Hz. A half-wave rectifier circuit, filter capacitors, and an MC7812CT 3-terminal regulator apply 12V to the CMOS logic and the triac. A single 1N4001 rectifier diode and a resistor-capacitor filter act as a waveform shaper; the shaped waveform is the 60-Hz clock for the MC14040 counters. The three cascaded MC14040s form a divider. MC14512 data selectors, controlled by the 12 programming switches, select the divider output that drives the latches.

Monostables and NAND gates form two edge-triggered S/R latches. The divider outputs set and clear the latches to select the correct On time and duty cycles. The outputs from the two latches are ANDed together by another IC that drives the triac (or optional optotriac and isolator). Thus, both latches must be set to allow the triac to be on.

A snubber circuit, consisting of a 0.1- μF capacitor in series with a 100Ω resistor, protects the triac from voltage spikes caused by the load. You can change these values if you expect to encounter highly inductive loads.

The table shows the effects of the programming switches on the times represented in the timing diagram of Fig 1. Although you can't use all of the 4096 possible switch positions (some combinations are invalid), you have a multitude of times to choose from. For example, you can select On times from 17 seconds to 36 minutes and total-cycle times from approximately 0.8 to more than 100 days.

Editor's Note: The author was employed at Motorola Linear ICs Inc when this Design Idea was accepted.

To Vote For This Design, Circle No 748

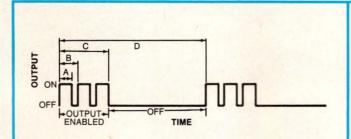


Fig 1—The Fig 2 circuit allows you to program times A, B, C, and D.

SWITCH	TIME	SWITCH	TIME	SWITCH	TIME	SWITCH	TIME
CBA	A	FED	В	IHG	C	LKJ	D
000	17 SEC	000	1.1 MIN	000	1.2 HR	000	19.4 HR
0 0 1	34 SEC	001	2.3 MIN	001	2.4 HR	001	1.6 DAY
010	1.1 MIN	010	4.6 MIN	010	4.9 HR	010	3.2 DAY
0 1 1	2.3 MIN	011	9.1 MIN	011	9.7 HR	011	6.5 DAY
100	4.6 MIN	100	18.2 MIN	100	19.7 HR	100	12.9 DAY
101	9.1 MIN	101	36.4 MIN	101	1.6 DAY	101	26 DAY
1 1 0	18.2 MIN	110	1.2 HR	110	3.2 DAY	110	62 DAY
111	36.4 MIN	111	2.4 HR	111	6.5 DAY	111	104 DAY
	VALID. OTH TIME A < 1 TIME B < 1 TIME C < 1	IER SWITCH SE TIME B TIME C TIME D	SITIONS THAT CETTINGS WILL C	AUSE UNPRED	ICTABLE RESU	ALITIES ARE LTS.	

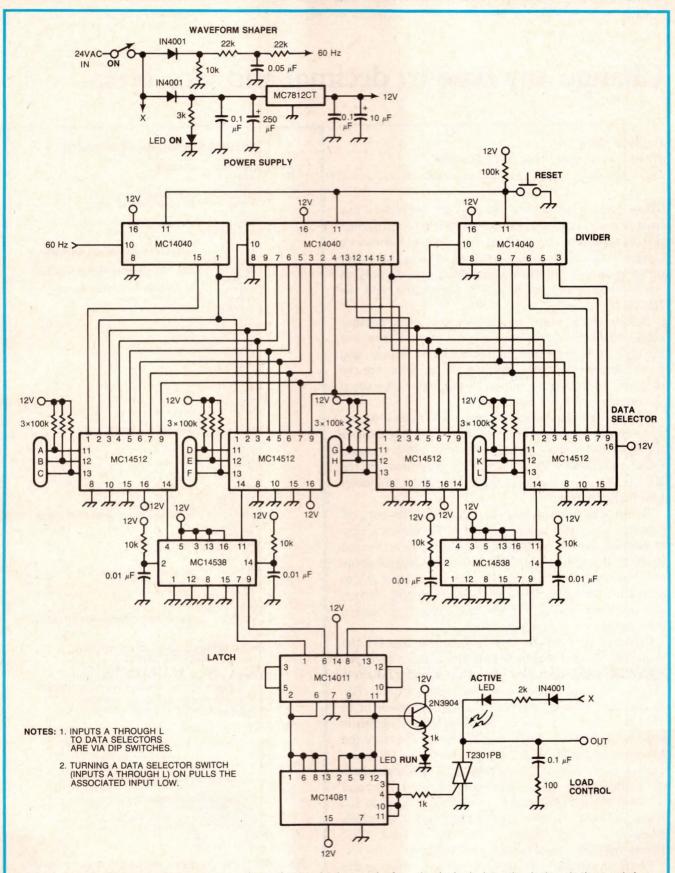


Fig 2—Using a 60-Hz timebase, counters, data selectors, latches, and a few other logic devices, the dual-mode timer switches loads to 200V ac at 1.5A.

Change any base to decimal and vice versa

David M Acre

McDonnell Aircraft Co, St Louis, MO

These two programs let you convert decimal to any base or any base to decimal using the HP-11C programmable calculator. Both fit easily into the calculator's program space. Moreover, you can combine them for direct base-to-base conversions. They operate only on integer values and are upwardly compatible with the HP-15C.

Before using these programs, note that because single-digit representations for bases greater than nine are difficult to represent on the calculator display, you must use their decimal equivalents. Also, note that the program addresses memories R_0 through R_9 by using the calculator's index register.

Fig 1 shows the decimal-to-base conversion program and a chart of its register usage. Likewise, Fig 2 shows the base-to-decimal conversion and its register usage. Label assignments let you load both programs into the HP-11C program memory; neither program will interfere with the other.

To use either program, you must load the base-of-conversion register before execution. To convert a base to decimal, load R_3 with the base value to be converted to (ie, hexadecimal=16). Then enter the decimal value that you want to convert, and press the f_A label key to start the conversion. The calculator makes the conversion and stores the factors of each power of the base in their respective memory registers.

Consider an example: Say you want to convert the value 255 (in decimal) to hexadecimal. Store 16 in R₃. Enter 255, and press the f_A key. After running for a few seconds, the calculator stops and displays 1.15. The integer part (the 1) says that the highest power of 16 needed to represent 255 in hexadecimal is 1, which is also the highest numbered register needed to store the hexadecimal result. The fractional part (the 15) is the decimal equivalent of a hexadecimal "F" and represents the 16¹ multiplier. The 1.15 is stored in register R₁, and the only other register that need be displayed is R₀. When you recall R₀, the calculator displays 0.15, which represents 15×16°, another hex "F," or just "15." Taken together, these results give you "FF."

Consider another example: Instead of converting 255 to hex, let's convert it to octal (base 8). Doing so yields the following sequence:

HP-11C DECIMAL-TO-BASE CONVERSION PREFIX COMMENTS FUNCTION LBL A STO .0 STO 2 SAVE ENTERED VALUE FIX 8 FIX FOR BOUNDING FUNCTION LOG GET THE BASE OF CONVERSION LOG RND ROUND THE RESULT TO GET PROPER VALUE INT STO 1 SAVE THE NUMBER OF MEMORIES NEEDED STOI RE-ITERATIVE CALCULATION SECTION RCL .2 <z> r.2 - r(i) *BASE! RCL .3 < V> RCL I <x> DIVIDE INT STO (i) RCL .3 RCL I MULTIPLY RCL .2 EXCHANGE X AND Y x < -> vSTO .2 SAVE NEW NUMBER RCL (i) DIVIDE BY 100 RCL I STO (i) STORE THE FINAL VALUE DECREMENT TO THE NEXT LOWER POWER DSE ENTER ENTER RCL I x < > 0 CHECK TO SEE IF FINISHED GTOO <no>GOTO LABEL 0 FIX 2 STOI DISPLAY COEFFICIENT OF HIGHEST POWER RCL (i) STOP HP-11C DECIMAL-TO-BASE CONVERSION REGISTER USAGE R0 TO R9 : STORE THE RESPECTIVE FACTORS FOR EACH POWER FOR THE NUMBER IN THE BASE CHOSEN. IE, IF b = BASE TO BE CONVERTED TO, THEN THE REPRESENTATION ON THE CALCULATOR DISPLAY IS: DISPLAY FORMAT 4.ee 3.dd 2.cc 1.bb + (b4) *ee + (b3) *dd + (b2) *cc + (b1) *bb + (b0) *aa R.O - HOLDS THE DECIMAL NUMBER ENTERED BY THE USFR R.1 - HIGHEST NUMBERED REGISTER USED FOR NEW BASE REPRESENTATION

R.2 — INTERMEDIATE CALCULATION REGISTER

R.4 TO R.9 — NOT USED RI — INDEX REGISTER

R.3 - BASE OF CONVERSION (HEXADECIMAL = 16)



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DESIGN IDEAS

DISPLAY KEYS PRESSED 8. STO .3 f A RUNNING 2.03 RCL 1 1.07 RCL 0 0.07

Thus, 255_{10} equals FF₁₆ and also equals 377_8 . You can pick any base, but a judicious choice of bases may give you a greater conversion range (eg, as in picking base 16 rather than base 2).

By the same token, you can enter a number's base and digits into their respective registers. Then you just enter the number of the highest register used (ie, enter 1 for R_1) and press f_B . The number's decimal equivalent will then appear on the display. Here's an example:

DISPLAY KEYS PRESSED STO .3 .0.15 STO 1 .0.14 STO 0 .1. f B RUNNING 254

It shows that hexadecimal "FE" equals 254.

The order in which you store the digits is the only important aspect of setting up the registers prior to conversion. In the decimal-to-base routine, the numeric values displayed to the left of the decimal point tell you which digit in the conversion process is being displayed. You don't need the numbers to the left of the decimal point when making entries in the base-to-decimal conversion.

The next step you can take is to make the two programs into subroutines by replacing R/S with a RETURN. You can then call them from a top-level program. This would let you convert one base directly to another. Fig 3 shows a short top-level program stored just above the two subroutines. The order of operations goes as follows: Store the number in registers R_9 through R_0 , respectively. Then, store the number's present base in R_3 . Store the base to which the number will be converted in R_4 . Next, enter the highest register used to store the original number and press f_A to begin execution. The calculator displays the results in the same format as does the decimal-to-base routine output.

Each time you run a program, you have to enter new data and bases. Consider this example:

This shows that hex "FE" equals octal 376. Note that, with this version of the programs, the calculator performed the hex-to-octal conversion without operator intervention.

To Vote For This Design, Circle No 749

HP-11C BASE-TO-DECIMAL CONVERSION

PREFIX	FUNCTION	COMMENTS
1	LBL B	
	STO .1	: SAVE THE USERS NUMBER OF DIGITS
	STOI	: SAVE ENTERED VALUE
	0	
	STO .2	
f	LBL 1	
	RCL (I)	
	FRAC	: USE FRACTIONAL PART OF THE ENTERED NUMBERS
	1	
	0	
	0	
	X	: MULTIPLY BY 100
	INT	: <z> CONVERT FRACTION TO INTEGER</z>
	RCL .3	: <y> GET THE BASE OF CONVERSION</y>
	RCL I	: <x> GET INDEX VALUE</x>
	YX	
	X	
	RCL .2	
	+	
	STO .2	
f	DSE	: GO TO NEXT LOWEST REGISTER
	ENTER	
	ENTER	
	RCLI	
	1	
	+	
g	x<>0	: CHECK TO SEE IF FINISHED
•	GTO 1	: <no> GO BACK TO LABEL 1</no>
f	FIX 0	: <yes></yes>
120	RCL .2	: DISPLAY DECIMAL RESULT
	STO .0	: SAVE IN .0 FOR USE WITH OTHER ROUTINE
	R/S	: STOP

HP-11C BASE-TO-DECIMAL CONVERSION REGISTER USAGE

R0 TO R9: STORE THE RESPECTIVE FACTORS FOR EACH POWER FOR THE NUMBER IN THE BASE CHOSEN.

IE, IF b = BASE TO BE CONVERTED TO, THEN THE REPRESENTATION FOR ENTRY ON THE CALCULATOR DISPLAY IS (x = DON'T CARE)

MEMORY R4 R3 R2 R1 R0
DISPLAY FORMAT x.ee x.dd x.cc x.bb x.aa

VALUE+ (b4) *ee + (b3) *dd +
(b2) *cc + (b1) *bb + (b9) *aa

R.0 — HOLDS THE EQUIVALENT DECIMAL VALUE
R.1 — HIGHEST NUMBERED REGISTER USED FOR OLD

BASE REPRESENTATION
R.2 — INTERMEDIATE CALCULATION REGISTER
R.3 — BASE OF CONVERSION (HEXADECIMAL = 16)
R.4 TO R.9 — NOT USED

RI - INDEX REGISTER

RET

number chosen in the respective register.

Fig 2—Complementing the Fig 1 program this base-todecimal program stores the factor for each power of the

Fig 3—Using the Fig 1 and 2 programs as subroutines, this short program makes direct nondecimal base-to-base conversions.



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Circuit handles multiple sync characters

Yadagari Gunda and B Vasantha ISRO Satellite Centre, Bangalore, India

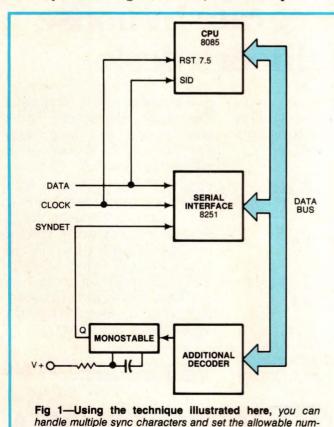
In TDM telemetry systems or synchronous data-communication systems, a long frame length makes the most efficient use of a communications channel. But as the frame length increases, so does the length of the frame sync code. You can use the technique outlined in Fig 1 to handle any number of sync characters or bits, and you can program the number of errors allowed in the sync code. In contrast, commercially available interfaces can handle at most two sync characters with no allowable error margins.

In Fig 1's circuit, the CPU checks the sync code. After each frame ends, the serial interface is programmed for External Sync and Enter Hunt mode. The CPU uses the RAM registers to store received data and uses the synchronous clock as the interrupting input. This clock will interrupt (via line RST 7.5) the system at every Low-to-High transition; the interrupt is en-

abled only during the frame-sync checking.

When an interrupt occurs, the CPU goes to the CHKFSC (Checking For Sync Characters) routine. Fig. 2 shows a flowchart of the routine; Fig 3 contains a program listing. The routine causes the CPU to read data into the accumulator and rotate the RAM registers (Fig 4). The CPU then compares the RAM registers to the frame-sync code to find the transmission errors, if any. If the number of errors found is less than the programmed limit for errors, the CPU will apply a SYNDET input to the serial interface and disable the RST 7.5 input. On the other hand, if the number of errors exceeds the programmed limit, the system will wait for another data bit to arrive, and this process will continue until the correct frame-sync code arrives. The CPU uses a frame-length counter to detect the end of the frame. Because the CPU executes the CHKFSC for every bit, the serial-data rate is limited.

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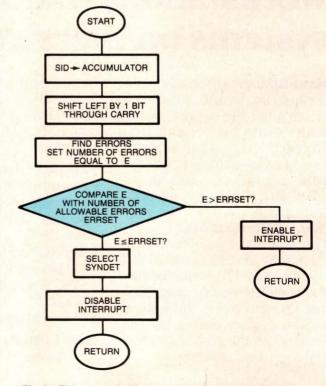


Fig 2—This checking-for-sync-characters routine is executed by the Fig 1 circuit's CPU for each data bit transmitted over a synchronous communication channel.

ber of data-transmission errors.

DESIGN IDEAS

```
LOC
       OBJ
                    LINE
                                    SOURCE STATEMENT
                     1;
                     2:
                     3
                                   ; THIS ROUTINE 32BIT LENGTH FRAME SYNCH CODE (4 BYTES)
                     4;
                     5 TEMREG
                                                        TOP ADDRESS OF THE TEMPARARY REGISTERS
                                   FOU
                                          2003H
2003
                                   EQU
                                                         TOP ADDRESS OF THE FRAME SYNCH CODE
3003
                     6 FSCODE
                                          3003H
0004
                     7 REGLEN
                                   EQU
                                          04H
                                                        ; FRAME SYNCH CODE LENGTH
                                                        : ADDRESS OF THE ERROR PORT
0000
                     8 ERRSET
                                   EQU
                                          OOH
                                                        ; ADDRESS OF SYNDET PORT
0001
                     9 SYNDET
                                   EQU
                                          01H
000B
                    10 DISFSC
                                   EQU
                                          OBH
                                   CSEG
                    11
0000
       210320
                    12 START:
                                   LXI
                                          H, TEMREG
                    13
                                   RIM
0003
       20
                                          D, REGLEN
0004
       1604
                    14
                                   MVI
                                   RLC
                                                        ; SID - CARRY
                    15
0006
       07
                    16 LOOP 1:
                                   MOV
                                                        ; ROTATES REG. SET BY ONE BIT
0007
       7E
                                          A, M
0008
       17
                    17
                                   RAL
                                   MOV
0009
                    18
                                           M. A
       77
000A
       2B
                    19
                                   DCX
                                          H
000B
       15
                    20
                                   DCR
                                          D
                                          LOOP1
000C
       C20700
                C
                    21
                                   JNZ
000F
       23
                    22
                                   INX
                                          H
0010
       010330
                    23
                                   LXI
                                          B, FSCODE
                                   MVI
                                          D. REGLEN
0013
       1604
                    24
0015
       1E00
                    25
                                   MVI
                                          E, OH
                                                        ; FINDS NUMBER OF ERRORS IN RECEIVED DATA
0017
       OA
                    26 LOOP:
                                   LDAX
                                          В
       CD2E00
                                   CALL
                                          COUNT
0018
                C
                    27
                    28
                                   DCX
                                           В
001B
       OB
001C
       15
                    29
                                   DCR
                                           D
                                           LOOP
       C21700
                C
                                   JNZ
001D
                    30
                                                        ; ALLOWABLE NO. OF ERRORS
0020
       DB00
                    31
                                   IN
                                           ERRSET
0022
       BB
                    32
                                   CMP
                                                        JUMPS IF RX DATA HAS LESS ERRORS THAN PROGRAMMED
       D22800
                C
                                   JNC
                                           CORRECT
0023
                    33
0026
       FB
                    34
                                   EI
                                   RET
0027
       C9
                    35
0028
       D301
                    36 CORRECT:
                                   OUT
                                           SYNDET
                                   MVI
                                           A. DISFSC
                    37
002A
       3E0B
002C
       30
                    38
                                   SIM
002D
       C9
                    39
                                   RET
                    40 COUNT:
                                   PUSH
                                          D
                                                        : COMPARES EACH BYTE-FINDS ERRORS
002E
       D<sub>5</sub>
                                           D, OSH
002F
       1608
                    41
                                   MVI
                    42 LOOP2:
                                   RLC
0031
       07
                                           SKIP
                C
0032
       D23600
                    43
                                   JNC
                                           E
                    44
                                   INR
0035
       1C
0036
       15
                    45 SKIP:
                                   DCR
                                           D
                                           LOOP2
                C
                                   JNZ
       C23100
0037
                    46
003A
       23
                    47
                                   INX
                                           H
                    48
                                   POP
                                           D
003B
       D1
                                   RET
003C
       C9
                    49
                C
                    50
                                   END
                                           START
0000
```

Fig 3—This CHKFSC code, whose operation is outlined in the Fig 2 flowchart, runs on the 8085.

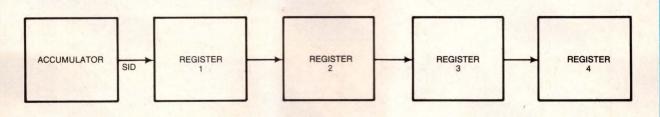


Fig 4—On every interrupt of the Fig 1 CPU, RAM registers are shifted one bit.

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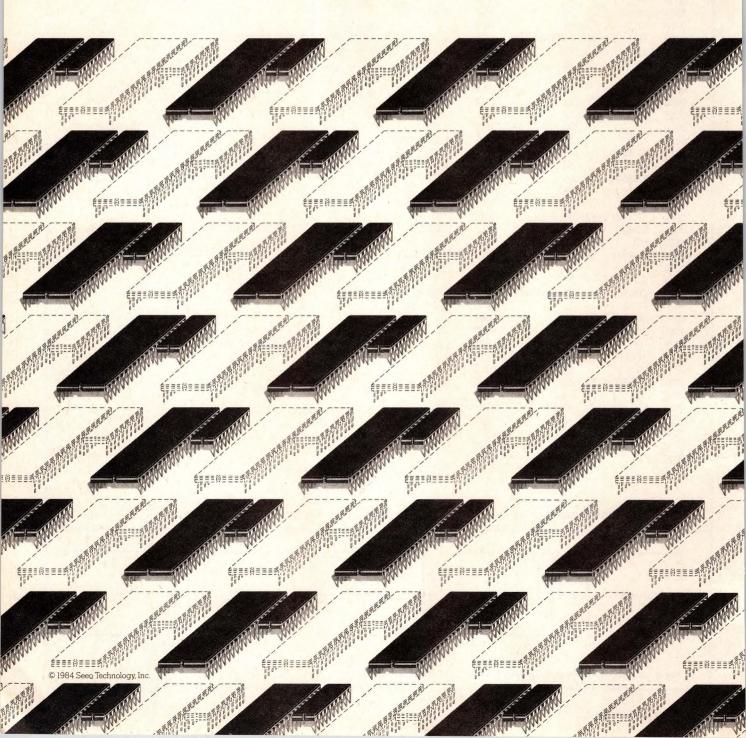
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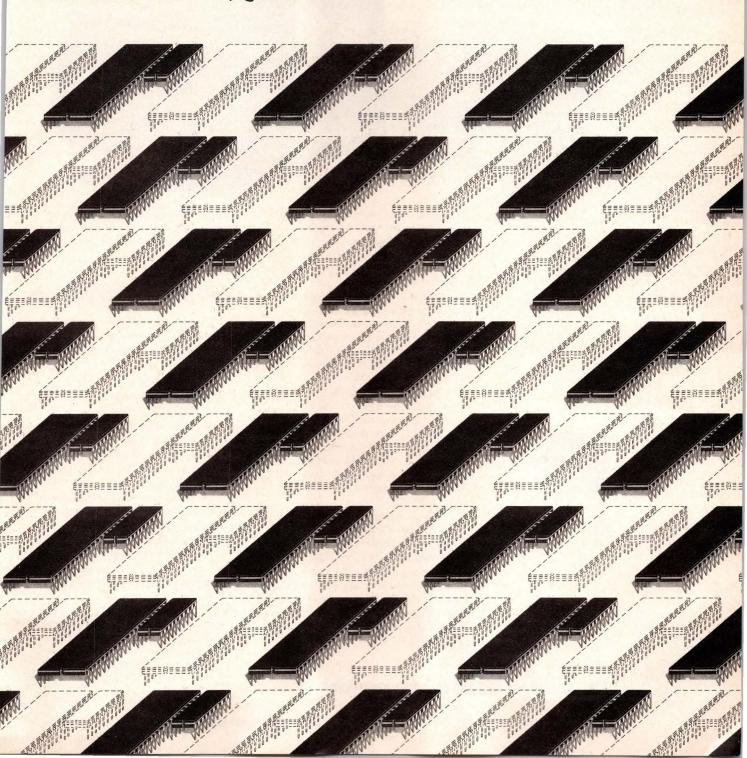
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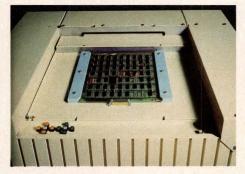
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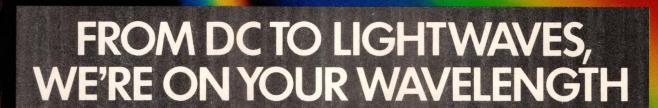
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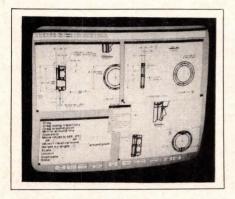
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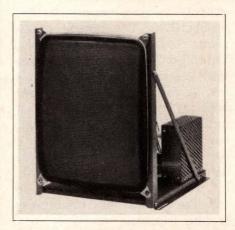
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Circle No 384

DATA TRANSFER. pcMainframe Release 1.2.0, for OS and DOS environments, is an update of the pcMainframe intelligent data-transfer system, which allows personal-computer users to download and upload generalized files in a real-time environment between personal computers and a host IBM mainframe computer. The release features enhanced support for 3278/9 terminal emulators and for

protocol, can access a database or multiple files, and can upload and update key-sequenced data-set (KSDS) files. The system supports such protocols as IBM's 3101, the ADM36I, TeleVideo 950, and the VT100. The system reformats data in BASIC, FIXED, or DIF (the data-interchange format used by Lotus 1-2-3 and Visicalc). The 1.2.0 release features controlled system access and supports character sets in English, French, German, Swedish, Italian, and Dutch. You can interface the package to the company's on-line electronic spreadsheet. To run the software, you need an IBM PC or compatible, MS-DOS or PC-DOS (1.1 or 2.0), and a 3270 protocol converter or similar board. For OS environments, including an 8-computer license, \$12,000. For DOS environments, including 8computer license, \$9000. License for each additional computer, \$300. Oxford Software Corp, 174 Boulevard, Hasbrouck Heights, NJ 07604. Phone (201) 288-1515.

Circle No 385

CROSS ASSEMBLER. The SX-68 cross assembler lets you develop 68000 software on the Apple II, II+, and IIe. The package consists of an editor and an assembler. Using the editor, you can write both 68000 assembler programs and text files and either save them on disk or use them as input to the assembler. The assembly process takes two passes: The assembler defines all symbols on the first pass, and on the second pass it generates the object code and listing. It reports errors on both passes. The assembler can evaluate expressions consisting of symbols and constants expressed in decimal, hexadecimal, octal, and binary. Expressions may consist of the following operators: +, -, *, and /. The program's limits are 24kbyte max text, 4k-byte max object code, 450 symbols max, and 9999 statements max. You can also access

DOS 3.3 from the software. The program comes on a 51/4-in. disk. \$100. Allen Systems, 2151 Fairfax Rd, Columbus, OH 43221. Phone (614) 488-7122.

Circle No 386

UNIX OS. VENIX/86 Encore, an update of VENIX/86, runs on the IBM PC and PC/XT, the AT&T 6300, the Zenith 150, the Compag Plus and Desk Pro, the TI Professional computer, the Eagle Spirit, 1600, and Turbo, the Columbia MPC, the Sharp PC 5000, the MAD 1 and the Sperry, Leading Edge, NCR, TeleVideo, and Corona personal computers. Its C compiler lets programs of more than 64k bytes run on personal computers. The operating system can copy MS-DOS and UNIX files among the partitions of a hard disk, making it possible to write UNIX files in a DOS format and vice versa. The system has the UNIX debugger adb, kernel libraries for adding new peripherals, support for the Berkeley VI editor, and such options as FOR-TRAN-77 and the Berkeley Pascal interpreter. With System V UNIX license, \$800. VenturCom Inc, 215 First St, Cambridge, MA 02142. Phone (617) 661-1230.

Circle No 387

C EXECUTIVE. C Executive Release 1.5, a real-time monitor that can be stored in ROM, features C support and a built-in C library. The monitor lets multiple C or Pascal tasks (or both) run concurrently, and it features intertask communication, resource coordination, and formatted I/O. The real-time preemptive scheduler is sensitive to both task priority and system events. The package can support multiple-user terminals. It also includes real-time clock support and time-based task initiation. The software comes in both binary and source form. The binary version includes C source code for several

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device drivers, including the IBM PC's asynchronous serial port, keyboard/CRT, and clock. The release supports the 1M-byte physical address space of the 8086/8088/80186 μP family as well as 64k bytes each of code and data. Program, \$500. Documentation and media, \$75. JMI Software Consultants Inc, Box 481, Spring House, PA 19477. Phone (215) 628-0846.

Circle No 388

OPTICAL THIN FILM. Four programs for the analysis and design of optical thin-film multilayers run on the IBM PC, the Apple IIe, or the Apple Macintosh. One program computes and displays the transmittance vs wavelength through as many as 200 layers on one or both sides of a substrate. Another derives the optimum Chebyshev blocking-filter design. A third computes the Herpin equivalent layers of arbitrary index, and the fourth simulates optical monitoring to determine manufacturability. Datatransfer utilities link all four programs. \$4000. Boston Electronics Corp, 72 Kent St, Brookline, MA 02146. Phone (617) 566-3821.

Circle No 389

BASIC INTERPRETER. Developed for the IBM PC/AT, the MEGABASIC language and interpreter addresses 1M byte of RAM and is compatible with MS-DOS, CP/M-86, MP/M-86, and TUR-BODOS. The package allows users to load libraries of programs, subroutines, and functions into memory and execute them at run time using a single statement. The software features variables with as many as 250 characters, trace and edit functions, and BCD arithmetic to eliminate rounding errors. Other features include a semicompiler that speeds execution by as much as 50%; a cross-reference program that provides listings of all variables, strings, arrays, subroutines, and functions; a compaction program that reduces program size by as much as 40%; and a scramble utility that protects the source code. American Planning Corp, 4600 Duke St, Alexandria, VA 22304. Phone (800) 368-2248; in VA, (713) 751-2574.

Circle No 390

CROSS ASSEMBLER, XMAC68K is an assembly-language development package for the MC68000. The software includes an assembler. macro preprocessor, link editor, librarian, symbol report generator, and several utility programs. Accepting standard 68000 assembly language as input, the software produces hexadecimal object-code files for Intel, Motorola, and Mostek formats. Other features include macro capability and structured assembly statements, cross referencing, and plain-English diagnostics. \$595 under CP/M, CP/M-86, PC DOS, and MS DOS. Unix versions are planned. Avocet Systems Inc. 10 Summer St, Rockport, ME 04856. Phone (207) 236-8227.

Circle No 391

BISYNCHRONOUS COMMUNI-CATIONS. Two Bisync Exchange packages provide a personal-computer-to-mainframe link by allowing an IBM PC, PC/XT, or PC-compatible system to emulate an IBM 3274/6 cluster controller and the IBM 3278 and 2780 terminals. The software also permits PC-to-PC communications at 4800 baud over voice grade or leased lines equivalent to one typewritten page per second. An automatic recovery feature ensures that data-transmission errors are detected and corrected immediately. Other features include electronic mail and telephone management. \$795. Intelligent Technologies International Inc, 151 University Ave, Palo Alto, CA 94301. Phone (415) 328-2411.

Circle No 392

GRAPHICS. The SP80/SP82 Siggraph Core, SP84 Contouring, and SP86 Metafile software systems run on the manufacturer's MC-500 family of computer systems and workstations. The software operates under that company's real-time Unix (RTU) operating system and provides users with virtual input, device-dependent 2D/3D graphics capability. The core system is written in FORTRAN, supports 2D/3D graphics primitives, 2D window-toviewport mapping, 3D viewing and clipping, and a variety of perspectives. It also includes temporary and retained segments with fully controllable attributes. The contouring system is a set of specialized subroutines that generates 2D contours and 3D data. It allows generation of contour points from randomly located or evenly spaced data and produces plots from any perspective with hidden-surface removal in realtime applications where 2D contours and 3D plots are used often. Metafile saves graphics sessions created via the Core system in a device-independent Metafile. The Metafile can subsequently be used to position, scale, superimpose, or assemble several graphics sessions. The Core system is priced at \$1200. The Contouring system is priced at \$450; the Metafile, at \$350. Masscomp Corp, One Technology Park, Westford, MA 01886. Phone (617) 692-6200.

Circle No 393

DATA ACQUISITION. Labtech Notebook is a general purpose menu-driven software package that runs on the IBM PC and compatibles and performs data aquisition, monitoring, and real-time control. The software operates with a hardware analog/digital interface, but insulates the user from the low-level instructions that this interface normally requires. Data can be collected at speeds as high as 20 kHz depending on the hardware and streamed to disk at 400 Hz. A pro-

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gramming option allows you to customize the software. You can interface the software with the Lotus 1-2-3 and Symphony spreadsheets. The software also performs realtime graphic data display; open- and closed-loop process control; data manipulation, reduction, and analysis; and curve fitting using as many as 10 parameters to model data. Other features include compatibility with the 8087 coprocessor and an on-line Help facility. \$795. Laboratory Technologies Corp, 328 Broadway, Cambridge, MA 02139. Phone (617) 497-1010.

Circle No 394

LOGIC SIMULATION. HILO-2 is a logic simulation system that runs on the Hewlett Packard 9000 Series 500 computers. The software is also available for the IBM, Apollo, Prime, Digital Equipment Corp, Computervision, CAE Systems,

Metheus Corp, and Valid Logic Systems workstations. HILO-2 aids in the test of cell arrays, custom circuits, and Merchant VLSI devices. Features include hierarchical simulation, race testing, worst-case and hazard-spike analysis, and fault simulation at the functional and gate level. \$50,000. GenRad Inc. 300 Baker Ave, Concord, MA 01742. Phone (617) 890-4900.

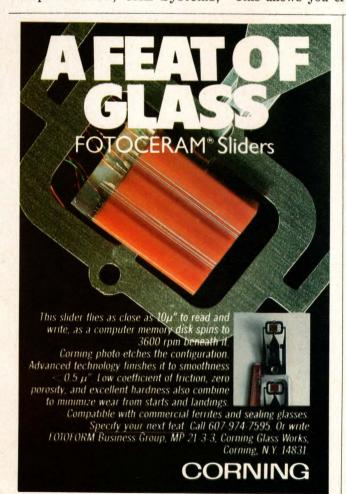
Circle No 395

DATABASE MANAGEMENT. The Integrator is an improvement on Alpha Software's Database Manager II. One of its most significant features is a utility program called Alphakey. This utility allows you to create keyboard macros, store a brief description of each macro, and call up a menu of macros in a window. Another important feature is the ability to summarize a database. This allows you create a single re-

cord for a number of database records that share at least one common field. The summarize feature also allows you to summarize more than one field. For example, if there are nine records for one company. but three of them are located at a second address, you can create two new records: one for the first address and one for the second, \$295. Alpha Software Corp, 30 B St, Burlington, MA 01803. Phone (617) 229-2924.

Circle No 396

DEBUGGER. Pfix 86, a dynamic debugger, and Pfix 86 Plus, an enhanced version with symbolic debugging and overlayed program debugging capabilities, suit use with the Intel 8088/86 family running PC DOS or MS DOS. The software is an addition to the company's Toolkit package, which already includes a linkage editor, Plink86, and text ed-





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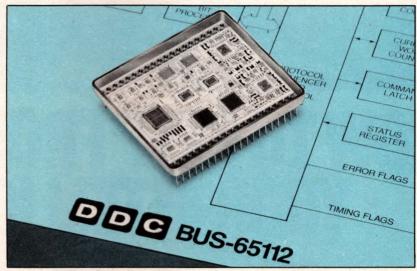
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THE LOWEST COST DUAL REDUNDANT 1553 RTU IN A SINGLE PACKAGE

DDC is pleased to announce the availability of BUS-65112, its new low cost intelligent Remote Terminal Unit (RTU). Based upon DDC custom monolithics, BUS-65112 is packaged in a small 1.9" x 2.1" hybrid and includes 2 transceivers, 2 encoder/decoders, 2 bit processors, RTU protocol, data buffers and timing control logic. It includes complete Remote Terminal protocol and supports all 13 mode codes for dual redundant operation, any combination of which can be illegalized. At \$1436.* the BUS-65112 is the price/performance leader in its class.

Data is transferred to and from the subsystem host CPU over a 16 bit parallel highway, which is isolated by a set of bidirectional buffers. BUS-65112 is compatible with most host CPUs, with its data transfers of request, grant, acknowledge DMA type handshaking. For those subsystems interfacing directly to RAM memory, read/write and data strobe control signals are provided to simplify the interface. BUS-65112 also provides latched outputs for the command word and word count. These signals can be used as address lines to map 1553 messages directly to and from RAM.

Inputs are provided to the host CPU to control 6 of the bits in the RTU Status Word. Particularly useful is the Illegal Command line, which may be used to set the message error bit and illegalize any combination of the 13 mode commands that the BUS-65112 executes. An external PROM, programmed with illegal mode commands, monitors the latched Command Word.



When the PROM identifies a mode command that is illegal, it drives the Illegal Command line LOW. The other Status Word bits that are host CPU controlled are: Subsystem Request, Accept Dynamic Bus Control, Remote Terminal Flag, Subsystem Busy, and Subsystem

Four error flags are provided to the host CPU to aid in assessing its condition. These error flags are Message Error, Remote Terminal Failure, Handshake Failure, and RT Address Error. The RT Failure flag reports the results of the BUS-65112 continuous online selftest. Each transmitted message is wrapped around to the decoder and compared to the correct message.

The BUS-65112 includes a 14 bit Built-In-Test (BIT) word register. The stored BIT Word contains information about the state of the Remote Terminal. When a Mode Command is received to transmit

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BUS-65112 is available screened to the requirements of MIL-STD-883, and it operates over the full -55°C to +125°C temperature

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Librascope's Communications Terminal uses a fully militarized Intel bubble memory subsystem.



itor, Pmate. Symbolic debugging eliminates linker maps by accepting symbol names whenever the user would normally have to type in an address. The software features a multiple-window display for simultaneously viewing program code and data, breakpoint settings, and current machine and register stack contents. It also provides breakpoint capabilities including permanent and temporary settings, an in-line assembler, and singlekeystroke tracing. Pfix86, \$195; Pfix86 Plus, \$395, Phoenix Computer Products Corp, 1416 Providence Highway, Suite 220, Norwood, MA 02062. Phone (617) 762-5030, TLX 710-345-0199.

Circle No 397

DISK FORMAT/COPY. Using Transmute, which runs on CP/M TeleVideo computers, you can copy data between disks that have different formats. As many as 30 formats from Avatar to Zorba are supported, and you can even add new formats. The program presents a menu of available disk formats. You then choose between formatting a disk or allowing the drive to read and write non-TeleVideo-formatted disks. The format software produces a disk that's a mirror image of the one produced on the original computer including special headers where neccessary. Two versions of the software are available. A singledrive version allows you to reconfigure drive B, and the multidrive version allows you to move data between two non-TeleVideo formats. Single-drive version, \$75. Multidrive version, \$100. Elliam Associates, 24000 Bessemer St, Woodland Hills, CA 91367. Phone (818) 348-4278.

Circle No 398

PROLOG SOFTWARE TOOLS.

For developing software in the language PROLOG, the DEC-10/20 PROLOG development package is

now available for Sun and VAX workstations. The software includes an incremental compiler, an interpreter, and a run-time debugging system. The system runs under TOPS10 and TOPS20. While the system's in the debug mode, the screen is split with the debugging environment displayed at the bottom of the screen and the source code displayed at the top of the

screen. Many editor commands are included in the debugger. Also included in the package is a library of public-domain utilities including a natural language geography query program called CHAT. The system is distributed on a 9-track tape. \$10,000 per CPU. Quintus Computer Systems Inc, 2345 Yale St, Palo Alto, CA 94306. Phone (415) 494-3612. Circle No 399



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SOFTWARE

C COMPILER, MWC86 is a C compiler for the DOS 2.0 environment and features a source-level debugger, common-code elimination. peephole optimization, and register variables. The manufacturer claims that this is the fastest C compiler for the DOS 2.0 environment. The software supports the full C language including recent enhancements such as the "void" and "enum" data types and structure assignments. Also supported are large and small models of compilation, the 8087 coprocessor, and DOS 2.0 path names. In the debugger, you can set tracepoints on variables and expressions or step interactively an expression at a time. Full history capability is included. Other debug functions allow you to walk through the stack; debug graphics programs without disturbing the program under test; and access online Help instructions, programs, and history windows. \$495. Mark Williams Co, 1430 W Wrightwood Ave, Chicago, IL, Phone (312) 472-6659.

Circle No 400

C CROSS COMPILER. The Destek C compiler is a multipass optimizing compiler written in C that acts as a cross compiler between the DG 4000 and the MC68000. The software includes a compiler, assembler, linker, loader, and run-time library and is compatible with Unix version 7, Unix system 5, and OS/RT, the company's real-time operating system. You can use the system to produce ROMable code or disk-based programs. The compiler features 32-bit pointers, data initialization, absolute load maps, and global symbol listings. Options include a Unix-like run-time library written in either source or object code. \$9600. The Destek Group, 830 E Evelyn, Sunnyvale, CA 94086. Phone (408) 737-7211.

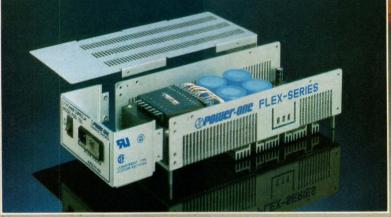
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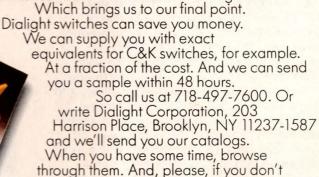
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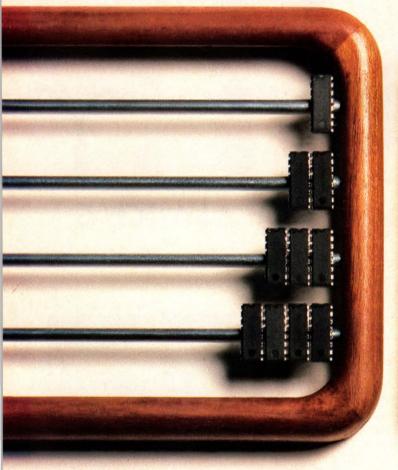


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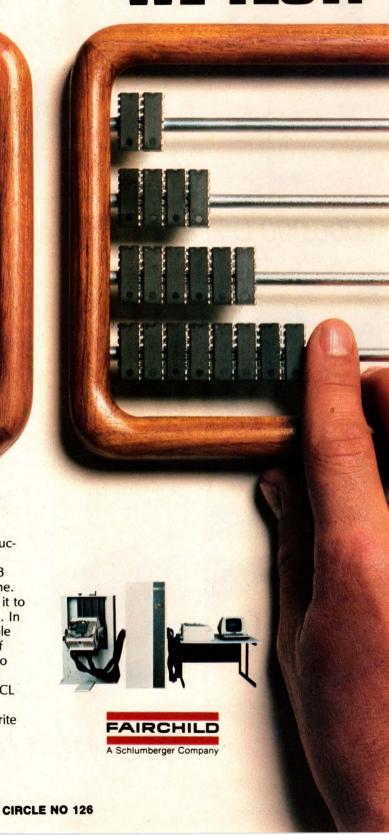


Parallel testing. Nobody's been doing it longer than us. And nobody does it better. Because our advanced 5588 memory test system is capable of testing up to eight devices. In parallel. In full production environments. At speeds of up to 25MHz.

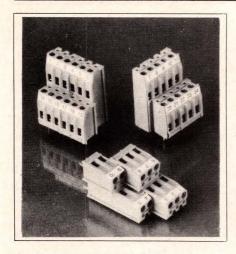
In fact, when it comes to throughput, the 5588 outperforms every tester on the market. Two to one.

The 5588's innovative hardware design allows it to accurately test 64k and 256k devices. And beyond. In bit, nibble or byte-wide configurations. With flexible features like pattern generation for a wide range of memory tests. And selectable "on-the-fly" timing to ensure accuracy in dynamic environments. We've even developed an option for testing high-speed ECL devices.

If you'd like to know more about the 5588, write us at Memory Test Systems, 3850 Royal Avenue, Simi Valley, CA 93063. Or call (805) 583-5290.



NEW PRODUCTS: COMPONENTS & PACKAGING



TERMINAL STRIP. 8190E Series terminal strips feature 2, 3, 8, or 12 poles. They have 5-mm pin spacing and two tiers of connectors that are separated by half of the pin spacing. Molded of Polyamide 6.6, the connectors withstand continuous-service temperatures to 100°C and are rated for 300V ac at 15A. The CSA Certified (10A) and VDE rated (0110 GR C) connectors are awaiting UL approval for both field and factory wiring. All metal parts are either recessed or enclosed in the connectors' insulating body to provide circuit protection and deadfront safety. The wire-clamping connectors handle wire sizes 12 through 22 AWG. Clamping connectors and screws are zinc-plated, chromated steel. The connectors' electroplated-copper, tin-plated solder pins come with or without markings. 3-pole terminal, \$237.88 per 100. Electrovert Inc, 399 Executive Blvd, Elmsford, NY 10523. Phone (914) 592-7322. TLX 646186.

Circle No 460

CONNECTORS. Series III cylindrical threaded connectors, which comply with MIL-C-38999, are self-locking and have an antidecoupling mechanism. 360° rotation of the coupling nut mates the connectors. They have RF and EMI shielding that's effective from 0.1 to 10 GHz. Interfacial silicone gaskets provide an environmental seal. The connec-

tors operate over -65 to +175°C, come in 33 versions in shell sizes 9 to 25, and accommodate 129 Size 22 contacts max. Medium-sized shell pairs, from \$50 (OEM qty). The Deutsch Co, Municipal Airport, Banning, CA 92220. Phone (714) 849-7822.

Circle No 461



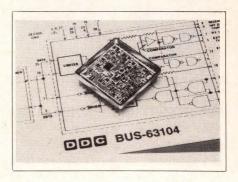
PRESSURE SENSORS. MPX10. MPX11, and MPX12 differential pressure sensors measure 0 to 1.5 psi differential pressures. Their fullscale outputs range from 20 to 50 mV for the MPX10, 30 to 60 mV for the MPX11, and 45 to 70 mV for the MPX12. Typical sensitivities spec at 24, 34, and 38 mV/psi, respectively. The MPX10 features ±1.0% min linearity; the MPX11, -0.5 to +3%; and the MPX12, 0 to 5%. The sensors are available as bare elements for custom packaging or housed in plastic cases. For differential applications (suffix DP), the element has a port for the vacuum side and one for the pressure side. For other applications, the elements come with the port on either the pressure side (suffix GP) or the vacuum side (suffix GV), MPX10, from \$30; MPX11, from \$26; MPX12, from \$22 (25). Motorola Semiconductor Products Inc. Box 20912, Phoenix, AZ 85036. Phone (602) 244-6786.

Circle No 462

solid-state Relays. 110R1D and 110R2D Series solid-state relays can handle 110A rms loads (resistive or inductive) and 2000A 1-cycle surge currents. They measure $2.25 \times 1.75 \times 1.1$ in. and weigh 4 oz.

The units operate on voltages from 48 to 248V ac rms. The 110R1D is a zero-crossing turn-on version that specs a 8.3-msec max turn-on time. It has a 3.5 to 32V dc control-voltage range and a 32V max reverse voltage. The 110R2D, a random phase-controllable turn-on version, specs a 0.02-msec max turn-on time and a 3.5 to 26V control-voltage range. Both relays have an 8.3-msec max turn-off time, a 3.5V dc mustturn-on voltage, and a 1.0V mustturn-off voltage. When turned Off, the switched voltage changes at 200V/µsec. The devices have a 12-mA max leakage current and an on-state voltage drop of 1.5V. \$50. Silicon Power Cube Corp, 2725 Seaboard Lane, Long Beach, CA 90805. Phone (213) 634-9390.

Circle No 463



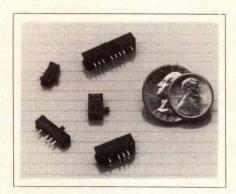
DATA TRANSCEIVER. The BUS-63104 data-bus transceiver meets all MIL-STD-1553A and -1553B specifications. It's a pin-compatible replacement for the CT3231. Its receiver section accepts Manchester phase-modulated bipolar data at the input and produces a biphase TTL signal at the output. The unit's transmitter section accepts TTL biphase data as input and produces a nominal 30V p-p differential signal across a 145Ω load. Measuring $1.25 \times 1.25 \times 0.2$ in. and weighing 0.4 oz, the data transceiver comes in a 24-pin hybrid package. It operates over -55 to +125°C and requires 5V±5% at 30 mA. \$295. ILC Data Device Corp, 105 Wilbur Pl, Bohemia, NY 11716. Phone (516) 567-5600. TWX 510-228-7324.

Circle No 464

COMPONENTS & PACKAGING

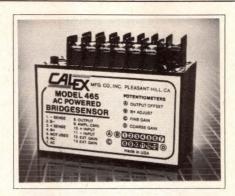
POSITION SENSOR. Series 11000 position sensors use an inductively coupled input shaft that is sealed from the transducer body. The shaft travels from 3 to 25 mm, depending on the model. The transducer produces a TTL-compatible, 50% duty-cycle pulse-train output; the period is 100 μsec at one limit of the shaft's travel and 200 μsec at the other. The transducers draw 5 mA at 5V and operate over -40 to +125°C. \$35 (1000). Technar Inc, 205 N Second Ave, Arcadia, CA 91006. Phone (818) 447-1187.

Circle No 465



SLIDE SWITCHES. MMS and SSJ slide switches have silver-plated double-wipe contacts rated for 100 mA at 30V dc. Their small size (the SSJ-12 measures $0.394 \times 0.157 \times 0.26$ in.) suits them for pc-board applications where space is limited. The switches' plastic cases have a snap detent. The MMS Series consists of 1-, 2-, and 4-pole versions. The 1-pole version has an upright actuator with an On-On function. The 2and 4-pole types come with upright or side actuators and a 2- or 3position On-On function. Two-position types have shorting contacts: nonshorting versions are available upon request. The SSJ Series comes in 1- or 2-pole versions with upright or side actuators. The 1-pole version comes with a 2- or 3-position On-On function. Spdt MMS version, \$0.36 (1000). Augat/Alcoswitch, 1551 Osgood St, North Andover, MA 01845. Phone (617) 685-4371. TWX 710-342-0552.

Circle No 466



BRIDGE SENSOR. Model 465, a self-contained bridge-sensor module, contains a differential amplifier and an adjustable-output bridge-excitation source. The module has a 3-M Ω input impedance, adjustable gain (10 to 1000), and <3-\(\mu\)V/°C drift. It draws 30-nA input-bias current and has 106-dB CMRR and ±10V output swing. Its 3-dB response point occurs at 5 Hz. The module measures $2\times3.75\times2.9$ in. You can adjust the bridge's excitation power supply from 4 to 15V; it delivers 150 mA max. The supply features 0.005% line and load regulation and 0.5-mV rms noise, and it operates from 115V ac. Other input voltages are available. \$245. Calex Mfg Co Inc, 3355 Vincent Rd, Pleasant Hill, CA 94523. Phone (415) 932-3911. TLX 338506.

Circle No 467



TRIMMERS. The 1208 is a rectilinear RJ12-style trimmer (1¹/₄ in. long) whose different versions spec 20, 50, or 100Ω resistance values at 20% tolerance or range from 200Ω to $10 \text{ k}\Omega$ at 10% tolerance. The 1268 (3% in.2) comes in versions that have resistance values ranging from 20 to 100Ω at 20% tolerance and 200Ω to

10 kΩ with 10% tolerance. The 1248's versions measure ¼ in.² and have resistance values from 20Ω to 5 kΩ at 10% tolerance. All three trimmers feature a ± 20 -ppm/°C temperature coefficient and 0.1% typ and 0.5% max change in settling stability. They can be set within 0.1%. Model 1268 5- to 10-kΩ versions, \$3.41. Model 1248 5- to 10-kΩ versions, \$4.75. Model 1208L 20Ω version, \$3.62 (1000). Vishay Resistive Systems Group, 63 Lincoln Hwy, Malvern, PA 19355. Phone (215) 644-1300.

Circle No 468



A/D CONVERTERS. Models DAS1157, DAS1158, and DAS1159 sampling D/A converters feature 14-, 15-, and 16-bit resolution, respectively, and consume 650 mW max. The DAS1157 and DAS1158 serve as second-source replacements for the A/D/A/M-834 and A/ D/A/M-835. Rated for operation from -25 to +85°C, the DAS Series combines an A/D converter, an S/H amplifier, a 10V reference, and 3state output buffers in 2×4×0.375-in. package. Maximum key specs for the DAS1157 include ±0.003% differential nonlinearity (DNL), $\pm 0.005\%$ integral nonlinearity, ±2-ppm/°C DNL temperature coefficient, and ±8-ppm/°C gain temperature coefficient. Maximum key specs for the DAS1158 and DAS1159 include $\pm 0.0015\%$ DNL, $\pm 0.003\%$ integral nonlinearity, ± 1 ppm/°C DNL temperature coefficient, and ±8-ppm/°C gain temperature coefficient. Dynamic specs for the series include 55-usec max conversion time, 18-kHz min throughput, 250-nsec aperture delay, and



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Typ. Power (W)	3.5	2.8	2.5	2.0	1.2	.6	
I/Os	120	120	84	76	56	36	
Gate Utilization	95%	95%	95%	85%	85%	85%	

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1-nsec aperture jitter. The converters operate from ±15 and 5V power supplies. They have pin-selectable input ranges of 5, 10, ±5, or ±10V. Output coding is binary, offset binary, or 2's complement. Hi-Enable and Lo-Enable pins select connections to 8- or 16-bit buses. DAS1157, \$219 (100); DAS1158, \$263; DAS1159, \$289. Analog Devices Inc, Three Technology Way, Nor-

wood, MA 02062. Phone (617) 329-4700.

Circle No 469

DIN CONNECTORS. These female DIN connectors mate with straight or right-angle DIN 41612 form E male sockets that are soldered to pc boards. Available with 32 or 48 gold-plated contact points and axial

screw clamps, the connectors handle 14- to 24-AWG solid or stranded wire with one or two wires per pole. They're rated for 250V at 5A and are keyed to avoid mismatched multiple combinations. The 32-pin connector, \$39.90 (500). Entrelec, Two Ram Ridge Rd, Spring Valley, NY 10977. Phone (800) 431-2308; in NY, (914) 425-7460. TLX 996619.

Circle No 559

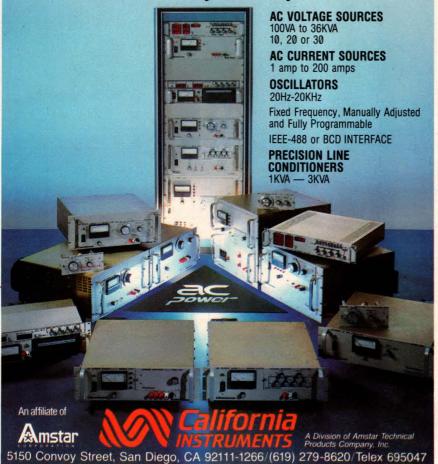
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ILLUMINATED SWITCHES. SMP Series switches (0.591 in.² and

0.512 in. high) let you use hotstamped legends or film messages, which are illuminated by the switches' LEDs. Featuring a 10⁶-cycle lifetime and operation over -10 to +65°C, the switches come with red, green, or yellow LEDs. Switch, \$1.89. Matching indicator, \$1.45 (500). Shelly Associates Inc, 2942 Dow Ave, Tustin, CA 92680. Phone (714) 544-9970.

Circle No 560

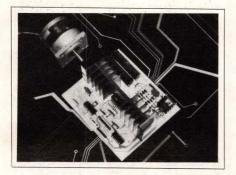


FLAME-RESISTANT CAPACITORS. Series B33074 polypropylene capacitors have an enclosure that complies with the requirements of UL-1414. The capacitors have axial leads and come in cylindrical shapes from 6.4×13 mm to 9.7×19 mm. They have capacitance values

COMPONENTS & PACKAGING

from 100 pF to 0.1 μ F and possess temperature coefficients from -150 to -300 ppm/°C. Specs include -40 to +85°C operation and a 100V dc voltage rating. Typical pricing is \$0.20 (1000). Delivery, 10 to 12 wks. Siemens Components Inc, 186 Wood Ave S, Iselin, NJ 08830. Phone (201) 321-4842.

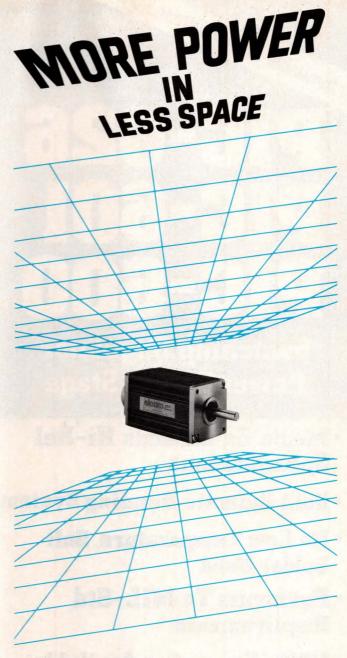
Circle No 561



DRIVER CARDS. Models LR-BP-20-35 and PW-BP-50-45 steppermotor driver cards have half- and full-step capability and are TTL compatible. They have direction, clock, inhibit, and reset inputs. LR-BP-20-35, a bipolar-driver card, uses a 35V input and has a 2A per phase output. It can accommodate series resistors to increase torque at higher step rates. PW-BP-50-45, a pulse-width-modulation driver card, uses a 45V supply, has a 5A per phase output, and doesn't require series resistors. LR-BP-20-35, \$100; PW-BP-50-45, \$350 (OEM qty). Delivery, 60 to 90 days ARO. Clifton Precision, Box 160, Murphy, NC 28906. Phone (704) 837-5115.

Circle No 562

HV RELAY. Pressurized with an electronegative gas that quenches arcs in hot-switching applications, Model K61C spdt relay switches 35 kV dc at 10A continuous current. It measures 3.75×2.5 in., is potted, and comes with high-voltage leads. The device operates on 26.5V dc and



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has a 120Ω coil. Its operation, including bounce, takes 15 msec. Withstanding temperatures from -55 to +85°C, the relay can endure 20G shock and 10G vibration at 55 to 500 Hz. \$235 (10). Kilovac Corp, Box 4422, Santa Barbara, CA 93103. Phone (805) 684-4560. TWX 910-336-1141.

Circle No 563



OPTICAL TRANSCEIVERS. TR1001S Series fiber-optic transceivers transmit data at rates to 100M bps NRZ. The TR1001SA version has an 8-dB system margin; the TR1001SB version has a 17-dB margin. TR1001SA. \$275: TR1001SB. \$550. American Photonics Inc. Box 289, Brookfield Center, CT 06805, Phone (203) 775-8950.

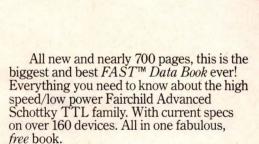
Circle No 564

ELECTROLYTIC CAPACITORS.

Series 3195 aluminum electrolytic capacitors come in values from 2800 μF to 1.2F and are rated for operation for 1000 hrs at 85°C at full-rated dc voltage. The capacitors range from 5 to 100V dc and come in 39 standard case sizes from 1% to 3 in. in diameter. They operate over -40to +85°C and come in pc-board mounting or standard screw-terminal configurations. Typical pricing for a $16,000-\mu F$, 50V unit with -10, +75% tolerance is \$3.75 (1000). Mepco/Electra Inc. Columbia Rd. Morristown, NJ 07960. Phone (201) 539-2000, TWX 710-986-7437.

Circle No 565

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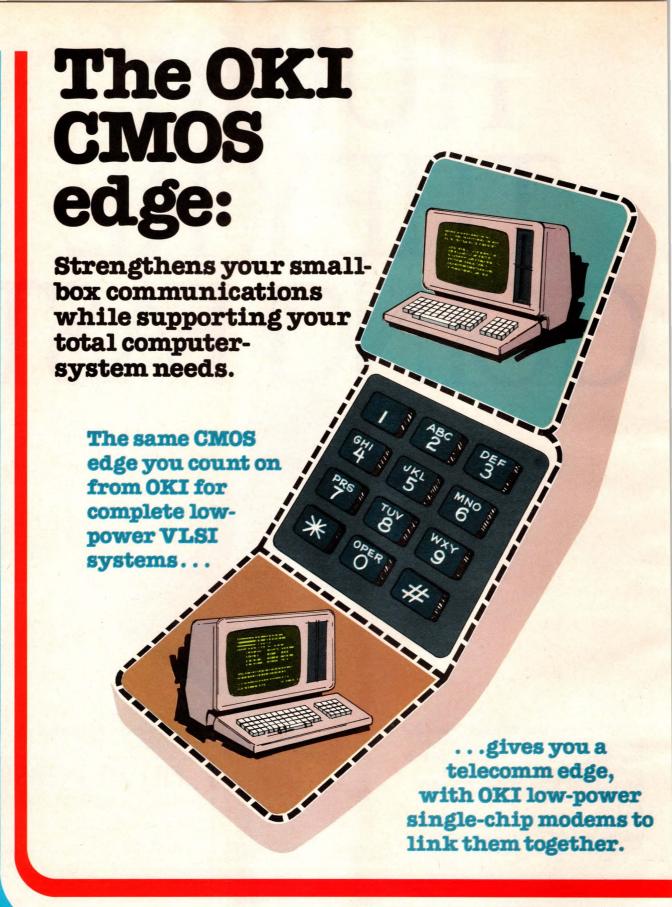
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	CCITT V.23, HDX	MSM6927	Now	
300/1200 Baud	Bell 212A, FDX	Hybrids	4Q84	
Auto-Switch		Chip Sets	1985	
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PC/AT EXPANSION. An internalexpansion kit for the IBM PC/AT consists of a hard disk and a 1/4-in. tape drive. The hard disk uses IBM's controller for AT software compatibility and is available in capacities of 40M, 65M, 140M, and 280M bytes. The integral tape unit backs up 65M bytes in 12 min. According to the manufacturer, this subsystem operates 30% faster than does IBM's 20M-byte hard disk, provides incremental database file growth beyond 32M bytes, and allows user-configurable disk caching of as much as 4M bytes. The system supports DOS 2.0, 2.1, 3.0, QNX, Concurrent DOS, UCSD-P System, PC/IX, and other PC-compatible networks. All necessary cables, a back-up and restore utility, and menu-driven hard-disk installation software are included. From \$1950. Emerald Systems Corp, 4901 Morena Blvd, San Diego, CA 92117. Phone (619) 270-1994.

Circle No 521

MEMORY EXPANSION. The 1Mbyte iSBC 010CX and the 2M-byte iSBC 020CX expand the system memory for products based on the iSBC 286/10 CPU board. In addition, prices on other boards in the series-the 256k-byte iSBC 056CX and the 512k-byte iSBC 012CXhave been reduced 14 and 37%. Compatible with Multibus and their manufacturer's iLBX (local bus exchange) product family, the 010CX and 020CX models include 256k-bit dynamic RAMs and on-board ECC; they feature 1-wait-state performance. 056CX, \$1750; 012CX,

\$2250; 010CX, \$4750; 020CX, \$8250. Intel Corp, 5200 NE Elam Young Parkway, Hillsboro, OR 97113. Phone (503) 640-7147.

Circle No 522



DUAL-SPEED DRIVE. The YD-380-1714 is a dual-speed, half-height 5.25-in. floppy-disk drive. The dualspeed feature allows you to use either the standard 1M-byte doubledensity, double-track format or the IBM PC/AT high-capacity 1.6Mbyte disk format. Because the IBM high-capacity format is compatible with the standard 8-in. media format, using the 5.25-in. YD-380-1714 to replace an 8-in. drive does not require that the data be put on several 5.25-in. disks. You can interchangeably use data and programs written on either standard or highcapacity media. The drive can read and write data at a track density of 96 tpi. The unit measures 1.63×5.75×8 in. and includes a disk pop-up mechanism, a disk lever clamp, an in-use indicator, and daisy chaining for as many as four drives. It also features steel-belt head positioning and a brushless direct-drive motor. \$200 (OEM qty). C Itoh Electronics Inc, Box 66903, Los Angeles, CA 90066. Phone (213) 306-6700. TLX 652451.

Circle No 523

PDP-11 UPGRADE. You can increase the effective memory size and CPU speed of your PDP-11 system with the Microverter. This quad-width card plugs into the Q Bus backplane and addresses up to 4M-bytes of Q Bus memory while driving 19 Unibus loads. The Micro-

verter, a modified Unibus backplane, and a voltage regulator compose a Microverter Plus. The Plus version, coupled with the 11/73 or 11/73+, transforms a PDP-11 system into a higher-speed Unibus system. Both products are compatible with current versions of RSTS/E and RSX-11. Microverter, \$2300. Microverter Plus, \$3575. Able Computer, 1732 Reynolds Ave, Irvine, CA 92714. Phone (714) 979-7030.

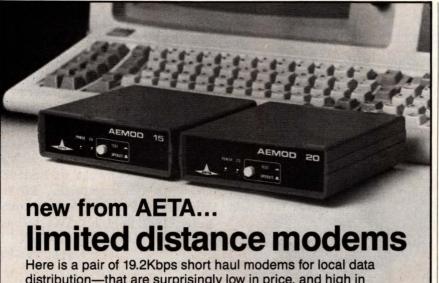
Circle No 524



IBM PC ADD-IN. Add Mr. Chips to your PC and monitor or control a variety of external devices. Its Real World Interface, a fully addressable 12-bit port, comprises an 8-bit bidirectional TTL bus as well as four bits of programmable output that communicates with thermostats, moisture detectors, photocells, and other devices. Another port monitors four resistive inputs and four digital inputs. In addition, an ac line controller sends ultrasonic signals to a BSR X-10 unit that controls up to 16 ac devices. Other features include a clock, calendar, serial and parallel printer ports, and a 1-year warranty. \$449. Orange Micro Inc, 1400 N Lakeview Ave, Anaheim, CA 92807. Phone (714) 779-2772.

Circle No 525

Z80 SYSTEM CLOCK. The ZTIME I installs in any Z80-based computer to provide a calendar and clock with battery backup. The hardware installs in the CPU socket and moves the Z80 onto the ZTIME I board. Resident software accesses the clock in both binary and ASCII formats and allows the console to set and display the time and date. The



distribution—that are surprisingly low in price, and high in performance. The AEMOD 15 gives you async operation, while the AEMOD 20 offers sync/async operation. Both types give you:

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CIRCLE NO 135

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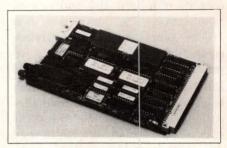
(An affiliate of the Sprague Electric Company) 134 Fulton Avenue Garden City Park, NY 11040 516-746-1385 TLX: 14-4533

CIRCLE NO 136

COMPUTER-SYSTEM SUBASSEMBLIES

software comes in BDS C. Turbo Pascal, KRT Pascal, and Microsoft BASIC. It works on any Z80-based computer whose clock speed is less than 5.5 MHz. Bare board, \$29: complete kit, \$69; fully assembled and tested, \$99. Kenmore Computer Technologies, Box 635, Kenmore, NY 14217. Phone (716) 877-0617.

Circle 526



MICROCOMPUTER BOARD. The GESMPU-4A is a 68000-based 16-bit system on a standard singleheight Euroboard (100×160 mm). The system offers two disk operating systems—CP/M 68K and OS-9 and clocks at 8 MHz. Fully G-64 Bus compatible, the board has four JEDEC-standard sockets that accommodate as much as 128k bytes of EPROM and 16k bytes of RAM. Finally, you also get a triple 16-bit timer and an RS-232C serial interface with a fully programmable baud rate. \$475. GESPAC Inc. 550 E Grandview, Mesa, AZ 85203. Phone (602) 962-5559. TLX 386575.

Circle No 527

SINGLE-BOARD COMPUTER.

The OB68K/MSBC1 uses the 68000 μP operating at 12.5 MHz on the IEEE-796 Multibus. The board carries 256k bytes of dual-ported, zerowait-state RAM with parity. When 256k-byte RAM is available, you can upgrade the memory to 2M bytes. Also included are four JEDEC-standard sockets for monitor, boot, or program PROMs, and you can configure the board for up to 128kbytes of ROM. Four serial ports run at rates to 1000k baud, with addi-

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For complete specifications on the 485, along with a Low Current Application Note, contact Keithley Telemarketing Dept. at 216/248-0400 or write: Keithley Instruments, 28775 Aurora Rd., Cleveland, OH 44139.

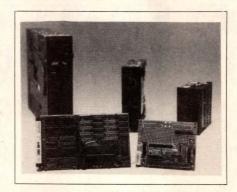
KEITHLEY



COMPUTER-SYSTEM SUBASSEMBLIES

tional I/O ports through the IEEE P959 (iSBX) expansion connector. Daughter boards for memory management and different microprocessors are options for this IEEE 796-compatible board. 256k-byte version, \$2495; 512k-byte version, \$2995. Omnibyte Corp, 245 W Roosevelt Rd, West Chicago, IL 60185. Phone (312) 231-6880.

Circle No 528



Low Cost Microprocessor Development System

Huntsville Microsystems offers a line of high performance in-circuit emulators and linking software packages which will turn any computer into a full microprocessor development system. The emulators feature real-time transparent emulation, mappable memory, hardware breakpoints, RS232 interface, in-line assembler/disassembler, upload/download hex files and complete debugging facilities. The units

can operate stand-alone with a CRT or when combined with the power of your computer, form a full microprocessor development system.

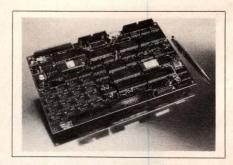
Software packages are available to allow operation with any IBM™PC, CP/M™ or ISIS™ system including the Intel™iPDS™ Cross-assemblers are available for the IBM PC and CP/M systems. Prices start at under \$2000. For complete specifications write to Huntsville Microsystems, Inc., 8200 S. Memorial Parkway, P.O. Box 12415, Huntsville, AL 35802 or call (205) 881-6005.



SINGLE-BOARD COMPUTER.

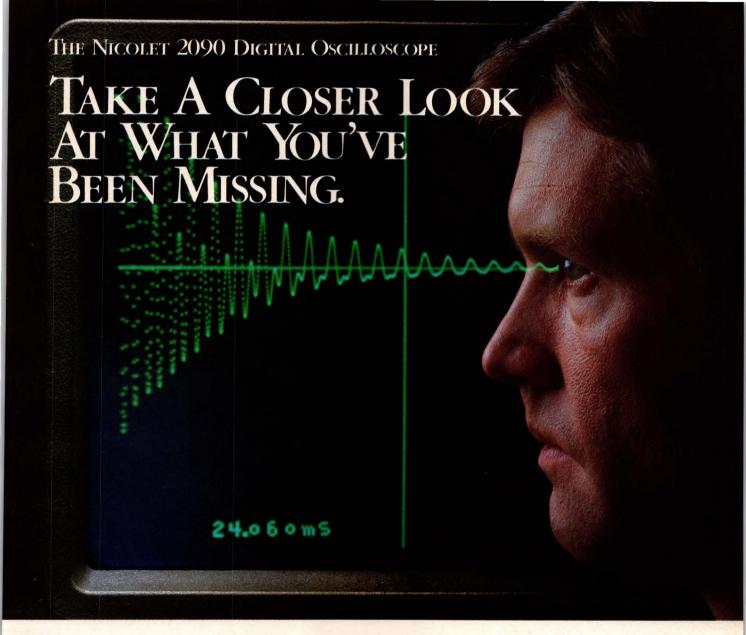
The 64K SBC includes a variety of features on 4×6-in. board: a videodisplay controller, a floppy-diskdrive controller, a 6-MHZ Z80B CPU, 64k bytes of RAM, and serial and parallel I/O. The video-display controller can connect directly to a composite or TTL monitor to display bit-mapped graphics or an 80column×35-line alphanumeric display. Also, the floppy-disk-drive conroller can run up to four drives. Among its I/O capabilities, the board contains 22 general-purpose parallel I/O lines, a Centronics-compatible parallel printer port, two RS-232C serial ports, and a peripheral expansion interface that accesses the CPU's data, address, and control lines. CP/M 2.2 with utilities, terminal and disk handlers, and an installation utility accompany the hardware on 8 or 51/4-in. diskettes. The 64k SBC, transition board, connector, CP/M 2.2 license, installation software, and source code, \$375. Megatel Computer Technologies, 1051 Clinton St., Buffalo, NY 14206. Phone (416) 745-7214.

Circle No 529



SINGLE-BOARD COMPUTER.

The MSC-ICO packs many features onto a board measuring less than 10×6 in.: a Z80 CPU, a 128k-byte RAM, an 80-character×24-line video controller, a floppy-disk controller, two RS-232C ports, a Centronics-compatible port, a 16-bit I/O port, a keyboard port, a clock/calendar, and CP/M Plus 3.0. The floppy-disk controller handles as



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Picture this. The smallest detail in 12-bit resolution, expansion to X64, with voltage and time coordinates alphanumerically displayed. Plus the ability to record 4K data points at speeds up to 50MHz, with the 205A plug-in. It's what you'd expect from the digital oscilloscope that's still setting the standards—Nicolet's 2090.

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The 2090 offers push button transient capture, at speeds selectable from 20 nanoseconds to 200 seconds per point, so you can record fast or slowly changing signals with ease. And *pre- and post-trigger capture* lets you see what led up to an event as well as what followed. Built-in floppy disk allows unattended operation just set and forget.

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Optional RS232 and IEEE-488 bidirectional interfaces give you the ability to coordinate and manipulate data by remote computer. That means



RS232 IEEE-488

the 2090 scope can be the front end of an entire analysis system. Not only that, the 2090's modular design allows you a choice of *four different plug*-

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Let us show you how easy the 2090 is to use. It's time *you* started benefiting from the tremendous digital advantage. Call us: (608) 273-5008. Or write: Nicolet Oscilloscope Division, 5225 Verona Road, Madison, WI 53711.

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When we say our Power Managers don't resort to performance-compromising tricks, we mean that there are no auto ranging transformer taps that create forbidden zones right where you need the power supply to work. There are no switching pre-regulators to slow things down and create noises in a sensitive test system, no SCRs to limit dissipation (and your speed). You can control the voltage (to 0.001%) and the current (to 0.005%) from zero through their full range, and get maximum rated voltage and current at the same time. The Kepco Power Managers are fast. The BOP's output time constant, in response to programming step inputs, is 80 usec or better over their full current and voltage ranges. The ATE's program time constant is as fast as 3.0 µsec. They have this remarkable capability because in creating their design Kepco accepts the responsibility for dissipating

KEPCO.

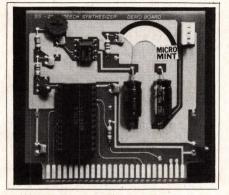
internally the heat that full range high speed operation demands. We use enough power transistors to deal with it safely. We cool them off with a patented, high efficiency finned heat sink using an integral fan. It gets rid of that heat with a temperature rise of less than 0.1° per Watt. So they run cool for high reliability.

Surprisingly, for systems that do so much so well, prices of the Kepco Power Managers start under \$800, for the quarter-rack-size ATE. We have a lot more to tell you, and most of it's in a new brochure we've prepared called "The Kepco Power Managers," which we'd be delighted to send you. Just write to Dept. GZF-12., KEPCO, INC., 131-38 Sanford Avenue, Flushing, NY 11352 USA • (718) 461-7000 TWX #710 582 2631 • FAX (718) 767-1102.



many as four drives. The computer also includes an expansion port for options such as more RAM, a harddisk controller, or a 68000 coprocessor. \$599. Artisoft Inc. Box 41436. Tucson, AZ 85719, Phone (602) 327-4305.

Circle No 530



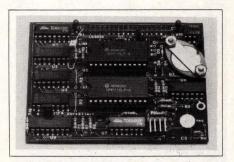
SPEECH SYTHESIZER. The Sweet Talker speaks for itself. Using the SSI 263 speech-synthesizing IC, the Sweet Talker produces music, sound effects, and speech at data rates between 50 and 70 bits/ sec. It includes 256 phoneme equivalents, 4096 pitch variations, and an on-board 1W amplifier with volume control. Built on a 3×31/4-in, board, the Sweet Talker has control inputs for connection to a computer bus or a parallel port. Also, it has 16 speed settings and 255 variations of frequency response for the vocal-tract filter. \$104. Micromint Inc, 561 Willow Ave, Cedarhurst, NY 11516. Phone (516) 374-6793.

Circle No 531

I/O EXPANSION SUBSYSTEM.

To expand the I/O capacity of your MPA-2000 CPU, plug in the MSX-2000 modular I/O expansion system. The MSX-2000 supports eight I/Osystem applications that use the MSX plug-in I/O adapter modules. In a daisy-chain configuration, up to 64 plug-in sites connect to one Multibus slot in the MPA-2000, which is an iAPX-186-based CPU and intelligent I/O controller for the Multibus. \$1375. Metacomp Inc., 9466 Black Mountain Rd, San Diego, CA 92126. Phone (619) 578-9840.

Circle No 532



BATTERY-BACKUP MEMORY.

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CIRCLE NO 142

COMPUTER-SYSTEM SUBASSEMBLIES

The vendor positions the LS3032 as an alternative to the iSBC 094 board for systems based on the iSBC 86/12, the iSBC 86/30, or the iSBC 86/40 single-board computers. \$290 (OEM qty). Computer Modules Inc, 1190 Miraloma Way, Suite Y, Sunnyvale, CA 94086. Phone (408) 737-7727.

Circle No 533



IBM PC EXPANSION CHASSIS.

The B106 6-slot expansion chassis and card cage expands the number of cards you can add to the bus of an IBM PC, PC/XT, 5531, or compatible computers. You need two Action bus expansion cards and an Action ribbon cable pair, which you can purchase as the B120 IBM PC Bus interface kit. Attach one card to the computer, the other to the expansion chassis, and use the remaining five chassis slots as a parallel extension of the computer's bus. The B106 and the B120 have a 3-year warranty. Action Instruments, 8601 Aero Dr. San Diego, CA 92123. Phone (619) 279-5726.

Circle No 534

IMAGING BOARD FOR PC. Turn your IBM PC or PC/XT into an imaging system with the DT2803 video-frame grabber and display board. The DT2803 captures a 256×256×8-pixel black-and-white video image 30 times a second from RS-170 (60 Hz) or CCIRR (50 Hz) input signals. It digitizes the input

into 6-bit pixels representing one of 64 possible gray levels. Through the use of look-up tables, the DT2803 can alter the output color and intensity of the stored and displayed images. When used with the Videolab software package, the PC can perform frame operations such as baseline correction, merge, difference, and histogram as well as real-time image acquisition and display. Videolab comprises Videotutor, an interactive tutorial on DT2803 use. and Videosub, a comprehensive library of subroutines for user-defined applications. DT2803, \$1495; Videolab, \$995. Data Translation, 100 Locke Dr. Marlboro, MA 01752. Phone (617) 481-3700. TLX 951646. Circle No 535

PC/AT EXPANSION. The Advantage multifunction expansion board adds memory and ports to the IBM PC/AT. The user-upgradable memory holds either 64k-byte or 256k-byte RAM ICs to allow you to add as much as 3M bytes of memory. In addition, Advantage offers an IBM-compatible parallel printer port, two serial ports, and a game port. The basic 128k-byte version costs \$495. AST Research Inc, 2121 Alton Ave, Irvine, CA 92714. Phone (714) 863-1333.

Circle No 536

STATIC-RAM BOARDS, The RAM 23 static-RAM board adds as much as 128k bytes of memory to systems based on the 8086, 8088, and 80286 CPUs. Operating at rates to 12 MHz, it consumes less than 4W typ at a nominal 8V bus voltage. It meets all IEEE 696/S-100 bus specs and transfers both 8-bit bytes and 16-bit words. Two configurations are available: One operates as a 64k×8-bit or a 32k×16-bit memory (\$400), and the other as a $128k\times8$ bit or 64k×16-bit memory (\$775). Compupro, 3506 Breakwater Ct. Hayward, CA 94545. Phone (415) 786-0909.

Circle No 537

COMPUTER-SYSTEM SUBASSEMBLIES



VIDEO-CIRCUIT TEST BOARD.

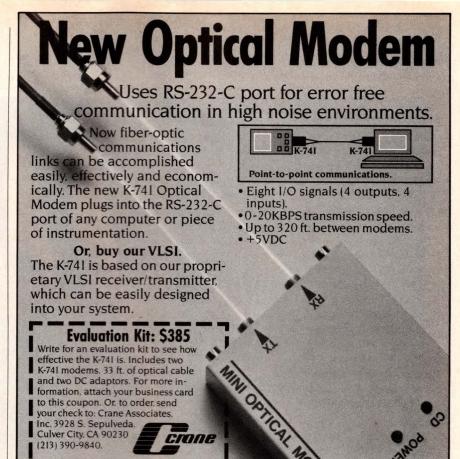
To test television, VTR/VCR, and teletext ICs and modules, you can add the VG600 video generator to the LTX Integrated Test System through the CX80 Consumer Extension. The VG600 stores multiple sets of test patterns, in NTSC or SECAM formats, coded into a 32kword memory-16k words of control memory and 16k words of event memory. Pattern-looping capabilities expand the size and complexity of the test patterns. The VG600 has a single-pass sample rate of 250 kHz and a multiple-pass sample rate of greater than 7 MHz. An integral, mutliple-measurement scheme collects up to 256 data samples in a single pass of the video line. \$45,000. LTX Corp, LTX Park at University Ave, Westwood, MA 02090. Phone (617) 329-7550.

Circle No 576

VIDEO CROSS-HAIR BOARD.

The AMS CHG-4 cross-hair generator superimposes as many as four adjustable indicator lines on a video image and produces a digitized video signal. Providing separate dual-axis sync outputs, the board produces a 1-bit digitized output for pattern recognition or image processing. Also, it automatically adjusts the shades of generated lines to meet contrast requirements of background images, enhances the area of interest, and allows remote position/threshold adjustment. An STD bus powers the board. \$240. Advanced Micro Systems Inc, 9 Executive Dr., Hudson, NH 03051. Phone (603) 882-1447.

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CIRCLE NO 144



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Circle No 538

GRAPHICS. The UI-100 Series raster-imaging microcomputers operate by accepting graphical object information via an RS-232C port from a language driver in the host-computer software, and then converting the description into a bit map. Each microcomputer features a Motorola 68000 CPU and the capability to perform image manipulations such as zoom, rotation, overlay, and half-toning. Three memory-configuration options pro-

vide varying levels of graphics complexity. Option 1 lets you use a variety of business-software graphics packages to access as many as 55,000 polygon and vector vertices in your UI-100 µC. Option 2 is a 110,000-vertex package that is suitable for use with mainframe graphics software such as IBM's GDDM. SAS/GRAPH, and Precision Visual's DI-3000. With Option 3's 220,000 polygon and vector vertices you can handle images produced with CAD and mapping software. UI-100, from \$3500; Option 1, \$1995; Option 2, \$4450; Option 3, \$6350. Lasergraphics, 17671 Cowan Ave, Irvine, CA 92714. Phone (714) 660-9497. TLX 753527.

Circle No 539



DATA TERMINAL. The Trans-Term 5 compact, keyboard/display teminal unit suits general-purpose data entry. The unit features a 24-key membrane keyboard-including eight programmable function keys and a 48-character LCD with a 2-line, 5×7 dot-matrix font that supports a 96-character upperand lower-case ASCII set. You can choose from eight baud rates, specify the number of bits per character, determine function-key codes, and select other parameters via keyboard commands that are saved in nonvolatile memory. Three operating modes allow for full- or halfduplex teletypewriter-compatible operation or for polled multidropping with as many as 128 units per 4-wire circuit. The standard communications interface is full-duplex RS-232C serial asynchronous ASCII, but optional RS-422 and 20-mA current loop interfaces are available. The unit can support an optional bar-code wand. The terminal measures $6.9 \times 5.6 \times 1.75$ in. and consumes 6W using either a 115V ac plug-in transformer or a 12V dc external source. \$249. Computerwise Inc, 4006 E 137th Terrace, Grandview, MO 64030. Phone (816) 765-3330.

Circle No 540



AUDIO COMMUNICATION. The Model T347B fiber-optic voice-communications set suits applications for which conventional audio circuits are not available. Communication is provided via a single-mode or multimode fiber. Typical ranges are 25 dB at 40 km for single-mode fiber and 40 dB at 10 km for multimode fiber. The set features a voice-activated headset, rechargeable battery, and call-alert button. \$6800. Delivery, 8 wks ARO. Plantronics Wilcom Inc, Box 508, Laconia, NH 03247. Phone (603) 524-2622. TWX 510-298-1120.

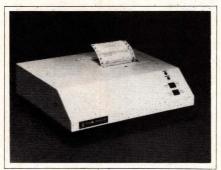
Circle No 541

VOICE MESSAGE SYSTEM.

Model IV is a small-capacity voice message-exchange system. The 4-port system provides voice storage and forwarding for 100 to 500 users and can be upgraded to serve as many as 1000 users with the addition of extra ports and memory. The system is small enough for you to incorporate it into an equipment rack as an integral component. Op-

tional features include call answering and a message function. Model IV can also be linked to other voice message exchanges through the manufacturer's proprietary network, Voicenet. \$50,000. VMX Inc, 1241 Columbia Dr, Richardson, TX 75081. Phone (214) 699-1461.

Circle No 542



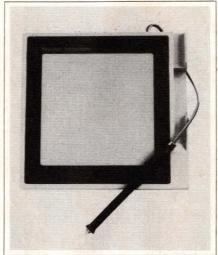
LABEL PRINTER. A 40-column dot-matrix label printer, the S400L flexible-format device incorporates an optical sensor, which ensures accurate data placement, regardless of label size or shape, by seeking the position of the top of the label and automatically advancing the label stock to its first data print position. The S400L operates at 72 lpm and provides the full 96-character ASCII set, printing upper- and lower-case characters in standard or elongated modes. You can choose from an RS-232C, Centronics parallel, or 20-mA current-loop interface to the host. \$800 (OEM qty). Printer Products, 25 Denby Rd, Boston, MA 02134. Phone (617) 254-1200. TLX 951589.

Circle No 543

DUAL-68000 μP. A Unix-based, 32-bit-processor system, Model 1124 suits on-line information processing. According to the manufacturer, this system runs 30% faster than the VAX-11/780 at one-third the cost because of the system's multithread architecture, which tightly couples the dual processors. Features include mirrored disk drives, power margining, a 33.3M-byte data-

transfer bus, and redundant cooling. In addition to supporting the Unix System V operating system, the 1124 also supports RM/COS, a COBOL-compatible operating system that offers high-speed file access. The unit measures 14×28×54 in, and has 10 card slots; three for CPU and memory cards, six for I/O expansion, and one for a memory controller that manages the data flow among system cards. Memory is available in 2M-byte increments. From \$60,000. Delivery, 60 days ARO. Areté Systems Corp, 2040 Hartog Dr, San Jose, CA 95131. Phone (408) 263-9711.

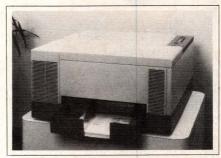
Circle No 544



DIGITIZER/MOUSE. The PC Pad dual-function graphics data-entry device operates either as a digitizer (to translate drawings into computer-readable data) or as a mouse (for cursor-control applications). The 8×7-in., wedge-shaped unit has a 5×5-in. active area that lets you address over 1 million points (10242) with a resolution of 200 points/in. Host interface is accomplished via an RS-232C-compatible connector. You can select the digitization rate according to baud rate and data format to a maximum of 19.2k band for a serial, binary format. Point, triggered, stream, switch-stream, and delta operating modes are offered. A 15V dc input is standard,

but an optional ac transformer is available. \$395. Delivery, 60 days ARO. **Houston Instrument**, Box 15720, Austin, TX 78761. Phone (512) 835-0900. TWX 910-874-2022.

Circle No 545

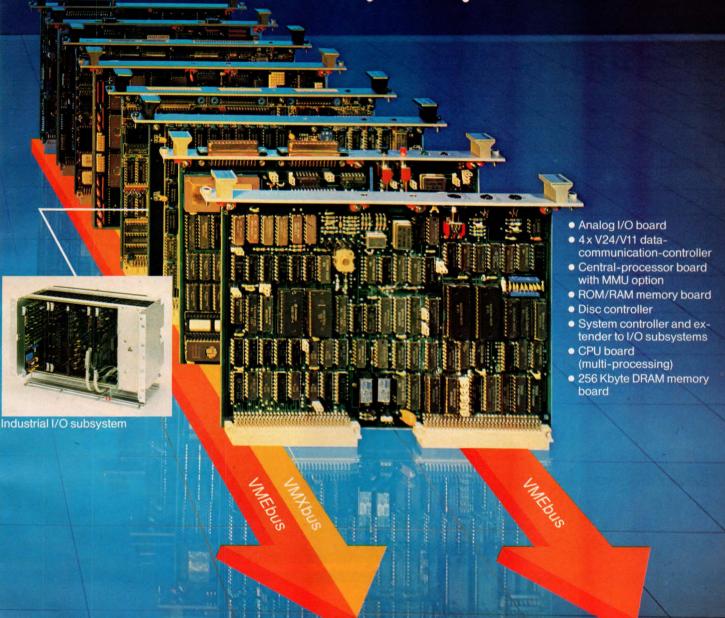


INK-JET PRINTER. The Dijit 1 ink-jet office printer offers fullpage, all-points-addressable printing that combines graphics and text at speeds to 18 pages/min. It includes 128k bytes of internal buffered RAM storage, a resident font set, automatic dual-sided printing, a Centronix interface, Xerox 2700 emulation, 500-sheet bin capacity, and self-test and operator diagnostics. In letter-quality print mode, the Dijit provides a resolution of 300×300 dots/in.; the draft-quality mode allows high-speed operation. You can combine type sizes ranging from 4 to 36 points within any document. Graphics and text can be combined or overlaid on the same page, and formats are controlled by the host terminal. The Dijit 1 uses binary-deflection, multiple-array ink-jet technology with continuous-flow imaging and accommodates plain bond, cut sheet paper, or transparencies. From \$5000 (OEM qty). Diconix Inc, Box 3230, Dayton, OH 45431. Phone (513) 898-3644.

Circle No 546

SHORT-HAUL LAN. This device connects RS-232C and RS-422A devices to multiple host computers located as far as 7000 ft away using RG62A/U cable (or 3000 ft via telephone station wire) at a 19.2k-baud asynchronous, full-duplex data rate. It uses on-off keyed technology and

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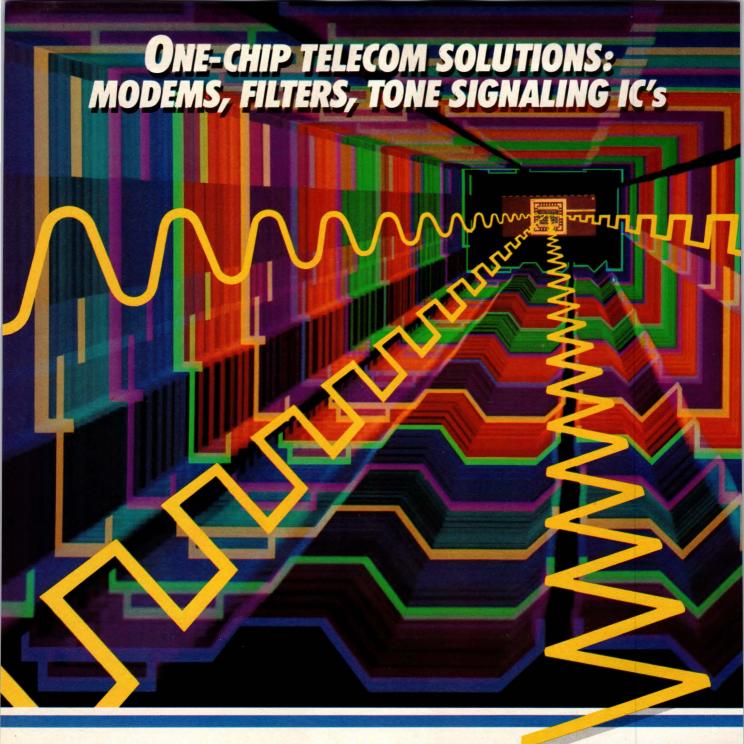
trollers. I/O modules. Even industrial I/O subsystems and assemblies. And new boards are being added continuously. Our handy rack holds up to 14 double VMEbus Eurocards and provides the power required. Speeding design of everything from simple controllers to the most complex multi-processor systems. To sum up, the VMEbus is the most powerful for designing 16-bit systems to day and

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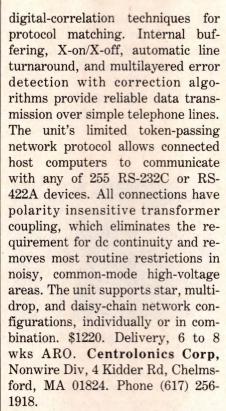
> For more information on our DTMF's, modems, speech synthesizers, and switched capacitor filter arrays, send for our Telecom Integrated Circuits brochure.



Silicon Systems, 14351 Myford Road, Tustin, CA 92680. (714) 731-7110.

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COMPUTERS & PERIPHERALS



Circle No 547



MICROCOMPUTERS. The 400 Series 68000-based, VME Bus microcomputers support multiuser localarea-networking applications with true vectored interrupts and optionally polled I/O. The 10-MHz systems' 256k bytes of RAM are standard, with maximum RAM capacity extending to 3M bytes. A 640k-byte floppy-disk drive is provided on each system, and an optional second drive is offered. The high-end Model 460 accommodates a maximum Winchester disk capacity of 448M bytes. A maximum of 15 users can use a variety of operating systems and languages, but the standard offering of software includes the Liaison

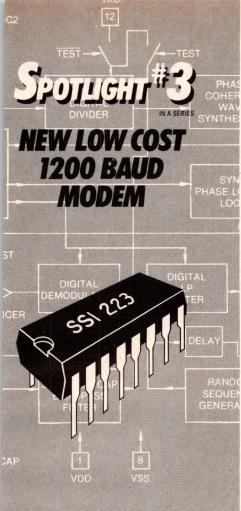
operating system, p-System IV.2 with LAN software, a screen editor, communications software, and several utilities. These microcomputers have a real-time clock with battery backup. Options include a 12-MHz processor with 120-nsec CPU RAM, a floating-point unit, and a memory-management unit. From \$2900. Stride Micro, 4905 Energy Way, Reno, NV 89502. Phone (702) 322-6868. TWX 910-395-6073.

Circle No 548

HIGH-SPEED PRINTERS. Models 2565A and 2566A dot-matrix devices print at 600 lpm and 900 lpm, respectively. You can install as many as 14 character fonts simultaneously and mix them in a single line of print. Both models print bar codes, provide high-speed graphics, and handle multipart forms. The standard ASCII character set and 11 European languages are supported. You can choose from the various character sets by using the printer's front control panel or via software commands. Optional OCR-A and OCR-B character sets are available to meet Department of Defense and European postal service standards for optical character codes. The manufacturer's IEEE-408 interface bus is included, but optional RS-232C, RS-422A, Centronics parallel, and 2608A interfaces are also available. 2565A, \$18,766; 2566A, \$21,766. Delivery, 24 wks ARO. Hewlett-Packard Co. 1820 Embarcadero Rd. Palo Alto, CA 94303. Phone local office.

Circle No 549

MODEMS. The Series/900 modems feature speed ranges from 1200 to 14,400 bps. The 911 is a full-duplex dial-up modem that's suitable for use in a 2-wire general-switched telephone network. It operates at 1200 or 2400 bps with automatic-calling and -answering functions through



Silicon Systems now introduces a low-cost 1200 baud FSK modem IC that is ideally suited for use with interactive terminals, videotex, personal computers, credit verification systems, point-of-sale terminals, and remote process control.

The new SSI 223 integrated circuit receives and transmits serial binary data over existing telephone networks using a frequency shift keying (FSK) design. It operates at 1200 baud and provides the filtering, modulation, and demodulation to implement a serial, asynchronous, data communication channel.

By utilizing advanced CMOS switched capacitor filter technology, Silicon Systems has been able to produce a chip that minimizes size and power consumption and maximizes reliability. Capable of simultaneous transmission and reception, the SSI 223 can be used for half-duplex operation over a single line system or full duplex operation over a two-line system.

For more information on this low-cost modem, contact: Silicon Systems, 14351 Myford Road, Tustin, CA 92680, (714) 731-7110, Ext. 575.



COMPUTERS & PERIPHERALS

the RS-232C interface. This unit has an integrated line monitoring speaker and meets CCITT V.22 and Bell 212A standards. The 910 (CCITT V.26, 1200/2400 bps), 920 (CCITT V.27, 2400/4800 bps), 930 (CCITT V.29, 4800/7200/9600 bps). and 940 (CCITT V.29, 4800/7200/ 9600/14,400 bps) are leased-line modems that operate over regular phone lines and contain an equalizer that adapts continuously to transmission-line characteristics, bridging line interruptions that last as long as 2 sec. Seven LEDs permit continuous monitoring of modem operation and DTE interface. An integral test-pattern generator and biterror-rate detector are included. The 920, 930, and 940 also feature an eye pattern generator to provide a standard pattern on an oscilloscope that gives a visual indication of how the signal is being received. The 930 and 940 modems also allow you to control port speed for local

and remote modems from one central site. From \$1095. Delivery, 60 days ARO. Digital Communications Associates Inc, 303 Technology Park, Norcross, GA 30092. Phone (404) 448-1400. TLX 261333.

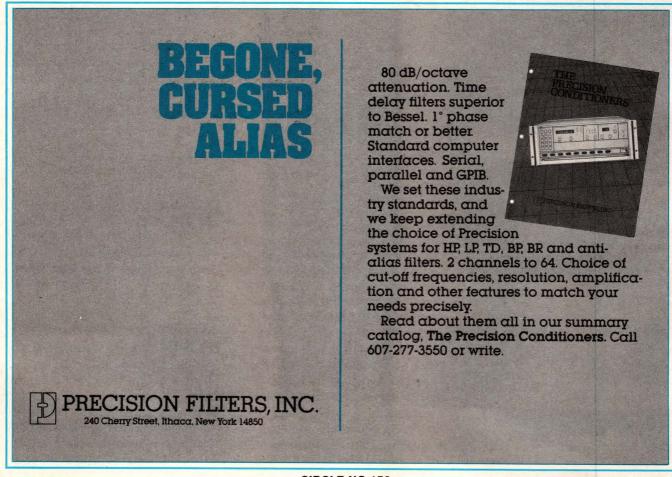


BAR-CODE READER. With the Symbtrak scanning system, your Apple IIe can read and print bar codes. The system includes a handheld scanning wand, ROM-based software, a tutorial diskette, and

instructions for application software integration. Software is available under DOS 3.3, ProDOS, or Pascal 2.0. Available code protocols include Code 3-of-9, Interleaved 2-of-5, Codabar, UPC, MSI Plessey, and Labelcode. Symbol-printing software allows you to mix symbols with text. Printer routines are written in assembly code for a variety of dot-matrix printers. Options include multiple scanner support and multiple code support. From \$495. Advanced Business Technology Inc, 1180 Coleman Ave, San Jose, CA 95110. Phone (408) 275-9880.

Circle No 551

LASER MICROCOMPUTER. The LPC-1000 laser microcomputer incorporates laser video-disk technology in an 8086-based microcomputer system to support interactive training and simulation applica-



tions. The 12-in. read-only laser disk provides 2G bytes of storage for text, software, video, and audio data. Benefits of this technology include high data security, long archival storage life, media durability, and a low cost/bit of information manufacture and distribution. One video disk can hold more than 100,000 still images, more than 100 hrs of audio, or 1 million pages of alphanumeric text. Any of these information forms, including digital data, can be combined on one laser disk. You can use the Pilot-Plus authoring language to premaster a tape with development software or data for replication onto an optical disk. The LPC-1000 includes a highresolution color-graphics generator that you can use to overlay images on a laser-disk picture. The LPC-1000 includes 650k bytes of RAM. an RGB monitor, a keyboard, a joystick, the CP/M-86 operating system, Pascal, FORTRAN, and C.

\$9750. Delivery, 16 wks ARO. Tomax Inc, 5800 Andover Ave, Montreal, Quebec, Canada H4T 1H4. Phone (514) 735-6541.

Circle No 552

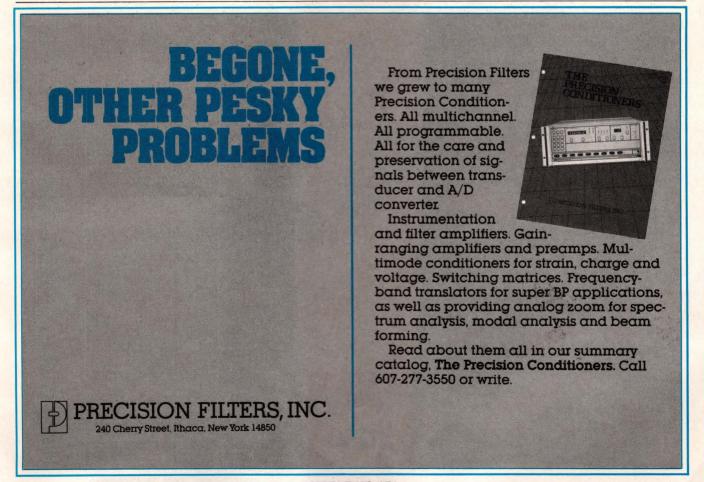


PRINTER. The OT-700 dot-matrix printer provides a 700-cps draft-quality print speed. You can also select correspondence quality printing at 350 cps. The unit offers dot-addressable graphics printing in two operating modes—50×69 dots/in. for high-speed output or 100×69 dots/in. for higher resolution copies.

Several foreign-language and special character sets are available. Protocol configuration is provided via menu-driven program commands. The printer has a carriage width of 136 columns with adjustable sprocket-feed tractors. The paper path can originate from the front or the bottom of the unit. The control panel features membrane switches and LED indicator lights. \$1495. Output Technology Corp, 606 110th Ave NE, Bellevue, WA 98004. Phone (800) 468-8788.

Circle No 553

GRAPHICS DISPLAY. You can use Model 2010 single-board, graphics display system as a stand-alone or host interactive device with Ethernet, Multibus, and Q Bus data networks. Pictures and images can reside locally without the need for continuous retransmission from the host. You can modify pictures by



WHEN CHOOSING OPTICAL ENCODERS, CONSIDER... The resolution and accuracy—to the contract of the

The resolution/accuracy relationship

Resolution and accuracy—they often get confused. Accuracy is the deviation of the actual position from the correct position expressed as error. Resolution defines the smallest measurable change in position. There is no guarantee that a product promising high resolution automatically ensures high accuracy. Nor can increased resolution compensate for low accuracy. If you want both, you have to specify both.

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stability. Its dual read-head cancels disc eccentricity and bearing errors. The Model 35 may be perfect for your needs. If your needs for accuracy and resolution aren't that exacting, we'll recommend another encoder to do the perfect job.

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DYNAMICS RESEARCH CORPORATION 60 CONCORD STREET WILMINGTON, MASSACHUSETTS 01887 TEL. 617/658-6100 TWX. 710/347-0611

COMPUTERS & PERIPHERALS

using parametric variables and simultaneous writing in any or all graphics memory planes. Display manipulation is accomplished through a variety of features such as local scaling, translation, rotation, view porting, highlighting, programmable color indexes, and segment copy operations. The 2010 provides a 7220 graphics processor with a 1M-byte video RAM, an 8086/87 processor, a 667-nsec per pixel vector-write rate, and a 19-in. monitor. The system comes in tabletop or rack-mount versions. \$8500. Aydin Controls, 414 Commerce Dr, Fort Washington, PA 19034. Phone (215) 542-7800. TWX 510-661-0518.

Circle No 554



FACILITY NETWORK. An integrated, expandable energy management and facilities automation system, the Alpha/Net 4000 system can be configured to control a facility with as few as 64 or as many as 10,000 monitor points. Hardware includes a CPU, a P4000 distributed processing unit, an operator's interface, and a printer. The P4000 provides a direct interface between the system and the monitor points via I/O cards and T4000 submultiplexers. The system's software handles communication among the operator, the central system, and the monitor

points. The control programs let the Alpha/Net 4000 perform functions such as electric demand limiting, adaptive optimized starting and stopping, duty cycling, point calculating, event controlling, trend logging, and report generating. From \$10,000. AMF Control Systems, Box 59469, Dallas, TX 75229. Phone (214) 241-9016. TLX 751948.

Circle No 555

PORTABLE µC. The SP Series of 8088-based portable microcomputers offers a minimum of 256k bytes of RAM, expandable to 640k bytes. Floppy-disk storage is 360k bytes per disk, and the SPX model features a 10M-byte fixed disk. Also included are as many as four internal expansion slots, one parallel port, and one RS-232C serial port. The 9-in., green-phosphor, nonglare screen has a 640×400-dot density. The system comes with a built-in monochrome graphics board; an optional color board lets you use an external monitor for color graphics. The SP Series uses the MS-DOS 2.11 operating system, and GW Basic is included. From \$2685. Sperry Corp, Computer Systems Div, Box 500, Blue Bell, PA 19424. Phone (215) 542-4213.

Circle No 556

COLOR GRAPHICS. The Rascol dedicated color-raster image processor translates your computer's graphics into full-resolution, halftoned color pictures at full printer speed. Color-raster, ink-jet printers supported by the Rascol include the Tektronix 4695, the Diablo C-150, and the Xerox 1770. The Rascol uses a Motorola 68000 CPU to convert graphics generated by the host computer's software into dot-matrix commands at 120 dots/in.; maximum output speed is 5 min/page. Because the Rascol assumes the computerintensive process of rasterizing im-



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Ávailable in 3C8 material, that offers low losses under high excitation levels; 3E2A material with superior wideband characteristics, and 3E5 material for high permeability applications. Prototypes for engineering evaluation are now available in five sizes, EP7 through EP20, with hardware and bobbins. For more information, call the Cube.



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COMPUTERS & PERIPHERALS

ages, your computer can transmit an image in a few seconds via an RS-232C interface and then be available for other tasks. When it isn't generating images, the Rascol operates as a 200k-character print buffer. Instead of the stick figures typically generated by standard color plotters, the Rascol provides six fonts that resemble typeset characters. \$1995. Lasergraphics Inc, 17671 Cowan Ave, Irvine, CA 92714. Phone (714) 660-9497.

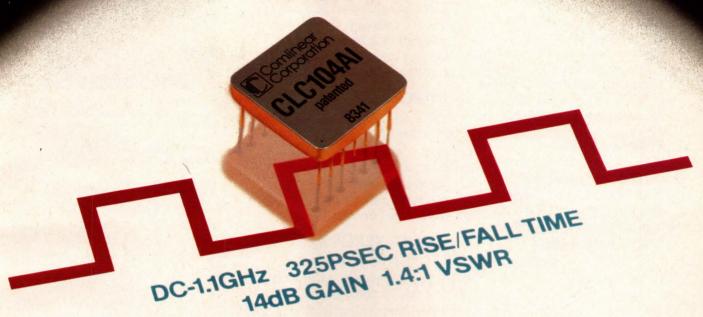
Circle No 557



MULTIUSER µC. A 68000-based multiuser, multitasking microcomputer, the Sun-Beam, supports four users and includes the Pick operating system, a relational databasemanagement program, spreadsheet software, and word processing. The 22M-byte Winchester disk system includes an 11M-byte fixed disk and an 11M-byte removable disk. Options include 1M bytes of internal memory, a 140M-byte hard disk, a ½-in. tape drive, a color-graphics package, and a 16-user system upgrade. The Sun-Beam comes configured to run laser video-disk and laser printer peripherals. From \$4995 (OEM gty). Climax Computer, 4790 Irvine Blvd, Suite 105-172, Irvine, CA 92715. Phone (714) 557-2398.

Circle No 558

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The Comlinear CLC104 linear amplifier. With these specs it may be the closest thing to an ideal amplifier on the market today. And it's priced at only \$315.

If you're working in high-speed data communications, fiber optics, broadband video, or radar/EW, then you should be using the Comlinear CLC104 Linear Amplifier. Simply add power supplies to achieve DC-1.1GHz -3dB bandwidth and 14dB gain.

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psec rise/fall times, 1.2:1 VSWR (DC-750 MHz), and <3% overshoot, and you have an amplifier ideally suited for applications involving high-speed pulsed information. Deviation from linear phase of less than 3 degrees contributes to the overall low distortion displayed by the CLC104. The result is a versatile new building block that can handle the fastest digital traffic with assurance, even when the demodulation scheme or the digital coding format requires that DC be maintained.

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Plug-in ease of use, low cost, and world-class performance specs. That's the Comlinear CLC104. Call or write us today for more information. Comlinear Corporation, 2468 East 9th Street, Loveland, CO 80537 (303) 669-9433.



FUNCTION × 6

New Keithley 195A Programmable Multimeter gives you temperature capability as a bonus.

Now, you can get the five measurement functions you expect from a Keithley system DMM, plus °F and °C temperature. Just add an RTD probe and you've got a full six-pack of measurement capabilities.

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All six functions are available via the front panel and the IEEE-488 bus. And the new programmable 195A is fully compatible with our full line of IEEE instruments.

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We use no trim pots in the 195A calibration circuitry. Constants for each range and function are stored in a non-volatile memory. On-the-bus calibration is time efficient. Or you can use the simple front panel procedure.

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The internal memory stores up to 100 readings at 9 selectable rates. You can also recall High, Low, or Average at any time. Rates and recall can be programmed either right from the front panel or over the bus.

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The 195A uses Keithley's unique approach to the Zero. A single button lets you create a new baseline for relative measurements, or for compensating offset voltage or lead resistance.



Other Keithley system components include: (bottom) New 100-channel 706 scanner for programmable high-density switching; (top right) 220 Programmable Current Source (or its twin, the 230 for voltage).

A VERY FUNCTIONAL PRICE

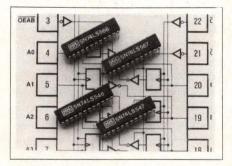
The base price of \$1K includes DCV, Ω , and temperature. Call or write for a brochure and Programming Guide. And add six full functions to your measurement system. Keithley Instruments, Telemarketing Dept., (216) 248-0400, 28775 Aurora Rd., Cleveland, OH 44139.



NEW PRODUCTS: ICs & SEMICONDUCTORS

VOLTAGE REGULATOR. The LT1038 supplies 10A at voltages from 1.2 to 32V. Packaged in a TO-3 case, the regulator is pin compatible with the company's LM117 and LM138. The IC's current-limiting circuitry allows it to supply 23A for 500 usec before current limiting occurs. It also has thermal limiting. The chip features 0.01%/V line regulation and 0.04% load regulation. It uses a 1.25V ±0.8% internal reference. The -MK suffix version operates from -55 to +150°C, and the -CK suffix version operates from 0 to 125°C. LT1038CK, \$9.95 (100). LT1038MK, \$39 (100). Linear Technology Corp, 1630 McCarthy Blvd, Milpitas, CA 95035. Phone (408) 942-0810. TLX 172110.

Circle No 430



INTERFACES. SN54/74LS546 and SN54/74LS547, both 8-bit registers, and the SN54/74LS566 and SN54/ 74LS567, both 8-bit latches, provide 32-mA output drives. The devices' input pins incorporate readback capability-the chips can return stored values to those pins while the output pins continue to function normally. Featuring 3-state output lines, these bidirectional devices come in plastic and ceramic DIPs. Ceramic, \$7.25. Plastic, \$6.18 (100). Monolithic Memories Inc, 2175 Mission College Blvd, Santa Clara, CA 95050. Phone (408) 970-9700. TWX 910-338-2374.

Circle No 431

NONVOLATILE RAMs. NVR2, organized in a 2k×8-bit configuration, is compatible with the HM6116

and the TC5517. NVR8, in an 8k×8bit configuration, is compatible with the HM6264 and TC5565. Each draws 5-µA standby current. To safeguard vital areas of memory, each device has a plated-on writeinhibit bar that is incorporated within the molding at one end. When you connect this optional feature, it prevents unauthorized data changes. NVR2, \$27.30. NVR8, \$65 (1000). LMS Electronics, (Representing Greenwich Instruments Ltd.) 3401 Monroe Rd, Charlotte, NC 28205. Phone (704) 376-7805. TLX 358905.

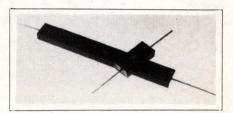
Circle No 432

D/A CONVERSION. The MP5528 or the MP5529, when combined with a 12-bit multiplying D/A converter, provides a complete voltage-output D/A converter with a reference. Each chip contains a 10V reference. a programmable negative-current source, an output amplifier, and a set of matched resistors. The units can provide unipolar or bipolar outputs. The ICs' output amplifiers are an OP-37 op amp with a 15V/µsec slew rate and 60-MHz f_T for the MP5528 and an OP-27 op amp with a 2.5V/µsec slew rate and 8-MHz f_T for the MP5529. Both devices have 100-μV typ initial offset voltages and 0.3-µV/°C typ offset drifts. Their reference-voltage temperature coefficients are 10, 20, and 30 ppm/°C and are available in commercial, industrial, and military temperature ranges. Depending on grade and temperature range, from \$5.75 to \$40.50. Micro Power Systems Inc, 3100 Alfred St, Santa Clara, CA 95050, Phone (408) 727-5350.

Circle No 433

64k EEROM. M52B33, in an 8k×8bit configuration, is specified for operation over the military temperature range. It requires a single 5V±10% supply for all operational modes, including byte erase, write, read, and chip erase. All modes use TTL inputs. The chip comes in a 28-pin DIP or a 32-pin LCC. Both packages' pinouts conform to JEDEC-approved pin configurations for byte-wide memories. Key specs include 1- or 10-msec bytewrite times, 10,000-byte write/ erase-cycle endurance, and 300-nsec byte-read time. M52B33H-300, in a 28-pin DIP and with 1-msec bytewrite time, \$359.45. M5233-300, in a 28-pin DIP and with 10-msec bytewrite time, \$312.55 (100). Seeq Technology Inc, 1849 Fortune Dr, San Jose, CA 95131. Phone (408) 262-5041.

Circle No 434



RECTIFIER STACKS. SSCHE Series rectifier stacks have PIV ratings from 4 to 20 kV, a 0.25A average current rating, and a 70-nsec reverse recovery time. The Series consists of assemblies of glass hermetically sealed diodes enclosed in an epoxy mold. 4-kV version, \$112 (100). Delivery, 8 wks ARO. RSM Electron Power Inc, Sensitron Semiconductor Div, 221 W Industry Ct, Deer Park, NY 11729. Phone (516) 586-7600.

Circle No 435

FILTER IC. R5635, a CCITT V.22 BIS full-duplex modem-filter IC, contains two switched-capacitor bandpass filter channels centered at 1200 and 2400 Hz, respectively. TTL or CMOS input to the chip switches the filters between transmit and receive modes using the chip's internal MUXes. Using a TTL or CMOS input, you can select between the chip's 550- and 1800-Hz guard-tone notch filters. There's a TTL or CMOS-compatible input pin

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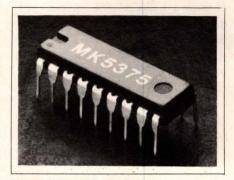
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ICs & SEMI-CONDUCTORS

to activate the device's self-test mode. The chip also has lowpass clock filters in the transmit and receive paths. The IC requires ±5 to ±10 supplies and a TTL or CMOS 153.6-kHz clock input for operation. <\$15. EG&G Reticon, 345 Potrero Ave, Sunnyvale, CA 94086. Phone (408) 738-4266. TWX 910-339-9343.

Circle No 436



DIALER. The MK5375 repertory dialer combines tone and pulse dialing in a single unit. It handles 10 16-digit numbers and can dial both star (*) and pound (#) DTMF signals. For security, you can disable its last-number redial feature. A chip-disable function lets you use several of these chips simultaneously to increase memory size. It comes in an 18-pin DIP. \$6.35 (1000). Mostek Corp, 1215 W Crosby Rd, Carrollton, TX 75006. Phone (214) 466-6000.

Circle No 437

128k ROM. NCR 23128S, a static ROM, which features a 16k× 8-bit organization, operates from a 5V supply, is TTL compatible, and has a 250-nsec access time. In its powerdown mode, it reduces consumption from 75 mA (active) to 10 mA (standby). The chip comes in a 28-pin DIP with JEDEC-standard pinouts for byte-wide devices. \$4.85 (10,000). Delivery, 6 wks ARO. NCR, Microelectronics Div, 8181 Byers Rd, Miamisburg, OH 45342. Phone (800) 543-5618; in OH, (513) 866-7217.

Circle No 438

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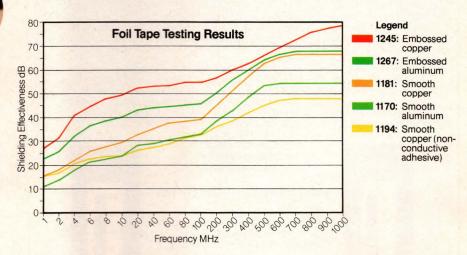
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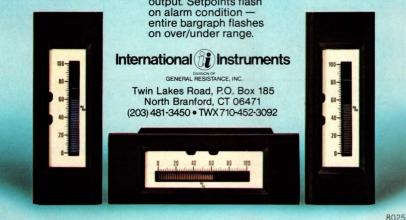
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ICs & SEMI-CONDUCTORS

256k DRAM DESIGNER KITS. The HM-DK1 designer kit contains four HM50256 dynamic RAMs and a data sheet. The HM-DK2 designer kit contains four HM50256-16 dynamic RAMs and a data sheet. The chips achieve access times from 120 to 200 nsec and consume 350 mW while active and 23 mW while on standby. HM-DK1, \$124.99. HM-DK2, \$109.95. Hitachi Ltd, 2210 O'Toole Ave, San Jose, CA 95131. Phone (408) 942-1500.

Circle No 439

DISPLAY CONTROLLER. The μPD7220A generates video signals at rates to 128 MHz and performs read-write-modify display-memory operations in 500 nsec. It can address as many as 4M bytes of videodisplay memory, program vertical and horizontal timing, and generate vectors for drawing arcs, circles, rectangles, and characters. It also includes such features as DMA control, zooming, panning, scrolling, and split screening. The 7220A comes in 6-, 7-, and 8-MHz versions. \$130 (100). NEC Electronics Inc, Box 7241, Mt View, CA 94039. Phone (415) 960-6000. TWX 910-379-6985.

Circle No 440

RECTIFIERS. These MIL-type custom rectifier assemblies come in voltage ratings to 50 kV PRV and current ratings to 3A. The assemblies incorporate JAN and JANTX, MIL-S-19500-grade rectifiers. From \$25. Electronic Devices Inc, 21 Gray Oaks Ave, Yonkers, NY 10710. Phone (212) 965-4400.

Circle No 441

DIALER. The MA527 repertory dialer stores and dials 10 18-digit numbers and has a 21-digit redial memory. Using the chip as a pulse dialer, you can connect it for 2:1 or 3:2 make/break ratios and 400- or 800-msec interdigit pauses. In the

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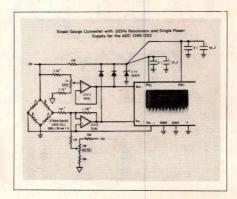
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DTMF mode, you can use an onboard unity-gain amplifier to facilitate tone filtering. Both operating modes can provide a flash to the telephone line-you have a choice of 100- and 600-msec flashes. You also have a choice of last-number redial: Either the dialer saves the last dialed number when the phone is placed on the hook or you manually save a number by activating the

chip's Save input. The chip has an optional output port to drive an LCD. It's active during dialing, and you can use it to check the contents of the redial and repertory memories. The IC's debounce circuitry considers keyboard inputs valid only if they have been present more than 14 msec. Standard 18-pin version, \$5.10; 20-pin version with filter amplifier, \$5.25; 24-pin version with filter amplifier and LCD output, \$5.85. Circuit Technology Inc. 160 Smith St, Farmingdale, NY 11735. Phone (516) 293-8686.

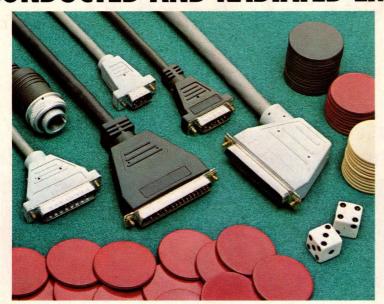
Circle No 442



CONVERTERS. A/D The ADC1205 and the ADC1225 CMOS 12-bit-plus-sign successive-approximation A/D converters interface directly to 8- or 16-bit data buses and operate from a 5V supply. The 24-pin ADC1205 produces a 13-bit result in two 8-bit bytes, formatted high-byte first with sign extended. The 28-pin ADC1225 produces a 13-bit word in parallel for direct interface to a 16-bit data bus. Negative numbers are represented in two's complement, and all digital signals are TTL and CMOS compatible. The two converters feature a 100-usec conversion time using a 1-MHz clock. The devices have differential analog inputs, consume 25 mW, can accommodate a unipolar input while operating from a unipolar supply, and can handle a ±5V input range when operated from ±5V supplies. The -B versions of the converters exhibit a 0.012% FS nonlinearity; the -C versions, 0.024%. The ADC1205 comes in a 24-pin DIP; the ADC1225, in a 28-pin DIP. ±1-LSB nonlinearity ADC1205CCJ-1 and ADC1225CCJ-1, \$19.95 (100). National Semiconductor Inc, 2900 Semiconductor Dr, Santa Clara, CA 95051. Phone (408) 721-5226, TWX 910-339-9240.

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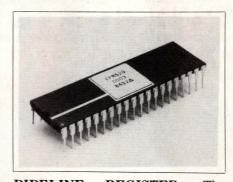
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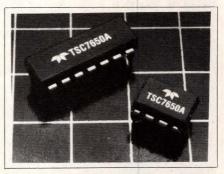


PIPELINE REGISTER. The CMOS LPR520/LPR521 is a 16-bit version of the AM29520 and AM29521 8-bit registers. The TTLcompatible chip features four 16-bit registers that can operate as two independent 2-level registers or one 4-level register. The IC operates at a 25-nsec max access speed. The two versions of the circuit operate differently: The LPR520 shifts data through its registers as new data comes in and overwrites data in the last register, and the LPR521 overwrites the first register and retains data in subsequent registers. An input instruction code determines the chips' register configuration, and data is latched into a register on a rising clock edge. 40-pin commercial-grade plastic DIP, \$20. Military-grade ceramic, \$64 (100). Logic Devices Inc, 628 E Evelyn Ave, Sunnyvale, CA 94086. Phone (408) 720-8630. TLX 172387.

Circle No 444

D/A CONVERTERS. DAC1265A and the DAC1265 12-bit D/A converters have a 35-nsec max 10 to 90% FS transition time and settle to <1/2 LSB in 200 nsec. The chips have a bipolar current output. Their gain temperature coefficient is ±15 ppm/°C. The converters incorporate thin-film resistors for use with external devices. DAC1265 ACJ. \$19.95; DAC1265LCJ. \$12.95 (100). National Semiconductor Corp, 2900 Semiconductor Dr, Santa Clara, CA 95051. Phone (408) 721-5000. TWX 910-339-9240.

Circle No 445



CMOS OP AMP. The TSC7650A. pin-compatible with the ICL7650, features 2.5-mA max power-supply current consumption, a 4V/µsec typ slew rate, and 0.2 µV/°C voltage drift. The chopper-stabilized op amp's key specs include 15-pA max input-bias current, a 120-dB openloop voltage gain, a 1-MHz f_T, and a −5 to +1.5V common-mode voltage range when operating from ±5V supplies. The amplifier's outputvoltage clamp reduces circuit gain when necessary to prevent outputstage saturation; this prevents overload-recovery delay. The device comes in 8- and 14-pin plastic or ceramic DIPs for 0 to 70°C and -25 to +85°C operation. From \$2.75 (100). Delivery, 6 to 8 wks ARO. Teledyne Semiconductor Inc, 1300 Terra Bella Ave, Mt View, CA 94043. Phone (415) 968-2941. TWX 910-379-6494.

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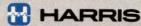
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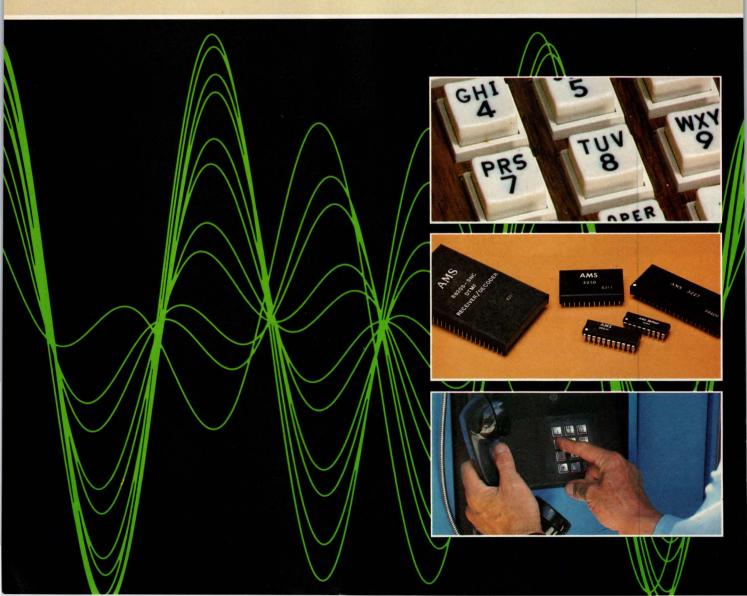
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Circle No 447

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Circle No 448

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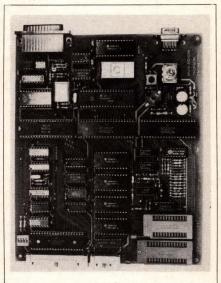
than 64,000 waveforms. The instrument measures repetitive signals in the nanosecond time region and can be used as a standard 100M-sample/ sec transient waveform analyzer. On-screen manipulations include curve normalization and subtraction, overlay of waveforms, peak search routines, horizontal axis calibration, and display of selected regions for detailed observation. Data archives are kept is on floppy disk, and an RS-232C serial port is standard. The system is a CP/M-based computer permitting further data manipulation. FORTRAN BASIC is provided. \$27,900. Delivery, 10 wks ARO. LeCroy Research Systems Corp, 700 S Main St, Spring Valley, NY 10977. Phone (914) 425-2000. TWX 719-577-2832.

Circle No 449



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Circle No 450



6805 EMULATOR. The Micro-AID 05A is an accessory for the IBM PC that supports the 6805 µP family. It includes a 6805 cross assembler, incircuit emulator, symbolic debugger, and EPROM/EEPROM programmer. The cross assembler, running on the IBM PC, processes 6805 source code into object and symbol-table files used by the emulator. The emulator features hardware and software breakpoints, instruction and register tracing, disassembler, and real-time execution timer. Emulator hardware includes 8k bytes of overlay RAM and eight real-time break points. The system emulates the MC146805E2 μP, and an interface pod is available for 14 types of single-chip 6805 μPs. The EPROM programmer handles 16 varieties of EPROMs or EE-PROMs, both NMOS and CMOS, from 8k to 256k. The Micro-AID/ 05A command set is a Forth extension. The Micro-AID/05A, \$1200; interface pod, \$250 (unit quantity). Thorson Engineering Co, 6225

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76th St SE, Snohomish, WA 98290. Phone (206) 334-4214.

Circle No 451



FUNCTION GENERATOR. Model 627 13-MHz programmable function generator offers sine, square, triangle, and haver waveforms, inverted waveforms, variable-symmetry waveforms, and dc. You can select frequencies from 100 µHz to 13 MHz using nine overlapping ranges. You can vary the frequency within each range over a ratio of 1300:1 remotely, from the front panel, using an external voltage, or over the IEEE-488 bus. Frequency, amplitude, offset, symmetry, and calibration sequence number get displayed on a 3½-digit LED display. Amplitude range is 10 mV p-p to 10V p-p into 50Ω , offset range is 0V to $\pm 5V$ peak into 50Ω , and symmetry range is 5%:95% to 95%:5% with 1% resolution. Model 627 gets calibrated from the front panel or under IEEE-488 bus control. Additional autocalibration sequences include frequency calibration to accuracies of 0.1% of setting. The unit measures 3.45×8.7×14 in. and weighs 7 lbs. \$1995. Delivery, 6 to 8 wks ARO. Exact Electronics, Box 1925, Carson City, NV 89702. Phone (800) 648-7952. Circle No 452

1-GHz CLOCK DRIVER. A series of high-power clock drivers that provide clock rates from dc to 1 GHz generate precise pulses even when over-driven. A nominal 4-dBm sinusoidal input is sufficient to over-drive the clock drivers; they also accommodate nonsinusoidal inputs,

very important ineering event designers of ectronics

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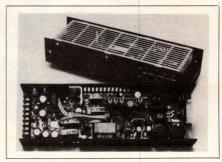


CIRCLE NO 172

INSTRUMENTATION & POWER SOURCES

both single-ended and differential. At lower clock rates the rise/fall times increase because of the limited gain of the clock drivers. For the 4-dBm sinusoidal input, the rise/ fall times increase at frequencies less than 10 MHz for the model CD5A clock driver and at frequencies less than 200 MHz for the CD5B and CD5C. When the clock drivers get driven with pulses having rise/ fall times of <5 nsec, the fastest output rise/fall times are obtained. The CD5A operates at clock rates to 350 MHz; the CD5B, to 1 GHz. Both operate down to dc. The CD5C, an ac-coupled version of the CD5B, allows a programmable dc-output offset level between -5V and +5V. Power supply requirements for all models (within 2%) are 15V (400 mA) and -15V (350 mA). CD5A, \$1450; CD5B, \$2400; CD5C, \$2600. Colby Instruments Inc., Box 84379, Los Angeles, CA 90073. Phone (213) 450-0261.

Circle No 453



210W SWITCHER. This 210W multiple-output magnetic-amplifier switcher tolerates high peak loads so that it can power hard-disk computers. The MASS210-1 has output configurations of 5V at 15A (20A peak), 12V at 6A (8A peak), and -12V at 1A (1.5A peak) packaged in a 2.5×4.25×13-in. U-channel chassis. The unit powers multiple 51/4-in. hard disks and floppy disks from one 12V output. Mag-amp design with isolated outputs provides initial start-up current for the drives without degradation of regulation characteristics. Other features include power-failure-detection circuitry

High-performance CMOS Static RAMs. There's never been a better deal.



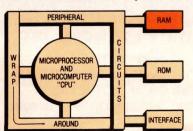
The Game

High performance. Reliable delivery. And a fair price. When it comes to CMOS Static RAMs, the stakes are too high to gamble on anything less.

Our Hand

That's why S-MOS offers the two most popular CMOS Static RAM types for large volume users: the SRM 2064 64K (8K×8) and the SRM 2016 16K (2K×8). Pin-compatible with 6264 and 6116 device families, respectively, they're designed for performance that meets or exceeds other vendors' premium grade products. But at prices equivalent to their standard grades.

Take our powerful 64K CMOS SRAM. It features an access time of just 150ns,



The S-MOS system

SRAM COMPARISON CHART								
16K (2K×8) 150ns	OPERATING (1) CURRENT (TYP) MAX	STANDBY (2) CURRENT (TYP) MAX	STANDBY (3) CURRENT (TYP) MAX					
LEADER'S STD, 6116	35mA 70mA	5mA 15mA	20μΑ 2000μΑ					
LEADER'S LP, 6116	30mA 60mA	4mA 12mA	2μΑ 50μΑ					
S-MOS' STD, 2016	20mA 35mA	.3mA 2mA	1μΑ 50μΑ					
64K (8K×8) 150ns								
LEADER'S STD 6264	60mA 110mA	1mA 3mA	20μΑ 2000μΑ					
LEADER'S LP 6264	60mA 110mA	1mA 3mA	2μΑ 100μΑ					
S-MOS' STD 2064	25mA 40mA	1.5mA 3mA	2μΑ 100μΑ					
(1) AVERAGE: MIN DUTY CYCLE, SST = VIH, CS2 = VIL (64K) SS = VIH (16K) (2) SST = VIH OR CS2 = VIL (64K) SS = VIH (16K)								
(3) CS1, CS2 ≥ VCC - 0.2V OR CS2 ≤ 0.2V (64K)								

Based on published data sheet parameters

worst case. Plus power consumption that's a mere 25mA operating; $2\mu A$ standby.

What's more, the device utilizes 2-micron selectox silicon gate CMOS technology. It's a proprietary process that optimizes speed and power while cutting production costs. So while you're increasing performance, you're also saving money.

The SRM 2016, like its 64K counterpart, cuts down on energy consumption and has an access time of just 150ns.

Both SRAMs feature industry-standard

pinouts and a choice of either plastic flat pack, cerdip, or plastic DIP packaging.

Our Raise

For outstanding reliability, our SRAM parts are 100% burned-in and temperature tested. And they are fabricated by Suwa Seikosha, one of the world's largest, most automated CMOS LSI manufacturers.

And remember, these premium devices are delivered at a price that's equivalent to the competition's standard grade. Now that's one sweet deal.

Our Call

So when the chips are down and you need more, stand pat with S-MOS. We've got a full house of 64K and 16K CMOS Static RAMs ready for immediate delivery.

S-MOS Systems.

Nothing beats a winning hand.



S-MOS Systems, Incorporated 50 West Brokaw Rd., Bldg. 7 San Jose, CA 95110 (408) 993-1212 and a hold-up time of 50 msec min at nominal input voltage and maximum output power. An isolated-output design eliminates cross-regulation effects. \$185 (OEM qty). Elpac Power Systems, 3131 S Standard Ave, Santa Ana, CA 92705. Phone (714) 979-4440.

Circle No 457

16-MHz 68000 LOGIC POD. A 68000 uP pod for the ML4100B logic analyzer clips directly over a 68000 or 68010 DIP and collects and formats data, filtering it for logic analysis and program disassembly. Features include full disassembly, including all exceptions and all bus cycles; hardware that implements Filtered mode (which deletes unused prefetches and prevents activation of unwanted trigger events, eliminating storage in memory); Jump mode, which records only changes in program flow; Transparent mode, which passes all bus cycles; and support of 68000 and 69010 µPs at speeds to 16 MHz. The 16-MHz 68000 µP logic pod, \$1860. Atrium Corp, 1931 Wright Circle, Anaheim, CA 92806. Phone (714) 978-9531.

Circle No 458



LCD LOGIC ANALYZERS. Models 1310 (10 MHz) and 1320 (20 MHz) perform logic timing, logic state, and signature analyses. These handheld, battery-powered units have 16-channel×256-word main and reference memories. Their 16-channel inputs also have one clock and one clock-qualifier line.

They measure $10 \times 5.5 \times 1.5$ in. Their LCD (2688 pixels) contrast adjusts for viewing in varied light. Other features include word trigger, glitch detection, external trigger, and qualifier (all TTL level); minimum glitch width is 15 nsec. Data gets displayed eight channels in parallel at one time. With the display system's scaling function, any portion of the data sequence expands four times. Hexadecimal, octal, binary, and ASCII-code displays are available. Compare and Search functions allow retrieval of a specified word, counting the number of specified words, or comparison with the reference data, which can also be displayed. Model 1310 (10 MHz, 16 channels, 256 words), \$1995; Model 1320 (10 MHz, 16 channels, 256 words), \$2495. North American Soar Corp. 1126 Cornell Ave. Cherry Hill, NJ 08002. Phone (609) 488-

Circle No 459





The Motorola VME Challenge



MVME120 MC68010; MMU 4KB Cache; 128KB(512KB)RAM



MVME115M MC68010 with MMU



MVME110-1 MC68000 with I/O Channel



MVME101 MC68000 Single Board Computer



MVME202 512 Kbyte High-Speed Dynamic RAM



MVME222-2 2 Mbyte High-Speed Dynamic RAM



MVME315 Floppy Disk Controller/SASI Interface



MVME320 Winchester and Floppy Disk Controller



IVME300 IEEE-488 PIB Controller



MVME330 LAN Ethernet Controller



MVME340 6-Channel Parallel I/O Module



MVME050 Combo Module Controller; I/O; Memory





MOTOROLA

VMEbus Products from Motorola

PRODUCT REFERENCE							
VME/10							
	VME/10 microcomputer system with 15 Mbyte						
	Winchester disk, 655 Kbyte floppy disk, 5-slot						
	VMEbus backplane and 4-slot I/O channel						
M68K102C2	backplane 2 As M68K102B2 with 40 MB Winchester						
Processor M MVME101	MC68000 with 256 KB on-board memory space,						
IVIVIVIL TO T	system controller functions, 1-level bus arbiter,						
	VMEbus interface, parallel I/O, 2 serial I/O ports,						
	timer						
MVME110-1	messess min zee nz en zem e memer, ep e e,						
	1-level bus arbiter, VMEbus interface, I/O channel						
	interface, 1 serial I/O port, timer						
MVME115M	MC68010 with MC68451 192 Kbytes on board memory						
MVME120	MC68010, MC68451, 64 Kbytes ROM area.						
	128 Kbytes dual ported RAM, 4 Kbytes Cache						
MVME121	As MVME120 but with 512 Kbytes RAM						
MVME128	MC68010/MC68451, 256 Kbytes dual ported RAM VMXbus interface						
Memory Mod	Julae						
MVME201	256 Kbytes dynamic RAM with parity						
MVME202	512 Kbytes dynamic RAM with parity						
MVME222-1	1 Mbyte dynamic RAM with parity						
MVME222-2	ME222-2 2 Mbytes dynamic RAM with parity						
MVME211	/ME211 1 Mbyte static CMOS RAM/ROM/						
	EPROM module						
System Cont	System Controllers						
MVME025	VME system controller						
MVME050	VME system controller with memory and I/O						

PRODUCT REFERENCE	DESCRIPTION						
Peripheral I/O (VMEbus)							
MVME300	IEEE-488 GPIB controller with DMA						
MVME310	Universal intelligent Peripheral Controller (UIPC) with free user area						
MVME315	Intelligent floppy disk controller and SASI/SCSI interface with DMA						
MVME316	VMEbus to I/O channel adapter						
MVME319	Floppy disk controller and SASI tape controller interface						
MVME320	Winchester/Floppy disk controller						
MVME330-UX	Ethernet controller module with UNIX S/W						
MVME330-VX	Ethernet controller module with VERSAdos S/W						
MVME331	6-Channel intelligent serial communications module						
MVME333	4-Channel intelligent high speed communications module						
MVME340	64-bit parallel interface module						
Peripheral I/0	O (I/O Channel)						
MVME400	Dual-Channel serial I/O						
MVME410	Dual-Channel 16-bit parallel I/O						
MVME420	SASI peripheral adapter						
MVME435	Buffered 9-track magnetic tape adapter						
Industrial (I/C	O Channel)						
MVME600	16-Channel analog input						
MVME601	16-Channel expansion for MVME600						
MVME605	4-Channel analog input						
MVME610	120V/240V 16-Channel AC input						
MVME615	120V/240V 16-Channel AC output Zero cross-over switching						
MVME616	120V/240V 16-Channel AC output						
MATCOO	Non-zero-cross-over switching						
MVME620	30V DC input						
MVME625	30V DC output						

Software Support

VERSAdos Realtime Multi-tasking Operating System.

UNIX, System V/68 Standard UNIX release jointly developed by Motorola and A.T. & T.



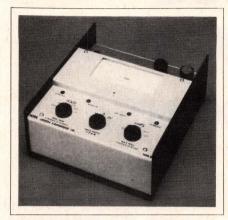
Call for more information included in this 28-page brochure.

Circle 271



European Distributors: Austria: Elbatex (2 22) 88 5611/Belgium: Diode (02) 216 21 00/Denmark: Danelec (01) 69 0511/Finland: Field (80) 6 92 25 77/France: Alfatronic (1) 7 91 44 44 · Feutrier (77) 74 67 33 · FIF (1) 7 72 46 46 · SCAIB (1) 6 87 23 13 · SCT (61) 22 04 22/Germany: Distron (0 30) 3 42 10 41 · EBV (0 89) 6110 51 · Elkose (0 71 41) 48 71 · Prosystem (0 61 07) 7 50 30/Greece: Comptel (1) 3 61 43 00/Italy: Celdis (2) 612 00 41/Netherlands: Manudax (0 41) 39 29 01/Norway: OTE (02) 26 99 55/Spain: Comelta (1) 7 54 30 01/South Africa: ASD (011) 8 02 58 20/Sweden: Traco (08) 13 21 60/Switzerland: Elbatex (56) 27 01 27 · Omni Ray (1) 8 35 21 11/Turkey: Era 64 65 00/United Kingdom: Crellon (0 62 86) 44 34 · Hawke (01) 9 79 77 99 · New-Tek (02 23) 22 12 21 · Thame (0 84) 4 21 45 61/Motorola Offices: Asia and Pacific Region: Hong Kong (0) 22 31 11 · Tokyo (3) 4 40 33 11

NEW PRODUCTS: INTERNATIONAL



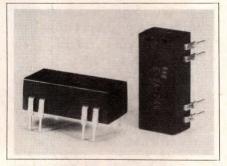
AC/DC TEST SET. The WM81 ac/dc test set features an overload capability of 1000V and 30A on any range. It also features audible and visible overload warning. The instrument has 6 rms voltage ranges from 3 to 1000V and 6 rms current ranges from 0.1 to 30A. You can also use it to measure power from 0.3W to 30 kW. The unit specs an accuracy of 2% of FS for voltage and current and 3% of FS for power. Bandwidth specs at dc to 20 kHz. Independent voltage and current inputs allow you to make 3-phase power measurements; an LED indicates negative power situations. £444. Delivery 4 to 6 wks ARO. Walden Precision Apparatus Ltd, Linton Station, Linton, Cambridge CB1 6NW, UK. Phone (0223) 892688.

Circle No 413

LOGIC ANALYZER. Effectively three separate logic analyzers in a single unit, the 7610's 32 or 48 channels can be split up into three groups, each with its own independent clock. Alternately, you can control each group by a combination of clocks. Any of the five clock qualifiers can be associated with the clocks via a Boolean expression. Maximum clock frequency measures 20 MHz, and memory depth equals 1024 bits/channel. You can reconfigure the 32-channel version to 8 channels of 3072 bits and the 48channel version to 16 channels of 2048 bits or 8 channels of 3072 bits. Logic thresholds are TTL, ECL, or

variable between $\pm 12.7V$ in 100-mV steps or ± 16.35 V in 50-mV steps. Eight sequential trigger levels are provided. The last seven of these each comprise two ORed conditions. and you can delay enabling of the next trigger level by number of occurrences, clock cycles, or real-time interval. Glitch detection can be incorporated into the trigger conditions. The 7610 includes a reference memory that you can automatically compare with captured data, optionally rearming the analyzer, depending on the result. A graph-mode display plots data values against time, giving, for example, a clear indication of address excursions in microprocessor-based systems. Its timing-diagram display is capable of showing 16 labeled channels, and it includes clock traces so that you can phase-relate the data. Personality probes and disassemblers are available for 8- and 16-bit uPs and for the IEEE-488 bus. £6100 for the 32channel version: £7600 for the 48channel version. Solartron Instrumentation Group, Victoria Rd, Farnborough, Hampshire GU14 7PW, UK. Phone (0252) 544433. TLX 858245.

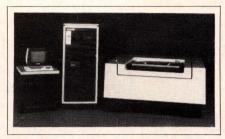
Circle No 414



REED RELAY. The E-2A series of DIP reed relays has a 10-VA load rating and an MTBF of 4.7×10^8 operations. Available with one or two normally open contacts, the units switch currents as high as 0.5A and carry 1A continuously. Maximum contact voltage measures 100V dc or ac peak and typical contact resistance equals $70 \text{m}\Omega$. Coil voltages of 24, 12, or 5V can be supplied. The

epoxy-resin encapsulation, which is suitable for flow soldering, meets the flammability requirements of UL94VO. From £1.11 (100). Erg Components, Luton Rd, Dunstable, Bedfordshire LU5 4LJ, UK. Phone (0582) 62241. TLX 82349.

Circle No 415



PHOTOPLOTTER. The EMMA 85 photoplotter features a plot accuracy of better than 0.015 mm over its entire plot area of 734×581 mm $(28.9 \times 22.9 \text{ in.})$. Resolution is 0.0025 mm. For less critical applications the unit has a high-speed plot facility. Because it uses film that is preloaded into a pallet impenetrable by light, the plotter does not require darkroom operation and is controlled via a local terminal. Input takes place via a magnetic-tape unit or through its RS-232C interface. Other interfaces are available. £57,500. Marconi CAE Systems, Quest House, Princes Rd, Ferndown, Dorset BH22 9HQ, UK. Phone (0202) 891010, TLX 41358.

Circle No 416

DIODE BRIDGE. The MB25 range of 25A, single-phase diode bridges includes versions with peak voltage ratings from 100 to 1200V. They handle 6A without a heat sink and 33A if the case temperature is limited to 55°C. Maximum operating-case temperature is 85°C. The bridges withstand a 350A surge for 10 msec. Excluding terminals, the package measures 28.5×28.5×11 mm. Marconi Electronic Devices Ltd, Power Div, Carholme Rd, Lincoln LN1 1SG, UK. Phone (0522) 29992. TLX 56163.

Circle No 417

You might feel good about buying Tektronix. But do your engineers?



As for service, we're established in every major city in the country. With more than 100 nationwide sales offices and Honeywell, G.E. and independent service centers.

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800-421-5334. In Alaska, California and Hawaii, call 213-515-6432. Leasing available.

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Ask them about triggering stability. About display contrast. Demonstrated reliability. Service turnaround. And availability.

And then, if they haven't already told *you* about us, you tell them.

We're Kik® Number four in worldwide scope sales.

And we've got a full line of high reliability oscilloscopes.

Our 6100 Series 100 MHz scope gives you three vertical channels, two simultaneous trigger views, a patented linear autofocus and a demonstrated MTBF over 20,000 hours.

Tektronix® doesn't. Not at any price.

Our 5000 Series 60 MHz scope offers three channels, eight traces (including a trigger view), and a demonstrated MTBF over 10,000 hours.

Tektronix doesn't match that. In any scope.

And we're on GSA with both of these series. Tektronix isn't.

Our 5000 Series storage scope gives you a 20 MHz bandwidth (theirs, only 10), a high contrast display and a vertical sensitivity of one millivolt per division.

Tektronix can't compare. No one does.



We're not riding on a reputation. We're making one.

"SEE US AT WESCON BOOTH #1133"

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POWER CONNECTOR. To simplify the assembly of power-input components, this CEE22 power connector has an integrated RFI filter and cartridge fuseholder. The thermoplastic body of the connector is encased in a metal housing with three 6.3-mm tab terminals. The singlepole fuse holder accepts standard 5×20-mm cartridge fuses. For safetv. the fuse holder cannot be accessed with the power cord in place. The connectors are suitable for use on Class 1 250V ac appliances and have SEV, VDE, UL, SEMKO, and CSA safety approval. Feller AG, Bergstrasse, 8810 Horgen, Switzerland. Phone (01) 7256565. TLX 53218.

Circle No 418



PC-BOARD CAD. Based on a Data General Model 10 computer, the MicroQuad pc-board-design workstation does more than generate board-layout artwork; it also produces parts lists, schematics, and assembly/drilling drawings. In addition, it compiles a database suitable for input into computer-aided-manufacture and test equipment such as NC-controlled drills, component-in-

sertion machines, and in-circuit testers. After design capture, which you can carry out on an IBM PC/XT, Multiroute software performs automatic component placement or allows you to predefine component positions and designate no-go areas. Using elastic-band techniques, you can then move components either individually or in groups. An output spooler allows you to plot at any stage in the board's design without interrupting the design process. From £30,000. Delivery, 6 wks ARO. Marconi CAE Systems, Quest House, Princes Rd, Ferndown, Dorset BH22 9HQ, UK. Phone (0202) 891010. TLX 41358.

Circle No 419

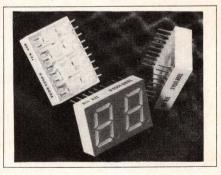


NETWORK ANALYZER. The ZAS scalar network analyzer performs scalar 2- and 4-wire voltage, transmission, and matching measurements in the 0.1- to 2500-MHz range, as well as swept-frequency and group-delay measurements. With a suitable sweep-frequency generator, you can make measurements on narrowband devices, such as crystal filters with a frequency resolution of 10 Hz. The unit's probes have a dynamic range of 95 dB and achieve an accuracy of ±0.5 dB. Three inputs provide you with two measurement channels and a reference channel. You can average data and display cursor, horizontal reference lines, frequency markers. reference curves, and tolerance graticules. 30,000 to 35,000 DM. Delivery from 1st qtr of 1985. Rohde & Schwarz GmbH & Co KG, Muehldorfstr 15, Postfach 801469, 8000 Munich 80, West Germany. Phone (089) 41292625. TLX 523703.

Circle No 420

MULTIMETER. The B1042 multimeter measures dc and rms ac voltages to 1 kV and 750V, respectively; dc and rms ac currents to 5A: and resistance to 50 M Ω with a scale length of ±5400 digits. You can select ranges manually or allow the instrument to autorange. Computational modes allow you to display percentage deviation or dB ratio, to offset readings by a given amount, or to limit-check the readings. Able to trigger readings at predefined time intervals, the B1042 stores the last ten measured values for subsequent examination. The multimeter has an IEC-625 (IEEE-488) interface and meets Class II requirements of DIN5744 and VDE0411. Siemens AG, Zentralstelle fuer Information, Postfach 103, 8000 Munich 1, West Germany. Phone (089) 2340. TLX 5210025.

Circle No 421

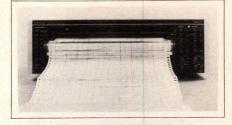


LED DISPLAY. The TDD Series 7-segment, dual-digit LED displays have a 13-mm character size. Housed in 18-pin packages, they are pin compatible with CQX87 dual-digit displays. Red, orange-red, yellow, and green versions are available in either common-anode or common-cathode configurations. AEG Telefunken, Theodor-Stern-Kai 1, 6000 Frankfurt/M 70, West Germany. Phone (0611) 6001.

Circle No 422



INTERNATIONAL



RECORDER. The PM8251A and PM8252A are (respectively) singleand double-line recorders featuring 15 input ranges from 1 mV to 50V full span, <0.2% of full scale deadband, and <2 μV/°C zero drift. Input impedance is 1 M Ω . Variable controls allow you to alter sensitivity between 95 and 250% of range and to shift the zero reference between -110 and +210% of span. The recorders use 250-mm-wide paper running at chart speeds between 10 and 300 mm/min or mm/hr. Additional features include channel inversion, servo kill, externally controlled dipmarker, and an output proportional to pen position. Both instruments can be supplied to stand alone or for 19-in, rack mounting, and both conform to IEC-348 safety requirements. Philips (S & I Div), Box 523, 5600 AM Eindhoven. Netherlands. Phone (040) 757005. TLX 51573.

Circle No 423

A/D, D/A CONVERTERS. Designed for video-processing applications, the PNA7507 A/D converter and PNA 7518 D/A converter have sampling rates of 15 and 30 MHz. respectively. The PNA7507 has 7-bit resolution with separate overand underflow outputs provided. You can select two's complement or binary coding for measured data. The converter has TTLlevel outputs and operates from 5 and 12V supplies; typical power consumption is 350 mW. The unit is housed in the 24-pin SOT-101A DIP. The PNA7518 8-bit multiplying D/A converter has transparent latch, TTL-level inputs, 12-MHz bandwidth, and an output with a linearity of $\pm \frac{1}{2}$ LSB. Its settling time, to

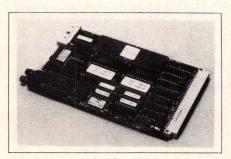
 ± 1 LSB, is typically 40 nsec with a 200-kΩ/6-pF load. The PNA7518 operates from a 5V supply and dissipates 300 mW typ. It is packaged in a 16-pin SOT-84B DIP. **Philips** (**Elcoma Div**), Box 523, 5600 AM Eindhoven, Netherlands. Phone (040) 757005. TLX 51573. **Signetics Corp**, 811 E Arques Ave, Sunnyvale, CA 94086. Phone (408) 739-7700.

Circle No 424

loaded glass paste in an organic solvent/resin medium. The organic components burn out at temperatures below 300°C, leaving a completely inorganic and inert bond. You can apply Ausub to substrates at room temperature. It is also suitable for use on alumina and beryllium-oxide ceramics as well as low-expansion alloys such as Nilo 42 and Kovar. Because the adhesive layer

absorbs stress between the chip and substrate during manufacture, it reduces the possibility that the die will crack. You can obtain an introductory pack containing 15g of Ausub, as well as processing information, for £100. Johnson Matthey Chemicals Ltd, Orchard Rd, Royston, Herts SG8 5HE, UK. Phone (0763) 44161. TLX 817351.

Circle No 426



POWER TRANSISTORS. DT100. DT150, and DT200 transistors are available with peak- and continuouscurrent ratings as high as 800A. They cover a V_{CEX} range of 300 to 1050V and a V_{CER(SUS)} range of 275 to 850V. Minimum forward current gain is 7 to 10 at 100 to 400A at a VCE of 2V and typical VCE(SAT) is <0.5V at rated current. Housed in the button R package, which allows double-sided cooling, the transistors have a mounting thermal resistance of <0.05°C/W. Suitable fast-recovery diodes can also be supplied. £95 (100+). Delivery, 3 to 4 wks for small quantities. Marconi Electronic Devices Ltd, Power Div, Carholme Rd, Lincoln LN1 1SG, UK. Phone (0522) 29992.

Circle No 425

DIE ADHESIVE. Replacing silicon-gold eutectic bonding and organic adhesives, Ausub is designed for the void-free bonding of largearea silicon chips in the production of hermetically sealed components such as ceramic DIPs, Sidebraze, pin-grid arrays, and ceramic chip carriers. The adhesive is a silver-



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INTERNATIONAL

BOARD COMPUTER. An enhanced SKC 85 Eurocard computer provides 8k bytes of EPROM space, 2k bytes of battery-backed nonvolatile CMOS RAM, and an 8085 CPU running at 3.072 MHz. The board also has two 14-bit counters and 46 I/O pins, and it will accept four prioritized interrupts. Siemens AG, Zentralstelle fuer Information, Postfach 103, 8000 Munich 1, West

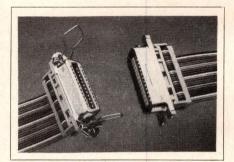
Germany. Phone (089) 2340. TLX 5210025.

Circle No 427

CPU CARD. Providing an 8-MHz 68000 CPU for G-64 bus systems, the GESMPU-4A single Eurocard has four memory sockets that you can load with 128k bytes of EPROM, 16k bytes of RAM, or a

RAM/EPROM mix. It also includes a baud-rate-programmable RS-232C serial interface and a triple timer. Debugging firmware and CP/M (68k) and OS-9 operating systems are available for the board. 1250 SFR. Gespac sa, 3 Chemin des Aulx, 1228 Geneva/Plan-les-Ouates, Switzerland. Phone (022) 713400. TLX 429989. Gespac Inc, 550 E Grandview, Mesa, AZ 85203. Phone (602) 962-5559. Circle No 428





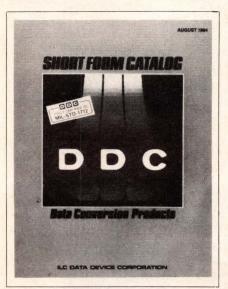
CONNECTOR. Available in 24- or 36-contact versions, the Delta range of plug and socket connectors is suitable for connection to ribbon cables or discrete wires or for direct soldering to pc boards. Ribbon-cable versions accommodate 0.050-in... 28-AWG stranded, or 30-AWG solid conductors. They incorporate strain-relief clips and can be supplied with metal or metallized-plastic shells. Discrete-wire types have solder-eyelet terminations, metal shells, and metal back shells that include a cable clamp. PC-boardmounting types include a vertical. plastic-shell version and a horizontal, plastic- or metal-shell type. The metal shell has a solder tag for grounding to the pc board. All Delta connectors have a temperature rating of -55 to +105°C, a current rating of 3A at 85°C, and a mechanical-endurance rating of 500 operations. Around £3 (100). Bicc-Vero Electronics Ltd, Hedge End Industrial Estate, Flanders Rd, Hedge End, Southampton SO3 3LG, UK. Phone (04892) 81424. TLX 477984. Bicc-Vero Electronics Inc. 40 Linderman Dr, Trumbull, CT 06611. Phone (203) 372-0038.

Circle No 429

Terms and definitions for software management

Management Bulletin No 4-1A, entitled Configuration Management for Digital Computer Programs, defines the terms and definitions to be used during the development, documentation, verification, and delivery cycles of new and modified software. It lists and defines common terms currently used in softwareconfiguration management. This bulletin updates and replaces Configuration Management Bulletin No 4-1 (published in May 1982). \$15. **Electronic Industries Association** Standard Sales Office, 2001 Eye St NW, Washington, DC 20006.

INQUIRE DIRECT



Data conversion and MIL-STD-1553 products

This 8-pg short-form catalog describes data-bus products, A/D and D/A converters, S/H amplifiers, synchro-to-digital and digital-to-synchro converters, T/H amplifiers, synchro and selsyn instruments, and MIL-STD-1553 components. Other products listed included control transformers, a synchro booster amplifier, SEM modules, and Inductosyn-to-digital converters. ILC Data Device Corp, 105 Wilbur Pl, Bohemia, NY 11716.

Circle No 375

4-volume set lists battery data

Eveready Battery Engineering Data is a 4-volume set that contains technical data and descriptions of the company's line of batteries. Volume I covers miniature batteries such as silver-oxide, mercuric-oxide, and manganese-dioxide types, and mercuric-oxide cylindrical types. Volume II describes alkaline cylindrical batteries and manganese-di-oxide miniature batteries. Volume III details general-purpose and heavy-duty carbon-zinc batteries, and Volume IV covers nickelcadmium batteries. For a given battery family (eg, mercuric oxide), the text describes the devices' construction, electrochemistry, temperature range, and applications. The booklets also give discharge curves (voltage vs time at a given temperature), dimensional drawings, and battery specifications. 4-volume set, \$20; individual volumes, \$5. Union Carbide Corp, Battery Products Div. Section B-2-155, Old Ridgebury Rd, Danbury, CT 08817.

INQUIRE DIRECT

Tools for RF testing

A pamphlet entitled Accessories for RF Testing describes broadband antennas, TEM cells, field-sensor systems, leveling preamplifiers, fiberoptic telemetry systems, directional couplers, power combiners and dividers, matching transformers, computer-interface modules, and system-assembly kits. It lists specifications for each device and includes B&W photographs. Amplifier Research, 160 School House Rd, Souderton, PA 18964.

Circle No 376

Booklet explains solder preforms

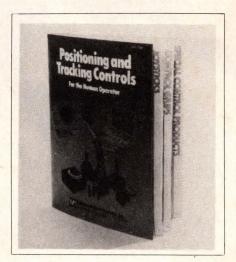
Solderforms Design and Specification Handbook discusses the pros and cons of using preforms and lists the specifications of the company's Solderforms that are made from foil solder, wire solder, and wire spheres. The 12-pg booklet contains a chart that lists the alloy compositions, their melting range, specific gravities, and tensile strength. The booklet also offers tips on when to use flux-coated or flux-cored preforms. **Kester Solder**, 4201 Wrightwood Ave, Chicago, IL 60639.

Circle No 377

See what's available in surface-mount components

The 2-color, 24-pg Surface Mount Components illustrates the company's products. Types include multilayer ceramic and solid-tantalum capacitors; resistor networks; transistors, rectifier diodes, and Zener diodes; and interface linear and Hall-effect designs. Sprague Electric Co, Technical Literature Service, Marshall St, North Adams, MA 01247.

Circle No 378



Mice and joysticks

Positioning and Tracking Controls describes a variety of man/machine interfaces, such control as mice, joysticks, force sticks, trackballs, and control grips. The 24-pg booklet also describes interfaces for these products. Measurement Systems Inc, 121 Water St, Norwalk, CT 06854.

Circle No 379

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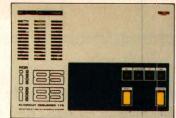
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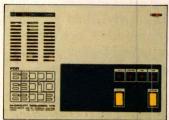
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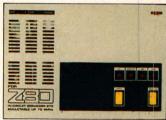


i8086/88 i8086 i8087 IRORR

Co-emulation of 8086 and 8087 or 8088 and 8087 processors to 5 MHz. Realtime emulation to 8 MHz for 8086/88 processors. Features: 128K bytes static RAM - expandable to 1 Mbyte, 4K deep x 40 bits deep realtime trace buffer, 30 different debugger commands.

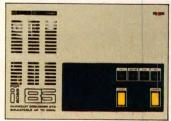


Emulates 68000, 68008 and 68010 in one unit to 10 MHz. Features; 128K of emulation memory expandable to 256K, 4K deep x 48 bits wide realtime trace buffer, 30 different debugger commands



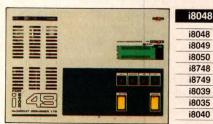
Z80 780 **Z80B** Z80H

Emulates Z80B microprocessors to 6 MHz and Z80H to 8 MHz. Features; 64K byte user emulation memory, 2K deep x 32 bits wide realtime trace buffer, 29 different debugger commands.



i8085 i8085A i8085A-1 i8085A-2

Emulates 8085 processors up to 6 MHz. Features; 64K byte user emulation memory, 2K deep x 32 bits wide realtime trace buffer, 29 different debugger commands.



i8048 i8049 i8050 i8748 i8749 i8039 i8035 i8040

Emulates entire 8048 family in one unit to 11 MHz. Features; 4K emulation memory, 2K deep x 32 bits wide realtime trace buffer, 29 different debugger commands, 8748 and 8749 units feature a built-in EPROM programmer.

Capacitor compendium

Capacitors describes mica (dipped, radial taped, chip, metal clad, and variable compression), ceramic-disk, monolithic-ceramic, aluminum-electrolytic, dipped-tantalum, polyester, and metallized-polyester capacitors and printer-filter capacitor networks. The 56-pg catalog also includes photographs, mechanical specifications, performance curves, and charts. Arco Electronics, 9822 Independence Ave, Chatsworth, CA 91311.

Circle No 380

Standard tests for fiber-optic cables

RS-455-45, Microscopic Method for Measuring Fiber Geometry of Optical Waveguide Fibers, describes a method of measuring the five fibergeometry parameters—core diameter, core ovality, cladding diameter, cladding ovality, and core-to-cladding offset—that characterize the electric joint loss you can expect when you join two fiber-optic waveguides by fusion or with a mechanical connector. \$8. Electronics Industries Association, Standard Sales Office, 2001 Eye St NW, Washington, DC 20006.

INQUIRE DIRECT

Papers on switched-capacitor filters

MOS Switched Capacitor Filters: Analysis and Design brings 50 published papers on this technology together in one volume. The papers place emphasis on the basic principles, analysis, design, and implementation of practical filters as opposed to network theory. In addition, the papers include methods and circuits used in current design. IEEE members, \$40.15; nonmembers, \$66.95. IEEE, Service Center, 445 Hoes Lane, Piscataway, NJ 08854.

INQUIRE DIRECT

Note discusses CRT recovery problems and cures

Recovery in CRTs is the controlled dissipation of stored energy in the deflection system. Application Note No 6 details the ways the mechanical layout of magnetic components, chassis components, and shields can affect CRT recovery. In particular, the pamphlet discusses the ac components of recovery (a function of resonant frequencies, deflectionyoke core characteristics, shields, and mounting structures) and the dc components (voke design, core shape, and materials). Syntronic Instruments Inc. 100 Industrial Rd, Addison, IL 60101.

Circle No 381

Circuit-design techniques for power semiconductors

The 152-pg Semiconductors Applications Handbook provides design techniques, examples, and applications covering power-switching techniques for on-card dc-to-dc conversion and secondary regulation of single- and multiple-output power circuits. It also covers dc-motor control, with constant-speed and constant-torque applications together with half-bridge and stepper-motor drives. In addition, the handbook discusses line-operated switching supplies. Lambda Semiconductors, 121 International Dr. Corpus Christi, TX 78410.

Circle No 382

How to use the moon for antenna measurements

An Error Analysis for the Use of Presently Available Lunar Radio Flux Data in Broadbeam Antenna-System Measurements (TN1073) describes how you can make satellite earth-station G/T measurements using the moon as a noise source. The method is useful for antennas receiving signals on frequencies between 1 and 10 GHz.





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**polyFORTH/32 is a trademark of Forth Inc.
†Idris is a trademark of Whitesmith, Ltd.
†Unix is a trademark of AT & T Bell Laboratories

A Look at Today. . . A Vision of Tomorrow.



LITERATURE

Stock No 003-003-02555-1, \$2. Superintendent of Documents, US Government Printing Office, Washington, DC 20402.

INQUIRE DIRECT

Get on board with stick-on patterns

Microelectronics Artwork Patterns, Catalog 601, describes patterns for hybrid surface-mounted devices, ICs, small-outline transistors, and small-outline artwork for high-density applications. Bishop Graphics Inc, Box 5007, Westlake Village, CA 91359.

Circle No 383

IEC standard covers time-delay switches

This standard, Publication 669-2-3, applies to hand- and remote-control operated time-delay switches with rated voltages to 440V and rated currents to 63A. Specifically, it covers those switches that have a mechanically, thermally, pneumatically, hydraulically, or electrically operated time-delay device or any combination thereof. 31 Swiss francs. International Electrotechnical Commission, 1, Rue de Varembé, 1211 Geneva 20, Switzerland.

INQUIRE DIRECT

How to design GHz and THz mixers

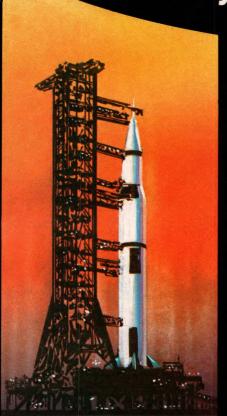
Microwave and Millimeter-Wave Mixers gathers papers on aspects of mixer theory and practice such as accurate modeling and computeraided analysis of Schottky-diode mixers, practical mixer implementations, harmonic mixers, intermodulation, cryogenic Schottky-barrier mixers, superconducting junction mixers, and FET mixers. The book includes a detailed introduction on mixer theory. IEEE members, \$35.95; nonmembers, \$66.95. IEEE, Service Center, 445 Hoes Lane, Piscataway, NJ 08854.

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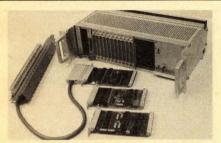
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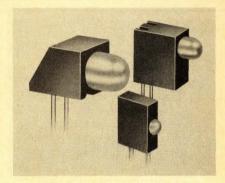


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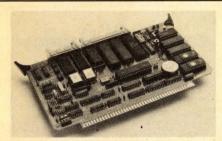
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New IC Generates Call Progress Tones

Now you can generate dial tone, busy tone, reorder tone, audible ringing, and other call-routing tones with just one 14-pin CMOS chip. Teltone's unique new M-991 call progress tone generator will produce combinations of seven frequencies from 350 to 1209 Hz using a single 5V to 12V supply. Binary input generates pure tone output with harmonics at least 35dB below the call progress frequency band. Currently the only call progress tone generator on the market, the M-991 utilizes a 3.58 MHz crystal timebase and is available for immediate delivery.



IC Detects Call Progress Tones

Teltone's new M-980 is a CMOS call progress tone detector. It monitors dial tone, circuits-busy, station-busy, audible ringing, and other call-routing tones in the telephone progress supervision band (300-640 Hz). It's sensitive to signals from 0 dBm to -40 dBm and detects tones which vary by location or call destination. It operates from a single 5V supply and uses an inexpensive 3.58 MHz crystal or external clock.



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CIRCLE NO 216

Quelo' Assembler

First Commercial Release

The QueloTM portable 68000 assembler conforms to the Motorola resident assembler, publication M68KMASM[D4].

Quelo™ 68000 Assembler Package Features:

Quelo "68000 Assembler Package Features: Input file concatenation, include function, macros, global parameter substitution from command line, listing date-time stamp, up to 31 character symbols, conditional assembly, structured programming directives, instruction, optimization, 88010 instructions, relocation and linking, complex expression linking (all operators), DB-0W-DL directives for ZBO byte order data generation, object library utility, software configuration tracking, conditional linking, options for assembler and linker to write complete symbol table to a file, detailed symbol table listings, assembler symbol cross-reference, linker global symbol cross-reference, object library symbol cross-reference supert linker load map, various HEX load formats produced by linker, error messages in English, extensive typeset manual with index, readily transported to any system with a C compiler and "UNIX like" system interface.

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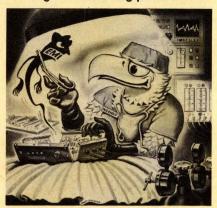
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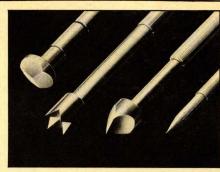
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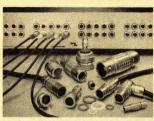


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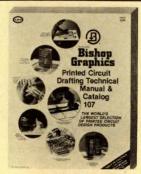
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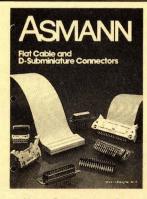


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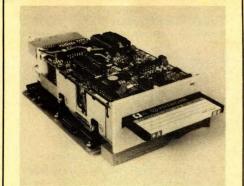


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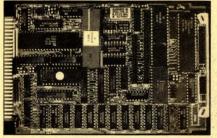
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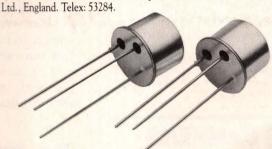
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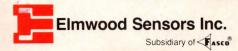
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NEW BOOKS

Hybrid Microelectronic Technology, Peter Moran, editor. 225 pgs; \$60 (hardcover); Gordon and Breach Science Publishers, New York, NY, 1984.

Volume 4 of the Electrocomponent Science Monographs series is a comprehensive guide to the newest techniques in the manufacture and industrial use of hybrid microelectronics. Included is a survey of state-of-the-art technology, with emphasis on methods of design, packaging, processing, application, and quality control.

Introduction to Integrated Circuit Layout, by Brian Spinks. 177 pgs; \$19.95; Prentice-Hall Inc, Englewood Cliffs, NJ, 1985.

Using the working vocabulary of the trade, this book examines the basic theory behind the layout of semiconductor integrated circuits as it leads you through a typical design cycle. Converting a logic diagram to a composite drawing is the main objective; the book also emphasizes chip planning, MOS transistors, test sites, packaging, logos, and input protection.

Engineering SOFTWHERE. 353 pgs; \$29.95; Moore Data Management Services, Minneapolis, MN, 1984.

This directory lists hundreds of programs from leading software vendors for a variety of applications. It contains a description of each program as well as information on price, training, hardware, operating systems, and source language. Programs are listed under such categories as database management, electrical, mechanical, aerospace, and math/statistics.

Digital Systems, 3rd edition by Ronald J Tocci. 591 pgs; \$31.95; Prentice-Hall Inc, Englewood Cliffs, NJ, 1985.

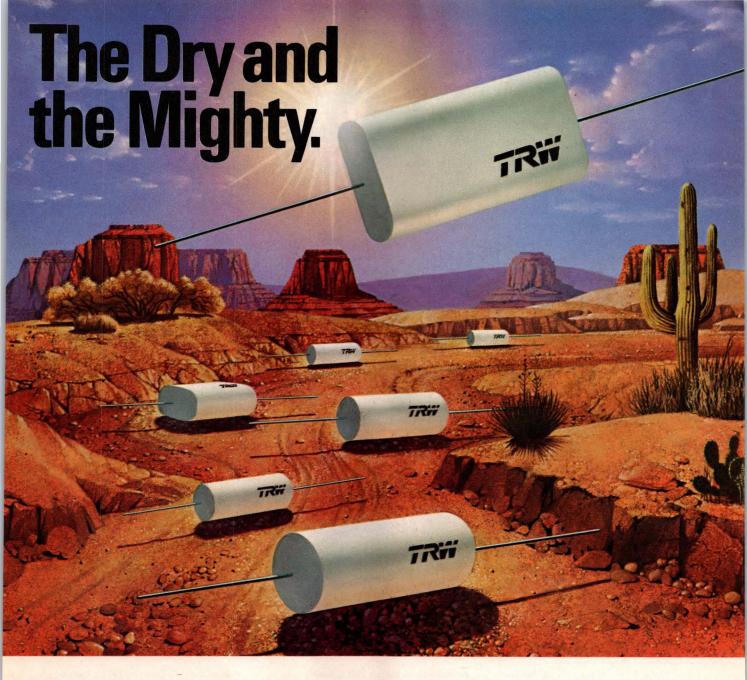
The third edition of Digital Systems retains features from the previous books but includes modificaextensions, and new applications for the material. The updated information reports on the latest devices and uses illustrations of actual ICs, timing diagrams, and waveforms as examples. Counters and registers, logic circuits, gates, flip flops, and memory devices are a few of the topics examined. Also covered are digital IC families, such as TTL, CMOS, MOS, ECL, and 3-state logic.

Basic Technical Writing, 4th edition, by Herman M Weisman. 414 pgs; \$20.95; Charles E Merrill Publishing Co, Columbus, OH, 1980.

In addition to detailing the fundamentals of technical writing, this edition includes new chapters on preparing oral reports and proposals. The author illustrates and analyzes examples of good and bad technical writing and includes problems and exercises for the reader to practice with. The chapter on semantics offers a strong foundation for understanding technical language, and there's an improved and expanded guide to punctuation, style, grammar, and usage.

Kierulff Designer's Guide. 350 pgs; \$75; Kierulff Electronics Inc, Los Angeles, CA, 1984.

This reference targets computer systems designers who must select products that help meet their design goals of function, performance, and cost. Included is a technical overview of products from a variety of companies, lists of specifications and performance features, data sheets, and photographs. The book also provides information on computer products and systems, software, peripherals, data communications equipment, and accessories from 25 of the leading manufacturers.



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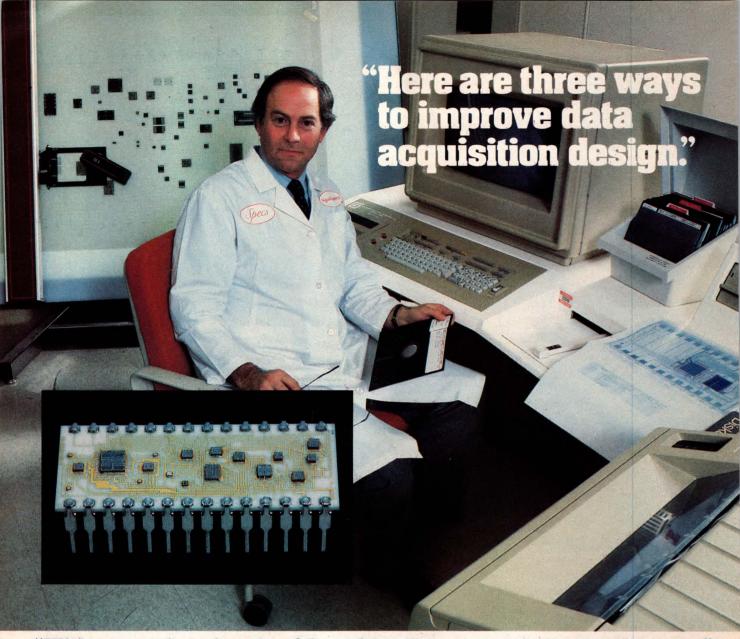
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CIRCLE NO 185

PROFESSIONAL ISSUES

Written and edited by Deborah Asbrand

Politically active EEs prove that government isn't just for lawyers

Every January, while most engineers are trying to avoid the postholiday doldrums, George Dean takes his engineering skills and experience to the state capitol building in Wichita, KS. Dean then spends the next three months as the representative from the 96th district to the Kansas House of Representatives.

Dean has served for the past six years as a representative in the state legislature, and this fall, he's campaigning for his fourth term. When the legislature isn't in session, he works as a guidance and control engineer for Beech Aircraft Co, where he has been employed for the past 19 years.

Dean disagrees with the notion that engineers tend to be apolitical and have technical backgrounds that leave them unprepared for activity in politics. At one time, as many as four members of the state legislature were trained engineers, Dean says. And although many people assume most legislators are lawyers, only 16 of his 125 fellow representatives are attorneys.

Engineers, he says, are no different from other professionals. "I think many engineers are interested [in the political process]. They just don't take that extra step [to become involved]," he says. "Engineers are more critical of themselves than they ought to be. I think they're interested in a lot of different things; they're no different than anybody else." In fact, in Dean's office at Beech Aircraft, his colleagues include one engineer who serves as a city commissioner and another who is a school-board member.

To work as both a politician and an engineer, Dean has had to juggle



IEEE Congressional fellow Joe Edminister (left) spent the past year working with Ohio Democrat Rep Dennis E Eckart (right) on environmental and energy issues.

a hectic schedule and make personal and professional sacrifices. "There are a lot of different prices to pay and one price is economics. You take time away from your job... and you lose money." Dean takes a 3-month leave of absence from his job to attend the legislative sessions. Although he's not paid while on leave, his company continues his seniority. Kansas legislators do draw a salary, but it's a relatively small compensation compared with Dean's engineering salary.

The time he has devoted to his political activities has impinged on Dean's professional status as well as his finances. Because he's away a quarter of each year, he has had to sacrifice some responsibilities and advancements. Even a company that's tolerant of your periodic leaves can't put you in a supervisory position, he acknowledges. "You can't be a supervisor," he says, "and be off for three months."

After five years as a representative to a neighborhood-based advisory council to Wichita's city commissioner, he made a successful bid for a seat in the House of Representatives in 1979. In the three terms he has served since, he has been a member of several committees: Public Health; Transportation; Local Government; Energy; and Computers, Communications, and Technology.

Kansas's need to dispose safely of hazardous waste became an important issue for the Energy Committee during Dean's second term. For example, toxic wastes in barrels buried underground were leaching into the water system. It was a key issue for Dean, who represents the urban southwest portion of Wichita and industrial constituents such as Boeing, Cessna, Gates Learjet, and his own employer, Beech Aircraft. Solid waste, such as the paint sludge that's generated during the

PROFESSIONAL ISSUES

manufacture of airplanes, is currently stored in above-ground tanks, and the problem is "in limbo," says Dean. Safe disposal of wastes is expected to be a key issue in the 1985 legislative session.

As the ranking minority member of the Computers, Communications, and Technology Committee, Dean spoke before the House in support of a bill that proposed adding a math and science specialist to the staff of the state department of education. He was instrumental in the success of the bill, which provided assistance to the school department in upgrading math programs and organizing a computer-education curriculum.

Dean expects the Computers, Communications, and Technology Committee's goals will include improving the engineering programs at the state's universities and upgrading math and science programs in secondary schools. In addition, the committee expects to improve the state's telecommunication division and improve the three Centers of Excellence located at state universities. Dean's Democratic party needs to gain 10 seats in the election to become the controlling party in the House; if the party succeeds, Dean could become chairman of the Computers, Communications, and Technology Committee.

Although a political career does have its disadvantages, it also has given Dean opportunities he would not otherwise have had. For example, his alma mater, the University of Kansas, invited him to serve as a member of the Industrial Advisory Committee, which reviews and evaluates the school's computer curriculum. "I wasn't a great student and I haven't achieved great position in industry," he says, "so that was a neat perk."

As chairman of the IEEE/USAB Government Activities Council, Dean is a member of the Congressional Fellows Committee, which gives engineers an opportunity to witness the political process at the



Because of his work on Capitol Hill as a legislative assistant to Sen Bill Bradley (D-NJ) (right), George Swetnam (left) says his Congressional experiences will benefit him when he returns to his job at Mitre Corp., a consulting firm to the US government.

national level. Congressional fellows spend one year on Capitol Hill as staff assistants to a senator or representative or to a committee. During that time, they continue to draw full salary, half of which is paid by the IEEE and the other half by their employer.

The American Association for the Advancement of Science (AAAS) provides two to three weeks of orientation for the IEEE Congressional fellows and for 35 or 40 other professionals from the "hard" and "soft" sciences. Once they've been schooled in the intricacies of life in the Capitol, the fellows are counseled in how to approach a US senator or representative about working with him or her. "One of the things AAAS coached us on is that you can be really unhappy working for somebody if you're a right-wing conservative and you wind up in the office of a left-wing liberal; you're going to be uncomfortable supporting most of the things he is supporting," says George Swetnam, an IEEE Congressional fellow who spent the past year as a legislative assistant to Senator Bill Bradley (D-NJ).

Swetnam, 47, specializes in com-

mand and control systems and communications at Mitre Corp in McLean, VA, and has done work on environmental pollution, solar energy, and urban transportation.

A close observer of Washington politics for many years, Swetnam was interested in witnessing federal decision making first hand. "I had a deep personal interest in Congress after living in the Washington suburbs for 15 years. You get to see Congress fairly close up, and it's a fascinating place. One of the reasons I chose a job on the personal staff of a member was that, for me, the member's office is where it's at: that's where the votes are and where the decisons are made, and I wanted to see how those decisions were influenced."

Swetnam has experienced "not one dull or boring day" during the past year. He has worked 50 hours a week, but only about 5% of his responsibilities have required an engineering background. "You don't come in here and do differential equations," he says. Swetnam was Bradley's troubleshooter in the areas of environment and transportation. His first responsibility was to be aware of any legislation in

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PROFESSIONAL ISSUES

either topic area and to know when it was scheduled for a committee vote or a floor vote. He would also tell Bradley what it meant nationally and what it meant to New Jersey, and which groups in the country supported and opposed it. If Bradley's office had received constituent mail on the legislation, Swetnam summarized what the constituents were saying. Finally, he made a recommendation on how he thought Bradley should vote.

Senator John Warner of Virginia is one of only three members of Congress with electrical-engineering backgrounds. Because of his activities in technological issues such as national security and energy, he has two engineering fellows working on his staff. Army Lt Col Guy Copeland, a research-and-development project manager, spent the past year working as an IEEE Congressional fellow in Warner's office.

Learning how Congress thinks

"My educational background was pretty good in understanding the viewpoint of industry and understanding the viewpoint of the government, at least the executive branch. But project managers, by the nature of the business these days, have a lot of interaction with Congress. I felt that I didn't have a good founding background in that area, so I applied for the fellowship," Copeland says.

Copeland spent much of his time studying issues of command and control, technology, and electronics for Warner, who is active in national security and foreign affairs. When the Armed Services Committee, of which Warner is a member, broke into working groups to examine the Department of Defense, Copeland represented Warner on a group studying procurement policies and helped draft the group's final report. Most of Copeland's contact with Warner occurred during informal meetings several times each week. But when Warner's legislative assistant for national security



Rep George Dean, a guidance and control engineer at Beech Air Craft Co, addresses the Kansas State Legislature.

entered the hospital during a critical period for the 1985 Defense Authorization Bill, Copeland pinch-hit and spent a great deal of time with Warner during the Senate hearings.

There "very definitely" is a role for engineers in the political process, Copeland says. While working in Warner's office, Copeland regularly received material from the Energy Committee of IEEE's Professional Activities Committees for Engineers (PACE). The group has been very effective in presenting its position papers on energy issues, he says. "There is definitely a role for the engineers. In fact, if anything, they're not active enough," says Copeland.

Joe Edminister is a former IEEE PACE chairman who spent the last year as a Congressional fellow working for Democrat Dennis Eckart, one of Ohio's 21 members in the House of Representatives. Edminister had known several Congressional fellows while serving as the PACE coordinator for his region, which included Washington, DC. When he opted for a career change last year after teaching electrical engineering at the University of Akron for 26 years, it seemed like the right opportunity to apply for a fellowship himself.

Edminister became interested in working for Eckart because of the representative's activity in environmental and energy issues. Eckart is a member of the House Energy and Commerce Committee, which recently passed a bill to safeguard drinking water from possible contamination by deteriorating underground storage tanks.

The switch from engineering to national politics required "playing catch-up ball," and, once he arrived in Washington, he spent many hours reading to educate himself on the workings of the government. "It's like total immersion," he says. "There are so many things about the federal government that, as engineers, we just don't know."

Most engineers don't realize that simply talking with their representatives is "a totally useless" effort, Edminister says. "You have to find out whether the congressman is in a position to do anything of any substance. That means he's got to be on the subcommittee where that legislation is being fashioned. Then you also have to be very timely, you have to be talking to his staff . . . He's got one person on his staff who will be the principal one to help guide the legislation and put the amendments on. If you want someone to know your position on a bill, you've got to get it in right there at the subcommittee level."

Time is the limited resource for most politicians, and you need clarity to make even a brief meeting with a legislator or a staff assistant work to your advantage. It's easy for professionals like engineers to lapse into technical jargon and weaken their presentation by inundating their representative with material. "You don't tell them everything you know," Edminister advises. "They don't want to know what you know. They only need to know . . . what it is you want and how it fits into the bill. It also helps if you let a congressman know how many engineers he's got in his own district. That catches his attention."

Ken McGowan, who has been involved in politics in Washington state for 10 years, educates engineers on how to avoid making these

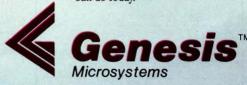


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"The Engineer in Politics: The IEEE and State Legislative Activity" is a 26-pg publication with information on how to form a State Intersociety Legislative Advisory (SILA) group. It discusses a recommended organizational structure, legislative planning matrix, forms for rating bills and assigning priorities, and other support documents. For more information on forming an SILA or to request a copy of the booklet, contact Ken McGowan, Coffman Engineering, 1021 112th Ave NE, Bellevue, WA 98004; phone (206) 453-8092 or (206) 643-6560.

mistakes. McGowan is IEEE's PACE government-action facilitator and the vanguard of the IEEE's efforts to organize legislative action groups in each state.

McGowan is a representative to the Architects and Engineers Legislative Council (AELC), an intersociety organization that monitors state legislation pertaining to hightechnology, taxation, environmental, and energy issues. AELC representatives meet once each week when the legislature is in session and once every other week when the legislators have adjourned. They retain a full-time lobbyist who sifts through the approximately 4000 proposed bills and selects 300 or 400 bills for the group to review. The group has a 100% success rate on bills they take priority on.

McGowan hopes to encourage other IEEE members to consolidate their state legislative efforts by forming State Intersociety Legislative Advisory groups (SILAs), using the AELC as a prototype. It's much more effective, he says, for the IEEE to "consolidate its efforts with the other technical and professional organizations to perform this technical input and review legislation. When you go down to the legislature and say that you represent 10,000 engineers that are concerned about energy issues, it's kind of like EF Hutton is talking. People stand back and listen."

In addition to their regular meetings, AELC members appear at caucuses and fund raisers. On the basis of the group's success in the

last few years, McGowan has taken more of an interest in the political process. "Engineers by nature tend to be conservative," he says. "Even on the national level, they've been one of the last learned professions to become experienced on the [Capitol] Hill...They've begun to realize they have to become a part of the solution to life's problems, particularly now that we're in a high-tech phase of development."

Swetnam's time on Capitol Hill was more than just an interesting way to spend a year. "The fellowship experience has sensitized me both to political issues and to professional ones," he says. "And I hope that I can do more in both those areas." He predicts his Congressional experience will make him a better consultant when he returns to Mitre. "My 15 years of experience have been with a variety of federal agencies. I've always seen the government from the executive-branch point of view. My belief is that most executive-branch agencies don't really understand the way Congress thinks. I knew I didn't, and most of the people I had advised didn't. I felt that if I could see that interface —the executive/legislative interface —from the other side, when I went back to consulting I'd be a better consultant. And I think that's going to be true." EDN

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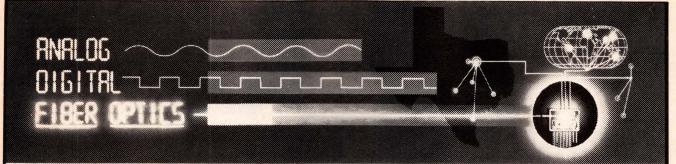
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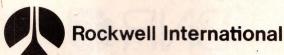
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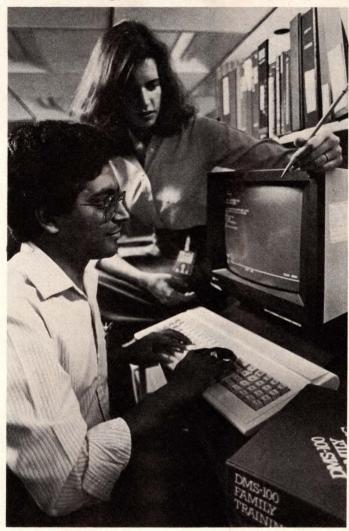
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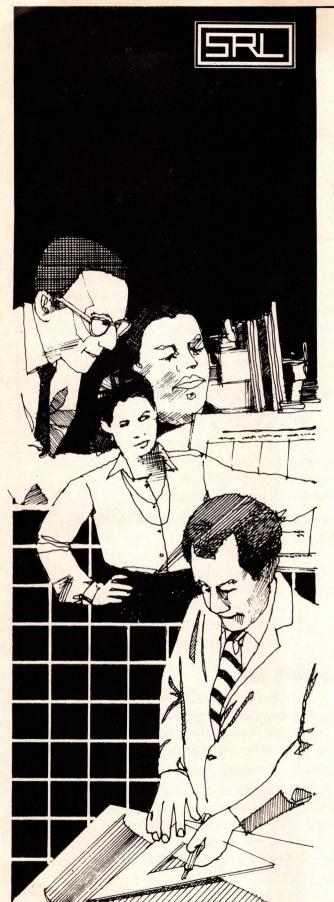
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	Motorola Semiconductor Products Inc 50-51, 77-78 180-181, 191-193	Zilog Inc
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MARKET FORECASTS

Impact of Technology Trends on Workstations (#1520). \$1500; Strategic Inc, Box 2150, Cupertino, CA 95015.

This market study analyzes current issues and the future impact of new technologies on the workstation market. It deals with all aspects of workstation development and the effects on software and packaging.

Micro/Minicomputer Power Equipment (#1322). 193 pgs; \$1500; Frost & Sullivan Inc, 106 Fulton St, New York, NY 10038.

The increased use of computers in daily life has escalated the demand for protection from electrical power disturbance. This report forecasts the market for power-conditioning equipment for micro and minicomputers and computer-based equipment. It offers a technology overview, describes the equipment and its uses, and looks at market trends and manufacturer strategies in the industry.

The Personal Robot Market (#615). 255 pgs; \$1650; International Resource Development Inc, 6 Prowitt St, Norwalk, CT 06855.

This extensive study of the present state and future growth of the US market for personal robots includes 10-year forecasts for personal robotics in the education, home, industry and commerce, medical, and hobby markets. It profiles key vendors and their products and examines opportunities for growth in the market.

Trends and Opportunities in Fourth-Generation Languages. \$750; Input, 1943 Landings Dr, Mt View, CA 94043.

Fourth-generation languages have aroused vendors' interest because they promise to increase employee productivity and lessen software development backlogs. This report analyzes the market for fourth-generation languages and

examines how the languages are used, their impact on organizations, and their strengths and weaknesses. The report provides a 5-year forecast detailing fourth-generation-language growth in related industries.

Henderson Electronic Market Forecast. \$750 per year; Henderson Ventures, 101 First St, Suite 444, Los Altos, CA 94022.

The August issue of this monthly publication highlights the major applications for GaAs semiconductors and provides a comprehensive forecast of the market for the next five years. The report emphasizes the difficulties passive-component manufacturers will face because of the rapid growth of the GaAs market.

Telecom Bypass Markets (#612). 193 pgs; \$985; International Resource Development Inc, 6 Prowitt St, Norwalk, CT 06855.

This report analyzes the growth of the telecom-bypass market and gives 10-year forecasts for the industry. It also describes the available technologies, including cable TV, digital termination systems, private microwave, satellite communications, and other local-loop alternatives.

Laser Market Opportunities (#606). 206 pgs; \$1285; International Resource Development Inc, 6 Prowitt St, Norwalk, CT 06855.

This analysis probes the governmental and commercial segments of the laser market for likely applications and discusses basic laser technology. In addition, it examines the market and industry structure and provides the reader with 10-year forecasts in each area.

Future Skills Requirements for Software Development. \$750; Input, 1943 Landings Drive, Mt View, CA 94043.

The increasing need for humanis-

tic as well as technological training in the field of systems analysis makes this a timely report for design managers in information systems. The report forecasts the development of the software environment and predicts the types of software skills that corporations will need to have in their information systems departments in the next few years.

Market for Add-on Boards, Systems & Equipment for the IBM PC. 241 pgs; \$1850; International Resource Development Inc, 6 Prowitt St, Norwalk, CT 06855.

Along with a complete review of IBM's personal computers and a listing of present and potential suppliers, this report assesses the market for add-on printers, storage devices, displays, communications products, input equipment, and boards. A 10-year market-growth forecast is provided for each area.

Large-Scale Systems Directions: Mid-Year Update-1984. \$750; Input, 1943 Landings Dr, Mt View, CA 94043.

This report analyzes IBM mainframe hardware and provides residual-value forecasts for the next five years. It delves into the large-scale systems strategies of IBM, Amdahl, and NAS. Questions about the future use of large mainframes are discussed in depth. Forecasts to 1989 are also included.

The Optical Memory Report, 1984 Edition. 372 pgs; \$1995; Rothchild Consultants, Box 14817, San Francisco, CA 94114.

This report includes market forecasts to 1990 on the US market for optical storage products and presents information on the products and their technology and marketing. It lists manufacturers and their products and specifications, prices, shipments, and development projects.

LOOKING AHEAD

Computer-keyboard sales to total \$769 million in 1987

Computer and business-equipment manufacturers will continue to be the principal consumers of keyboards in 1987, accounting for 63.8% of a projected \$769 million market. Keyboard sales in 1982 reached \$282.9 million; computer and business-equipment makers reportedly accounted for \$180.5 million of that total and the same 63.8% of the market, according to Venture Development Corp, a Wellesley, MA market-research firm.

The next largest market for computer keyboards is in instrumentation applications. But instrumentation manufacturers will have different keyboard needs from those of computer and business-equipment manufacturers. Keyboard manufacturers with an understanding of the diverse needs of keyboard consumers will be well positioned to offer products appropriate for the different markets.

In the computer and businessequipment segment, for instance, OEMs who purchase keyboards for use in high-growth products are looking for keyboard manufacturers who can fill large orders. They're also paying attention to ergonomic considerations: They want to maximize productivity with office-automation keyboards that are comfortable and easy to use.

Another design consideration is the appearance of the keyboard: Consumers will seek the sophisticated, high-technology appearance associated with a smaller, lighter keyboard. Business-equipment consumers will be concerned with environmental considerations, too. For most applications they'll require a keyboard impervious to liquid spills, but some consumers will also be looking for resistance to chemicals and grease. Switch coverings to prevent pencil punctures will be important to many buyers.

The market will also see an increase in demand for user-definable function keys in business and computer keyboards. Users of electronic cash registers, for instance, are increasingly requesting dummy keys by which they can add their own classifications or new departments. Finally, business keyboard consumers indicate almost no demand for keyboard lighting except for the shift-lock light on some alphanumeric terminals.

Significant opportunities for growth also exist in sales of key-

Edited by Joanne Clay boards to instrumentation manufacturers. Their share of the market is expected to rise from 1982's 20% to 23% in 1987—from \$57.4 million to \$177.2 million. Instrumentation products include such tools as process- and factory-control devices, medical instrumentation, and test and measurement devices.

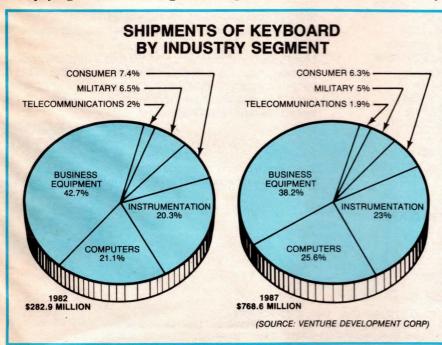
Programmable controllers to invade process control

Annual shipments of batch-control systems based on programmable controllers will more than triple in the next seven years, according to Venture Development Corp, a management consulting firm based in Wellesley, MA. Currently at \$70.5 million per year, total sales are expected to climb to \$214.9 million by 1990.

Shipments of programmable-controller-based systems are expected to increase at the rate of 17.3% per year, while the average growth rate of all batch systems will be 12.4%.

VDC attributes the rapid growth of programmable controllers in the batch-process-control market to several factors. Principally, the major manufacturers of programmable controllers also offer complete integrated control systems that include communications networks, an operator interface and the ability to perform regulatory control. Also, programmable-controller-based systems cost less than distributed or centralized systems.

The biggest markets for these batch systems are the pharmaceutical and food and beverage industries, and programmable controllers are suited to the simple, straightforward applications in these environments. Also, because these industries are not highly automated at present, they offer a great opportunity for the future growth of the market for systems based on programmable controllers.







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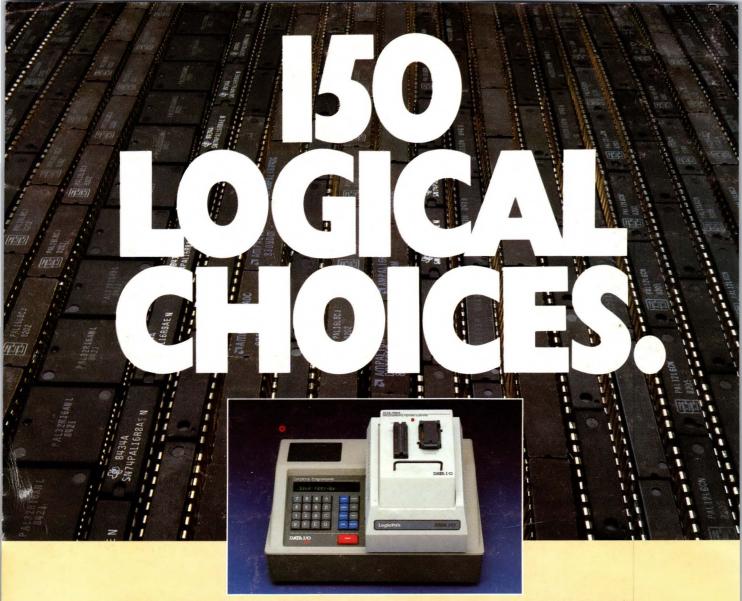
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